

## Introduction

Flow-based models are continuous-time models that gradually transform base distributions into desired target distributions. Such models have been popular in the field of normalizing flow, where the target distribution is pre-specified as the standard multivariate Gaussian. In this context, flow-based models allow accurate density estimation of and efficient sampling from the base distribution.

However, in many problems, our objective is not to model the current data distribution but to find a density transport map that fits other goals. In this sense, we need to *extrapolate* the data distribution along certain directions.

In this work, our particular consideration is the problem of distributionally robust optimization (DRO) [2], which aims to find robust optimal solutions that minimize certain risk over the worst-case distribution within a pre-specified uncertainty set. An essential aspect of solving DRO is to **find the worst-case distribution**, which is an infinite-dimensional optimization problem that is particularly challenging in high dimension for general risk functions.

## Problem setup

Consider a real-valued *risk function*  $\mathcal{R}$  taking as inputs a  $d$ -dimensional distribution  $P$  with a finite second moment and a measurable test function  $\phi$ . Specifically, we assume there is a pre-specified loss function  $\ell$  so that  $\mathcal{R}(P, \phi) = \mathbb{E}_{X \sim P}[\ell(X, \phi)]$ . We are interested in solving the following distributionally robust optimization (DRO) problem:

$$\min_{\phi \in \Phi} \max_{P \in \mathcal{P}_r} \mathcal{R}(P, \phi). \quad (1)$$

In (1),  $\Phi$  denotes the constraint set for  $\phi$  and  $\mathcal{P}_r$  is the Wasserstein-2 ( $W_2$ ) ball around the data distribution  $P_X$ . Namely, we let

$$\mathcal{P}_r = \{P : W_2^2(P, P_X) \leq r^2\}, \quad (2)$$

where by the Monge formulation, the  $W_2$  distance  $W_2^2(P_2, P_1)$  between two  $d$ -dimensional distributions  $P_2, P_1$  with finite second moments is written as

$$W_2^2(P_2, P_1) = \min_{T: T_{\#}P_1=P_2} \mathbb{E}_{X \sim P_1} \|T(X) - X\|_2^2. \quad (3)$$

In (3),  $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$  denotes the transport map and  $T_{\#}$  denotes the push-forward operation by  $T$ , where  $(T_{\#}P)(A) = P(T^{-1}(A))$  for a measurable set  $A$ .

## Our approach

We focus on solving for the worst-case distribution within  $\mathcal{P}_r$  (i.e., the maximizer of the inner problem of (1)), assuming  $\phi$  is given. Note that for each  $r > 0$ , there is an  $h > 0$  dependent on  $r$ , such that we have the following equivalent unconstrained problem:

$$\min_{P \in \mathcal{P}} -\mathcal{R}(P, \phi) + \frac{1}{2h} W_2^2(P, P_X). \quad (4)$$

Under (3), it is also equivalent to solving the optimal transport map  $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$ :

$$\min_{T: \mathbb{R}^d \rightarrow \mathbb{R}^d} \mathbb{E}_{X \sim P_X} \left[ -\ell(T(X), \phi) + \frac{1}{2h} \|T(X) - X\|_2^2 \right]. \quad (5)$$

To yield a tractable and meaningful solution of  $T$ , we parametrize it as the solution map of a NeuralODE model [1]. Specifically, given a neural network  $f(x(t), t; \psi)$  with trainable parameters  $\psi$ , define the solution map  $T_s^t$  over interval  $[s, t]$  as

$$T_s^t(x; \psi) = x + \int_s^t f(x(s'), s'; \psi) ds'. \quad (6)$$

Using (6), the problem of finding  $T$  in (5) thus reduces to training  $\psi$  in the following problem:

$$\min_{\psi} \mathbb{E}_{X \sim P_X} \left[ -\ell(T_0^1(X; \psi), \phi) + \frac{1}{2h} \|T_0^1(X; \psi) - X\|_2^2 \right]. \quad (7)$$

We have also developed a step-wise training algorithm using (7), which is inspired by the JKO approach [5].

## Main contributions

1. Re-formulate the problem of finding worst-case distributions in DRO into its Wasserstein proximal form and subsequently reduce the infinite-dimensional problem into **solving for a transport map**.
2. Parametrize the transport map by **continuous-time flow** neural networks and develop an efficient block-wise training algorithm to train the flow parameters.
3. Demonstrate the **effectiveness** of FlowDRO on various high-dimensional problems from adversarial attack and differential privacy.

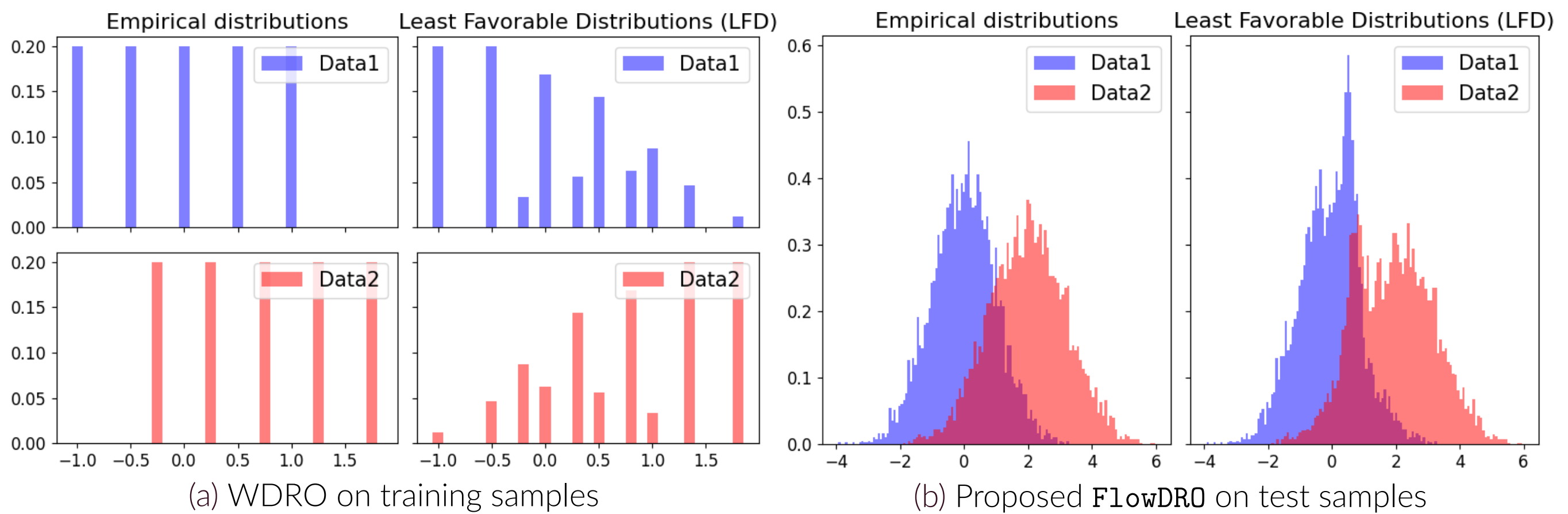


Figure 1. Comparison of WDRO and **FlowDRO** on the 1D example following [4, Figure 1]. **Left of (a) and (b):** Empirical distributions of two sets of *training* (shown in (a)) and *test* (shown in (b)) samples from  $\mathcal{N}(0, 1)$  and  $\mathcal{N}(2, 1.2)$ . **Right of (a) and (b):** Least-favorable distributions (LFD) found by WDRO and **FlowDRO**, where LFDs are within the  $W_2$  ball (2) with radius  $\varepsilon = 0.1$ . Note that WDRO solves a convex problem to obtain the LFD by moving the probability mass on *discrete training samples*. In particular, WDRO does not generalize to a test sample unless it coincides exactly with some of the training samples. In comparison, **FlowDRO** yields a one-to-one continuous-time transport map that can be directly applied to both training and test samples, meanwhile leading to a continuous LFD.



Figure 2. Adversarial samples found by **FlowDRO** and by PGD- $\ell_2$ . Captions show prediction by the pre-trained classifier  $\phi$  on input images  $X_{test}$  (before attack) and  $\tilde{X}_{test}$  (after attack).

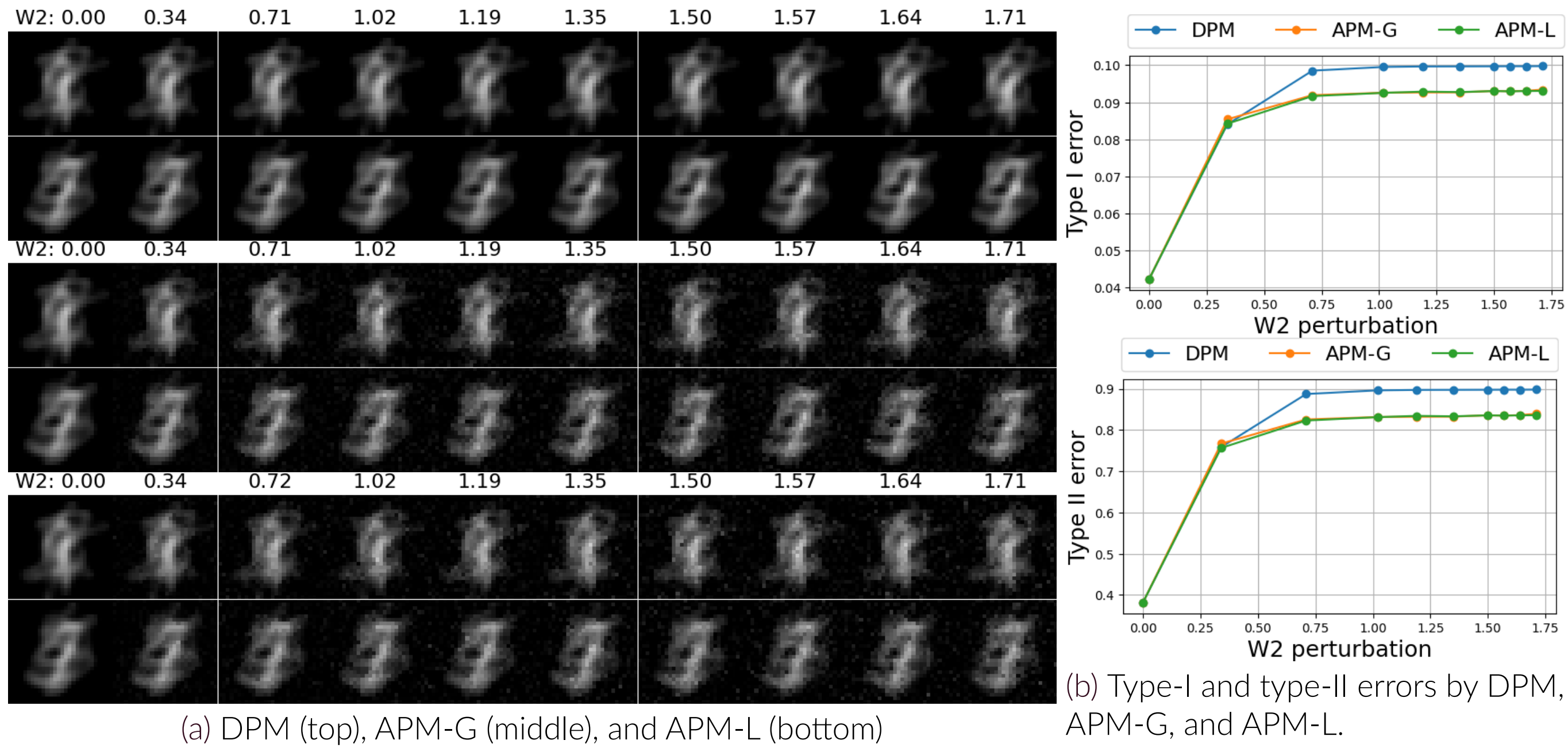


Figure 3. Differential privacy example of one-neighborhood digit missing. Figures (a) visualize privacy-protected queries  $\mathcal{M}_r(q(S))$  by DPM, APM-G, and APM-L within different Wasserstein-2 balls with radius  $r$  around the distribution of  $q(S)$ . Figure (b) examines the type-I and type-II errors over different  $r$ . We control the value of  $r$  by different DP mechanisms to be identical for a fair comparison.

## Numerical results

We showcase the proposed **FlowDRO** on adversarial attack of MNIST and CIFAR10 and differential privacy on membership inference attack. We also show preliminary results on solving the min-max problem (1) to get more robust decision functions  $\phi$  (see Figure 5).

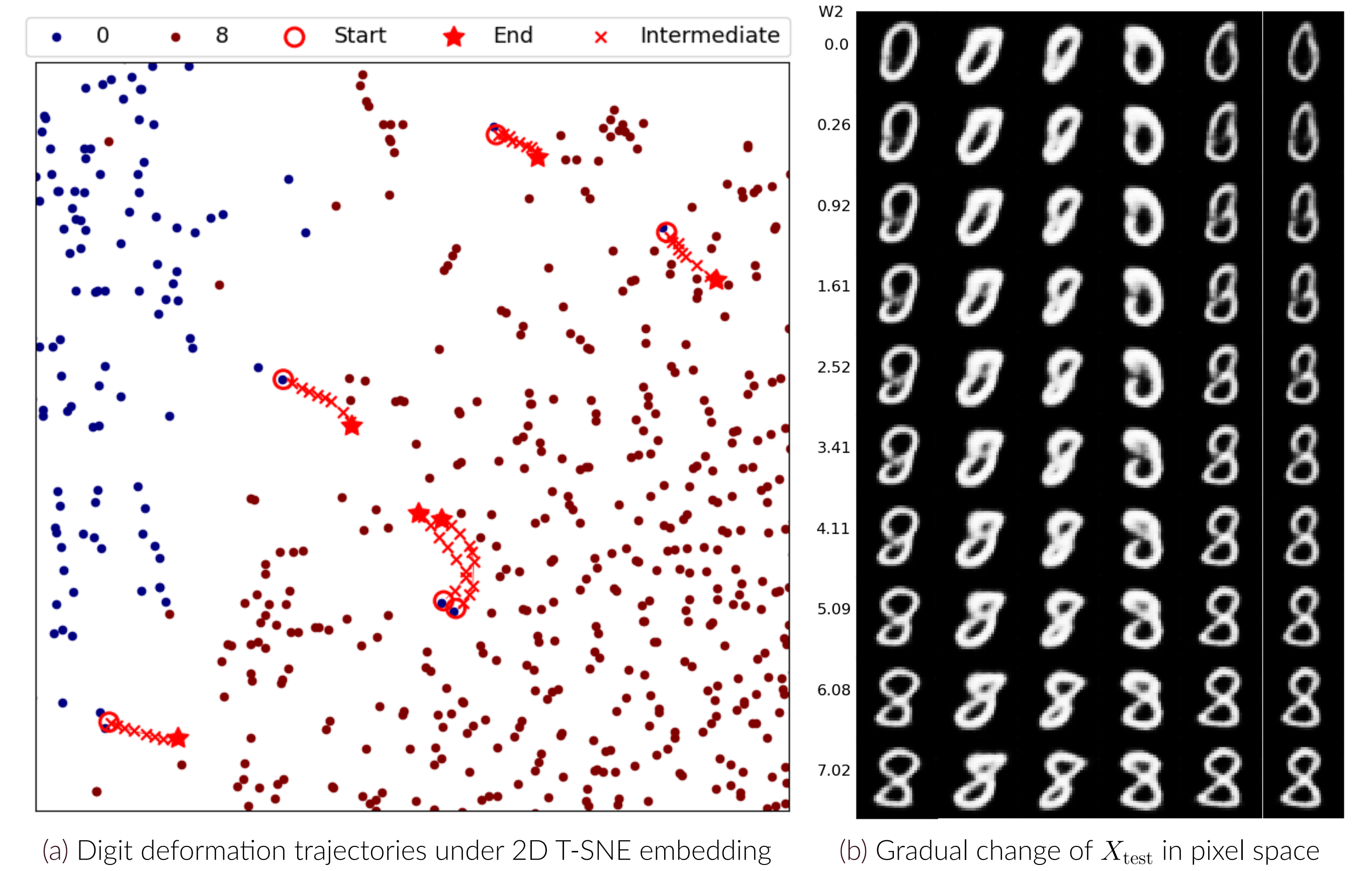


Figure 4. **FlowDRO** perturbation of MNIST digits over blocks and time integration. Figure (a) visualizes the perturbation trajectories from digits 0 to 8 under 2D T-SNE embedding. Figure (b) shows the trajectory in pixel space, along with the corresponding  $W_2$  perturbation between original and perturbed images over time.

## Classification error under PGD attack

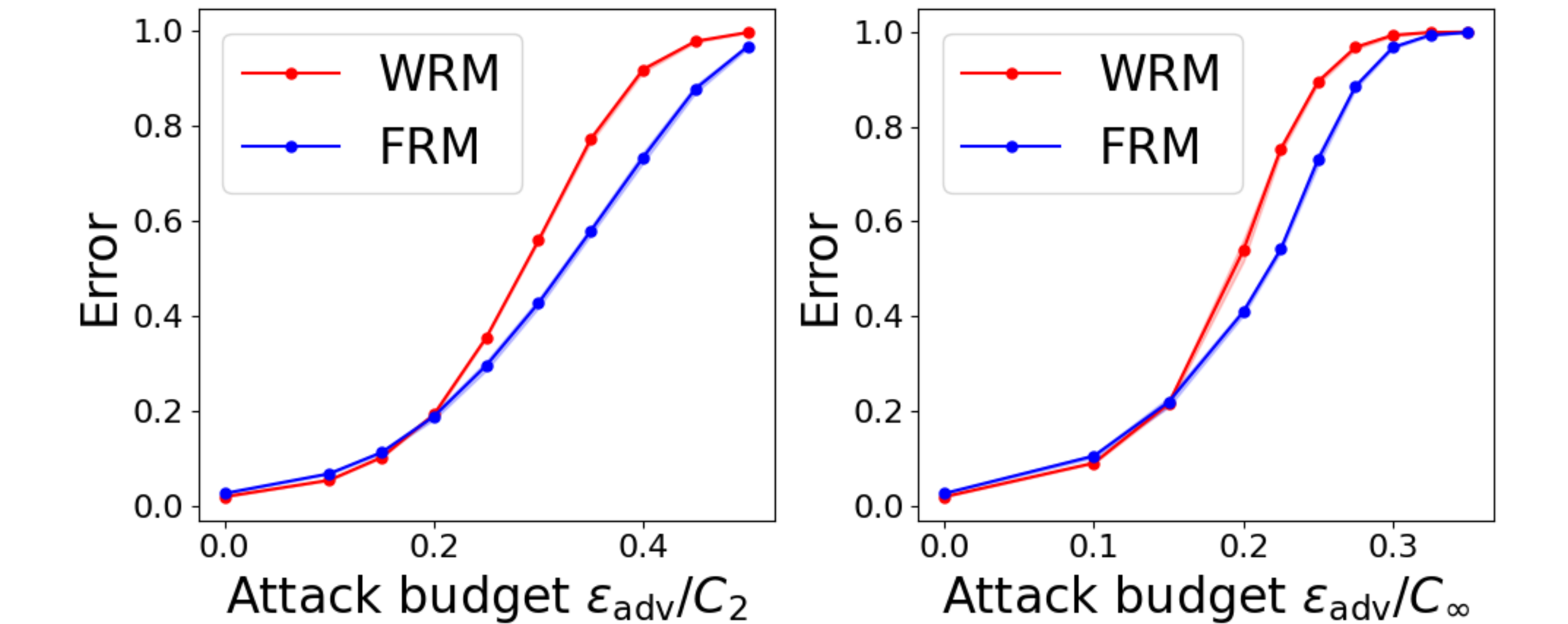


Figure 5. Performance of trained robust classifier on MNIST, using FRM (ours leveraging **FlowDRO**) vs. WRM [3].

## References

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