

Problem Set 5

Issued: Monday 30th November, 2020

Due: Monday 14th December, 2020

Notations: We use $\mathbf{x}, \mathbf{y}, \mathbf{w}$ and $\underline{x}, \underline{y}, \underline{w}$ to denote random variables and random vectors.

5.1. *Cramer-Rao inequality with a bias term.* Let $\mathbf{y} \sim f(\mathbf{y}; x)$ and let $\hat{x}(\mathbf{y})$ be an estimator for x . Let $b(x) = \mathbb{E}[\hat{x}(\mathbf{y})] - x$ be the bias of the estimator. Show that

$$\mathbb{E}[(\hat{x}(\mathbf{y}) - x)^2] \geq \frac{[1 + b'(x)]^2}{J_{\mathbf{y}}(x)} + b^2(x)$$

5.2. (a) Let

$$p_{\mathbf{y}}(y; x) = \begin{cases} x & \text{if } 0 \leq y \leq 1/x \\ 0 & \text{otherwise} \end{cases}$$

for $x > 0$. Show that there exist no unbiased estimators $\hat{x}(\mathbf{y})$ for x . (Note that because only $x > 0$ are possible values, an unbiased estimator need only be unbiased for $x > 0$ rather than all x .)

(b) Suppose instead that

$$p_{\mathbf{y}}(y; x) = \begin{cases} 1/x & \text{if } 0 \leq y \leq x \\ 0 & \text{otherwise} \end{cases}$$

for $x > 0$. Does a minimum-variance unbiased estimator for x based on \mathbf{y} exist? If your answer is yes, determine $\hat{x}_{\text{MVU}}(\mathbf{y})$. If your answer is no, explain.

5.3. Suppose, for $i = 1, 2$

$$\mathbf{y}_i = x + \mathbf{w}_i$$

where x is an unknown but non-zero constant, \mathbf{w}_1 and \mathbf{w}_2 are statistically independent, zero-mean Gaussian random variables with

$$\begin{aligned} \text{var}(\mathbf{w}_1) &= 1 \\ \text{var}(\mathbf{w}_2) &= \begin{cases} 1 & x > 0 \\ 2 & x < 0 \end{cases}. \end{aligned}$$

(a) Calculate the Cramér-Rao bound for unbiased estimators of x based on observation of

$$\underline{\mathbf{y}} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}.$$

(b) Show that a minimum variance unbiased estimator $\hat{x}_{\text{MVU}}(\underline{\mathbf{y}})$ does not exist.

Hint: Consider the estimators

$$\begin{aligned} \hat{x}_1(\underline{\mathbf{y}}) &= \frac{1}{2}y_1 + \frac{1}{2}y_2, \\ \hat{x}_2(\underline{\mathbf{y}}) &= \frac{2}{3}y_1 + \frac{1}{3}y_2. \end{aligned}$$

5.4. Let $\underline{y} = [y_1 \ y_2]^T$ be a vector random variable whose components are i.i.d. Bernoulli random variables with parameter x , $0 < x < 1$, i.e., $\mathbb{P}(y_i = 1) = x, i = 1, 2$.

- (a) Show that $t(\underline{y}) = y_1 + y_2$ is a sufficient statistic.
- (b) Let $\hat{x}(\underline{y}) = y_1$ be an estimator of the parameter x from the observation \underline{y} . Find $\text{MSE}_{\hat{x}}(x)$, the mean-square error of this estimator.
- (c) Let $\hat{x}'(t) = \mathbb{E}[\hat{x}(\underline{y}) | \underline{t} = t]$ be an estimator of the parameter x that uses the sufficient statistic t instead of the observations \underline{y} .
 - i. Show that $\hat{x}'(t)$ is a valid estimator, i.e., it does not depend on x .
 - ii. Show that $\text{MSE}_{\hat{x}'}(x) = \gamma \text{MSE}_{\hat{x}}(x)$ and find the constant γ .
- (d) We now consider a generalization of this problem. Let \underline{y} be a random variable generated by a distribution $p_{\underline{y}}(\cdot; x)$ and $\underline{t}(\underline{y})$ be a sufficient statistic. Let $\hat{x}(\underline{y})$ be an estimator of the parameter x based on the observation \underline{y} . We define an alternate estimator $\hat{x}'(\underline{t}) = \mathbb{E}[\hat{x}(\underline{y}) | \underline{t} = \underline{t}]$.
 - i. Show that $\hat{x}'(\underline{t})$ is a valid estimator, i.e., it does not depend on x .
 - ii. Show that for any cost function $C(x, \hat{x})$ that is convex in \hat{x} , the following inequality holds:

$$\mathbb{E}[C(x, \hat{x}'(\underline{t}))] \leq \mathbb{E}[C(x, \hat{x}(\underline{y}))].$$

5.5. For a non-bayesian case $p_{\underline{y}}(y; x)$, we do a binary hypothesis testing where $x \in \{H_0, H_1\}$. Please prove that $t(y) = \frac{p_{\underline{y}}(y; H_1)}{p_{\underline{y}}(y; H_0)}$ is a complete sufficient statistics.

5.6. In class we developed the EM algorithm for maximum likelihood estimation (EM-ML). That is, we gave an iterative procedure to compute

$$\hat{x}_{ML}(y) = \arg \max_a p_{\underline{y}}(y; a).$$

and showed that the likelihood was non-decreasing with each iteration. Please develop the EM-MAP algorithm for MAP estimation:

$$\hat{x}_{MAP}(y) = \arg \max_a p_{\underline{x}|\underline{y}}(a|y)$$

where the complete data \underline{z} is an arbitrary random vector. (Please follow the procedures in the lecture note)