大家好,这篇是有关台大机器学习课程作业五的详解。

我的github地址:

https://github.com/Doraemonzzz

个人主页:

http://doraemonzzz.com/

作业地址:

https://www.csie.ntu.edu.tw/~htlin/course/ml15fall/

#### 参考资料:

https://blog.csdn.net/a1015553840/article/details/51085129

http://www.vynguyen.net/category/study/machine-learning/page/6/

http://book.caltech.edu/bookforum/index.php

http://beader.me/mlnotebook/

https://blog.csdn.net/gian1122221/article/details/50130093

### **Problem 1**

回顾下问题的形式

$$egin{aligned} \min_{w,b,\xi} & rac{1}{2} w^T w + C \sum_{n=1}^N \xi_n \ & ext{subject to} & y_n(w^T x_n + b) \geq 1 - \xi_n \ & \xi_n \geq 0 (n = 1, \dots, N) \end{aligned}$$

除了 $x_n, y_n$ , 其余量均为参数, 注意 $w \in \mathbb{R}^d$ , 所以我们的参数有

$$w=(w_1,\ldots,w_d),\xi_1,\ldots,\xi_N,C$$

一共d+N+1个。限制条件为

$$y_n(w^Tx_n+b) \geq 1-\xi_n \ 
onumber \ 
onumbe$$

一共有2N个。

#### **Problem 2**

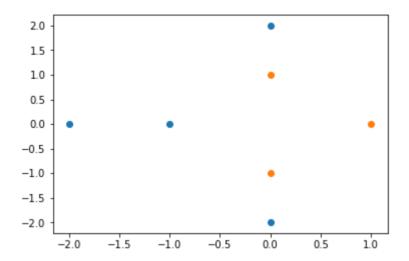
首先作图看下

```
import numpy as np
import matplotlib.pyplot as plt

x = np.array([[1,0],[0,1],[0,-1],[-1,0],[0,2],[0,-2],[-2,0]])
z = np.array([-1,-1,-1,+1,+1,+1])
```

```
x1 = x[z>0][:,0]
y1 = x[z>0][:,1]
x2 = x[z<0][:,0]
y2 = x[z<0][:,1]

plt.scatter(x1,y1)
plt.scatter(x2,y2)
plt.show()</pre>
```



可以看到,如果用二次曲线的话,应该可以分类,现在做特征转换之后的图像。

转换之后的标记为+1的点为

$$z_4 = (5, -2), z_5 = (7, -7), z_6 = (7, 1), z_7 = (7, 1)$$

转换之后的标记为+1的点为

$$z_1 = (1, -2), z_2 = (4, -5), z_3 = (4, -1)$$

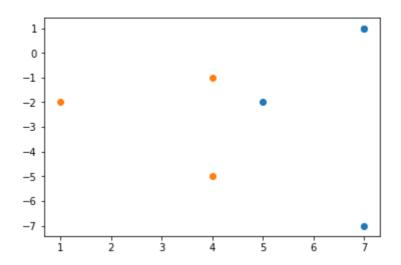
```
def phi_1(x):
    return x[1]**2-2*x[0]+3

def phi_2(x):
    return x[0]**2-2*x[1]-3

X = []
for i in x:
        X.append([phi_1(i),phi_2(i)])
X = np.array(X)

X1 = X[z>0][:,0]
Y1 = X[z>0][:,1]
X2 = X[z<0][:,0]
Y2 = X[z<0][:,1]
plt.scatter(X1,Y1)</pre>
```

plt.scatter(X2,Y2)
plt.show()



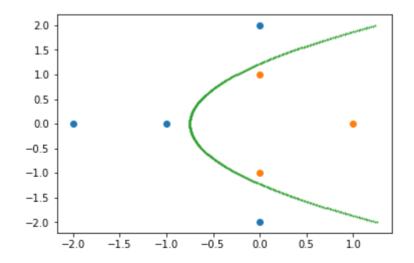
从这个图像中可以看出,最大间隔分类器为 $\varphi_1(x)=4.5$ ,将 $\varphi_1(x)=x_2^2-2x_1+3$ 带入可得最大间隔分类器为

$$x_2^2 - 2x_1 + 3 = 4.5$$
$$x_1 = \frac{x_2^2 - 1.5}{2}$$

### 最后看下曲线的图。

```
y3 = np.arange(-2,2,0.01)
x3 = np.array([(i*i-1.5)/2 for i in y3])

plt.scatter(x1,y1)
plt.scatter(x2,y2)
plt.scatter(x3,y3,s=1)
plt.show()
```



# **Problem 3**

利用sklearn处理即可。

```
from sklearn import svm

clf = svm.SVC(kernel='poly',degree=2,coef0=1,gamma=1,C=1e10)
clf.fit(x,z)
```

```
SVC(C=10000000000.0, cache_size=200, class_weight=None, coef0=1,
  decision_function_shape='ovr', degree=2, gamma=1, kernel='poly',
  max_iter=-1, probability=False, random_state=None, shrinking=True,
  tol=0.001, verbose=False)
```

看下哪几个向量为支持向量。

```
clf.support_
```

```
array([1, 2, 3, 4, 5])
```

这说明第2到6个向量均为支持向量,再来看下对偶问题的系数。

```
clf.dual_coef_
```

```
array([[-0.59647182, -0.81065085, 0.8887034 , 0.20566488, 0.31275439]])
```

这些系数分别支持向量对应的系数,非支持向量对应的系数为0,这里还要注意一点,对偶问题的系数为 $y_n\alpha_n$ ,所以如果我们要得到原系数,就要乘以 $y_n$ 

```
z[clf.support_]*clf.dual_coef_[0]
```

```
array([ 0.59647182, 0.81065085, 0.8887034, 0.20566488, 0.31275439])
```

所以

```
(\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5, \alpha_6, \alpha_7) = (0, 0.59647182, 0.81065085, 0.8887034, 0.20566488, 0.31275439, 0)
```

支持向量为

$$x_2, x_3, x_4, x_5, x_6$$

#### **Problem 4**

为了求得曲线方程, 我们需要利用以下几个式子

$$egin{aligned} b^* &= y_s - \sum_{lpha_n^* > 0} y_n lpha_n^* z_n^T z_s \ g(x) &= ext{sign}(\sum_{n=1}^N y_n lpha_n^* z_n^T z + b^*) \ z &= (1, x_1, x_2, x_1^2, x_1 x_2, x_2^2) \end{aligned}$$

利用这两个式子计算即可。

```
def g(x):
    r = np.sqrt(2)
    return np.array([1,r*x[0],r*x[1],x[0]**2,x[0]*x[1],x[1]*x[0],x[1]**2])

support = clf.support_
    coef = clf.dual_coef_[0]
    x4 = np.array([g(i) for i in x])

#取第一个支持向量
    s = support[0]

b = z[s] - coef.dot(x4[support].dot(x4[s]))
    k = (coef).dot(x4[support])

b,k
```

所以曲线方程为

$$k^T z + b = 0$$

### **Problem 5**

我们来作图, 利用等高线的技巧。

```
#构造等高线函数

def g(x,y,k,b):
    r = np.sqrt(2)
    return k[0]+k[1]*r*x+k[2]*r*y+k[3]*(x**2)+(k[4]+k[5])*x*y+k[6]*(y**2)+b

#点的数量
n = 1000
r = 3

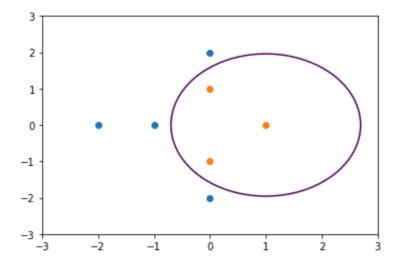
#作点
```

```
p = np.linspace(-r,r,n)
q = np.linspace(-r,r,n)

#构造网格
P,Q = np.meshgrid(p,q)

#绘制等高线
plt.contour(P,Q,g(P,Q,k,b),0)

plt.scatter(x1,y1)
plt.scatter(x2,y2)
plt.show()
```



可以看到, 图像和之前的抛物线是不一样的。

# **Problem 6**

结合课件的推导, 我们可知

$$egin{aligned} L(R,c,\lambda) &= R^2 + \sum_{n=1}^N \lambda_n(||x_n-c||^2 - R^2) \ \lambda_n &> 0 \end{aligned}$$

所以在 $||x_n - c||^2 \le R^2$ 条件下

$$\sum_{n=1}^{N} \lambda_n(||x_n-c||^2-R^2) \leq 0 \ \max\{\sum_{n=1}^{N} \lambda_n(||x_n-c||^2-R^2)\} = 0$$

从而

$$\min_{R \in \mathbb{R}, c \in \mathbb{R}^d} \max_{\lambda_n \geq 0} L(R, c, \lambda) = \min_{R \in \mathbb{R}, c \in \mathbb{R}^d} R^2$$

# **Problem 7**

将上述问题转化为对偶问题

$$\min_{R \in \mathbb{R}, c \in \mathbb{R}^d} \max_{\lambda_n \geq 0} L(R, c, \lambda) = \max_{\lambda_n \geq 0} \min_{R \in \mathbb{R}, c \in \mathbb{R}^d} L(R, c, \lambda)$$

所以现在可以对 $L(R,c,\lambda)$ 求无条件极值,分别求偏导可得

$$\begin{split} \frac{\partial L(R,c,\lambda)}{\partial c} &= \frac{\partial [R^2 + \sum_{n=1}^N \lambda_n (||x_n - c||^2 - R^2)]}{\partial c} \\ &= \frac{\partial [R^2 + \sum_{n=1}^N \lambda_n (x_n^T x_n - 2x_n^T c + c^T c - R^2)]}{\partial c} \\ &= \frac{\partial [R^2 + \sum_{n=1}^N \lambda_n (x_n^T x_n - 2x_n^T c + c^T c - R^2)]}{\partial c} \\ &= \sum_{n=1}^N \lambda_n \frac{\partial (x_n^T x_n - 2x_n^T c + c^T c - R^2)}{\partial c} \\ &= \sum_{n=1}^N \lambda_n (2c - 2x_n) \\ &= 2(c \sum_{n=1}^N \lambda_n - \sum_{n=1}^N \lambda_n x_n) \end{split}$$

令 $\frac{\partial L(R,c,\lambda)}{\partial c}=0$ 可得

$$egin{aligned} c \sum_{n=1}^{N} \lambda_n - \sum_{n=1}^{N} \lambda_n x_n &= 0 \ c &= rac{\sum_{n=1}^{N} \lambda_n x_n}{\sum_{n=1}^{N} \lambda_n} \ rac{\partial L(R,c,\lambda)}{\partial R} &= rac{\partial [R^2 + \sum_{n=1}^{N} \lambda_n (||x_n - c||^2 - R^2)]}{\partial R} \ &= 2R - 2 \sum_{n=1}^{N} \lambda_n R \end{aligned}$$

令 $\frac{\partial L(R,c,\lambda)}{\partial R}=0$ 可得

$$\sum_{n=1}^{N} \lambda_n = 1$$

结合这个条件,关于c的条件可以简化

$$c = rac{\sum_{n=1}^{N} \lambda_n x_n}{\sum_{n=1}^{N} \lambda_n} = \sum_{n=1}^{N} \lambda_n x_n$$

### **Problem 8**

将 $\sum_{n=1}^N\lambda_n=1,c=\sum_{n=1}^N\lambda_nx_n$ 这两个条件带入 $L(R,c,\lambda)$ ,先带入 $\sum_{n=1}^N\lambda_n=1$ 

$$egin{aligned} L(R,c,\lambda) &= R^2 + \sum_{n=1}^N \lambda_n (||x_n - c||^2 - R^2) \ &= \sum_{n=1}^N \lambda_n ||x_n - c||^2 + R^2 - R^2 \sum_{n=1}^N \lambda_n \ &= \sum_{n=1}^N \lambda_n ||x_n - c||^2 \end{aligned}$$

再对 $\sum_{n=1}^{N}\lambda_{n}||x_{n}-c||^{2}$ 进行处理可得

$$egin{aligned} L(R,c,\lambda) &= \sum_{n=1}^{N} \lambda_n ||x_n - c||^2 \ &= \sum_{n=1}^{N} \lambda_n (x_n^T x_n - 2 x_n^T c + c^T c) \ &= \sum_{n=1}^{N} \lambda_n x_n^T x_n - 2 (\sum_{n=1}^{N} \lambda_n x_n^T) c + c^T c \sum_{n=1}^{N} \lambda_n x_n^T x_n - 2 (\sum_{n=1}^{N} \lambda_n x_n^T) c + c^T c \end{aligned}$$

再带入 $c = \sum_{n=1}^N \lambda_n x_n$ 

$$egin{aligned} L(R,c,\lambda) &= \sum_{n=1}^N \lambda_n x_n^T x_n - 2c \sum_{n=1}^N \lambda_n x_n^T + c^T c \ &= \sum_{n=1}^N \lambda_n x_n^T x_n - 2(\sum_{n=1}^N \lambda_n x_n^T)(\sum_{n=1}^N \lambda_n x_n) + (\sum_{n=1}^N \lambda_n x_n^T)(\sum_{n=1}^N \lambda_n x_n) \ &= \sum_{n=1}^N \lambda_n x_n^T x_n - (\sum_{n=1}^N \lambda_n x_n^T)(\sum_{n=1}^N \lambda_n x_n) \end{aligned}$$

所以问题转换为

在条件 
$$\sum_{n=1}^N \lambda_n=1, \lambda_n\geq 0$$
下,最小化  $f(\lambda)=\sum_{n=1}^N \lambda_n x_n^T x_n-(\sum_{n=1}^N \lambda_n x_n^T)(\sum_{n=1}^N \lambda_n x_n)$ 

# **Problem 9**

这题是要利用 $z_n = \phi(x_n)$ 以及 $K(x_n, x_m)$ 来简化问题, 先对 $f(\lambda)$ 进行处理

$$egin{aligned} f(\lambda) &= \sum_{n=1}^N \lambda_n x_n^T x_n - (\sum_{n=1}^N \lambda_n x_n^T) (\sum_{n=1}^N \lambda_n x_n) \ &= \sum_{n=1}^N \lambda_n x_n^T x_n - \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m x_n^T x_m \end{aligned}$$

将 $x_n$ 替换为 $z_n = \phi(x_n)$ ,然后代入 $K(x_n, x_m) = z_n^T z_m$ 可得

$$egin{aligned} f(\lambda) &= \sum_{n=1}^N \lambda_n z_n^T z_n - \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m z_n^T z_m \ &= \sum_{n=1}^N \lambda_n K(x_n,x_n) - \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m K(x_n,x_m) \end{aligned}$$

### **Problem 10**

由Problem 6的推导过程我们可知,

$$\lambda_n(||x_n - c||^2 - R^2) = 0$$

$$n = 1, \dots, N$$

这里讨论的是特征转换之后的问题, 所以上述问题可以修改为

$$\lambda_n(||z_n - c||^2 - R^2) = 0$$

$$n = 1, \dots, N$$

所以如果存在 $\lambda_i \neq 0$ , 那么

$$||z_i - c||^2 - R^2 = 0$$

结合 $c=\sum_{n=1}^{N}\lambda_{n}z_{n}$ ,就能计算出R了

### **Problem 11**

首先看下现在的问题,假设假设 $x_n \in \mathbb{R}^k$ 

$$egin{aligned} \min_{w,b,\xi} & rac{1}{2} w^T w + C \sum_{n=1}^N \xi_n^2 \ & ext{subject to} & y_n(w^T x_n + b) \geq 1 - \xi_n \end{aligned}$$

转换成hard-margin的关键问题在于把  $\frac{1}{2}w^Tw+C\sum_{n=1}^N\xi_n^2$ 写成  $\frac{1}{2}\tilde{w}^T\tilde{w}$ 

$$rac{1}{2}w^Tw + C\sum_{n=1}^N \xi_n^2 = rac{1}{2}(w^Tw + 2C\sum_{n=1}^N \xi_n^2)$$

从这点可以想到

$$ilde{w} = egin{bmatrix} w \ \sqrt{2C} \xi_1 \ \dots \ \sqrt{2C} \xi_N \end{bmatrix}$$

从而

$$ilde{w}^T ilde{w}=w^Tw+2C\sum_{n=1}^N \xi_n^2$$

这样变换之后也要对条件进行变换,将条件化为 $y_n(w^T \tilde{x}_n + b) \geq 1$ 的形式

$$egin{aligned} y_n(w^Tx_n+b) &\geq 1-\xi_n \Leftrightarrow \ y_n(w^Tx_n+b+y_n\xi_n) &\geq 1 \Leftrightarrow \ y_n(w^Tx_n+\sqrt{2C}\xi_n(rac{1}{\sqrt{2C}}y_n)+b) &\geq 1 \end{aligned}$$

结合 $\tilde{w}$ 的式子,我们可以定义 $\tilde{x}_n$ ,注意 $x_n \in \mathbb{R}^k$ 

$$ilde{x}_n = \left[egin{array}{c} x_n \ 0 \ \dots \ rac{1}{\sqrt{2C}} y_n \ \dots \ 0 \end{array}
ight] \in \mathbb{R}^{k+N}$$

其中 $ilde{x}_n$ 的第k+1到k+N的分量中,除了第k+n个为 $\frac{1}{\sqrt{2C}}y_n$ ,其余均为0,这样就把问题转化为

$$egin{aligned} \min_{w,b,\xi} & rac{1}{2} ilde{w}^T ilde{w} \ \end{aligned}$$
 subject to  $y_n( ilde{w}^Tx_n+b)\geq 1$ 

如果已经计算出了 $\tilde{w}$ ,那么由于

$$ilde{w} = egin{bmatrix} w \ \sqrt{2C} \xi_1 \ \dots \ \sqrt{2C} \xi_N \end{bmatrix}$$

所以取 $\tilde{w}$ 的前k个分量即可得到w

#### **Problem 12**

只要看这些映射对应的Gram矩阵是否半正定即可,设 $K, K_1, K_2$ 对应的Gram矩阵为 $M, M_1, M_2$ 

(a)
$$K(x,x^{'})=K_{1}(x,x^{'})+K_{2}(x,x^{'})$$
可得 $M=M_{1}+M_{2}$   $y^{T}My=y^{T}(M_{1}+M_{2})y=y^{T}M_{1}y+y^{T}M_{2}y\geq 0$ 

所以 $K(x,x^{'})=K_{1}(x,x^{'})+K_{2}(x,x^{'})$ 为kernerl

(b)
$$K(x,x^{'})=K_{1}(x,x^{'})-K_{2}(x,x^{'})$$
可得 $M=M_{1}-M_{2}$ 

这个一看就不是kernel, 反例也很好构造

$$M_1=egin{bmatrix}1&0\0&1\end{bmatrix}, M_2=egin{bmatrix}2&0\0&2\end{bmatrix}, M=M_1-M_2=egin{bmatrix}-1&0\0&-1\end{bmatrix}$$

显然M不是半正定的,所以 $K(x,x^{'})=K_{1}(x,x^{'})-K_{2}(x,x^{'})$ 不是kernel (c)首先计算下式子的形式。

$$egin{aligned} K(x,x^{'}) &= K_{1}(x,x^{'})K_{2}(x,x^{'}) = \phi_{1}(x)^{T}\phi_{1}(x^{'})\phi_{2}(x)^{T}\phi_{2}(x^{'}) \ &= \sum_{i=1}^{n}\phi_{1}^{i}(x)\phi_{1}^{i}(x^{'})\sum_{j=1}^{n}\phi_{2}^{j}(x)\phi_{2}^{j}(x^{'}) \ &= \sum_{i=1}^{n}\sum_{j=1}^{n}\phi_{1}^{i}(x)\phi_{1}^{i}(x^{'})\phi_{2}^{j}(x)\phi_{2}^{j}(x^{'}) \ &= \sum_{i=1}^{n}\sum_{j=1}^{n}(\phi_{1}^{i}(x)\phi_{2}^{j}(x))(\phi_{1}^{i}(x^{'})\phi_{2}^{j}(x^{'})) \end{aligned}$$

根据这个形式,可以做以下定义

$$\Phi^i(x) = \phi^i_1(x)(\phi^i_2(x), \dots, \phi^n_2(x))^T \ \Phi(x) = (\Phi^1(x), \dots, \Phi^n(x))^T$$

我们来计算下这个式子

$$(\Phi^{i}(x))^{T}(\Phi^{i}(x^{'})) = \sum_{j=1}^{n} (\phi_{1}^{i}(x)\phi_{2}^{j}(x))(\phi_{1}^{i}(x^{'})\phi_{2}^{j}(x^{'})) \ (\Phi(x))^{T}\Phi(x^{'}) = \sum_{i=1}^{n} (\Phi^{i}(x))^{T}(\Phi^{i}(x^{'})) = \sum_{i=1}^{n} \sum_{j=1}^{n} (\phi_{1}^{i}(x)\phi_{2}^{j}(x))(\phi_{1}^{i}(x^{'})\phi_{2}^{j}(x^{'})) = K(x,x^{'})$$

根据核函数的定义可知, $K(x,x^{'})=K_{1}(x,x^{'})+K_{2}(x,x^{'})$ 为kernele

$$(\mathsf{d})K(x,x^{'})=K_{1}(x,x^{'})/K_{2}(x,x^{'})$$

这个也不是kernel, 反例如下

$$M_1=egin{bmatrix}1&2\2&3\end{bmatrix}, M_2=egin{bmatrix}2&1\1&1\end{bmatrix}, M=M_1/M_2=egin{bmatrix}rac12&2\2&3\end{bmatrix}$$

M行列式小于0,所以必然不是半正定的,所以 $K(x,x^{'})=K_{1}(x,x^{'})/K_{2}(x,x^{'})$ 不是kernel 所以这题答案为(a)(c)

# **Problem 13**

设 $K, K_1$ 对应的Gram矩阵为 $M, M_1$ 

(a)

$$M_1 = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}, M = egin{bmatrix} (1-1)^2 & (1-0)^2 \ (1-0)^2 & (1-1)^2 \end{bmatrix} = egin{bmatrix} 0 & 1 \ 1 & 0 \end{bmatrix}$$

M的行列式小于0,所以 $K(x,x^{'})=(1-K_{1}(x,x^{'}))^{2}$ 不是kernel

(b)

$$M = 1126 M_1$$

因为 $M_1$ 半正定,所以M半正定,从而 $K(x,x^{'})=1126K_1(x,x^{'})$ 是kernel

(c)

$$M_1 = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}, M = egin{bmatrix} e^{-1} & 1 \ 1 & e^{-1} \end{bmatrix}$$

M的行列式小于0,所以 $K(x,x^{'})=\exp(-K_{1}(x,x^{'}))$ 不是kernel (d)利用 $f(x)=rac{1}{1-x}$ 在(0,1)区间的泰勒展开可得

$$egin{aligned} K(x,x^{'}) &= (1-K_{1}(x,x^{'}))^{-1} \ &= \sum_{i=0}^{+\infty} (K_{1}(x,x^{'}))^{i} \end{aligned}$$

由上题的(b)我们知道 $K_1(x,x^{'})^i$ 为kernel,再有上题的(a)我们知道kernel的和也为kernel,所以

$$K(x,x^{'}) = \sum_{i=0}^{+\infty} (K_{1}(x,x^{'}))^{i}$$

也为kernel

#### **Problem 14**

首先回顾下对偶问题对应的QP问题

我们来看如果用新的kernel, $ilde{K}(x,x^{'})=pK(x,x^{'})+q$ ,并且 $ilde{C}=rac{C}{p}$ 会产生什么情况

$$ilde{Q}_D = egin{bmatrix} y_1 y_1 ilde{K}_{11} & \dots & y_1 y_N ilde{K}_{1N} \ y_2 y_1 ilde{K}_{12} & \dots & y_2 y_N ilde{K}_{2N} \ \dots & \dots & \dots \ y_N y_1 ilde{K}_{N1} & \dots & y_N y_N ilde{K}_{NN} \end{bmatrix} \ = egin{bmatrix} y_1 y_1 (pK_{11} + q) & \dots & y_1 y_N (pK_{1N} + q) \ y_2 y_1 (pK_{12} + q) & \dots & y_2 y_N (pK_{2N} + q) \ \dots & \dots & \dots \ y_N y_1 (pK_{N1} + q) & \dots & y_N y_N (pK_{NN} + q) \end{bmatrix} \ = pQ_D + q(y_1, \dots, y_N)^T (y_1, \dots, y_N) \ ilde{A}_D = A_D \ ilde{A}_D = egin{bmatrix} 0 \ 0 \ 0 \ 0_{N imes N} \ ilde{C} & ilde{X} & I_{N imes N} \end{bmatrix} = egin{bmatrix} 1 \ 0 \ 0 \ 0_{N imes N} \ ilde{C} & ilde{X} & I_{N imes N} \end{bmatrix} = egin{bmatrix} 1 \ 0 \ 0 \ 0_{N imes N} \ ilde{C} & ilde{X} & I_{N imes N} \end{bmatrix}$$

接着我们来计算 $\alpha^T \tilde{Q}_D \alpha$ 

注意
$$(y_1,\ldots,y_N)lpha=0$$
  
所以 $lpha^T ilde{Q}_Dlpha=lpha^TpQ_Dlpha+lpha^Tq(y_1,\ldots,y_N)^T(y_1,\ldots,y_N)lpha=plpha^TQ_Dlpha$ 

所以我们的目标函数为

$$rac{1}{2}lpha^T ilde{Q}_Dlpha-1_N^Tlpha=rac{1}{2}plpha^T ilde{Q}_Dlpha-1_N^Tlpha=rac{1}{p}[rac{1}{2}(plpha)^TQ_D(plpha)-1_N^T(plpha)]$$

由于p为常数,所以目标函数可以简化为

$$\frac{1}{2}(p\alpha)^TQ_D(p\alpha)-1_N^T(p\alpha)$$

再看下限制条件

$$ilde{A}_Dlpha \geq ilde{u} \Leftrightarrow A_Dlpha \geq rac{1}{p}u \Leftrightarrow A_D(plpha) \geq u$$

我们令 $\overline{\alpha} = p\alpha$ ,那么问题可以转换为

$$egin{aligned} & & & \min _{lpha \in R^N} : rac{1}{2} \overline{lpha}^T Q_D \overline{lpha} - 1_N^T \overline{lpha} \ & & & ext{subject to} : A_D \overline{lpha} \geq u \ Q_D = egin{bmatrix} y_1 y_1 K_{11} & \dots & y_1 y_N K_{1N} \ y_2 y_1 K_{12} & \dots & y_2 y_N K_{2N} \ \dots & \dots & \dots \ y_N y_1 K_{N1} & \dots & y_N y_N K_{NN} \end{bmatrix}, A_D = egin{bmatrix} y^T \ -y^T \ I_{N imes N} \ -I_{N imes N} \end{bmatrix}, u = egin{bmatrix} 0 \ 0 \ 0 \ 0 \ N imes N \ C imes I_{N imes N} \end{bmatrix} \end{aligned}$$

可以看出,这个问题和原问题是一致的,记原问题的最优解为 $\alpha^*$ ,那么该问题的最优解 $\tilde{\alpha}^*$ 满足以下条件

$$\alpha^* = p\tilde{\alpha}^*$$

我们根据这个条件开始讨论问题。

回顾下soft-margin得到的计算公式

$$w^* = \sum_{n=1}^N lpha_n^* y_n z_n$$
  $eta_n^* = C - lpha_n^* (n=1,\ldots,N)$   $b^* = y_m - w^{*T} z_m = y_m - (\sum_{n=1}^N lpha_n^* y_n z_n)^T z_m = y_m - \sum_{n=1}^N lpha_n^* y_n K(x_n,x_m)$  其中 $z_m$ 对应的 $lpha_m^* \neq 0$   $g(x) = ext{sign}(w^{*T}z + b) = ext{sign}((\sum_{n=1}^N lpha_n^* y_n z_n)^T z + b) = ext{sign}(\sum_{n=1}^N lpha_n^* y_n K(x_n,x) + b^*)$ 

如果我们将kernel换成

$$ilde{K}(x,x^{'})=pK(x,x^{'})+q$$

利用之前的条件 $lpha^*=p ilde{lpha}^*$ 以及 $ilde{C}=rac{C}{p},\sum_{n=1}^Nlpha_n^*y_n=0$ ,可以对变换kernel之后的问题求解

$$\begin{split} \tilde{w}^* &= \sum_{n=1}^N \tilde{\alpha}_n^* y_n z_n = \frac{1}{p} (\sum_{n=1}^N \alpha_n^* y_n z_n) = \frac{w^*}{p} \\ \tilde{\beta}_n^* &= \tilde{C} - \tilde{\alpha}_n^* = \frac{C}{p} - \frac{\alpha_n^*}{p} = \frac{1}{p} (C - \alpha_n^*) = \frac{\beta_n}{p} (n = 1, \dots, N) \\ \tilde{b}^* &= y_m - \sum_{n=1}^N \tilde{\alpha}_n^* y_n \tilde{K}(x_n, x_m) \\ &= y_m - \sum_{n=1}^N \alpha_n^* y_n (pK(x_n, x_m) + q) \\ &= y_m - \sum_{n=1}^N \alpha_n^* y_n K(x_n, x_m) - \frac{q}{p} \sum_{n=1}^N \alpha_n^* y_n \\ &= y_m - \sum_{n=1}^N \alpha_n^* y_n K(x_n, x_m) \\ &= b^* \\ \tilde{g}(x) &= \text{sign}(\sum_{n=1}^N \tilde{\alpha}_n^* y_n \tilde{K}(x_n, x) + \tilde{b}^*) \\ &= \text{sign}[\sum_{n=1}^N \frac{\alpha_n^*}{p} y_n (pK(x_n, x) + q) + b^*] \\ &= \text{sign}[\sum_{n=1}^N \alpha_n^* y_n K(x_n, x) + \frac{q}{p} \sum_{n=1}^N \alpha_n^* y_n + b^*] \\ &= \text{sign}(\sum_{n=1}^N \alpha_n^* y_n K(x_n, x) + b^*) \\ &= g(x) \end{split}$$

这说明这样变换之后我们的分类器没有变。

### **Problem 15**

首先读取数据

```
train = "featurestrain.txt"

X_train,Y_trian = transformdata(train)

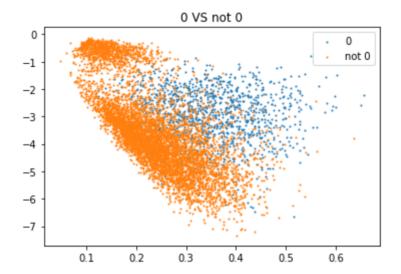
test = "featurestest.txt"

X_test,Y_test = transformdata(test)
```

注意此题是区分0和非0,作图看下。

```
x1 = X_train[Y_trian==0][:,0]
y1 = X_train[Y_trian==0][:,1]
x2 = X_train[Y_trian!=0][:,0]
y2 = X_train[Y_trian!=0][:,1]

plt.scatter(x1,y1,s=1,label = '0')
plt.scatter(x2,y2,s=1,label = 'not 0')
plt.title('0 VS not 0')
plt.legend()
plt.show()
```

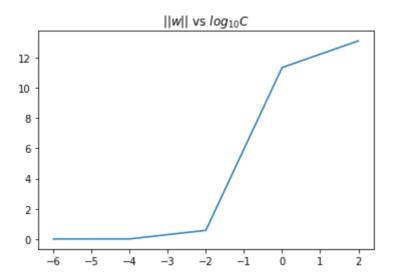


现在可以训练模型并作图了。

```
Y_trian1 = (Y_trian==0)
C = [-6,-4,-2,0,2]
W = []

for i in C:
    c = 10**i
    clf = svm.SVC(kernel = "linear",C = c)
    clf.fit(X_train,Y_trian1)
    w = clf.coef_[0]
    W = np.append(W,np.sqrt(np.sum(w*w)))

plt.plot(C,W)
plt.title("$||w||$ vs $log_{10}C$")
plt.show()
```



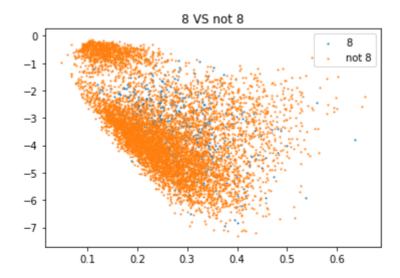
# **Problem 16**

注意这题是8和not 8

```
x3 = X_train[Y_trian==8][:,0]
y3 = X_train[Y_trian!=8][:,1]

x4 = X_train[Y_trian!=8][:,0]
y4 = X_train[Y_trian!=8][:,1]

plt.scatter(x3,y3,s=1,label = '8')
plt.scatter(x4,y4,s=1,label = 'not 8')
plt.title('8 VS not 8')
plt.legend()
plt.show()
```



注意17题要计算 $\sum_{n=1}^N \alpha_n$ ,所以我们这题把系数也算出来, 由于sklearn只能计算对偶系数 $y_n\alpha_n$ ,所以这里要把标签转换为+1,-1,方便计算。

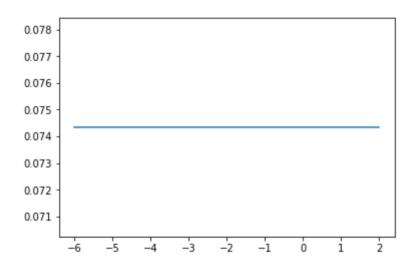
```
Y_trian2 = 2*(Y_trian==8)-1

C = [-6,-4,-2,0,2]
Ein = []
alpha = []

for i in C:
    c = 10**i
    clf = svm.SVC(kernel='poly',degree=2,coef0=1,gamma=1,C = c)
    clf.fit(X_train,Y_trian2)
    e = np.sum(clf.predict(X_train) != Y_trian2)/len(X_train)
    support = clf.support_
    coef = np.sum(clf.dual_coef_[0]*Y_trian2[support])
    alpha.append(coef)
Ein.append(e)
```

作图。

```
plt.plot(C,Ein)
plt.show()
```

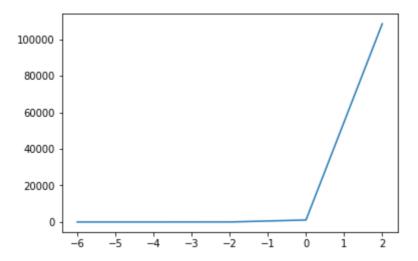


比较奇特的是这题的 $E_{in}$ 都一样。

# **Problem 17**

利用上题的数据作图即可。

```
plt.plot(C,alpha)
plt.show()
```



可以看到尽管上题的 $E_{in}$ 一致,但是这里 $\sum_{n=1}^{N} \alpha_n$ 会增加。

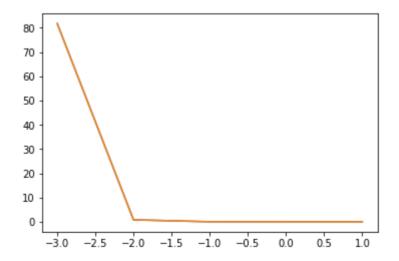
# **Problem 18**

这题要计算距离,注意距离为 $\frac{1}{||w||}$ 

```
C = [-3,-2,-1,0,1]
Distance = []

for i in C:
    c = 10**i
    clf = svm.SVC(kernel='rbf',gamma=1,C = c)
    clf.fit(X_train,Y_trian1)
    w = clf.dual_coef_[0].dot(clf.support_vectors_)
    distance = 1/np.sum(w*w)
    Distance.append(distance)

plt.plot(C, Distance)
plt.show()
```



随着~增加,距离超平面的距离在减少。

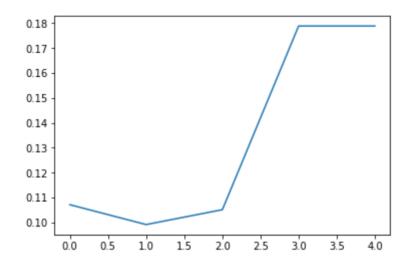
### **Problem 19**

```
Y_test1 = (Y_test==0)

Gamma = range(5)
Eout = []

for i in Gamma:
    gamma = 10**i
    clf = svm.SVC(kernel='rbf',gamma=gamma,C = 0.1)
    clf.fit(X_train,Y_trian1)
    e = np.sum(clf.predict(X_test) != Y_test1)/len(X_test)
    Eout.append(e)

plt.plot(Gamma,Eout)
plt.show()
```



可以看到, $\log_{10}C=1$ 时, $E_{out}$ 最小,说明C不能太大,也不能太小。

### **Problem 20**

这题要构造交叉验证集,多次实验,做直方图,先做一些预处理。

```
from sklearn.model_selection import train_test_split

#对数据合并,方便调用train_test_split函数

Data = np.concatenate((X_train,Y_trian1.reshape(-1,1)),axis=1)

N = 100

Cnt = np.zeros(5)

Gamma = range(5)

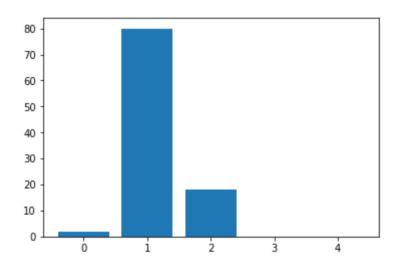
for _ in range(N):
    train_set, val_set = train_test_split(Data, test_size=0.2)
    #取特征
```

```
Xtrain = train_set[:,:2]
#取标签
Ytrain = train_set[:,2]
Xval = val_set[:,:2]
Yval = val_set[:,2]
Eval = np.array([])

for i in Gamma:
    gamma = 10**i
    clf = svm.SVC(kernel='rbf',gamma=gamma,C = 0.1)
    clf.fit(Xtrain,Ytrain)
    e = np.sum(clf.predict(Xval) != Yval)/len(Xval)
    Eval = np.append(Eval,e)
index = np.argmin(Eval)
Cnt[index] += 1
```

作图

```
plt.bar(Gamma,Cnt)
plt.show()
```



可以看到大部分最优解对应的 $\log_{10}\gamma$ 都为1,和上一题说明同一个道理,说明 $\gamma$ 不能太大,也不能太小。

### 附加题

### **Problem 21**

这题的问题是求hard-margin SVM对偶问题的的对偶问题,我们来看一下。

首先回顾下hard-margin SVM对偶问题。

$$egin{aligned} & ext{minimize}: rac{1}{2} \sum_{m=1}^{N} \sum_{n=1}^{N} y_n y_m lpha_n lpha_m x_n^T x_m - \sum_{n=1}^{N} lpha_n \ & ext{subject to}: \sum_{n=1}^{N} y_n lpha_n = 0, lpha_n \geq 0 (n=1,\ldots,N) \end{aligned}$$

根据拉格朗日乘子法, 我们将上述问题转化为

$$\min_{\alpha \in R^N} \max_{\lambda_i \geq 0} : \frac{1}{2} \sum_{m=1}^N \sum_{n=1}^N y_n y_m \alpha_n \alpha_m x_n^T x_m - \sum_{n=1}^N \alpha_n + \lambda_0 (\sum_{n=1}^N y_n \alpha_n) - \sum_{n=1}^N \lambda_n \alpha_n$$

这里肯定是默认KKT条件成立, 所以上述问题可以转化为

$$\max_{\lambda_i \geq 0} \min_{\alpha \in R^N} : \frac{1}{2} \sum_{m=1}^N \sum_{n=1}^N y_n y_m \alpha_n \alpha_m x_n^T x_m - \sum_{n=1}^N \alpha_n + \lambda_0 (\sum_{n=1}^N y_n \alpha_n) - \sum_{n=1}^N \lambda_n \alpha_n$$

这个最小值问题转化为为一个无条件极值, 现在做以下记号

$$f(\lambda,lpha) = rac{1}{2}\sum_{m=1}^N\sum_{n=1}^N y_n y_m lpha_n lpha_m x_n^T x_m - \sum_{n=1}^N lpha_n + \lambda_0 (\sum_{n=1}^N y_n lpha_n) - \sum_{n=1}^N \lambda_n lpha_n$$

关于 $\alpha_i$ 求偏导可得

$$egin{aligned} rac{\partial f}{\partial lpha_i} &= rac{1}{2} \sum_{n=1}^N y_n y_i lpha_n x_n^T x_i + rac{1}{2} \sum_{m=1}^N y_i y_m lpha_m x_i^T x_m - 1 + \lambda_0 y_i - \lambda_i \ &= \sum_{n=1}^N y_n y_i lpha_n x_i^T x_n - 1 + \lambda_0 y_i - \lambda_i \end{aligned}$$

令偏导为0可得

$$\sum_{n=1}^N y_n y_i lpha_n x_i^T x_n = 1 - \lambda_0 y_i + \lambda_i$$

对这个式子作以下变形可得

$$egin{bmatrix} \left[ \ y_i y_1 x_i^T x_1 & \dots & y_i y_N x_i^T x_N \ 
ight] \begin{bmatrix} lpha_1 \ \dots \ lpha_N \end{bmatrix} = 1 - \lambda_0 y_i + \lambda_i \end{split}$$

这个形式是见过的,我们回顾下Learning from data第28页,我们知道hard-margin SVM对偶问题也可以写成如下的形式

$$egin{aligned} & & \operatorname{minimize}: rac{1}{2} lpha^T Q_D lpha - 1_N^T lpha \ & & \operatorname{subject} \ \operatorname{to}: A_D lpha \geq 0_{N+2} \ Q_D = egin{bmatrix} y_1 y_1 x_1^T x_1 & \dots & y_1 y_N x_1^T x_N \ y_2 y_1 x_2^T x_1 & \dots & y_2 y_N x_2^T x_N \ \dots & \dots & \dots \ y_N y_1 x_N^T x_1 & \dots & y_N y_N x_N^T x_N \end{bmatrix} \ ext{and} \ A_D = egin{bmatrix} y^T \ -y^T \ I_{N imes N} \end{bmatrix} \end{aligned}$$

(1)的等式左边的第一个向量对应着 $Q_D$ 的每一行,所以如果我们对(1)式中i从1取到N,可以把(1)的条件转化为

$$Q_Dlpha = 1_N - \lambda_0 y + \lambda \ lpha = egin{bmatrix} lpha_1 \ lpha_N \end{bmatrix}, y = egin{bmatrix} y_1 \ lpha_N \end{bmatrix}, \lambda = egin{bmatrix} \lambda_1 \ lpha_N \end{bmatrix}$$

在这个记号下, 我们问题改写下

将 $Q_D \alpha = 1_N - \lambda_0 y + \lambda$ 带入可得

$$f(\lambda, \alpha) = \frac{1}{2} \alpha^T Q_D \alpha - 1_N^T \alpha + \lambda_0 \alpha^T y - \alpha^T \lambda$$

$$= \frac{1}{2} \alpha^T (1_N - \lambda_0 y + \lambda) - 1_N^T \alpha + \lambda_0 \alpha^T y - \alpha^T \lambda$$

$$= -\frac{1}{2} \alpha^T 1_N + \frac{1}{2} \lambda_0 \alpha^T y - \frac{1}{2} \alpha^T \lambda$$

$$= -\frac{1}{2} \alpha^T (1_N - \lambda_0 y + \lambda)$$

如果 $Q_D$ 可逆,那么

$$lpha = Q_D^{-1}(1_N - \lambda_0 y + \lambda)$$

代入可得

$$egin{aligned} -rac{1}{2}lpha^T(1_N-\lambda_0 y+\lambda) &= -rac{1}{2}[Q_D^{-1}(1_N-\lambda_0 y+\lambda)]^T(1_N-\lambda_0 y+\lambda) \ &= -rac{1}{2}(1_N-\lambda_0 y+\lambda)^TQ_D^{-1}(1_N-\lambda_0 y+\lambda) \end{aligned}$$

所以问题转化为

$$egin{aligned} & ext{maxmize} : -rac{1}{2}(1_N - \lambda_0 y + \lambda)^T Q_D^{-1}(1_N - \lambda_0 y + \lambda) \ & ext{subject to} : \lambda_i \geq 0 (n = 0, 1, \dots, N) \end{aligned}$$

把负号提出来,可以转化为标准的QP问题

$$egin{aligned} & ext{minimize}: rac{1}{2}(1_N - \lambda_0 y + \lambda)^T Q_D^{-1}(1_N - \lambda_0 y + \lambda) \ & ext{subject to}: \lambda_i \geq 0 (n = 0, 1, \dots, N) \end{aligned}$$

可以看到,这和最开始的问题是非常类似的。