

| ID | Activity | Description | Deliverables | Duration (Days) | People | Resources | Predecessors |
|-------|--|---|---|-----------------|----------------------------------|--|--------------|
| 1 | Power Design | | | | | | |
| 1.1 | Component Selection | Selection of initial components to be used to develop various systems | Develop fully itemized budget of parts | 1 | All | | |
| 1.2 | Detachable Housing | Allow for the entire apparatus to easily attach and detach to a cane | Housing can attaches and detaches in an easy fashion | 4 | Arthur Helmen, Matthew Giuffrida | Collapsible cane, pvc pipe | 1.1 |
| 1.3 | Adjustable Clamp | Allow for apparatus to attach to canes of various diameters and lengths | Clamp should be able to attach to various cane diameters with ease | 2 | Arthur Helmen, Matthew Giuffrida | Pipe bracket, finished housing, collapsible cane | 1.1 |
| 2 | Software Design | | | | | | |
| 2.1 | Outdoor Navigation | | | | | | |
| 2.1.1 | Utilize GPS Information | Gather GPS information through either GPS module or IOS application | GPS info should be available and easily interpreted | 3 | Baltazar Guerra | GPS Module, Raspberry Pi | |
| 2.1.2 | Identify Campus Buildings | Utilize AggieMap or Google Maps to identify each campus building | Buildings should be able to be identified with their GPS locations | 5 | Baltazar Guerra | GPS Module, Raspberry Pi | 2.1.1 |
| 2.1.3 | Establish routes | Establish points along said map to guide users along set paths on campus | Points must be established to guide user to from a given building to another building along routes that currently exist on campus | 7 | Baltazar Guerra | GPS Module, Raspberry Pi | 2.1.2 |
| 2.1.4 | Provide Feedback | Trigger feedback systems that aid in the process of guiding the user | User should receive their choice of audio and haptic feedback at the appropriate times | 3 | Arthur Helmen, Matthew Giuffrida | RPi, ultrasonic sensors, vibrations motors | 2.1.3 |
| 2.2 | In-building Navigation | | | | | | |
| 2.2.1 | Determine room orientation | Determine direction and orientation in respect to key points in buildings | Users should be able to determine direction relative to how they entered and exited the building | 7 | Jonathan Williams | RPi, GPS Module | |
| 2.2.2 | Establish routes | Allow users to set destinations and guide them along paths that they have previously traveled along | Users should be able to traverse 'bread crumb' trail that they have set to guide them back along the same path | 8 | Jonathan Williams | RPi, Xcode | 2.2.1 |
| 2.2.3 | Provide Feedback | Trigger feedback systems that aid in the process of guiding the user | User should receive their choice of audio and haptic feedback at the appropriate times | 3 | Arthur Helmen | iphone app accelerometer functionality, vibration motors | 2.2.2 |
| 2.3 | IOS Application | | | | | | |
| 2.3.1 | Establish connection with RPi | Allow the communication of data through a bluetooth connection between IOS device and RPi | IOS device and RPi can share basic information | 4 | Shawn Popal, Baltazar Guerra | Xcode | |
| 2.3.2 | Collect and send GPS data | Send GPS information gathered by IOS device to the RPi | IOS device can gather GPS information and deliver it to the RPi | 8 | Shawn Popal, Baltazar Guerra | Xcode | 2.3.1 |
| 2.3.3 | Trigger feedback from navigation systems | Interpret information gathered and trigger the appropriate feedback systems | GPS location is interpreted and feedback systems are triggered accordingly | 4 | Shawn Popal | Xcode | 2.3.2 |
| 2.4 | Obstacle Detection | | | | | | |
| 2.4.1 | Determine distance from objects | Through the use of OpenCV, gather distance information from cameras and determine distances to detected objects | Gather and interpret information from OpenCV software | 2 | Jonathan Williams | Cameras, RPi | |

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|-------|---------------------------------|---|---|---|----------------------------------|----------------------|-------|
| 2.4.2 | Evaluate distance thresholds | Compare gathered values to set thresholds | Compare interpreted information against preset values | 1 | Arthur Helmen, Matthew Giuffrida | Sensor/motor network | 2.4.1 |
| 2.4.3 | Provide feedback when necessary | Trigger feedback systems if threshold limits are met | Trigger feedback systems at the appropriate times | 3 | Arthur Helmen, Matthew Giuffrida | sensor/motor network | 2.4.2 |
| 3 | Power Design | | | | | | |
| 3.1 | Power delivery | Provide power to the RPI through the use of a battery | RPI should be powered when toggled so | 1 | Matthew Giuffrida, Arthur Helmen | Battery Pack, wires | |
| 3.2 | Rechargeable system | Allow the battery to be conveniently recharged | Battery is rechargeable and easy to do | 1 | Matthew Giuffrida, Arthur Helmen | Wires, wall plug | 3.1 |