

# Theory of Computation

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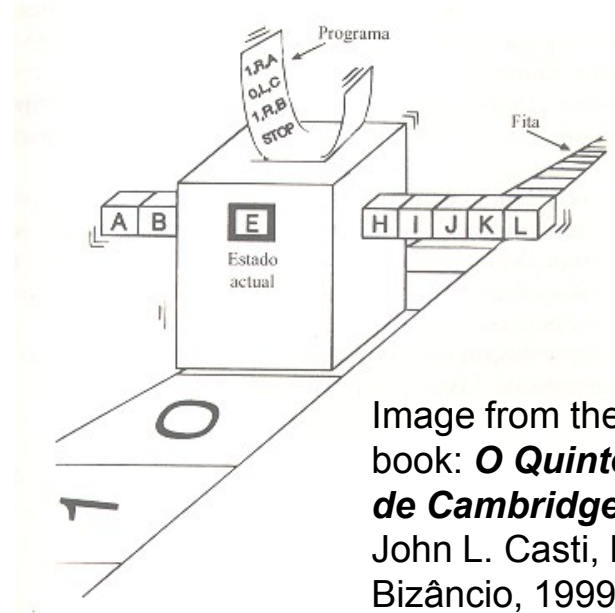


Image from the book: ***O Quinteto de Cambridge***, John L. Casti, Ed. Bizâncio, 1999.

# Motivation

- ▶ Undecidable Problems
  - ▶ There is no algorithm
- ▶ Intractable Problems
  - ▶ The known algorithms are very costly
  - ▶ Simplification and the use of heuristics
- ▶ Simple model to study the computability
  - ▶ Turing Machines
  - ▶ A model of a computer

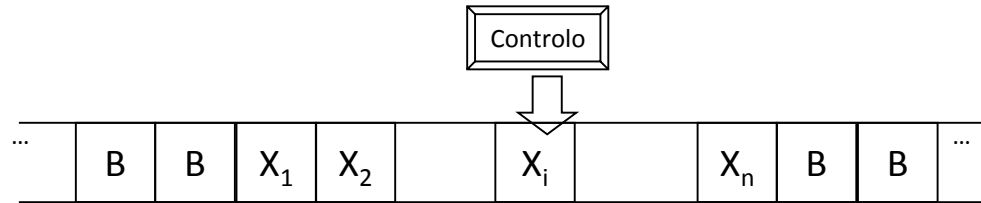
# Context

- ▶ David Hilbert (beginning of 20th century)
  - ▶ Is there a way to determine whether any formula in the first-order predicate calculus, applied to integers, is true?
- ▶ Kurt Gödel (1931)
  - ▶ Incompleteness theorem. He constructed a formula in the predicate calculus applied to integers, which asserted that the formula itself could be neither proved nor disproved within the predicate calculus.
- ▶ Alan Turing (1936)
  - ▶ proposed the Turing machine as a model of any possible computation
- ▶ A. Church
  - ▶ Church-Turing hypothesis (unprovable)
  - ▶ “any general way to compute will allow us to compute only the partial-recursive functions” (or equivalently to what Turing machines or modern-day computers can compute)

# The Church-Turing Thesis

- ▶ *“All reasonable models of (general-purpose) computers are equivalent. In particular, they are equivalent to a Turing machine.”*
- ▶ A Turing Machine is, according to the Church-Turing thesis, a general model of computation, potentially able to execute any algorithm.
- ▶ First formulated by Alonzo Church in the 1930s and is usually referred to as Church’s thesis, or the Church-Turing thesis

# Turing Machine



- ▶ Finite State Controller
  - ▶ Finite number of states
- ▶ Tape with infinite length and consisting of cells
  - ▶ Each cell can store a symbol
- ▶ Input
  - ▶ Finite string consisting of symbols of the input alphabet
  - ▶ Placed in the tape in the beginning (all other cells are marked with blank (B))
- ▶ Symbols in the tape
  - ▶ Input alphabet + blank + other symbols if needed

# Turing Machine

## ▶ Head of the tape

- ▶ Always positioned in a cell
- ▶ In the beginning it is in the leftmost cell of the input string

## ▶ Movement or step of the machine

- ▶ Function of the state of the control and of the symbol being read by the head
- ▶ 1. State transition
  - ▶ It can be the same
- ▶ 2. Write of a symbol in the cell where is the head
  - ▶ It can be the same
- ▶ 3. Movement of the head by one cell left or right
  - ▶ A transition always implies a step of the head in the tape

# Formal Definition

- ▶ Turing Machine (TM)  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ 
  - ▶  $Q$ : Finite set with the control states
  - ▶  $\Sigma$ : Finite set of the input symbols
  - ▶  $\Gamma$ : Finite set of symbols in the tape
  - ▶  $\delta$ : Transition function  $\delta(q, X) = (p, Y, D)$ 
    - ▶  $q$  is a state,  $X$  is a symbol in the tape
    - ▶  $p$  is the next state (in  $Q$ );
    - ▶  $Y$  is a symbol in  $\Gamma$  which substitutes  $X$ ;
    - ▶  $D$  is L or R, left or right ( $\leftarrow$  or  $\rightarrow$ ), direction in the movement of the head after the substitution of the symbol in the tape
  - ▶  $q_0$ : initial state
  - ▶  $B$ : blank, a symbol to represent the blank symbol and the tape is fully filled (excepting the cells with the input string) with this symbol
  - ▶  $F$ : Set of final or accept states,  $F \subseteq Q$



# Computations

- ▶ Instantaneous descriptions
  - ▶  $X_1X_2\dots X_{i-1}qX_iX_{i+1}\dots X_n$
  - ▶ Cells from the first non-blank to the last non-blank (finite number)
    - ▶ With blank suffixes and prefixes depending where the head is
  - ▶ The state ( $q$ ) and the cell ( $i$ ) where the head is
- ▶ Step of the Turing Machine  $M$  (  $\vdash^*_M$ ;  $\vdash^*_M - 0$  or more steps)
  - ▶ Supposing  $\delta(q, X_i) = (p, Y, L)$
  - ▶  $X_1X_2\dots X_{i-1}qX_iX_{i+1}\dots X_n \vdash^*_M X_1X_2\dots X_{i-2}pX_{i-1}YX_{i+1}\dots X_n$ 
    - ▶ Transition from  $q$  to  $p$ ;  $X_i$  cell is changed to  $Y$ ; head moves left
    - ▶ If  $i=1$ :  $qX_1X_2\dots X_n \vdash^*_M pBYX_2\dots X_n$
    - ▶ If  $i=n$  and  $Y=B$ :  $X_1X_2\dots X_{n-1}qX_n \vdash^*_M X_1X_2\dots X_{n-2}pX_{n-1}$
    - ▶ Symmetric for  $\delta(q, X_i) = (p, Y, R)$

# Example $0^n1^n$

▶ TM to accept the language  $\{0^n1^n \mid n \geq 1\}$

▶ Idea

- ▶ In the beginning the tape contains the input string (0s and 1s)
- ▶ Change the first 0 to X; move to right until the first 1 and change it to Y; move to left until the first X; move o right; repeat
- ▶ If in a state there is a symbol in the tape not expected the TM dies
  - ▶ If the input is not  $0^n1^n$
- ▶ If in the iteration that marks the last 0 it also marks the last 1 then it accepts

# Example $0^n1^n$

| State | 0             | 1             | X             | Y             | B             |
|-------|---------------|---------------|---------------|---------------|---------------|
| $q_0$ | $(q_1, X, R)$ |               |               | $(q_3, Y, R)$ |               |
| $q_1$ | $(q_1, 0, R)$ | $(q_2, Y, L)$ |               | $(q_1, Y, R)$ |               |
| $q_2$ | $(q_2, 0, L)$ |               | $(q_0, X, R)$ | $(q_2, Y, L)$ |               |
| $q_3$ |               |               |               | $(q_3, Y, R)$ | $(q_4, B, R)$ |
| $q_4$ |               |               |               |               |               |

- $M = (\{q_0, q_1, q_2, q_3, q_4\}, \{0, 1\}, \{0, 1, X, Y, B\}, \delta, q_0, B, \{q_4\})$ 
  - $q_0$ : changes 0 to X
  - $q_1$ : moves to right until the first 1 and it is changed to Y
  - $q_2$ : moves to the left until it finds an X and goes to  $q_0$
  - If it has a 0 reinitiates the loop; if it has a Y goes to right; if it finds a blank goes to  $q_4$  and accepts; otherwise dies without accepting

# Computations for the Previous Example

## ► Input 0011

► Initial instantaneous description:  $q_00011$

►  $q_00011 \vdash Xq_1011 \vdash X0q_111 \vdash Xq_20Y1 \vdash q_2X0Y1 \vdash$

►  $Xq_00Y1 \vdash XXq_1Y1 \vdash XXYq_11 \vdash XXq_2YY \vdash Xq_2XYY \vdash$

►  $XXq_0YY \vdash XXYq_3Y \vdash XXYq_3B \vdash XXYq_4B$

► accepts

## ► Input 0010

►  $q_00010 \vdash Xq_1010 \vdash X0q_110 \vdash Xq_20Y0 \vdash q_2X0Y0 \vdash$

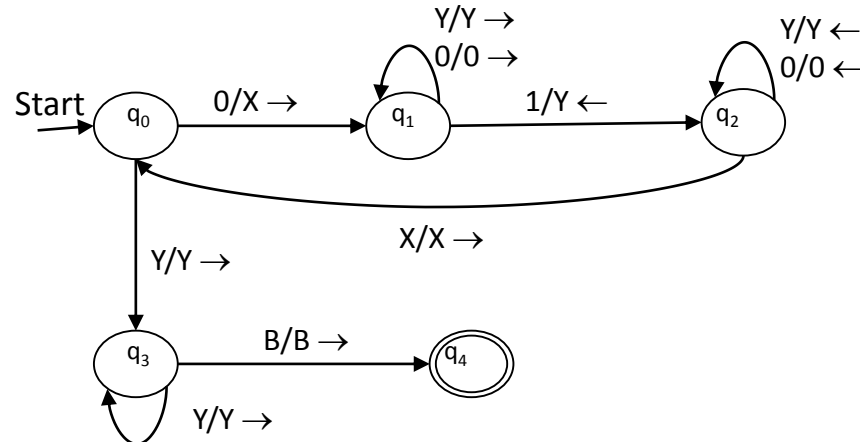
►  $Xq_00Y0 \vdash XXq_1Y0 \vdash XXYq_10 \vdash XXY0q_1B$

► dies

# Transition Diagram

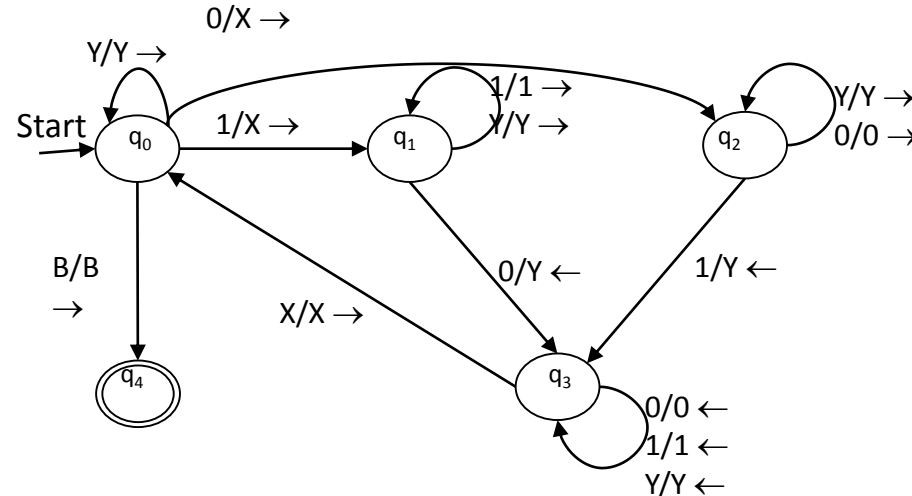
## ► Similar to PDA

- Nodes are TM states
- Edge from q state to p state with label  $X/YD$ 
  - $\delta(q,X) = (p,Y,D)$ , X and Y are symbols in the tape and D is L or R ( $\leftarrow$  or  $\rightarrow$ )
- “Start” arrow indicates the initial state; double circle represents final states; B, blank



# Example

- Transition diagram for a TM which accepts the language of the strings with equal number of 0s and 1s



- $q_0 0110 \vdash x q_2 110 \vdash q_3 XY10 \vdash x q_0 Y10 \vdash xy q_0 10 \vdash xyx q_1 0 \vdash xy q_3 XY \vdash xyx q_0 Y \vdash xyxy q_0 B \vdash xyxy B q_4 B$
- $q_0 110 \vdash x q_1 10 \vdash x1 q_1 0 \vdash x q_3 1Y \vdash q_3 X1Y \vdash x q_0 1Y \vdash xx q_1 Y \vdash xxy q_1 B$

# Example (cont.)

- ▶ Basic idea of the behavior of the MT
  - ▶ Identify in the tape 0-1 or 1-0 pairs, marking with X the first element and with Y the second element, until cannot find another pair (the case where the TM dies) or find blank (the case where the TM accepts)
- ▶ Meaning of the states
  - ▶  $q_0$ : goes to right until it finds the first element of the next pair; if it finds a blank goes to accept state
  - ▶  $q_1$ : found 1; goes to right until it finds a 0 or dies if it finds a blank;
  - ▶  $q_2$ : found 0; goes to right until it finds a 1 or dies if it finds a blank;
  - ▶  $q_3$ : found the second element of a pair; goes back to the left until it finds the rightmost X, case in which it transits to  $q_0$ ;
  - ▶  $q_4$ : accept.

# Exercise 1

- ▶ Design a Turing Machine able to convert an input binary number to its two's complement representation. In case of overflow, i.e., if the operation produces a number with more bits than the ones in the input number, that extra bit is ignored, maintaining the same number of bits.
  - ▶ Describe the meaning of each state.
  - ▶ Show the Computing trace when the input is 100.

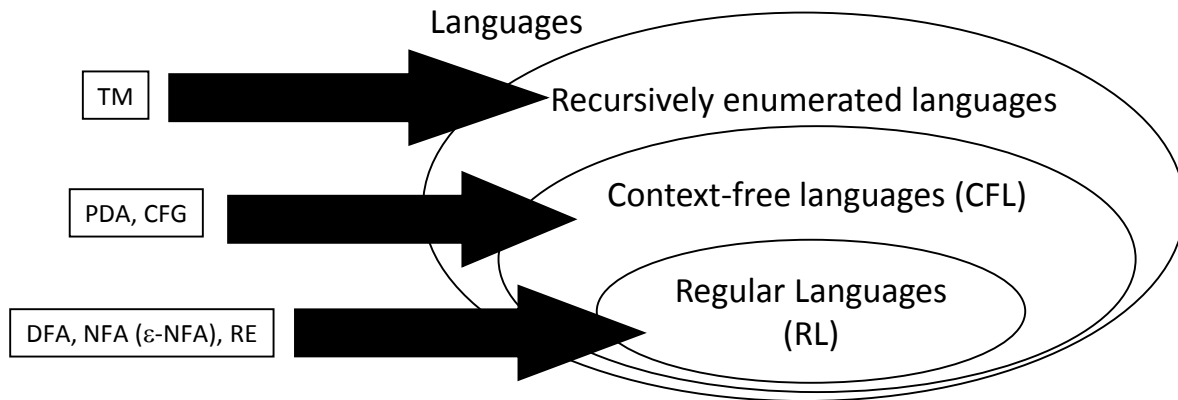


## Exercise 2

- ▶ Design a Turing Machine able to decrement by 1 an input binary number.
  - ▶ What are the strings accepted by the machine?
  - ▶ Where is the head of the machine in the end of the processing?
  - ▶ Show the sequence of instantaneous descriptions of the machine when it processes the input 100.

# Language of a TM

- ▶ Input string placed in the tape
  - ▶ Head of the machine in the leftmost symbol of the input
- ▶ If the machine stops in an accept states, the input string is accepted
- ▶ Language of the TM  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ 
  - ▶ Set of strings  $w$  in  $\Sigma^*$  such that  $q_0w \vdash^* \alpha p \beta$  and  $p \in F$
  - ▶ Recursively Enumerated Languages (Turing-recognizable)



# Stop

- ▶ A TM stops if it enters in a state  $q$ , reads a symbol  $X$  and  $\delta(q,X)$  is not defined
  - ▶ It allows to approach a TM as executing a computation with start and end
    - ▶ example: calculate the sum of two integers
  - ▶ TMs that always stop, accepting or not the input, constitute models of algorithms (recursive languages)
- ▶ We can assume that a TM always stops when accepts
- ▶ Unfortunately it is not always possible to enforce that a TM stops when it does not accept (the halting problem)
  - ▶ Undecidability (recursively enumerated languages)
  - ▶ Possibility of a TM to refer to itself (it can be undecidable)

# Techniques to program a TM

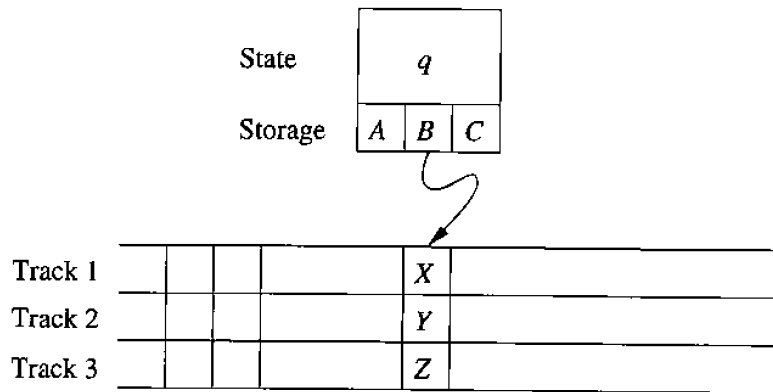
- ▶ A TM is as powerful as any actual computer (but too slow)
- ▶ Memory in the state
  - ▶ State = control + data memory
  - ▶ See the state as a tuple
- ▶ Additional symbols used in the tape can make easier the programming of the TM

# Techniques to program a TM: subroutines

- ▶ A TM is a set of states which executes a process
  - ▶ It as an input and final states
- ▶ Seen as a subroutine of a major TM
  - ▶ Call goes to initial state
  - ▶ There is not notion of a return address
    - ▶ Return is done by using a state
  - ▶ If a subroutine is called from various distinct states we copy it (like a macro) to return to the states where was called

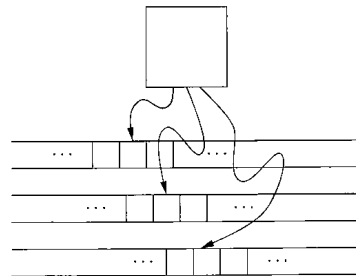
# Extensions to TMs

- ▶ Multiple tracks in a tape
  - ▶ A tape consists now by a finite number of tracks: a symbol in each track
  - ▶ Alphabet in tape consists of a tuple
- ▶ TM power is not changed



# Extensions

- ▶ TM with various tapes
  - ▶ Each one has a head
  - ▶ Input string only in the first tape
  - ▶ Movement: left, right, stationary
  - ▶ Equivalent to one tape
    - ▶ Quadratic temporal complexity
- ▶ Non-Deterministic TMs
  - ▶ Transition function give set of tuples  $(q, Y, D)$
  - ▶ Equivalent to deterministic
    - ▶ Place in the tape a queue with the instantaneous descriptions to be processed
    - ▶ Simulate the non-determinism traversing them by breath first order
- ▶ They do not empower in terms of language recognition



# Restrictions

## ▶ Machines with several stacks

### ▶ A PDA with two stacks is equivalent to a Turing Machine

- ▶ In the first stack we store what is in the left of the head of the TM
- ▶ In the second stack we store what is on the right of the TM (the top contains the current symbol read by the head)
- ▶ In the controller we simulate the control of the TM
- ▶ Movement of the head of the TM is to do a pop in a stack and a push in the other



# Restrictions (cont.)

## ▶ Machines with counters

- ▶ The same structure of a machine with multiples stacks
- ▶ Each stack is a counter
  - ▶ Contains a non-negative integer (number of X in stack)
  - ▶ We only distinguish if the counter is 0 or different of 0
- ▶ Movement depends
  - ▶ State
  - ▶ Input symbol
  - ▶ Each one of the counters is 0
- ▶ In the movement
  - ▶ Change state (or stay in the same)
  - ▶ Adds or subtracts 1 to each counter independently

# Power of the machines with counters

- ▶ Theorem: the machines with 3 counters are equivalent to the TM, i.e., they accept the recursively enumerated languages
- ▶ A counter simulates a stack
  - ▶ A stack  $X_1X_2...X_n$  in an alphabet with  $r-1$  symbols can be seen as a number in base  $r$   $X_n r^{n-1} + X_{n-1} r^{n-2} + ... + X_2 r + X_1$
  - ▶ Pop is to divide by  $r$  and remove the remainder ( $X_1$ )
- ▶ Two counters for 2 stacks ( $\equiv$  TM) and another one for the multiplication and division operations
- ▶ Theorem: the machines with 2 counters are equivalent to the TM
  - ▶ Code the 3 counters  $i, j, k$  in a counter  $2^i 3^j 5^k$  (2,3,5 are primes)
  - ▶ Second counter for operations

# TMs and computers

- ▶ A Computer is able to simulate a TM
  - ▶ The number of states and transitions is finite: states represented by strings and table of transitions
  - ▶ Number of symbols in the tape is finite: strings of fixed length
  - ▶ Tape infinite!
    - ▶ If the memory of the Computer is finite, this is a finite automaton
      - ▶ Only regular languages!
    - ▶ Assuming the capability to change disks: it is reasonable to consider infinite memory
      - ▶ Stack of disks in the left and in the right of the tape: disk in use according to the position of the head
      - ▶ Recursively enumerable language

# TMs and Computers (cont.)

- ▶ Simulate a Computer with a TM
  - ▶ memory: long sequence with words with an address
  - ▶ Program stored in memory
    - ▶ Simple instructions, assembly
    - ▶ Consider indirect addressing
  - ▶ Each instruction uses a limited number of words and changes one word at the maximum
  - ▶ Registers of the Computer considered as more memory
- ▶ TM with multiple tapes simulates a computer ( $\equiv$  TM with 1 tape)
  - ▶ Memory (address-value pairs) + Instruction counter + memory address + Input file + area of temporaries
  - ▶ Simulate the instruction cycle; copy, sum, jump, ...

The multi-tape TM simulates  $n$  steps of a Computer in  $O(n^3)$  of its own steps; and a TM simulates  $n$  steps of a Computer in  $O(n^6)$  TM steps [See Hopcroft book]

# Summary

- ▶ The TM is a valid representation of what a Computer can compute
- ▶ It is realistic to consider the TM as equivalent to a Computer
  - ▶ Relation between execution times is polynomial
  - ▶ The division between tractable and intractable problems is between the polynomial and greater than polynomial complexity
  - ▶ It allows to study the efficiency of the algorithms in the TM and not only the decidability