

Software Design:

- Controller
- Data Source

Haptics

- Left - L
- Right - R
- Object - L

Data Source:

- Accelerometer
- Gyroscope
- GPS/Location

Hardware:

- Set up casing
- Component testing

Controllers:

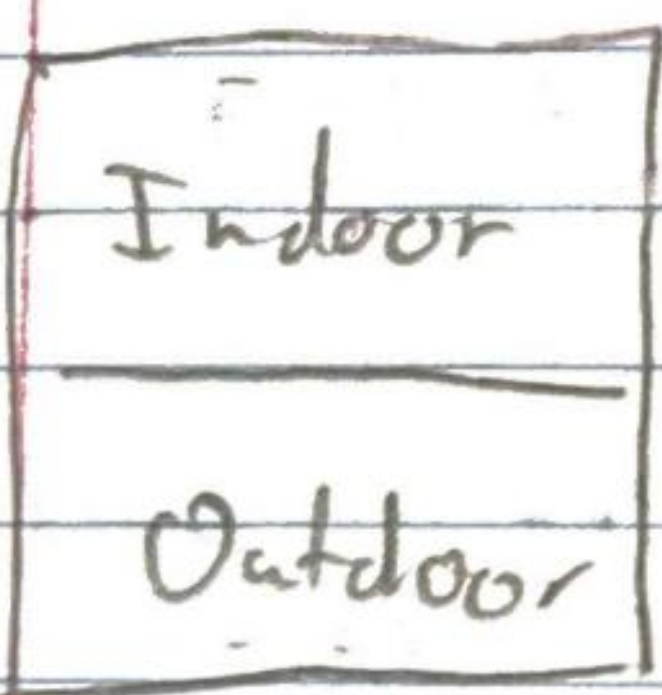
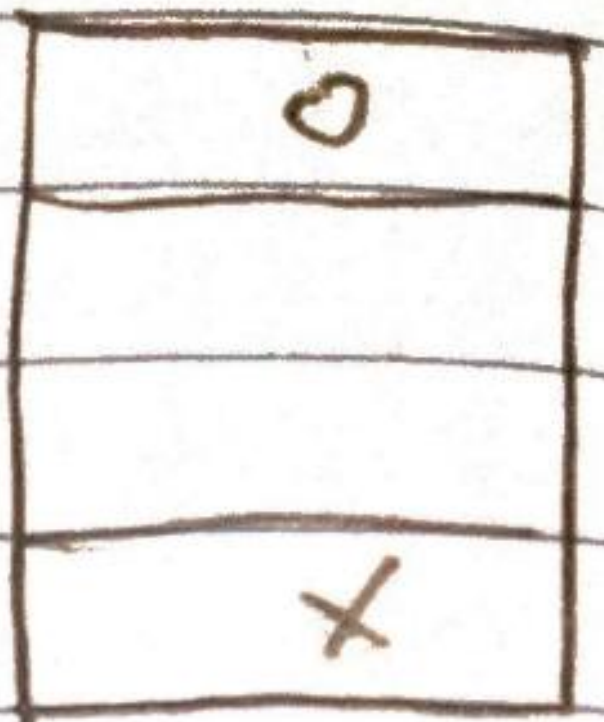
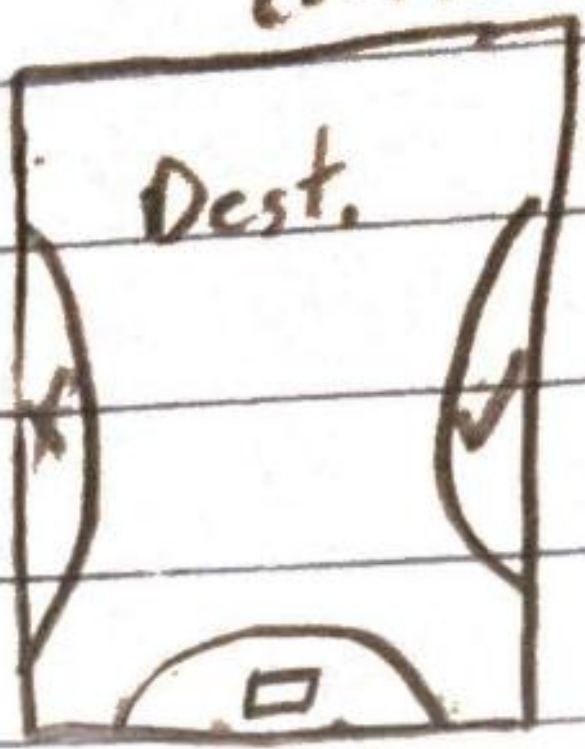
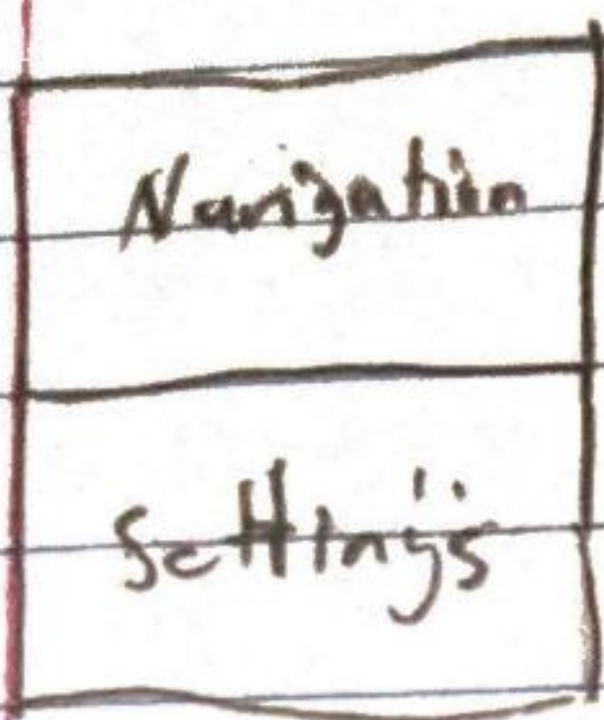
- Feedback type
- Thresholds
- Destination
- Misc. Setting

Start:

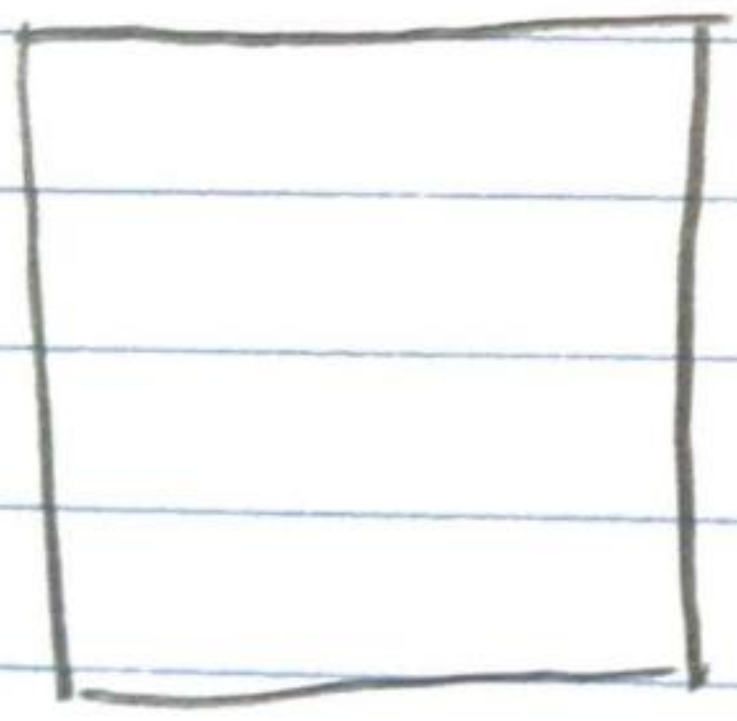
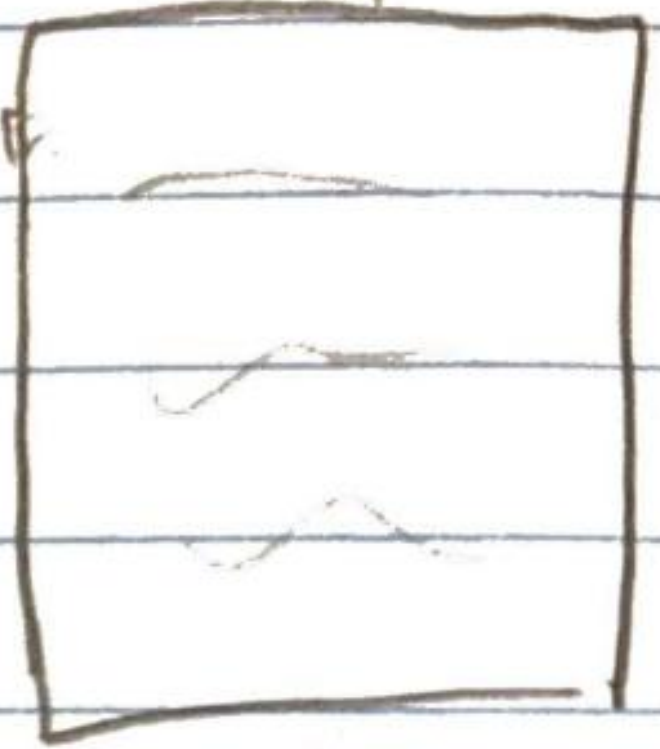
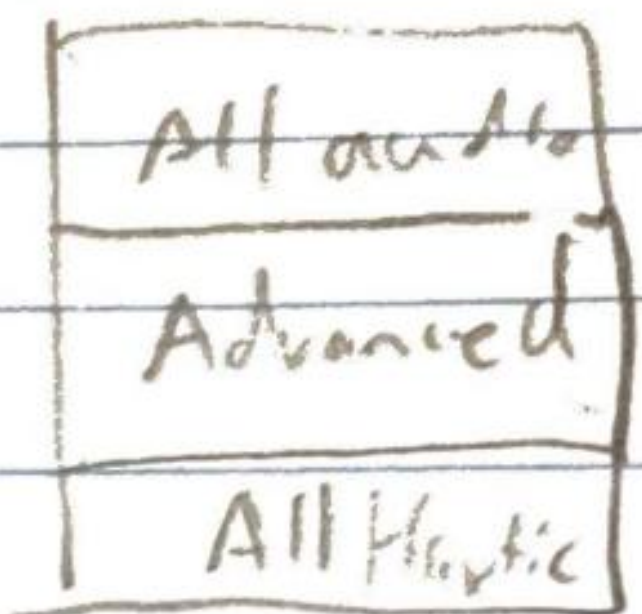
Navi settings:

In Navi

Swipe to continue/next



Feedback:



Start Dtd.

curr. loc.

Cancel now

Distance/Time to dest

Components:

ultrasonic: 5 ft

Battery: 12 hours

Camera: ✓

