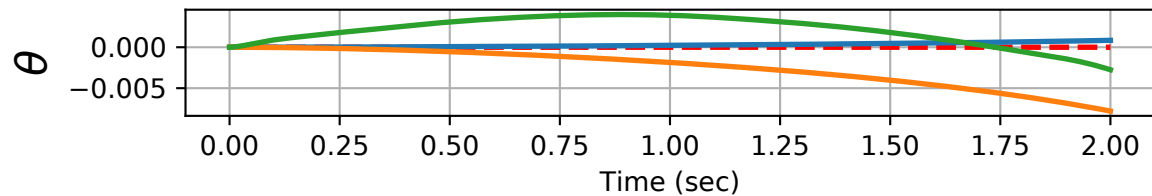
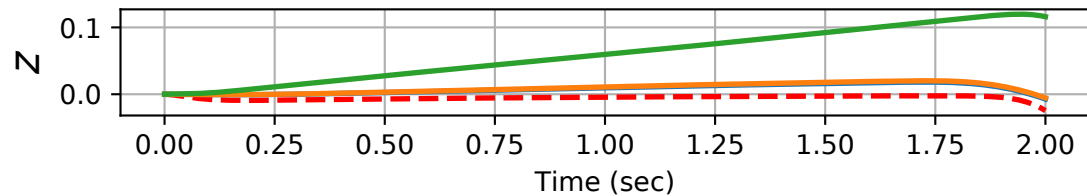
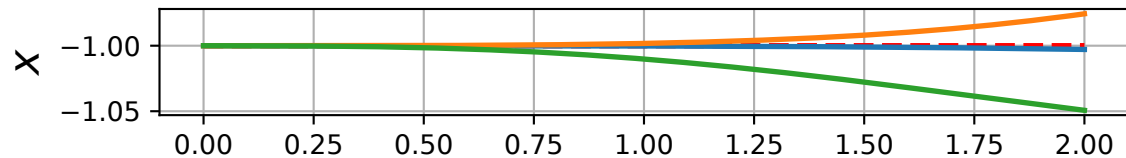


# Trajectory tracking based on DMD, EDMD and bilinear EDMD models

## States



## Control action

