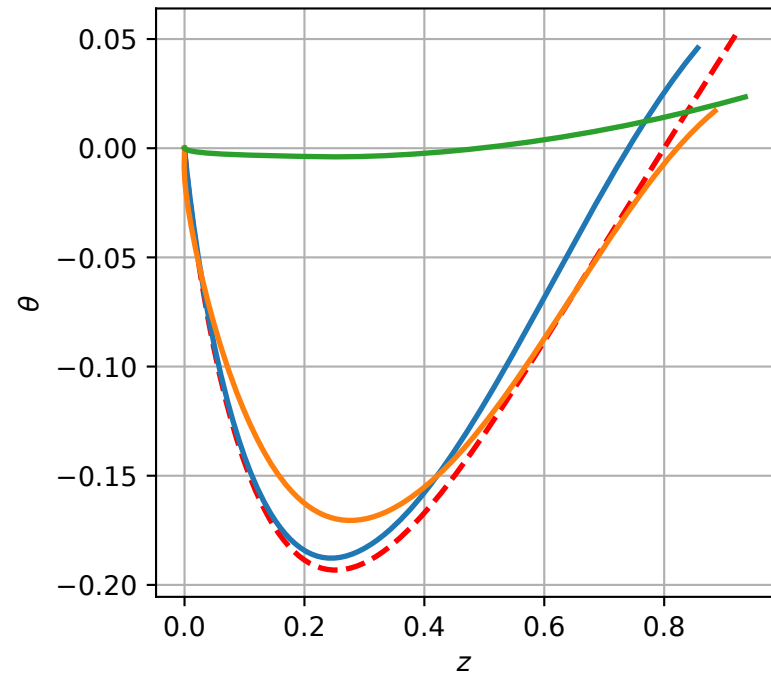
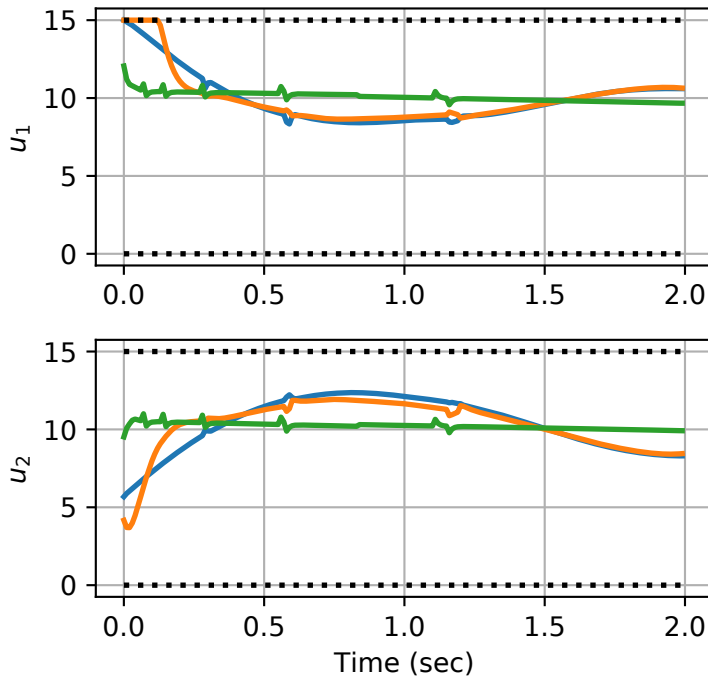


Trajectory tracking with MPC based on linearized, EDMD and bilinear EDMD models

Phase plot



Control action



Normalized cost

