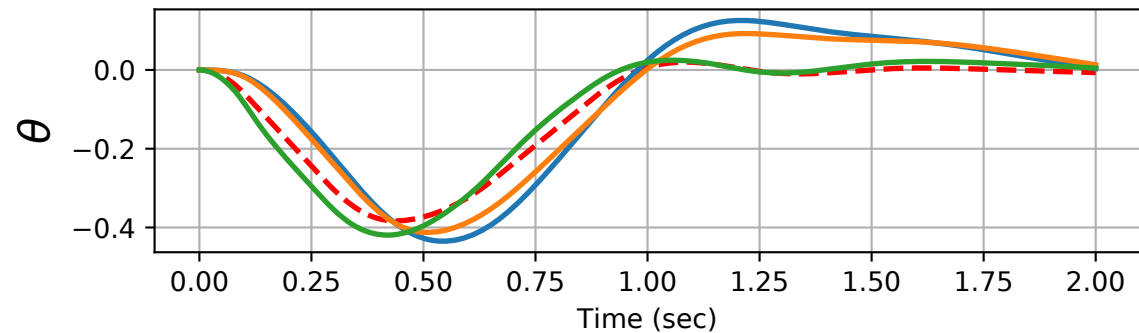
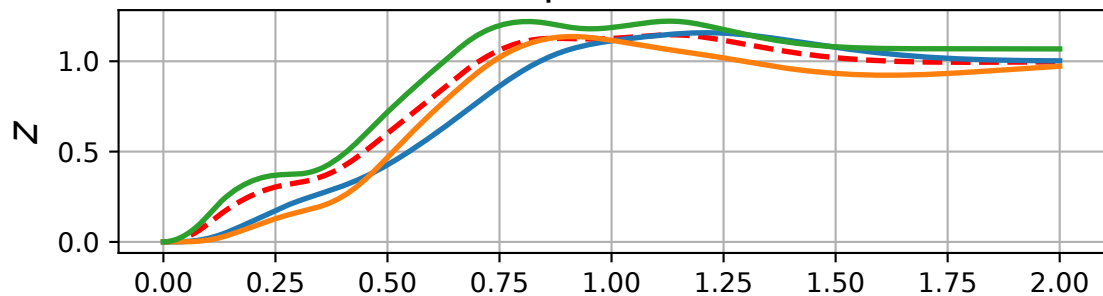


Trajectory tracking based on DMD, EDMD and bilinear EDMD models

Output states



Control action

