

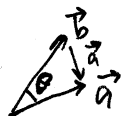
Vectors & Matrices.

1. Vectors.

- Dot Product: eg. $\vec{a} = \langle a_1, a_2, a_3 \rangle$, $\vec{b} = \langle b_1, b_2, b_3 \rangle$, then

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3 \quad \vec{a} \cdot \vec{a} = \|\vec{a}\|^2$$

$$\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta.$$

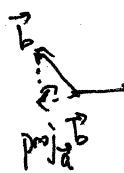


proof: $\|\vec{a} - \vec{b}\|^2 = \|\vec{a}\|^2 + \|\vec{b}\|^2 - 2(\|\vec{a}\| \|\vec{b}\| \cos \theta).$

$$\Leftrightarrow (\vec{a} - \vec{b}) \cdot (\vec{a} - \vec{b}) = \|\vec{a}\|^2 - 2\vec{a} \cdot \vec{b} + \|\vec{b}\|^2$$

$$\Leftrightarrow \vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta.$$

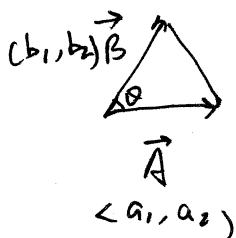
$\vec{a} \cdot \vec{b} = 0 \Leftrightarrow$ two vectors are orthogonal.



$$\text{proj}_{\vec{a}} \vec{b} = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|^2} \vec{a}$$

or: $\text{proj}_{\vec{a}} \vec{b} = \|\vec{b}\| \cos \theta$
 $= \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|} \vec{u}$ $\vec{u} \rightarrow$ unit vector
 $\vec{u} = \frac{\vec{a}}{\|\vec{a}\|}$

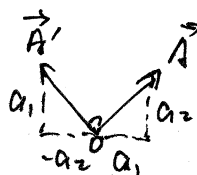
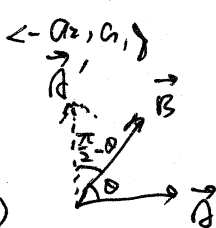
- Area



$$S_{\Delta} = \frac{1}{2} \|\vec{A}\| \|\vec{B}\| \sin \theta$$

$$= \frac{1}{2} \|\vec{A}\| \|\vec{B}\| \cos(\frac{\pi}{2} - \theta)$$

$$= \frac{1}{2} \vec{A}' \cdot \vec{B}$$



$$\frac{1}{2} \langle -a_2, a_1 \rangle \cdot \langle b_1, b_2 \rangle = \frac{1}{2} (a_1 b_2 - a_2 b_1) = \frac{1}{2} \det(\vec{A}, \vec{B}) = \frac{1}{2} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

$$\therefore S_{\Delta} = \det(\vec{A}, \vec{B})$$

- Cross Product

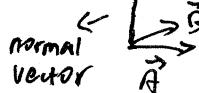
3-D
 \mathbb{R}^3

$$\vec{A} \times \vec{B} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = \begin{vmatrix} a_y & a_z \\ b_y & b_z \end{vmatrix} \vec{i} - \begin{vmatrix} a_x & a_z \\ b_x & b_z \end{vmatrix} \vec{j} + \begin{vmatrix} a_x & a_y \\ b_x & b_y \end{vmatrix} \vec{k}$$

$$= \langle a_y b_z - b_y a_z, -(a_x b_z - b_x a_z), a_x b_y - b_x a_y \rangle$$

$\text{dir}(\vec{A} \times \vec{B}) = \perp$ to plane of the \square

with right hand rule, (from \vec{A} to \vec{B})

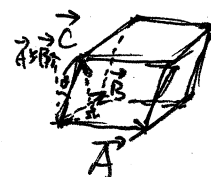


$$\vec{A} \times \vec{B} = -(\vec{B} \times \vec{A})$$

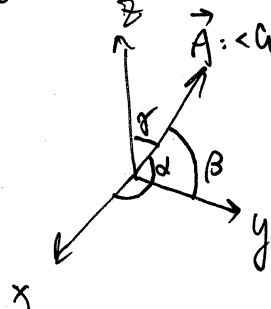
$$\vec{A} \times \vec{A} = 0.$$

3-D: $\det(\vec{A}, \vec{B}, \vec{C}) = \pm \text{Volume of parallelepiped}$
 $|\vec{A} \times \vec{B}| |\vec{C}| \cos \theta$

$$= \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \vec{A} \cdot (\vec{B} \times \vec{C}) = (\vec{A} \times \vec{B}) \cdot \vec{C}$$



- Cosines:



$$\vec{A} = \langle A_x, A_y, A_z \rangle$$

$$\cos \alpha = \frac{\vec{A} \cdot \vec{i}}{|\vec{A}|} = \frac{A_x}{|\vec{A}|}$$

$$\cos \beta = \frac{A_y}{|\vec{A}|}, \quad \cos \gamma = \frac{A_z}{|\vec{A}|}$$

Q. Question: if $\frac{3}{5} \sin \theta + \frac{4}{5} \cos \theta = 1$, get $\tan \theta$.

not vector:

Solve: Assume $\vec{e}_1 = \langle \sin \theta, \cos \theta \rangle$, $\vec{e}_2 = \langle \frac{3}{5}, \frac{4}{5} \rangle$

$$\vec{e}_1 \cdot \vec{e}_2 = 1 = |\vec{e}_1| \cdot |\vec{e}_2| \cos \alpha \Rightarrow \vec{e}_1 \parallel \vec{e}_2$$

$$\therefore \sin \theta = \lambda \cdot \frac{3}{5}, \cos \theta = \lambda \cdot \frac{4}{5} \Rightarrow \tan \theta = \frac{3}{4}$$

$$\sum \cos^2 \theta = 1, \text{ unit vector: } \frac{\vec{A}}{|\vec{A}|} = \langle \cos \alpha, \cos \beta, \cos \gamma \rangle$$

- derivative

vector function

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle, \quad \frac{d}{dt}(\vec{r} \cdot \vec{s}) = \vec{r} \cdot \frac{d\vec{s}}{dt} + \vec{s} \cdot \frac{d\vec{r}}{dt}; \quad \frac{d}{dt}(\vec{r} \times \vec{s}) = \vec{r} \times \frac{d\vec{s}}{dt} + \vec{s} \times \frac{d\vec{r}}{dt}$$

2. Matrix.

$$\begin{cases} a_{11}x + a_{12}y + a_{13}z = b_1 \\ a_{21}x + a_{22}y + a_{23}z = b_2 \\ a_{31}x + a_{32}y + a_{33}z = b_3 \end{cases}$$

$$\vec{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad \vec{A}\vec{x} = \vec{b}$$

transposition

$$\vec{A}^T = (a_{ji})$$

$$\vec{A} \cdot \vec{B} = \vec{C}$$

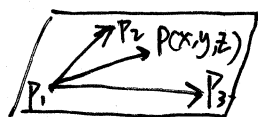
m x n n x p m x p

$$c_{ij} = \sum_{k=1}^n a_{ik} \cdot b_{kj}$$

2x3 3x1 2x1

$$\text{eg. } \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \cdot \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} = \begin{pmatrix} 1 \cdot 7 + 2 \cdot 8 + 3 \cdot 9 \\ 4 \cdot 7 + 5 \cdot 8 + 6 \cdot 9 \end{pmatrix} = \begin{pmatrix} 50 \\ 122 \end{pmatrix}$$

3. Equations of Planes



Plane $P_1P_2P_3$, if $P \in P_1P_2P_3$, $\det(\vec{P_1P_2}, \vec{P_1P_3}, \vec{P_1P}) = 0$

or $\vec{P_1P} \cdot (\vec{P_1P_2} \times \vec{P_1P_3}) = 0$ △

- plane $ax + by + cz = d$, if we know normal vector, and another point, we could find a plane.

eg. normal vector $\vec{N} = \langle 1, 5, 10 \rangle$, pass $P_0 = (2, 1, -1)$, the plane's eqn function:

Assume $P \in \text{Plane}$, $P = (x, y, z)$

$$\Rightarrow \vec{P_0P} \cdot \vec{N} = 0 \Leftrightarrow \langle x-2, y-1, z+1 \rangle \cdot \langle 1, 5, 10 \rangle \Leftrightarrow 1x + 5y + 10z = -3 \quad (\text{Find a Plane})$$

coefficient is \vec{N} 's x, y, z.

linear sys.

eg. 3x3: line P_1P_2 intersects P_3 in a point = solution

3 planes $P_1P_2P_3$

$$\vec{A}^{-1} = \frac{1}{|\vec{A}|} \text{adj}(\vec{A}), \quad |\vec{A}| \neq 0 \quad (\vec{A} \cdot \vec{A}^{-1} = \vec{I}_{(n \times n)})$$

identity matrix

\vec{A} is $n \times n$ matrix, then $\vec{A}\vec{x} = 0 \Rightarrow$ homogeneous, $\vec{A}\vec{x} = \vec{b}$, $\vec{b} \neq 0 \Rightarrow$ inhomogeneous.

Theorem 1. $|\vec{A}| \neq 0 \Rightarrow \vec{A}\vec{x} = \vec{b}$ has the unique solution $\vec{x} = \vec{A}^{-1}\vec{b}$, if $\vec{b} = 0$, $\vec{x} = 0$ trivial solutions

Theorem 2. $|\vec{A}| = 0 \Rightarrow \vec{A}\vec{x} = 0$ has non-zero solutions (non-trivial solutions)

$\Rightarrow \vec{A}\vec{x} = \vec{b}$ usually has no solutions, but has ones for some \vec{b} .