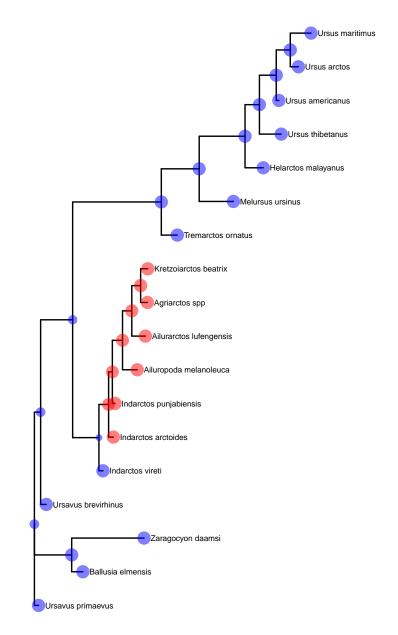
## mk\_simple.char\_45.ase



## State

- Absent
- Present

## Posterior Probability

- 0.7
- 0.8
- 0.9
- 1.0