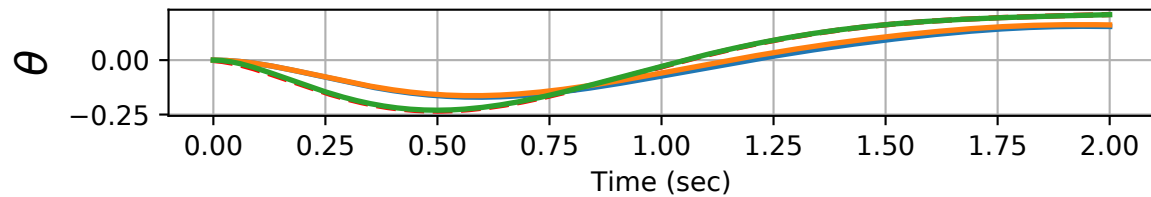
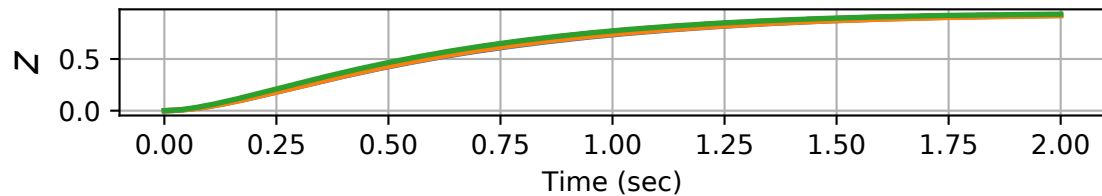
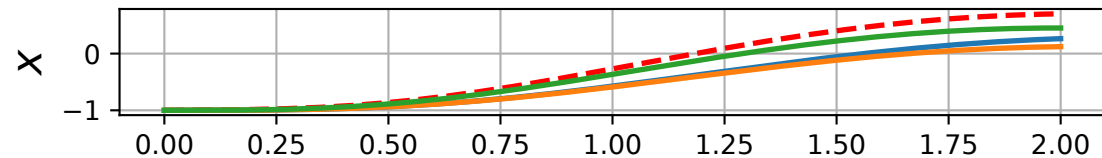


Trajectory tracking based on DMD, EDMD and bilinear EDMD models

States



Control action

