

- $\diamond \diamond \zeta_B$


```
void time_add(){
    ...
    t.second++;
    if (t.second == 60) {
        t.second = 0;
        t.minute++;
        if (t.minute == 60) {
            t.minute = 0;
            t.hour++;
            if (t.hour == 24) {
                t.hour = 0;
                t.day++;
                if (t.day == 32) {
                    t.day = 1;
                    t.month++;
                    if (t.month == 13) {
                        t.month = 1;
                        t.year++;
                    }
                }
            }
        }
    }
    ...
}

...
SetEventCallBack(enumEventSys1S, time_add);
```


νïädcĠrḥĵıãlight_show()û'adcĠĠĠ
گ''

2.3.4 ls

'ğnDTH11
' k1 π趨ұŭk1

LJlsğDTH11lsŸrY趨
K' 'گċwŁClsqḥ
ł£

```

unsigned char COM(void) {
    unsigned char i,dat=0;

    for(i = 0; i < 8; i++) {
        while(P1_0)
            ;
        while(!P1_0)
            ;
        Delay_10us();
        Delay_10us();
        Delay_10us();
        Delay_10us();
        Delay_10us();
        dat <<= 1;
        if(P1_0) {
            dat |= 1; // 0
        };
    } // rof
    return dat;
}

```

```

void RH(void) {
    // 18ms
    P1_0 = 0;
    Delay10ms();
    Delay10ms();
    P1_0 = 1;
    // 20us
    Delay_10us();
    Delay_10us();
    Delay_10us();
    // P1_0 = 1;
    if(!P1_0) // T !
    {
        while(!P1_0)
            ;
        Delay_10us();
        Delay_10us();
        Delay_10us();
        Delay_10us();
        Delay_10us();
        U8RH_data_H=COM();
    }
}

```

ls()

- [illegible]

◆◆◆◆flag_auto_set=3/4/5/6

2.3.11 (reset)

س ا ã ħ 酖 趨 ¶ ŋ 8 j ɬ ' и

2.3.12 (set)

◆ ◆ ◆趨勢

?IJ??????????????ز?????ف□?趨

? ? ? ? ? فب ? ? ? ? ? ت ? د ? ? ? ? ? J ? ? ? ? ? ä ? ? ? ? ? ö

趨 set 2 " 'ü autoset

2.3.13 '◆◆◆◆'























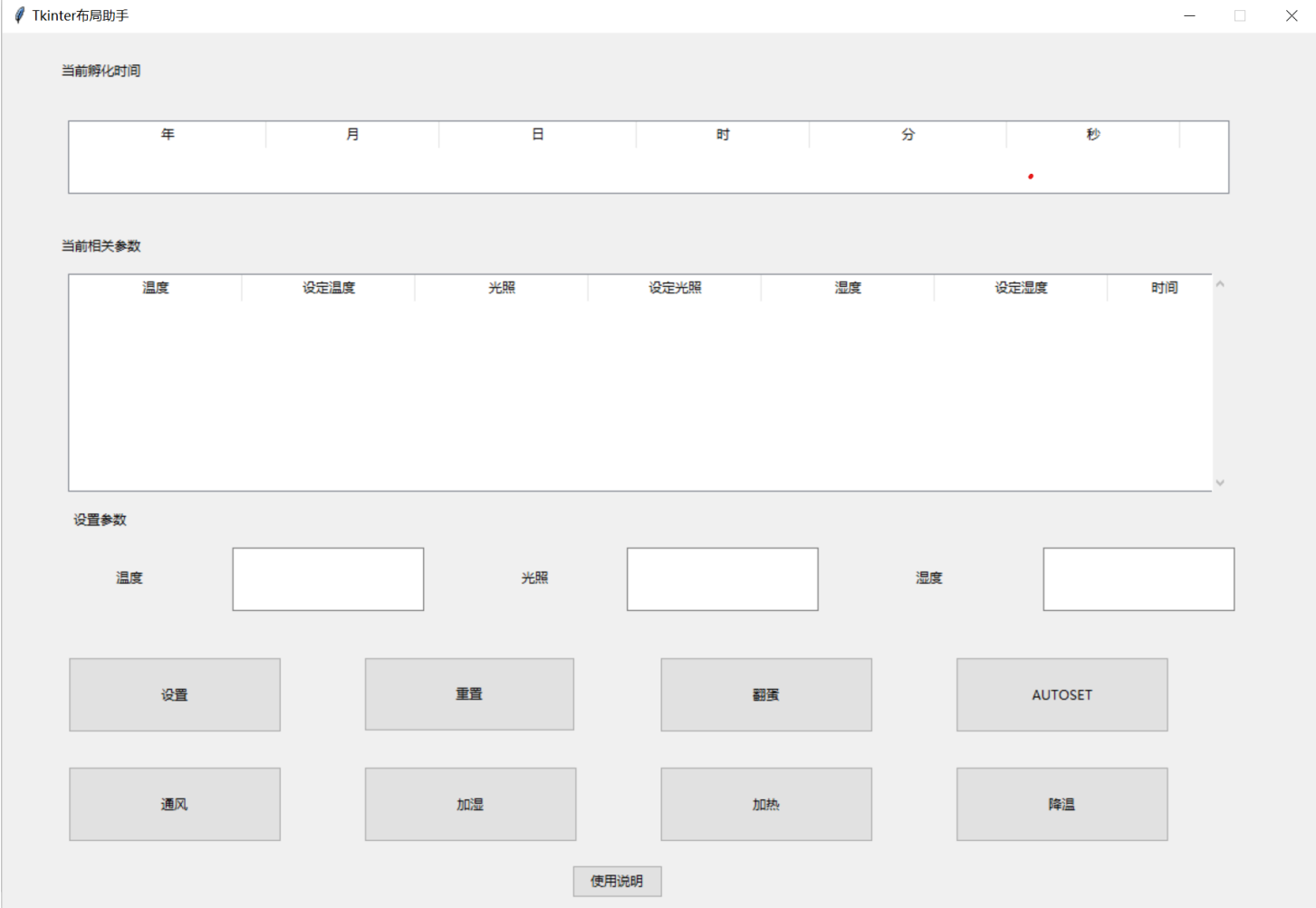









2.4 UI???



2.5 ?????牙

- 1. stc-bax??
- 2. DTH11??ls??g??

2.6 天?????'÷????

- 1. ???_?j?_????|?
 - 2. ???ls??g?養????????|????stc-bax??
 - 3. ??j?_????B????
- ??
- 1. ??py?|~????x?????'"????flag_auto_set=0
 - 2. ??ص?autoset????ò?????û????~????

[illegible]

```

void deal_info()
{
    int flag_person_set = whether_set();
    int whether_set_pars;

    flag_reset = 0;
    // unsigned char get_buffer[8]
    set_temp      = get_buffer[0];
    set_light     = get_buffer[1];
    set_wet       = get_buffer[2];
    flag_move_egg = get_buffer[3];
    flag_get_wind = get_buffer[4];
    flag_get_wet  = get_buffer[5];
    flag_get_hot  = get_buffer[6];
    flag_get_cold = get_buffer[7];
    if (flag_get_wind == 2 && flag_move_egg == 2 && flag_get_hot == 2 && flag_get_wet == 2 && fl
        t.year      = 0;
        t.month     = 0;
        t.day       = 0;
        t.hour      = 0;
        t.minute    = 0;
        t.second     = 0;
        flag_reset  = 1;
    }

    flag_auto_set = 0;
    if (flag_move_egg == 3) {
        EmStop(enumStepMotor2);
        EmStop(enumStepMotor3);
        flag_auto_set = 1; // "auto"
        return;
    }
    whether_set_pars = whether_set_parameters(); //==>

    // 8
    if (whether_set_pars == 1) {
        EmStop(enumStepMotor2);
        EmStop(enumStepMotor3);
        flag_auto_set = 2;
    }

    // "
    if (flag_reset == 1) {
        // move_egg();
        EmStop(enumStepMotor1);
        EmStop(enumStepMotor2);
        EmStop(enumStepMotor3);
        flag_auto_set = 0;
    }
}

```

```

if (flag_move_egg == 1) {
    if (whether_set_pars == 2) {
        move_egg();
    } else {
        move_egg();
        flag_auto_set = 2;
    }
}

if (flag_get_wind == 1) {
    if (whether_set_pars == 2) {
        get_more_wind();
    } else {
        get_more_wind();
        EmStop(enumStepMotor2);
        flag_auto_set = 3;
        // return;
    }
}

if (flag_get_wet == 1) {
    if (whether_set_pars == 2) {
        get_more_wet();
    } else {
        get_more_wet();
        EmStop(enumStepMotor2);
        flag_auto_set = 4;
        // return;
    }
}

if (flag_get_hot == 1) {
    if (whether_set_pars == 2) {
        get_more_hot();
    } else {
        get_more_hot();
        EmStop(enumStepMotor3);
        flag_auto_set = 5;
        // return;
    }
}

if (flag_get_cold == 1) {
    if (whether_set_pars == 2) {
        get_more_cold();
    } else {
        get_more_cold();
        EmStop(enumStepMotor3);
        flag_auto_set = 6;
        // return;
    }
}
}

```

10. reset? □ ? ? ? ? ? h ? ? (SUCCESS)

??j???

1. ????j? (success)
2. ??p??h??ŷ?(????)
3. û?av?j???趨?ll????
4. ?□?set?趨?ll?(SUCCESS)
5. ??ils?g??
6. ??deal_info?g????д????Ç?趨h?? ???-?ls???趨(success)
7. ??h?c?緇?? 'ò??????
8. ??ls?т?λCдед??now_seg_show??
9. set_info??tempj?ö?h????(SUCCESS)
10. ?□?c?ls'?ò?????j?к? ?Ы????к?'???? жg?ж?led?P?n??=>?????'?seg??' ?????'?ijh?led????==>?????'?led????eg0x101
11. ?趨?????c?? ?ls (SUCCESS)
12. ???r?,??У??4??

?????~?

1. ??h?L?д??h?g?黻????h?g??
2. ????h??h????д?꺠?g?? ?ε?h?????伊
3. □□?????????????J?c?~????z?????h?????□?L????

ps????ll????Ç????g?? ????llA??趨?ll8?set->s??(????)

1. ls????У?????趨?У????(SUCCESS)
2. ???x????? ????L????
v????h??İ4????w????İ2
3. seg+????h??h??.?h??
4. ??h????ط????ls?j?????adc??'????

??ls? >motor2

???? >motor3

????>motor1

????-????

?趨h??exter_func>????ж??P????в??(????)

???r???12 ???x???8

????h????

? ? ? ? ? ? ? ? ? ? ? ? ? ? ✖ ?

??h??趨?¶?~????e??ǰ?4??

◆ ? ◆ ? ◆ X ◆ ? ◆ ? ◆ ? ◆ ? 2

ls?j?X ??5




¹




²






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2






5 6-->hot cold

1. 趨'ù??.?

?? Σ^B

<https://zhuanlan.zhihu.com/p/114975190>