# GPU Programming I

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### Portable models: SYCL

- Open standard for accelerator programming
  - Royalty-free, vendor-agnostic, high-level
- Single-source model based on C++17
  - Requires compiler support and C++ knowledge
  - Content warning: lambda functions, templates, exceptions
- Interoperability with native features (at the expense of portability)

### Standard vs. implementation

SYCL itself is only a *standard*, with several open-source *implementations*:

- Intel oneAPI DPC++ (a.k.a. Intel LLVM)
  - Supports Intel GPUs natively, and NVIDIA and AMD GPUs with Codeplay oneAPI plugins
  - Also CPUs and FPGAs
- AdaptiveCpp (a.k.a. hipSYCL, Open SYCL): supports AMD, Intel, NVIDIA GPUs
  - Also CPUs
  - MooreThreads support contributed
- ComputeCPP, triSYCL, motorSYCL, SYCLops, Sylkan, ...

### Typical GPU application

- 1. Select/initialize the device
- 2. Allocate memory on the device
- 3. Copy input data from host to device
- 4. Launch kernel on the device
- 5. Copy output from device to host
- 6. Free allocated memory

Error checking: in SYCL, exceptions are thrown

### sycl::queue

- A way to submit tasks (kernels, memory copies) to be executed on the device
- Can also be used as a handle for memory management
- Tasks are launched asynchronously!

```
#include <sycl/sycl.hpp>
int main() {
   // Create an out-of-order queue on the default device sycl::queue q;
   // Now we can submit tasks to q!
}
```

### **Initialization**

- Queue is associated with a device
- There can be multiple queues, on one or multiple devices
- Queues can have properties

### Getting started on Dardel (lazy)

Found device: AMD MI250X

```
$ ssh abcd@dardel.pdc.kth.se
$ ml PDC/22.06 adaptivecpp/23.10.0-cpeGNU-22.06-rocm-5.3.3-llvm
 export SLURM_ACCOUNT=edu23.aqti SLURM_TIMELIMIT=00:05:00
 export SLURM_PARTITION=gpu SLURM_RESERVATION=XYZ
$ srun acpp-info -1
==============Backend information============
Loaded backend 0: OpenMP
  Found device: hipSYCL OpenMP host device
Loaded backend 1: HTP
  Found device: AMD MI/150X
  Found device: AMD MI250X
  Found device: AMD MI250X
```

### Getting started on Dardel (explicit)

```
$ ssh abcd@dardel.pdc.kth.se
$ ml PDC/22.06 adaptivecpp/23.10.0-cpeGNU-22.06-rocm-5.3.3-llvm
 srun -Aedu23.aqti -t 1:00 -pgpu --reservation X acpp-info -l
===========Backend information===============
Loaded backend 0: OpenMP
  Found device: hipSYCL OpenMP host device
Loaded backend 1: HTP
  Found device: AMD MI250X
 Found device: AMD MI250X
  Found device: AMD MI250X
  Found device: AMD MI250X
```

# Getting started on TCBLab (interactive mode)

```
$ ssh-copy-id wsXX@login.tcblab.org # Password: Aq2023$MudCow
$ ssh wsXX@login.tcblab.org
$ salloc
salloc: Nodes gouyy are ready for job
$ ssh gpuYY
$ module load adaptivecpp/23.10.0-clang16-cuda12.1
$ acpp-info -1
==============Backend information=============
Loaded backend 0: CUDA
 Found device: NVIDIA RTX A5000
Loaded backend 1: OpenMP
 Found device: hipSYCL OpenMP host device
```

### list\_devices.cpp

```
#include <iostream>
#include <sycl/sycl.hpp>
int main() {
  std::vector<sycl::device> all_gpus =
      sycl::device::get_devices(sycl::info::device_type::gpu);
  for (const auto &device : all_gpus) {
    std::cout << "Found device " << device.get_info<sycl::info::device::name>() << "\n";</pre>
    std::cout << " It has "
              << device.get_info<sycl::info::device::global_mem_size>() / 1024 / 1024
              << " MiB of memory\n";
    // Now we can create a queue and submit tasks to the device
    // sycl::queue q(device, {sycl::property::queue::in_order()});
  return 0;
```

### Exercise: build and run list\_devices (TCBLab)

```
$ cp /mnt/cephfs/home/aqtivate-ws/* ./
$ acpp -03 list_devices.cpp -o list_devices
$ ./list_devices
Found device NVIDIA RTX A5000
    It has 24247 MiB of memory
```

### Exercise: build and run list\_devices (Dardel)

```
$ cp /cfs/klemming/home/a/andreyal/Public/* ./
$ acpp -03 list_devices.cpp -o list_devices
$ srun ./list devices
Found device
   It has 65520 MiB of memory
Found device
   It has 65520 MiB of memory
```

### Typical GPU application

- Select/initialize the device ✓
- 2. Allocate memory on the device
- 3. Copy input data from host to device
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### Programming paradigms

#### **USM**

- Raw pointers.
- Manual data movement, allocation, synchronization.
- Works best with in-order queues.
- Ideal for translating CUDA/HIP code.
- Three kinds: device, host, shared.
- More control of the execution.

#### **Buffer-accessor**

- Define data-dependency graph through data access.
- Automatic data movement, resource allocation, synchronization.
- Works best with out-of-order queues.
- Allows more optimizations by the runtime.
  - Currently, runtimes are not stellar.

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### Allocate and copy memory (USM)

```
sycl::queue q{{sycl::property::queue::in_order()}};
int n = //...
int* arr_host = //...

// Allocate `n` integers on a device associated with `q`
int* arr_device = sycl::malloc_device<int>(n, q);

// Copy data from `arr_host` to `arr_device`
q.copy<int>(arr_host, arr_device, n);
```

### Allocate and copy memory (USM)

```
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int n = //...
int* arr_host = //...
// Allocate `n` integers on a device associated with `g`
int* arr_device = sycl::malloc_device<int>(n, q);
// Copy data from `arr_host` to `arr_device`
q.copy<int>(arr_host, arr_device, n);
// Copy is not done yet!
q.wait(); // Wait for all operations to finish
// Tidy up: free memory when it's no longer needed
sycl::free(arr_device, q);
```

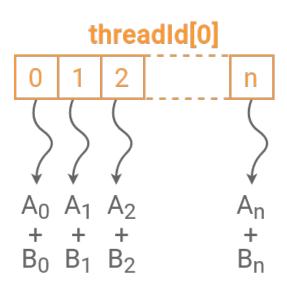
### Typical GPU application

- Select/initialize the device ✓
- Allocate memory on the device ✓
- 3. Copy input data from host to device ✓
- 4. Launch kernel on the device
- 5. Copy output from device to host ✓
- 6. Free allocated memory ✓

### Launching kernels

```
sycl::range<1> global_size(n);

q.submit([&](sycl::handler &h) {
    h.parallel_for<class VectorAdd>(global_size,
       [=](sycl::item<1> threadId) {
       int tid = threadId[0];
       Cd[tid] = Ad[tid] + Bd[tid];
    }
    );
});
```



### Getting it all together: Vector addition

```
sycl::queue q{{sycl::property::queue::in_order()}};
float *Ad = sycl::malloc_device<float>(N, q); // Allocate the arrays on GPU
q.copy<float>(Ah.data(), Ad, N); // Copy the input data from host to the device
sycl::range<1> global_size(N); // Define grid dimensions
// Run our kernel
q.submit([&](sycl::handler &h) {
 h.parallel_for<class VectorAdd>(global_size, [=](sycl::item<1> threadId) {
    int tid = threadId[0]; // Get thread index
   Cd[tid] = Ad[tid] + Bd[tid]; // Do the math
 });
});
q.copy<float>(Cd, Ch.data(), N); // Copy results back to the host
// All the operations before were asynchronous!
q.wait(); // Wait for the copy to finish
sycl::free(Ad, q); // Free the GPU memory
// Work with Ch
```

### Exercise: run vector addition (USM)

### Look at the source code. Try modifying it:

- Compute vector subtraction
- Compute rolling sum: C[i] = A[i-1] + A[i] + A[i+1]

# Programming paradigms: USM (device/host)

```
sycl::queue q{{sycl::property::queue::in_order()}};
// Create a device allocation of n integers
int* v = sycl::malloc_device<int>(n, q);
// Submit a kernel into a queue; cgh is a helper object
q.submit([&](sycl::handler &cgh) {
  // Define a kernel: n threads execute the following lambda
  cgh.parallel_for<class Kernel>(sycl::range<1>{n}, [=](sycl::item<1> i) {
    // The data is directly written to v
   v[i] = /*...*/
// If we want to access v, we should copy it to CPU
q.copy<int>(v, v_host, n).wait(); // and wait for it!
// After we're done, the memory must be deallocated
sycl::free(v, q);
```

# Programming paradigms: USM (shared)

```
sycl::queue q{{sycl::property::queue::in_order()}};
// Create a shared (migratable) allocation of n integers
int* v = sycl::malloc_shared<int>(n, q);
// Submit a kernel into a queue; cgh is a helper object
q.submit([&](sycl::handler &cgh) {
  // Define a kernel: n threads execute the following lambda
  cgh.parallel_for<class Kernel>(sycl::range<1>{n}, [=](sycl::item<1> i) {
    // The data is directly written to v
   v[i] = /*...*/
 });
// If we want to access v, we have to ensure that the kernel has finished
q.wait();
// After we're done, the memory must be deallocated
sycl::free(v, q);
```

### Programming paradigms: Buffer-accessor

```
sycl::queue q; // out-of-order by default
// Create a buffer of n integers
auto buf = sycl::buffer<int>(sycl::range<1>(n));
// Submit a kernel into a queue; cgh is a helper object
q.submit([&](sycl::handler &cgh) {
  // Create write-only accessor for buf
  auto acc = buf.get_access<sycl::access_mode::write>(cgh);
  // Define a kernel: n threads execute the following lambda
 cgh.parallel_for<class Kernel>(sycl::range<1>{n}, [=](sycl::item<1> i) {
    // The data is written to the buffer via acc
   acc[i] = /*...*/
/* If we now submit another kernel with accessor to buf, it will not
 * start running until the kernel above is done */
```

### Exercise: run vector addition (buffers)

Look at the source code. Try modifying it:

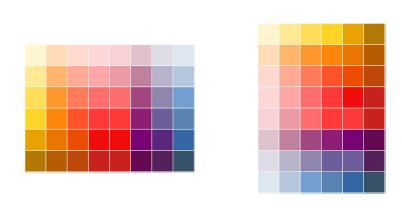
- Get rid of an extra buffer and store the result in A: A[i] = A[i] + B[i]
  - o Use sycl::access\_mode::read

# Exercise: Try Intel oneAPI compiler (only on TCBLab)

```
$ module unload adaptivecpp
$ module load intel-oneapi/2023.2.1 cuda/12.1
$ clang++ -fsycl -fsycl-targets=nvidia_gpu_sm_86 \
            vector_add.cpp -o vector_add
S ./vector add
Running on NVIDIA RTX A5000
A = \{ 0 \ 1.93538 \ \dots \ 2.28384 \ 1.463 \}
B = \{ 1.1 \ 0.594333 \ \dots \ 0.130176 \ -0.848779 \ \}
A + B (GPU) = \{ 1.1 \ 2.52972 \ ... \ 2.41401 \ 0.614221 \}
Total error: 0
```

### Exercise: Matrix transpose

- Build and run transpose\_matrix\_v0.cpp
- For now, it just copies the matrix
- Look at the source code
  - Many new constructs there! More on them tomorrow
- Modify the code to transpose the matrix



 $M \times N$ 

 $N \times M$