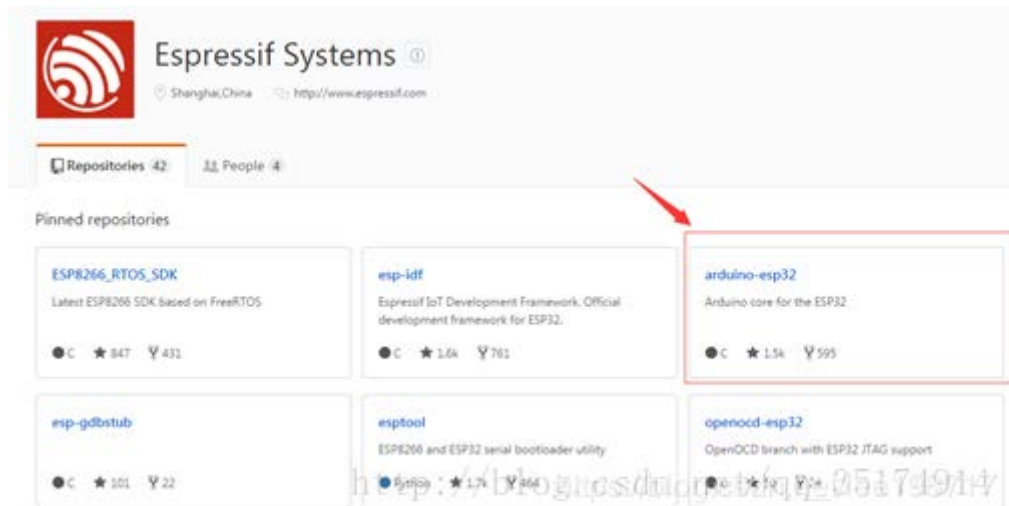


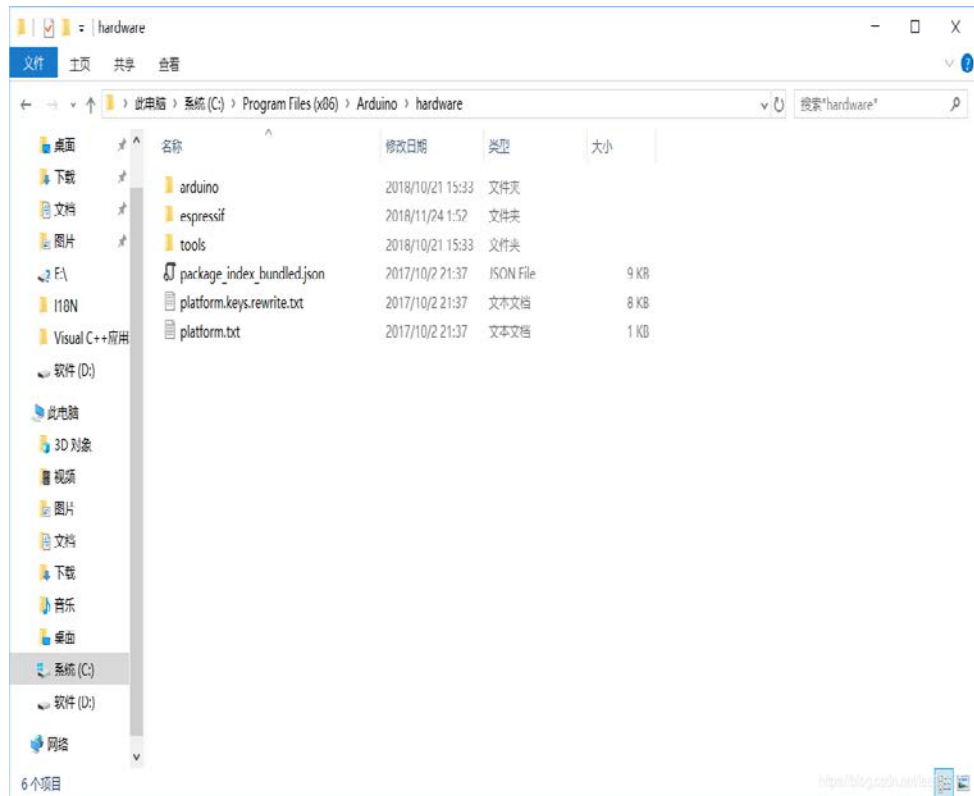
# ESP32 Arduino 开发环境搭建

## 一、安装 arduino 的 ESP32 开发工具包

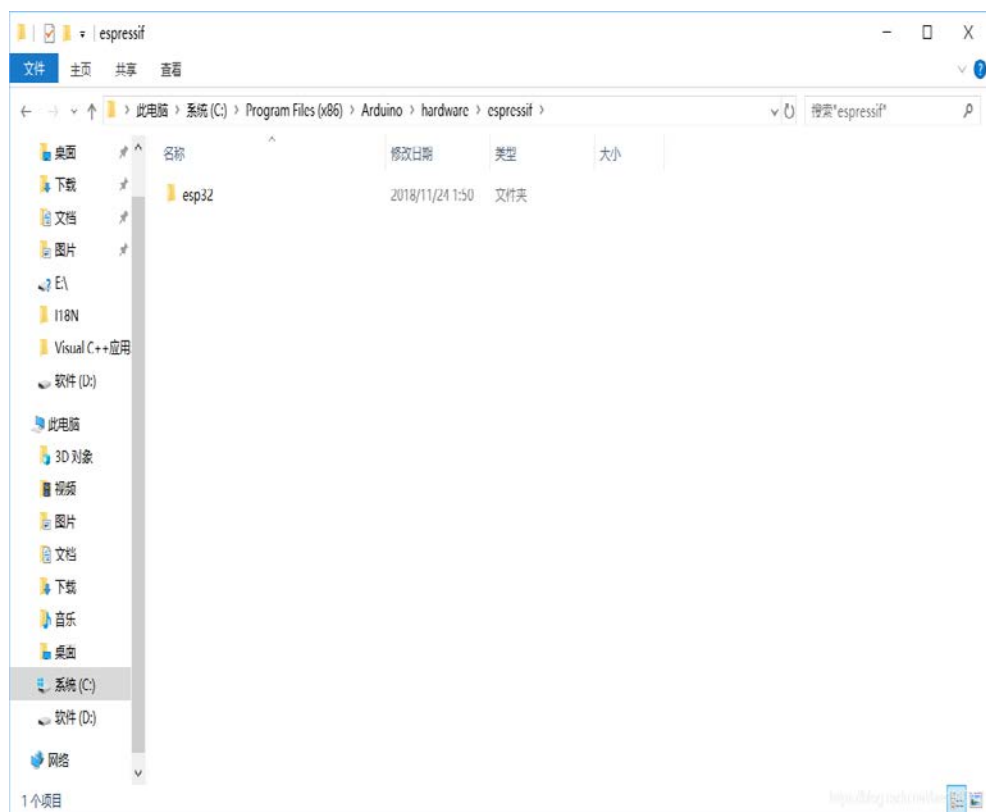
1. 进入 espressif 的仓库 <https://github.com/espressif> 选择 arduino-esp32, 将所有文件打包下载。



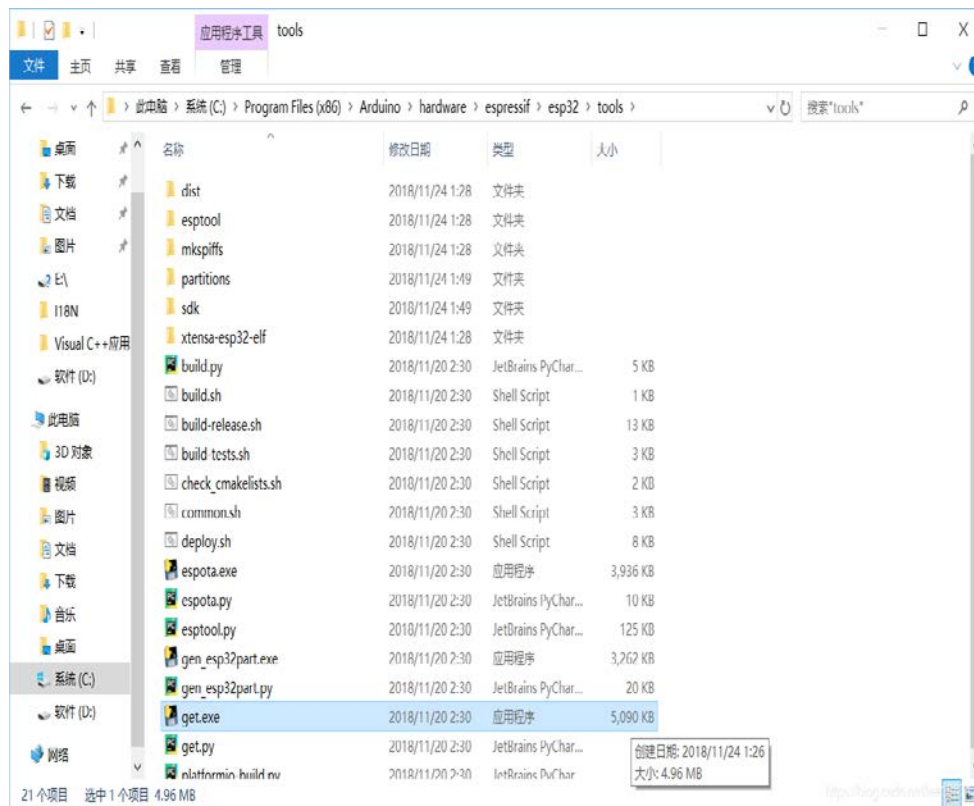
2. 找到 Arduino 软件的安装路径，进入 hardware 文件夹，新建一个名叫 espressif 的空白文件夹。



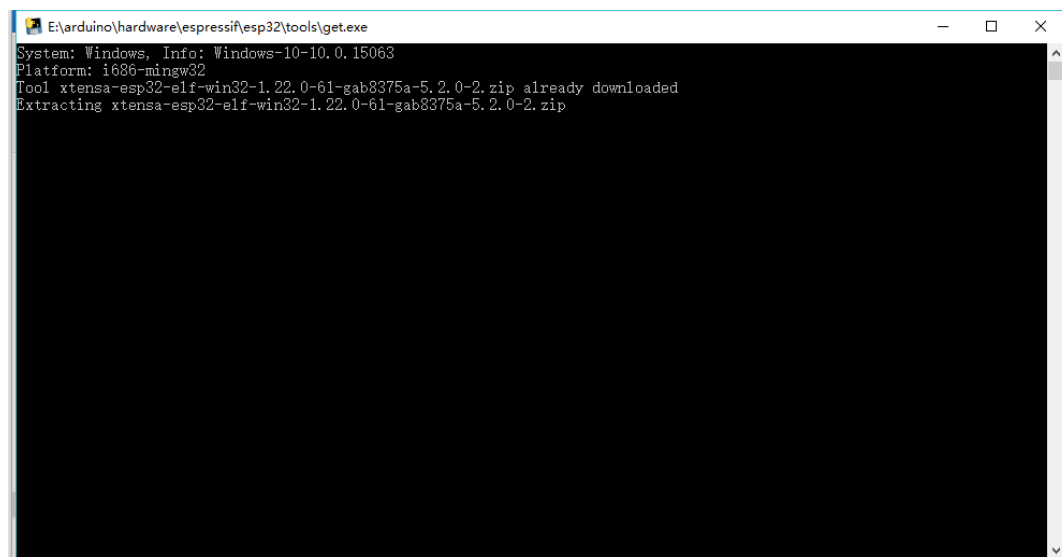
3. 然后在 espressif 文件夹下新建一个名叫 esp32 的空白文件夹，将下载下来的压缩包解压，内容复制到 esp32 文件夹中。



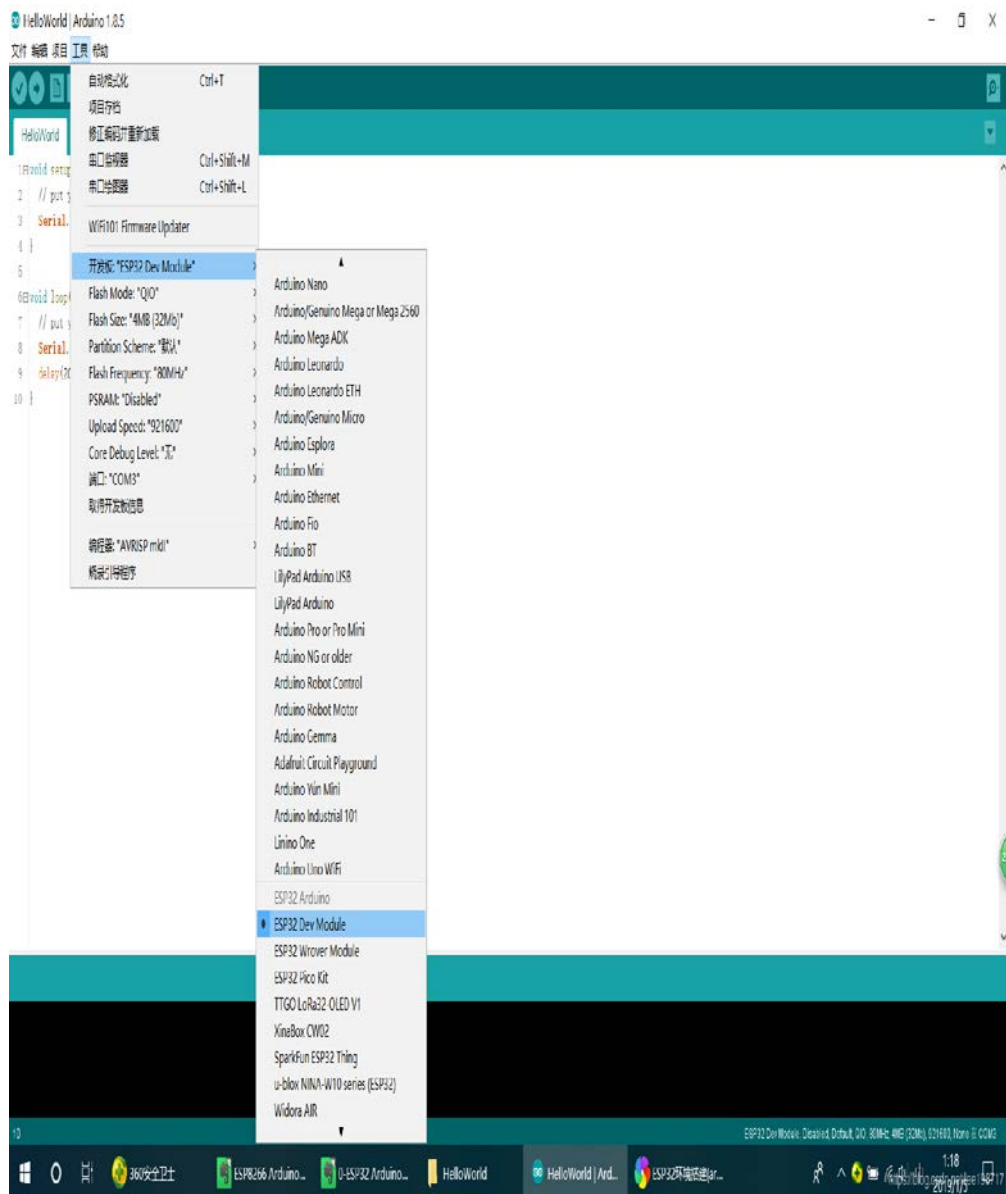
4. 进入 tools 文件夹，点击 get.exe 运行程序。（前提是你的电脑已经安装了 Python）



然后确保网络畅通，等待程序自动运行完毕，黑框自动关闭。



重启 Arduino 软件，打开工具，开发板，选择 ESP Dev Module 作为开发板表示安装成功。

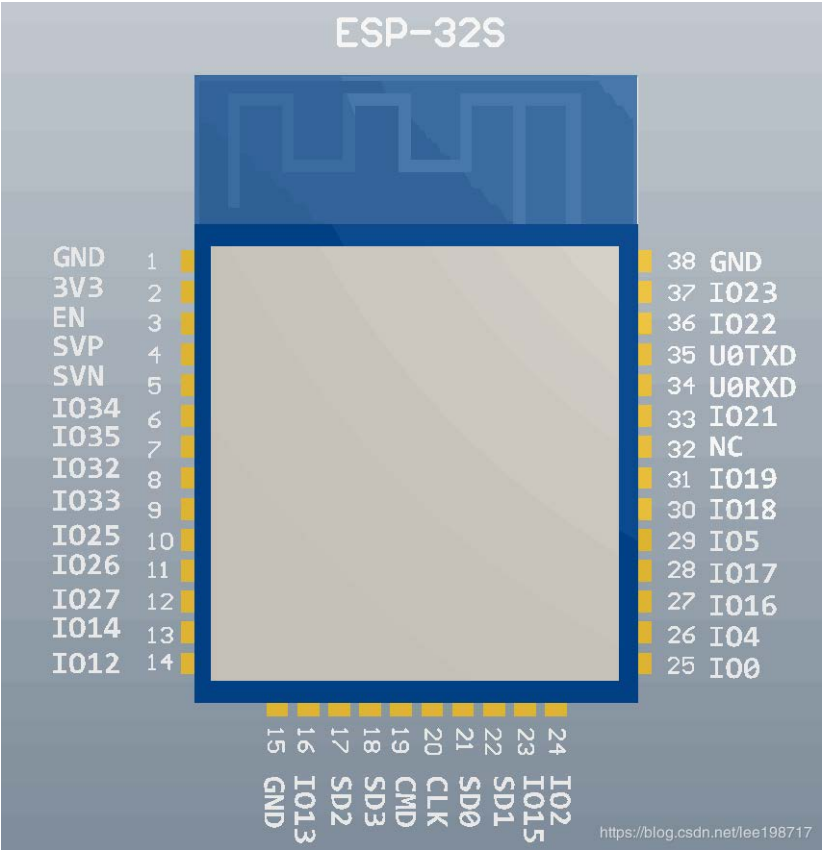


## 二、下载程序

点击 IDE 中的上传按钮，等到提示：“Connecting.....”时按住 BOOT 键，点击 EN 按钮并放开后进入下载模式，下载完成放开 BOOT 后芯片自动重启。

## 三、ESP32 模块资料

ESP-32S 管脚图：



ESP-32S 管脚功能定义：

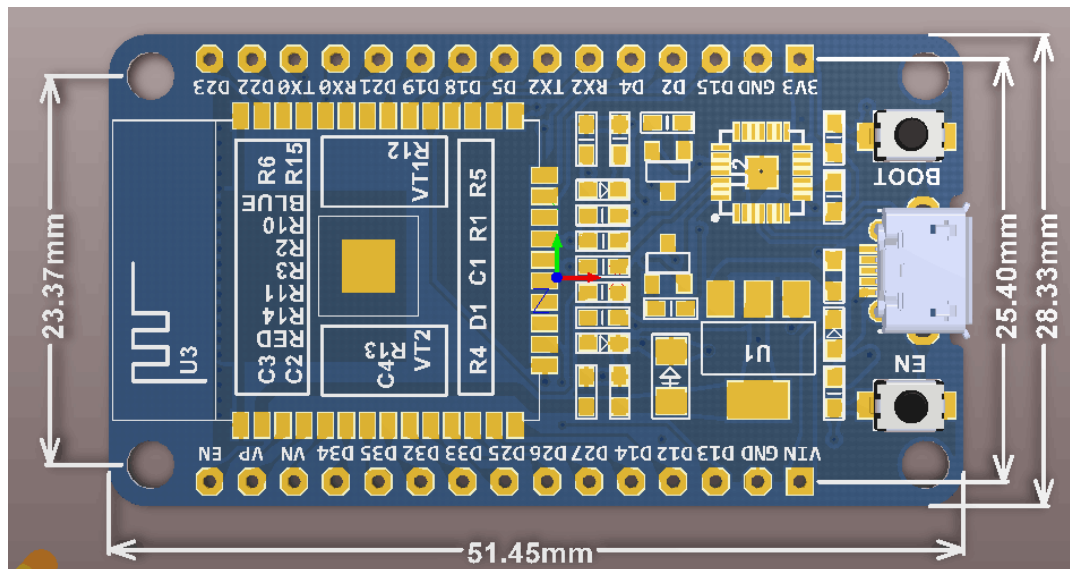
名称	序号	功能
GND	1	接地
3V3	2	供电
EN	3	使能芯片，高电平有效。
SENSOR_VP	4	GPI36, SENSOR_VP, ADC_H, ADC1_CH0, RTC_GPIO0
SENSOR_VN	5	GPI39, SENSOR_VN, ADC1_CH3, ADC_H, RTC_GPIO3
IO34	6	GPI34, ADC1_CH6, RTC_GPIO4
IO35	7	GPI35, ADC1_CH7, RTC_GPIO5
IO32	8	GPI032, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4, TOUCH9, RTC_GPIO9
IO33	9	GPI033, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5, TOUCH8, RTC_GPIO8
IO25	10	GPI025, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0
IO26	11	GPI026, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1
IO27	12	GPI027, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV

I014	13	GPI014, ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK, HS2_CLK, SD_CLK, EMAC_TXD2
I012	14	GPI012, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ, HS2_DATA2, SD_DATA2, EMAC_TXD3
GND	15	接地
I013	16	GPI013, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3, SD_DATA3, EMAC_RX_ER
SHD/SD2	17	GPI09, SD_DATA2, SPIHD, HS1_DATA2, U1RXD
SWP/SD3	18	GPI010, SD_DATA3, SPIWP, HS1_DATA3, U1TXD
SCS/CMD	19	GPI011, SD_CMD, SPICS0, HS1_CMD, U1RTS
SCK/CLK	20	GPI06, SD_CLK, SPICLK, HS1_CLK, U1CTS
SD0/SD0	21	GPI07, SD_DATA0, SPIQ, HS1_DATA0, U2RTS
SDI/SD1	22	GPI08, SD_DATA1, SPID, HS1_DATA1, U2CTS
I015	23	GPI015, ADC2_CH3, TOUCH3, MTD0, HSPICS0, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3
I02	24	GPI02, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, SD_DATA0
I00	25	GPI00, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK
I04	26	GPI04, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER
I016	27	GPI016, HS1_DATA4, U2RXD, EMAC_CLK_OUT
I017	28	GPI017, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180
I05	29	GPI05, VSPICS0, HS1_DATA6, EMAC_RX_CLK
I018	30	GPI018, VSPICLK, HS1_DATA7
I019	31	GPI019, VSPIQ, U0CTS, EMAC_TXD0
NC	32	—
I021	33	GPI021, VSPIHD, EMAC_TX_EN
RXD0	34	GPI03, U0RXD, CLK_OUT2
TXD0	35	GPI01, U0TXD, CLK_OUT3, EMAC_RXD2
I022	36	GPI022, VSPIWP, U0RTS, EMAC_TXD1
I023	37	GPI023, VSPID, HS1_STROBE
GND	38	接地

ESP-32S 工作模式:

管脚	默认	SPI 启动模式	下载启动模式
GPI00	上拉	1	0
GPI02	下拉	无关项	0

## 四、ESP32 开发板资料



## 五、ESP32 开发板 Arduino 管脚定义

```

#ifndef Pins_Arduino_h
#define Pins_Arduino_h
#include <stdint.h>

#define EXTERNAL_NUM_INTERRUPTS 16
#define NUM_DIGITAL_PINS 40
#define NUM_ANALOG_INPUTS 16

#define analogInputToDigitalPin(p) (((p)<20)?(esp32_adc2gpio[(p))):-1)
#define digitalPinToInterrupt(p) (((p)<40)?(p):-1)
#define digitalPinHasPWM(p) (p < 34)

static const uint8_t LED_BUILTIN = 2;
#define BUILTIN_LED LED_BUILTIN // backward compatibility

static const uint8_t TX = 1;
static const uint8_t RX = 3;

static const uint8_t SDA = 21;
static const uint8_t SCL = 22;

```

```
static const uint8_t SS = 5;  
static const uint8_t MOSI = 23;  
static const uint8_t MISO = 19;  
static const uint8_t SCK = 18;
```

```
static const uint8_t A0 = 36;  
static const uint8_t A3 = 39;  
static const uint8_t A4 = 32;  
static const uint8_t A5 = 33;  
static const uint8_t A6 = 34;  
static const uint8_t A7 = 35;  
static const uint8_t A10 = 4;  
static const uint8_t A11 = 0;  
static const uint8_t A12 = 2;  
static const uint8_t A13 = 15;  
static const uint8_t A14 = 13;  
static const uint8_t A15 = 12;  
static const uint8_t A16 = 14;  
static const uint8_t A17 = 27;  
static const uint8_t A18 = 25;  
static const uint8_t A19 = 26;
```

```
static const uint8_t T0 = 4;  
static const uint8_t T1 = 0;  
static const uint8_t T2 = 2;  
static const uint8_t T3 = 15;  
static const uint8_t T4 = 13;  
static const uint8_t T5 = 12;  
static const uint8_t T6 = 14;  
static const uint8_t T7 = 27;  
static const uint8_t T8 = 33;  
static const uint8_t T9 = 32;
```

```
static const uint8_t DAC1 = 25;  
static const uint8_t DAC2 = 26;
```

```
#endif /* Pins_Arduino_h */
```



## 六、Arduino ESP32 开发环境的文件结构

电脑 > 软件 (D:) > Software > Arduino > hardware > arduino-esp32 > esp32 >				
名称	修改日期	类型	大小	
.git	2017/9/9 22:33	文件夹		
cores	2017/9/9 22:33	文件夹		
docs	2017/9/9 22:33	文件夹		
libraries	2018/1/16 16:52	文件夹		
package	2017/9/9 22:33	文件夹		
tools	2017/9/9 22:33	文件夹		
variants	2017/9/9 22:33	文件夹		
.gitignore	2017/8/30 15:20	GITIGNORE 文件	1 KB	
.travis.yml	2017/8/30 15:20	YML 文件	3 KB	
appveyor.yml	2017/8/30 15:20	YML 文件	1 KB	
boards.txt	2017/9/5 22:37	文本文档	48 KB	
component.mk	2017/8/30 15:20	Makefile	1 KB	
Kconfig	2017/8/30 15:20	文件	3 KB	
Makefile.projbuild	2017/8/30 15:20	PROJBUILD 文件	1 KB	
package.json	2017/8/30 15:20	JSON File	1 KB	
platform.txt	2017/8/30 15:20	文本文档	8 KB	
programmers.txt	2017/8/30 15:20	文本文档	0 KB	
README.md	2017/8/30 15:20	MD 文件	3 KB	

**Core 文件夹：**乐鑫提供的 ESP32 底层内核文件，包括 `gpio` `timer` `iic` `spi` `touch` `uarts` 等外设驱动，还有二次封装好的 TCP UDP Server 等常用 `arduino` 库文件。

**libraries 文件夹：**包含各厂家的 `arduino` 例程，我们的例程文件夹是 `ESP-32F`

**variants 文件夹：**各种 `esp32` 开发板的引脚定义头文件（如果需要添加的自己开发板，则需要在该文件夹内加入自己开发板的引脚定义头文件，添加方法可以参考其他开发板的头文件，依样画葫芦即可）

**Tools 文件夹：**`esp32` `sdk` 和编译工具链

**Boards.txt：**定义开发板的各项参数，这些参数将会在 `arduino ide` 选择开发板型号和参数的面板中体现出来。

```
#####

esp-32f.name=ESP-32F //定义开发板名称

esp-32f.upload.tool=esptool //定义开发板下载工具
esp-32f.upload.maximum_size=1310720 //定义Flash空间
esp-32f.upload.maximum_data_size=294912 //定义data区空间
esp-32f.upload.wait_for_upload_port=true

esp-32f.serial.disabledDTR=true
esp-32f.serial.disableRTS=true

esp-32f.build.mcu=esp32
esp-32f.build.core=esp32
esp-32f.build.variant=esp-32f
esp-32f.build.board=ESP-32F

esp-32f.build.f_cpu=240000000L //定义cpu频率
esp-32f.build.flash_mode=dio //定义flash类型
esp-32f.build.flash_size=4MB
esp-32f.build.boot=bootloader
esp-32f.build.partitions=default

esp-32f.menu.FlashFreq.80=80MHz //定义可选flash频率
esp-32f.menu.FlashFreq.80.build.flash_freq=80m
esp-32f.menu.FlashFreq.40=40MHz
esp-32f.menu.FlashFreq.40.build.flash_freq=40m

esp-32f.menu.UploadSpeed.921600=921600 //定义可选波特率
esp-32f.menu.UploadSpeed.921600.upload.speed=921600
esp-32f.menu.UploadSpeed.115200=115200
esp-32f.menu.UploadSpeed.115200.upload.speed=115200
esp-32f.menu.UploadSpeed.256000.windows=256000
esp-32f.menu.UploadSpeed.256000.upload.speed=256000
esp-32f.menu.UploadSpeed.230400.windows.upload.speed=256000
esp-32f.menu.UploadSpeed.230400=230400
esp-32f.menu.UploadSpeed.230400.upload.speed=230400
esp-32f.menu.UploadSpeed.460800.linux=460800
esp-32f.menu.UploadSpeed.460800.macosx=460800
esp-32f.menu.UploadSpeed.460800.upload.speed=460800
esp-32f.menu.UploadSpeed.512000.windows=512000
esp-32f.menu.UploadSpeed.512000.upload.speed=512000
```

sketch\_jan19a | Arduino 1.8.4

文件 编辑 项目 工具 帮助

