





# M2CAL WORKFLOW CHALLENGE 2016 Fine tuning CNN with HMM smoothing

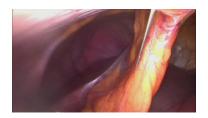
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Context





Videos resolution is  $1920 \times 1080$ , shot at 25 frames per second at the IRCAD research center in Strasbourg, France.

- 27 training videos ranging from 15mn to 1hour
- 15 test videos

Context



#### 1 of 8 classes for each frames:

- TrocarPlacement
- Preparation
- CalotTriangleDissection
- ClippingCutting
- GallbladderDissection
- GallbladderPackaging
- CleaningCoagulation
- GallbladderRetraction

#### M2CAI Workflow Goal and Measure



#### Goal

Online prediction :  $P(y|x_i, x_{i-1}, x_{i-2}, ...)$  $x_i := \text{frame } i, \text{ and } y := \text{classes}$ 

#### Useful to

- Monitor surgeons
- Trigger automatic actions

### Measures

- Jaccard similarity coefficient :  $J(A, B) = \frac{|A \cap B|}{|A \cup B|} = \frac{|A \cap B|}{|A| + |B| |A \cap B|}$
- Accuracy top1 : nb frames well classified / nb total frames

Context



## 1. Frames classifier using Deep Learning

- From Scratch Convolutional Neural Network (CNN)
- Features Extraction CNN
- Fine tuning CNN

## 2. Smoothing predictions

- 1 Averaging predictions over last 15 frames
- 2 Hidden Markov Model (HMM) as a "denoizer"

### Creating a trainset and valset of images



# Creating validation set by random split

■ Training set: 22 videos

■ Validation set : 5 videos {2, 9, 10, 13, 27}

### Extracting one frame every 25 frames (1 frame per second)

■ Training set: 59,493 images

■ Validation set: 8,062 images

■ Testing set: 28,732 images



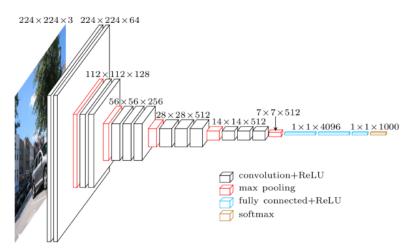
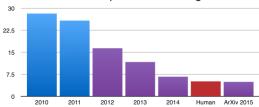


Figure 1: Vgg16 [Simonyan et Zisserman 2014], top2 ILSVRC2014



#### ILSVRC top-5 error on ImageNet

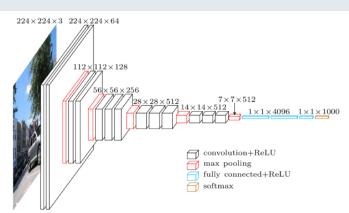


## Using representations learned on ImageNet



#### Pre-trained CNN as Features Extractor

- 1 Extracting features somewhere
- 2 Training a Support Vector Machine

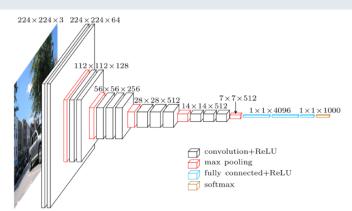


### Adapting representations learned on Imagenet



#### Fine tuning a pre-trained CNN

- Same process than CNN From Scratch
- But smaller learning rate for pre-trained layers



# Which CNN to use? Possible in production?



Model	Input	Param.	Depth	Implem.	Time (ms)
Vgg16	224	138M	16	GPU	
InceptionV3	399	24M	42	GPU	0
ResNet-200	224		200	GPU	
InceptionV3	399	24M	42	CPU	0

Table 1: Forward+Backward with batches of 30 images.



Model	Туре	Accuracy (%)
InceptionV3	Extraction (repres. of ImageNet)	60.53
InceptionV3	From Scratch (repres. of M2CAI)	69.13
InceptionV3	Fine-tuning (both representations)	79.06
ResNet200	Fine-tuning (both representations)	79.24

Table 2: Accuracy on the validation set.

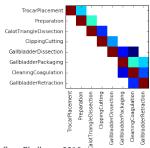
#### Gaussian Hidden Markov Model

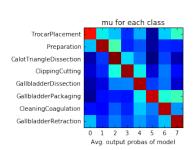


# HMM on the smoothed predictions over last 15 frames

- Initial state probabilities
- Matrix of probabilities of transition between states
- Gaussian parameters for emissions of observations :

  -> mean and co-variance matrix







# Training process

- Counting, Counting
- Counting

### Testing process

- Offline testing: Viterbi algorithm to obtain the most likely sequence of states
- Online testing : to predict  $x_t$  we apply Viterbi on the sequence  $y_1, ..., y_t$

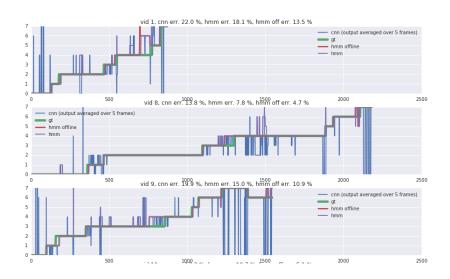


Temporal Method	Accuracy Val (%)	Jaccard Val	Jaccard Test
Avg Smoothing	85.97	74.67	-
Avg + HMM Online	88.90	81.60	71.9
Avg + HMM Offline	93.47	87.59	_

Table 3: With the predictions of our fine tuned ResNet-200

### Visualization





#### Visualization







### Conclusion

- Deep Learning efficient
- Fine Tuning most accurate approach
- HMM is usefull to smooth the predictions

#### Future work

- Fine tuning CNN on full trainset (not only 80%)
- Ensembling several fine tuned CNNs

Code available: github.com/Cadene/torchnet-m2caiworkflow

#### References I



Simonyan, Karen et Andrew Zisserman (2014). "Very deep convolutional networks for large-scale image recognition". In: ICLR.