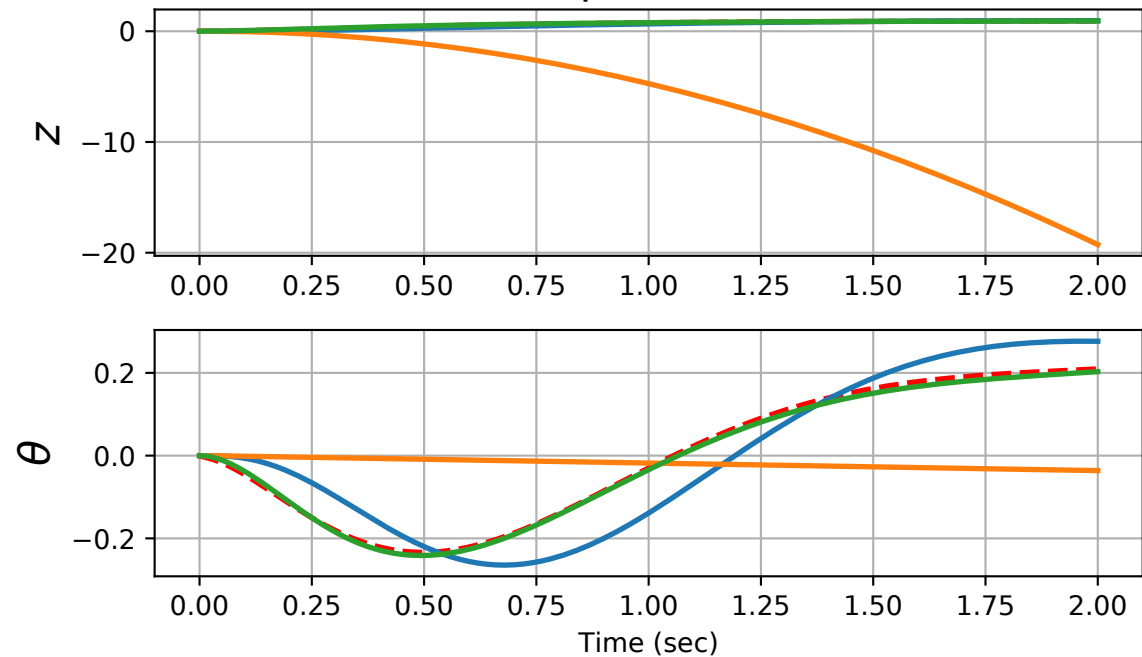


# Trajectory tracking based on DMD, EDMD and bilinear EDMD models

## Output states



## Control action

