

Smoothness

Intuition: If X is a k -variety then $X(k[\epsilon]/\epsilon^2)$ parametrizes a k -point $x \in X(k)$ and a "tangent" direction.

A'_k $\xrightarrow{\text{from}} \text{Affine line}$
 $\text{Spec } k[\epsilon]/\epsilon^2$ $\xrightarrow{\text{from}} \text{(infinitesimal affine) line}$

Given $x \in X(k)$ we obtain a

$$\begin{array}{ccc} T_x X & \rightarrow & * \\ \downarrow & & \downarrow \\ X(k[\epsilon]/\epsilon^2) & \rightarrow & X(k) \end{array}$$

Given a map of varieties
 $f: X \rightarrow Y$ we set

$$\begin{array}{ccc} df: T_x X & \rightarrow & T_{f(x)} Y \\ \uparrow & & \uparrow \\ X(k[\epsilon]/\epsilon^2) & \rightarrow & Y(k[\epsilon]/\epsilon^2) \end{array}$$

Definition A closed immersion $i: S_0 \rightarrow S$ of schemes is a first order thickening if the ideal sheaf $\mathcal{I} = \text{Ker}(\mathcal{O}_S \rightarrow i_* \mathcal{O}_{S_0})$ satisfies $\mathcal{I}^2 = 0$.

A first order thickening is split if there is $s: S \rightarrow S_0$ with $s \circ i = \text{Id}_{S_0}$.

Example $\text{Spec } k \rightarrow \text{Spec } k[\epsilon]/\epsilon^2 \rightarrow \text{Spec } k$
is split.

$\text{Spec } \mathbb{F}_p \hookrightarrow \text{Spec } \mathbb{Z}/p^2\mathbb{Z} \rightarrow \text{Spec } \mathbb{Z}$ is split.

Remark Given a quasicohent \mathcal{O}_{S_0} -module \mathcal{M} we can consider a f.o.t.

by letting $S = \text{Spec}(\mathcal{O}_{S_0} \oplus \mathcal{M})$

with ring structure given by

$$(f, m) \cdot (g, m') = (fg, fm' + gm).$$

All split f.o.t. arise in this way.

Definition Let $f: X \rightarrow Y$ be a map of schemes. Let $S_0 \rightarrow S$ be a f.o.t. of affine schemes.

Suppose we are given a commutative diagram $C =$

$$\begin{array}{ccc} S_0 & \xrightarrow{u_0} & X \\ \downarrow & \nearrow u & \downarrow f \\ S & \xrightarrow{\quad} & Y \end{array}$$

we let $\text{Lift}(C)$ denote the set of u making the diagram commutative.

- 1) f is formally smooth if for all such C $|\text{Lift}(C)| \geq 1$ (\exists)
- 2) f is formally étale if $|\text{Lift}(C)| = 1$ ($\exists!$)
- 3) f is unramified if $|\text{Lift}(C)| \leq 1$ ($!$)

Remark $\text{Lift}(c)$ can be computed
on the basechange

$$\begin{array}{ccccc}
 S_0 & \xrightarrow{\quad} & X^* S & \xrightarrow{\quad} & X \\
 \downarrow & \nearrow \dots & \downarrow & \lrcorner & \downarrow \\
 S & \xrightarrow{\quad} & S & \xrightarrow{\quad} & Y \\
 & \text{id} & & &
 \end{array}$$

in particular the properties are stable
under basechange.

Example: 1) open immersions are
formally étale.

2) closed immersions are formally
unramified.

3) $A_S^n \rightarrow S$ is formally smooth

If $S = \text{Spec } R$ $S_0 = \text{Spec } R_0$ and

$S_0 \rightarrow S$ is a f.o.t. the

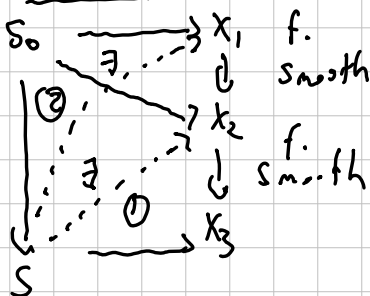
map $R[x_1 \dots x_n] \rightarrow R_0$ can be
lifted

since $R \rightarrow R_0$ is surjective.

Proposition Formally smooth, étale, unramified
Satisfy BC, COMP, LOCS, LOCT.

Remark 1) BC, COMP are easy

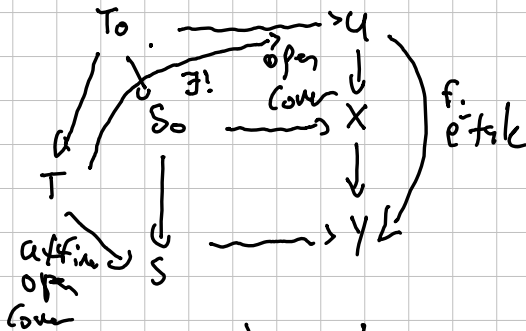
Example:



2) LOCS, LOCT for f. étale and
f. unramified are also easy.

key point: Uniqueness allows us
to glue.

Example:



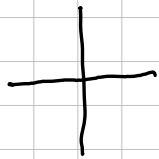
the map $T \rightarrow X$ glues by uniqueness.

Definition $f: X \rightarrow Y$ is

- 1) Smooth (resp. étale) if it is f -smooth (resp. f -étale) and finitely presented.
- 2) Unramified if it is f -unramified and of finite type.

Example $\text{Spec } k[t] \rightarrow \text{Spec } k$ is formally smooth, but it is not smooth (not finite type).

Example: Let $X = \text{Spec } k[t_1, t_2] / (t_1 t_2)$



is it smooth over $\text{Spec } k$?

$$C = \begin{array}{ccc} \text{Spec } k & \xrightarrow{x=0, y=0} & X \\ \downarrow & & \downarrow \\ \text{Spec } k[\varepsilon]/\varepsilon^2 & \rightarrow & \text{Spec } k \end{array}$$

$$\text{Lift}(c) \quad \begin{array}{l} t_1 \mapsto a_1 \varepsilon \\ t_2 \mapsto a_2 \varepsilon \end{array}$$

This suggests it might be smooth

We need all f.o.t.

$$\begin{array}{ccc} \text{Spec } k[x, y]/(x^2, xy, y^2) & \xrightarrow{u_0} & X \\ \downarrow \text{f.o.t.} & \searrow \text{---} & \downarrow \\ \text{Spec } k[x, y]/(x^3, x^2y, x^2y, y^3) & \xrightarrow{u} & \text{Spec } k \end{array}$$

$$u_0: \begin{array}{l} t_1 \mapsto x \\ t_2 \mapsto y \end{array}$$

$$u: \begin{array}{l} t_1 \mapsto x + p(x, y) \\ t_2 \mapsto y + q(x, y) \end{array}$$

p, q homogeneous of degree 2

$$\left. \begin{array}{l} \text{but} \\ u(t_1) \cdot u(t_2) \\ = xy \\ \neq 0. \end{array} \right\}$$

Differentials:

Intuition:

Given $x \in U \xrightarrow{\text{open}} X$ and $f \in \Gamma(U, \mathcal{O}_U)$
with $f(x) \neq 0$ we set a derivative

$$df_x : T_x \longrightarrow T_x / \mathcal{I}_x = k$$

A differential is an element

$df \in \text{Hom}_k(T_x, k)$. and we have a

pairing $\langle \cdot, \cdot \rangle : T_x^\vee \times T_x \longrightarrow k$ and

a tangent vector $t \in T_x$ is determined
by the transformation $\langle df, t \rangle : T_x^\vee \longrightarrow k$.

as f varies over functions $f \in \Gamma(U, \mathcal{O}_U)$.

Example If A is a k -algebra

$x: \text{Spec } k \longrightarrow \text{Spec } A$ a point.

then $t \in T_x \text{Spec } A$ corresponds to

a map $t^*: A \longrightarrow k[\epsilon]/\epsilon^2$

$$t^*(f) = f(x) + df_x(t) \epsilon$$

For this rule to be an algebra map we need:

$$\begin{aligned} 1) \quad t^*(fg) &= (f(x) + df_x(t) \varepsilon) (g(x) + dg_x(t) \varepsilon) \\ &= f(x)g(x) + [g(x)df_x(t) + f(x)dg_x(t)] \varepsilon \end{aligned}$$

$$2) \quad t^*(f+g) = f(x) + g(x) + [df_x(t) + dg_x(t)] \varepsilon$$

$$3) \quad t^*(\lambda) = \lambda + 0 \cdot \varepsilon$$

In other words, given fixed $x \in \text{Spec } A$ we can treat k as an A -module through the surjection $A \twoheadrightarrow k$ and finding $t \in T_x \text{Spec } A$ is equivalent to finding $d := d(_)_x[t]: A \twoheadrightarrow k$

$$1) \text{ Leibniz rule: } 1) \quad d(fg) = g \cdot df + f \cdot dg$$

$$k\text{-linearity: } \begin{cases} 2) \quad d(f+g) = df + dg \\ 3) \quad d(\lambda) = 0 \quad \forall \lambda \in k \end{cases}$$

Definition Let $R \rightarrow A$ be map of rings, M an A -module.

A derivation of A over R with values in M is an R -linear map

$$d: A \rightarrow M \quad \text{s.t.} \quad \forall a, b \in A \\ d(ab) = a d(b) + b d(a)$$

We let $\text{Der}_R(A, M)$ denote the set of derivations.

Note that $\text{Der}_R(A, M)$ is an A -module.

Proposition There exists a universal derivation $d: A \rightarrow \Omega_{A/R}^1$.

In other words,

$$\text{Hom}_A(\Omega_{A/R}^1, M) \cong \text{Der}_R(A, M).$$

Proof

We let $\Omega_{A/k}^1 = \text{Coker} \left(G_2 \xrightarrow{\Phi} G_1 \right)$

where $G_1 = \bigoplus_{f \in A} A \cdot df$ and G_2

so that 1) $d(fg) = f dg + g df$

2) $d(f+g) = df + dg$

3) $d(\lambda f) = \lambda df$

generate the image $\Phi(G_2)$.

Definition The representing object

$\Omega_{A/k}^1$ is the A -module of
Kähler differentials.

Back to intuition: $x \in \text{Spec } A$

then

$$\begin{aligned} T_x \text{Spec } A &= \text{Der}_k(A, k) = \text{Hom}_A(\Omega_{A/k}^1, k) \\ &= \text{Hom}_k(\Omega_{A/k}^1 \otimes_A k, k) = (\Omega_{A/k}^1 \otimes_A k)^\vee. \end{aligned}$$

