

Learning From Data

Lecture 8: ICA, CCA, & HGR Maximal Correlation

Yang Li yangli@sz.tsinghua.edu.cn

TBSI

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Today's Lecture

Unsupervised Learning (Part II)

- ▶ Independent Component Analysis (ICA)
- ▶ Canonical Correlation Analysis (CCA)
- ▶ HGR Maximal Correlation

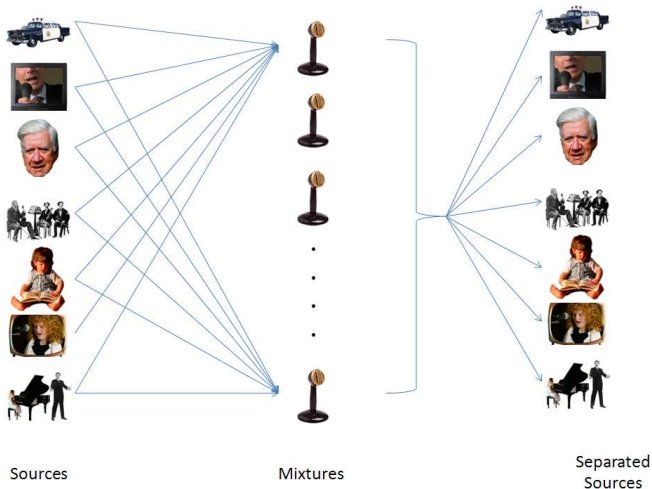
Written Assignment 3 is due next Saturday.

Programming Assignment 4 and project will be released next week.

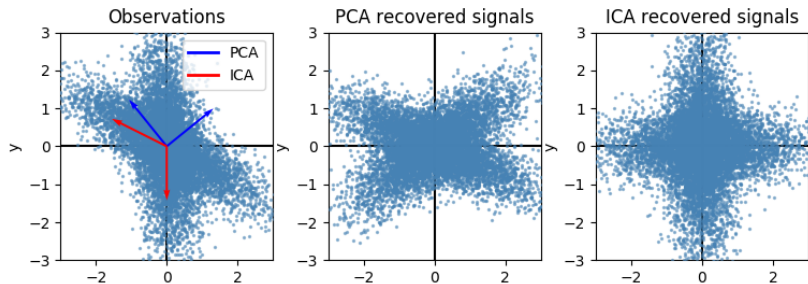
Independent Component Analysis

The cocktail party problem

- ▶ n microphones at different locations of the room, each recording a mixture of n sound sources
- ▶ How to “unmix” the sound mixtures?

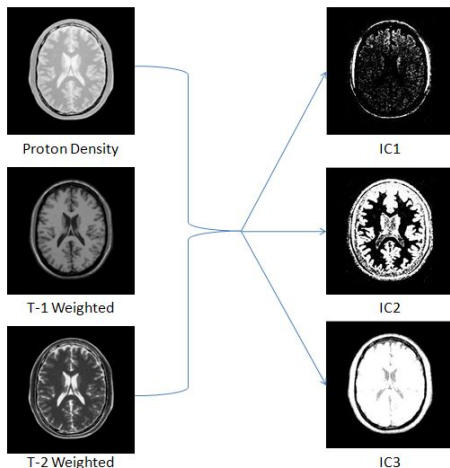


ICA vs PCA



Brain imaging

- ▶ Different brain matters: gray matter, white matter, cerebrospinal fluid (CSF), fat, muscle/skin, glial matter etc.
- ▶ An MRI scan is a mixture of different brain matters

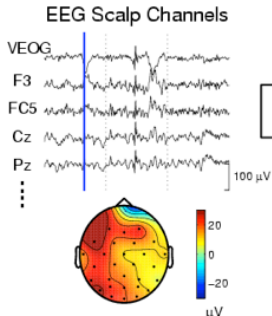
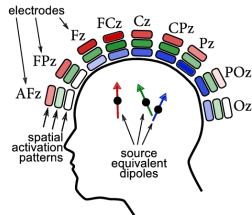


MRI Scans (x)

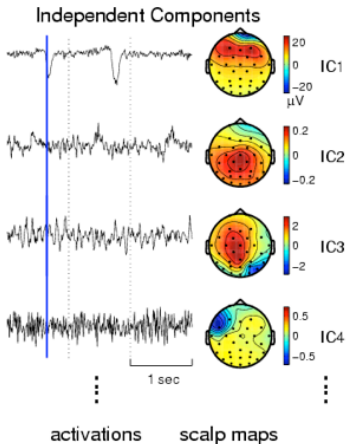
Independent Components (s)

EEG Analysis

- ▶ Electrodes on patient scalp measure a mixture of different brain activations
- ▶ Finding independent activation sources helps removing artifacts in the signal



unmixing
(W)



Problem Model

Case: $n = 2$

- ▶ Observed random variables: x_1, x_2
- ▶ Independent sources: $s_1, s_2 \in \mathbb{R}$

$$x_1 = a_{11}s_1 + a_{12}s_2$$

$$x_2 = a_{21}s_1 + a_{22}s_2$$

A is called the **mixing matrix**

$$x = As$$

The blind source separation (cocktail party) problem

Given repeated observation $\{x^{(i)}; i = 1, \dots, m\}$, recover sources $s^{(i)}$ that generated the data ($x^{(i)} = As^{(i)}$)

Independent Component Analysis (ICA)

The blind source separation (cocktail party) problem

Given repeated observation $\{x^{(i)}; i = 1, \dots, m\}$, recover sources $s^{(i)}$ that generated the data ($x^{(i)} = As^{(i)}$)

Let $W = A^{-1}$ be the **unmixing matrix**

Goal of ICA: Find W , such that given $x^{(i)}$, the sources can be recovered by $s^{(i)} = Wx^{(i)}$

$$W = \begin{bmatrix} -w_1^T - \\ \vdots \\ -w_n^T - \end{bmatrix}$$

ICA Ambiguities

Assume data is **non Gaussian**, ICA has two ambiguities:

- ▶ Permutation of original sources s_1, \dots, s_n
- ▶ Scaling of w_i

Why is Gaussian data problematic?

As long as the data is non-Gaussian, given enough data, we can recover the n independent sources.

Densities and Linear Transformations

Theorem 1

If random vector s has density p_s , and $x = As$ for a square, invertible matrix A , then the density of x is

$$p_x(x) = p_s(Wx)|W|,$$

where $W = A^{-1}$

ICA Algorithm

Joint distributions of *independent* sources $s = \{s_1, \dots, s_n\}$:

$$p(s) = \prod_{i=1}^n p_s(s_i)$$

The density on $x = As = W^{-1}s$:

$$p(x) = \prod_{i=1}^n p_s(w_i^T x) |W|$$

Choose the sigmoid function $g(s) = \frac{1}{1+e^{-s}}$ as the *non-Gaussian* cdf for p_s , then

$$p_s(s) = g'(s)$$

ICA Algorithm

Given a training set $\{x^{(1)}, \dots, x^{(m)}\}$, the log likelihood is

$$l(W) = \sum_{i=1}^m \left(\sum_{j=1}^n \log g'(w_j^T x^{(i)}) + \log |W| \right)$$

Stochastic gradient ascent learning rule for sample $x^{(i)}$:

$$W := W + \alpha \left(\begin{bmatrix} 1 - 2g(w_1^T x^{(i)}) \\ \vdots \\ 1 - 2g(w_n^T x^{(i)}) \end{bmatrix} x^{(i)T} + (W^T)^{-1} \right)$$

Check this at home!

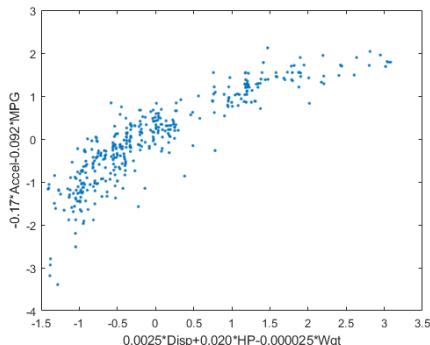
Canonical Correlation Analysis

Canonical Correlation Analysis

Canonical correlation analysis (CCA) finds the associations among two sets of variables.

Example: two sets of measurements of 406 cars:

- Specification: Engine displacement (Disp), horsepower (HP), weight (Wgt)
- Measurement: Acceleration (Accel), MPG



find important features that explain covariation between sets of variables

CCA Definitions

- ▶ Random vectors $X = \begin{bmatrix} x_1 \\ \vdots \\ x_{n_1} \end{bmatrix}$ and $Y = \begin{bmatrix} y_1 \\ \vdots \\ y_{n_2} \end{bmatrix}$
- ▶ Covariance matrix $\Sigma_{XY} = \text{cov}(X, Y)$
- ▶ CCA finds vectors a and b such that the random variables $a^T X$ and $b^T Y$ maximize the correlation

$$\rho = \text{corr}(a^T X, b^T Y)$$

- ▶ $U = a^T X$ and $V = b^T Y$ are called **the first pair of canonical variables**
- ▶ Subsequent pairs of canonical variables maximizes ρ while being *uncorrelated* with all previous pairs

Review: Singular Value Decomposition

A generalization of eigenvalue decomposition to rectangle ($m \times n$) matrices M .

$$M = U\Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

- ▶ $U \in \mathbb{R}^{m \times m}$, $V \in \mathbb{R}^{n \times n}$ are orthogonal matrices
- ▶ $\Sigma \in \mathbb{R}^{m \times n}$ is a **rectangular diagonal matrix**.

Examples:

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \\ 0 & 0 & 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1 & 0 & 0 & 0 \\ 0 & \sigma_2 & 0 & 0 \\ 0 & 0 & \sigma_3 & 0 \end{bmatrix}$$

Diagonal entries $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_k$, $k = \min(n, m)$ are called **singular values of M** .

Review: Singular Value Decomposition

A non-negative real number σ is a singular value for $M \in \mathbb{R}^{m \times n}$ **if and only if** there exist unit-length $u \in \mathbb{R}^m$ and $v \in \mathbb{R}^n$ such that

$$Mv = \sigma u$$

$$M^T u = \sigma v$$

u is called the **left singular value** of σ , v is called the **right singular value** of σ

Connection to eigenvalue decomposition

Given SVD of matrix $M = U\Sigma V^T$,

- ▶ $M^T M = (V\Sigma^T U^T)(U\Sigma V^T) = V(\Sigma^T \Sigma)V^T \leftarrow v_i$ is an eigenvector of $M^T M$ with eigenvalue σ_i^2
- ▶ $MM^T = (U\Sigma V^T)(V^T \Sigma^T U) = U(\Sigma \Sigma^T)U^T \leftarrow u_i$ is an eigenvector of MM^T with eigenvalue σ_i^2

CCA Derivations

The original problem:

$$(a_1, b_1) = \underset{a \in \mathbb{R}^{n_1}, b \in \mathbb{R}^{n_2}}{\operatorname{argmax}} \operatorname{corr}(a^T X, b^T Y) \quad (1)$$

Assume $\mathbb{E}[x_1] = \dots = \mathbb{E}[x_{n_1}] = \mathbb{E}[y_1] = \dots = \mathbb{E}[y_{n_2}] = 0$,

$$\begin{aligned} \operatorname{corr}(a^T X, b^T Y) &= \frac{\mathbb{E}[(a^T X)(b^T Y)]}{\sqrt{\mathbb{E}[(a^T X)^2] \mathbb{E}[(b^T Y)^2]}} \\ &= \frac{a^T \Sigma_{XY} b}{\sqrt{a^T \Sigma_{XX} a} \sqrt{b^T \Sigma_{YY} b}} \end{aligned}$$

(1) is equivalent to:

$$\begin{aligned} (a_1, b_1) = \underset{\substack{a \in \mathbb{R}^{n_1}, b \in \mathbb{R}^{n_2} \\ a^T \Sigma_{XX} a = b^T \Sigma_{YY} b = 1}}{\operatorname{argmax}} \quad & a^T \Sigma_{XY} b \end{aligned} \quad (2)$$

CCA Derivations

Define $\Omega \in \mathbb{R}^{n_1 \times n_2}$, $c \in \mathbb{R}^{n_1}$ and $d \in \mathbb{R}^{n_2}$,

$$\Omega = \Sigma_{XX}^{-\frac{1}{2}} \Sigma_{XY} \Sigma_{YY}^{-\frac{1}{2}}$$

$$c = \Sigma_{XX}^{\frac{1}{2}} a$$

$$d = \Sigma_{YY}^{\frac{1}{2}} b$$

(2) can be written as

$$(c_1, d_1) = \underset{\substack{c \in \mathbb{R}^{n_1}, d \in \mathbb{R}^{n_2} \\ \|c\|^2 = \|d\|^2 = 1}}{\operatorname{argmax}} c^T \Omega d \quad (3)$$

(c_1, d_1) can be solved by SVD, then the first pair of canonical variables are

$$a_1 = \Sigma_{XX}^{-\frac{1}{2}} c_1, \quad b_1 = \Sigma_{YY}^{-\frac{1}{2}} d_1$$

CCA Derivations

$$(c_1, d_1) = \underset{\substack{c \in \mathbb{R}^{n_1}, d \in \mathbb{R}^{n_2} \\ \|c\|^2 = \|d\|^2 = 1}}{\operatorname{argmax}} c^T \Omega d$$

Proposition 1

c_1 and d_1 are the left and right unit singular vectors of Ω with the largest singular value.

Theorem 2

c_i and d_i are the left and right unit singular vectors of Ω with the i th largest singular value.

CCA Algorithm

Input: Covariance matrices for centered data X and Y :

- ▶ Σ_{XY} , invertible Σ_{XX} and Σ_{YY}
- ▶ Dimension $k \leq \min(n_1, n_2)$

Output: CCA projection matrices A_k and B_k :

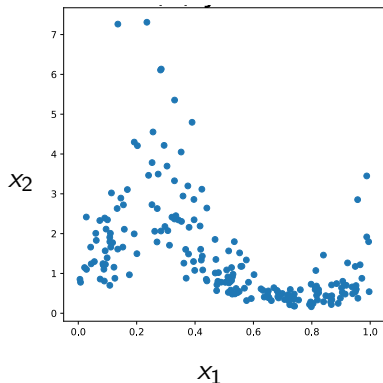
- ▶ Compute $\Omega = \Sigma_{XX}^{-\frac{1}{2}} \Sigma_{XY} \Sigma_{YY}^{-\frac{1}{2}}$
- ▶ Compute SVD decomposition of Ω

$$\Omega = \begin{bmatrix} | & \dots & | \\ c_1 & \dots & c_{n_1} \\ | & \dots & | \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \\ & & & 0 \end{bmatrix} \begin{bmatrix} -d_1^T - \\ \vdots \\ -d_{n_2}^T - \end{bmatrix}$$

- ▶ $A_k = \Sigma_{XX}^{-\frac{1}{2}}[c_1, \dots, c_k]$ and $B_k = \Sigma_{YY}^{-\frac{1}{2}}[d_1, \dots, d_k]$

Discussion of CCA

- ▶ CCA only measures linear dependencies
- ▶ Non-linear generalizations:
 - ▶ Kernel CCA (KCCA)
 - ▶ Deep CCA (DCCA)
 - ▶ Maximal HGR Correlation



Non-linear dependency between x_1 and x_2

Maximal HGR Correlation Analysis

A Non-linear Measure of Dependence

Hirschfeld-Gebelein-Renyi (HGR) maximal correlation

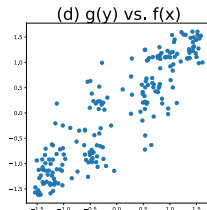
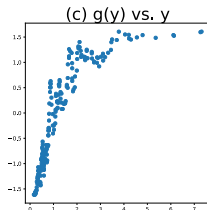
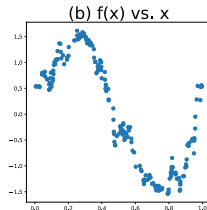
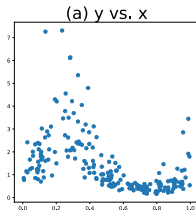
Given random variables X, Y , the HGR maximal correlation is

$$\begin{aligned}\rho(X; Y) &= \max_{f(X), g(Y)} \mathbb{E}[f(X)g(Y)] \\ &s.t. \mathbb{E}[f(X)] = \mathbb{E}[g(Y)] = 0 \\ &\quad \mathbb{E}[f^2(X)] = \mathbb{E}[g^2(Y)] = 1\end{aligned}$$

where $f : \mathcal{X} \rightarrow \mathbb{R}$ and $g : \mathcal{Y} \rightarrow \mathbb{R}$ are real-valued functions

Example of HGR maximal correlation











Synthesized data: $y^{(i)} = \exp\left(\sin\left(2\pi x^{(i)} + \frac{\epsilon^{(i)}}{2}\right)\right)$, $e^{(i)} \approx \mathcal{N}(0, 1)$
for $i = 1, \dots, 200$



$$\rho(X; Y) = 0.902$$

Example of HGR maximal correlation

Use multi-dimensional HGR maximal correlation to learn unsupervised features from MNIST.

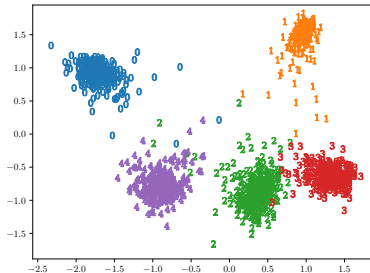
X		Y
	0	
	4	
	2	
	1	
	3	
⋮		⋮

$$y^{(i)} = x^{(i)} + 4$$

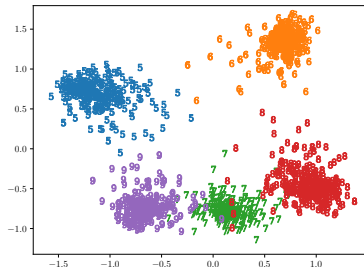
Example of HGR maximal correlation

Use multi-dimensional HGR maximal correlation to learn unsupervised features from MNIST.

$f_1(x)$ vs $f_2(x)$



$g_1(y)$ vs $g_2(y)$



How to solve it?

Assume X and Y are both discrete with alphabet \mathcal{X} , \mathcal{Y} .

$$\mathbb{E}[f(x)g(y)] = \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x,y) f(x) g(y)$$

Define $\phi(x) \triangleq \sqrt{P_X(x)} f(x)$, $\psi(y) \triangleq \sqrt{P_Y(y)} g(y)$, then

$$\mathbb{E}[f(x)g(y)] = \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} \frac{P_{X,Y}(x,y)}{\sqrt{P_X(x)P_Y(y)}} \phi(x) \psi(y) = \psi^T B \phi$$

- ▶ Matrix $B \in \mathbb{R}^{|\mathcal{Y}| \times |\mathcal{X}|}$, where $B(y,x) \triangleq \frac{P_{X,Y}(x,y)}{\sqrt{P_X(x)P_Y(y)}}$
- ▶ Vectors $\phi \in \mathbb{R}^{|\mathcal{X}|}$, $\psi \in \mathbb{R}^{|\mathcal{Y}|}$

How to represent the constraints using ϕ and ψ ?

How to solve it?

Given $\phi(x) = \sqrt{P_X(x)}f(x)$, $\psi(y) = \sqrt{P_Y(y)}g(y)$

Unit-variance constraints

- ▶ $\mathbb{E}[f(x)^2] = 1 \implies \sum_x P_X(x) \left(\frac{\phi(x)}{\sqrt{P_X(x)}} \right)^2 = \sum_x \phi(x)^2 = \|\phi\|^2 = 1$
- ▶ Similarly, $\mathbb{E}[g(y)^2] = 1 \implies \|\psi\|^2 = 1$

Zero-mean constraints

- ▶ $\mathbb{E}[f(x)] = 0 \implies \sum_x P_X(x) \frac{\phi(x)}{\sqrt{P_X(x)}} = \sum_x \phi(x) \sqrt{P_X(x)} = \langle \phi, \sqrt{P_X} \rangle = 0$, i.e. $(\phi \perp \sqrt{P_X})$
- ▶ Similarly, $\mathbb{E}[g(y)] = 0 \implies \langle \psi, \sqrt{P_Y} \rangle = 0$, i.e. $(\psi \perp \sqrt{P_Y})$

HGR Maximal Correlation as an SVD problem

Alternative definition for HGR Maximal Correlation

$$\begin{aligned}\rho(X, Y) &= \max_{\phi \in \mathbb{R}^{|X|}, \psi \in \mathbb{R}^{|Y|}} \psi^T B \phi \\ \text{s.t. } & \|\phi\|^2 = \|\psi\|^2 = 1 \\ & \phi \perp \sqrt{P_X}, \psi \perp \sqrt{P_Y}\end{aligned}$$

Proposition 2

$(u_1, v_1) = \operatorname{argmax}_{\|u\|=\|v\|=1} u^T B v$ are the largest left and right singular vector of B .

Proposition 3

The largest left and right singular vectors are $\sqrt{P_Y}$ and $\sqrt{P_X}$

Proposition 4

ψ^* and ϕ^* are the 2nd largest left and right singular vectors of B , respectively.

Alternating Condition Expectation (ACE)

A generalization of power iteration for finding singular vectors:

ACE algorithm for 1d data [Breiman & Friedman 1985]

Data: Discrete data samples $x^{(1)}, \dots, x^{(m)}$

Result: compute $f^*(x), g^*(y)$

Randomly choose $g(y), y \in \mathcal{Y}$ such that $\mathbb{E}[g(Y)] = 0$;

while σ not converged **do**

$f(x) \leftarrow \mathbb{E}_m[g(Y)|X = x]$

 Normalize $f(x) \forall x \in \mathcal{X}$;

$g(y) \leftarrow \mathbb{E}_m[f(X)|Y = y]$;

 Normalize $g(y) \forall y \in \mathcal{Y}$;

$\sigma \leftarrow \mathbb{E}_m[f(X)g(Y)]$;

end

Breiman, L. and Friedman, J. H. Estimating optimal transformations for multiple regression and correlation. J. Am. Stat. Assoc., 80(391),1985b

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$f(x) \leftarrow \mathbb{E}_m[g(Y)|X = x]$ // $\mathbb{E}_m[\cdot]$: sample expectation ;

 Normalize $f(x) \forall x \in \mathcal{X}$;

$g(y) \leftarrow \mathbb{E}_m[f(X)|Y = y]$;

 Normalize $g(y) \forall y \in \mathcal{Y}$;

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Extension to high dimension case

k-dimensional HGR Maximal Correlation

$$\rho(X; Y) = \max_{\substack{f: \mathcal{X} \rightarrow \mathbb{R}^k \\ g: \mathcal{Y} \rightarrow \mathbb{R}^k}} \mathbb{E}[f(X)^T g(Y)] \leftarrow \text{optimize } k \text{ values in parallel}$$

$$\text{s.t. } \mathbb{E}[f_i(X)] = \mathbb{E}[g_i(Y)] = 0, \forall i = 1, \dots, k$$

$$\mathbb{E}[f_i(X)^T f_j(X)] = \mathbb{E}[g_i(Y)^T g_j(Y)] = \mathbf{1}\{i = j\}, \forall i, j = 1, \dots, k$$

ACE algorithm for k-d data

Data: Discrete data samples

$$x^{(1)}, \dots, x^{(m)}$$

Result: compute $f^*(x), g^*(y)$

Randomly choose $g(y), y \in \mathcal{Y}$

such that $\mathbb{E}[g(Y)] = 0$;

while σ not converged **do**

$$f(x) \leftarrow \mathbb{E}_m[g(Y)|X = x];$$

Normalize $f(x) \forall x \in \mathcal{X}$;

$$g(y) \leftarrow \mathbb{E}_m[f(X)|Y = y];$$

Normalize $g(y) \forall y \in \mathcal{Y}$;

$$\sigma \leftarrow \mathbb{E}_m[f(X)^T g(Y)];$$

end

Normalize k-d feature: for all $x \in \mathcal{X}$,

$$\triangleright f(x) \leftarrow f(x) - \mathbb{E}_m[f(X)]$$

$$\triangleright f(x) \leftarrow f(x) \mathbb{E}_m[f(X)f(X)^T]^{-\frac{1}{2}}$$

$g(y)$ is normalized similarly for all $y \in \mathcal{Y}$.

Discussion on HGR Maximal Correlation

- ▶ Useful for modal estimation from data
- ▶ ACE in Python: <https://github.com/mace-cream/xyace>
(limited to discrete X and Y)
- ▶ Extension to continuous case: a deep neural network implementation of HGR maximal correlation [Wang et. al. 2018]

An Efficient Approach to Informative Feature Extraction from Multimodal Data, Wang, Lichen, et al. AAAI (2018).