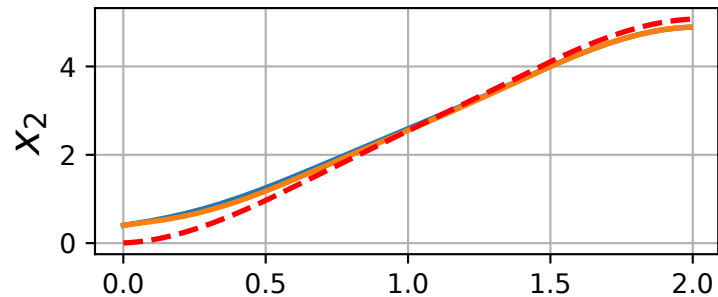
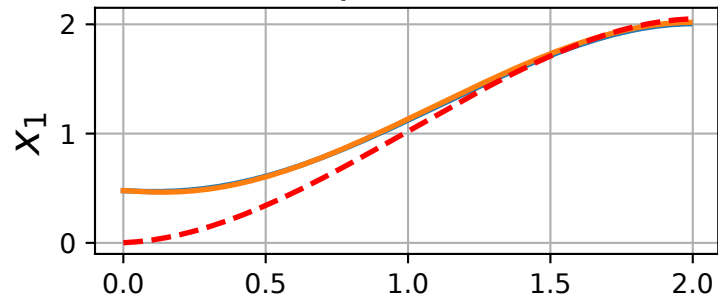
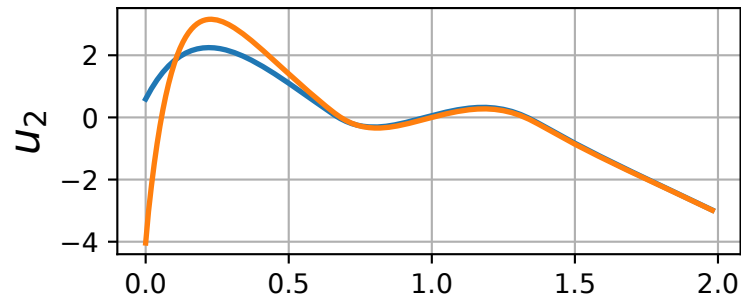
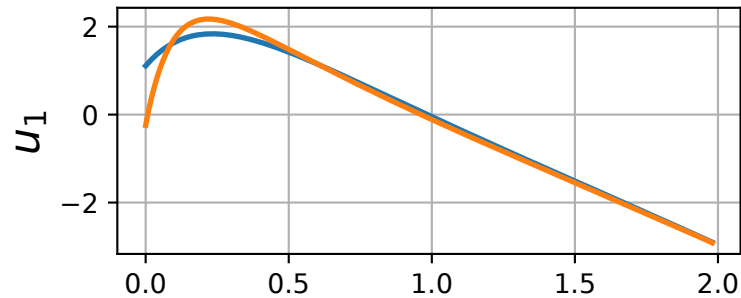


Output states



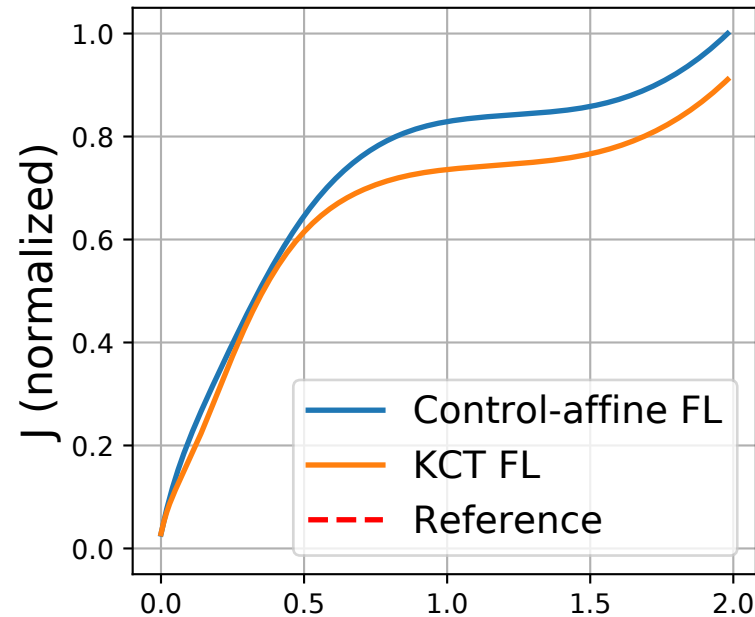
Time (sec)

Control action



Time (sec)

Normalized cost



Time (sec)

Control-affine FL
KCT FL
Reference