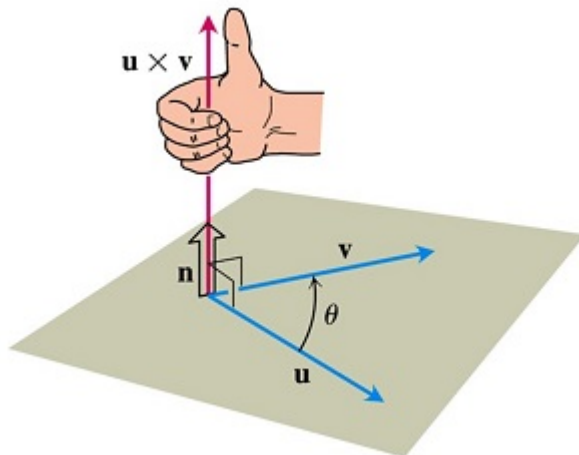


§10.3. The Cross Product in 3-Space

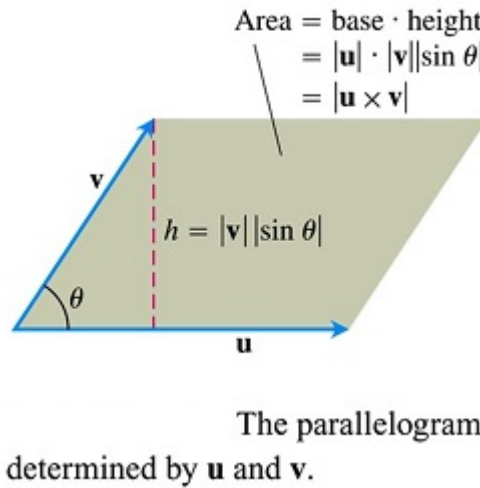
In this section we will see another kind of product of two vectors in 3-space which is called a **cross product** or **vector product**.

Definition. For any vectors \vec{u} and \vec{v} in \mathbb{R}^3 , the cross product $\vec{u} \times \vec{v}$ is the unique vector satisfying the following three conditions:

- i. $(\vec{u} \times \vec{v}) \bullet \vec{u} = 0$ and $(\vec{u} \times \vec{v}) \bullet \vec{v} = 0$,
- ii. $|(\vec{u} \times \vec{v})| = |\vec{u}||\vec{v}|\sin \theta$, where θ is the angle between \vec{u} and \vec{v} .
- iii. \vec{u} , \vec{v} and $\vec{u} \times \vec{v}$ form a right-handed triad.



From the definition one may say $\vec{u} \times \vec{v}$ is perpendicular to both \vec{u} and \vec{v} and has length equal to the area of the following shaded parallelogram.



If \vec{u} and \vec{v} have their tails at the point P , then $\vec{u} \times \vec{v}$ is normal (i.e., perpendicular) to the plane through P in which \vec{u} and \vec{v} lie. These properties make the cross product very useful for description of tangent planes and normal lines in \mathbb{R}^3 .

Theorem 1. If $\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k}$ and $\vec{v} = v_1 \vec{i} + v_2 \vec{j} + v_3 \vec{k}$, then

$$\vec{u} \times \vec{v} = (u_2 v_3 - u_3 v_2) \vec{i} + (u_3 v_1 - u_1 v_3) \vec{j} + (u_1 v_2 - u_2 v_1) \vec{k}.$$

The formula for the cross product in terms of components may seem awkward and asymmetric however it can be written more easily in terms of a determinant.

Example 1. (Calculating cross products)

- (a) $\vec{i} \times \vec{i} = \vec{0}$, $\vec{j} \times \vec{j} = \vec{0}$ and $\vec{k} \times \vec{k} = \vec{0}$.
- (b) $\vec{i} \times \vec{j} = \vec{k}$, $\vec{j} \times \vec{k} = \vec{i}$ and $\vec{k} \times \vec{i} = \vec{j}$.
- (c) $\vec{j} \times \vec{i} = -\vec{k}$, $\vec{k} \times \vec{j} = -\vec{i}$ and $\vec{i} \times \vec{k} = -\vec{j}$.

Some properties of cross product

If \vec{u} , \vec{v} and \vec{w} are any vectors in \mathbb{R}^3 , and t is a real number (a scalar), then

- (i) $\vec{u} \times \vec{u} = \vec{0}$,
- (ii) $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$, (The cross product is **anticommutative**.)
- (iii) $(\vec{u} + \vec{v}) \times \vec{w} = \vec{u} \times \vec{w} + \vec{v} \times \vec{w}$,
- (iv) $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$,
- (v) $(t\vec{u}) \times \vec{v} = \vec{u} \times (t\vec{v}) = t(\vec{u} \times \vec{v})$,
- (vi) $\vec{u} \bullet (\vec{u} \times \vec{v}) = \vec{v} \bullet (\vec{u} \times \vec{v}) = 0$.

Note that the cross product is **not associative**. In general,
 $\vec{u} \times (\vec{v} \times \vec{w}) \neq (\vec{u} \times \vec{v}) \times \vec{w}$.

Determinants:

In this part we will introduce 2×2 and 3×3 determinants. A determinant is an expression that involves the elements of a square array (matrix) of numbers. The determinant of the 2×2 array of numbers is (about the first row),

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = (-1)^{1+1}ad + (-1)^{1+2}bc = ad - bc.$$

Similarly, the determinant of a 3×3 array of numbers is (about the first row) defined by,

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = (-1)^{1+1}a(ei - hf) + (-1)^{1+2}b(di - gf) + (-1)^{1+3}c(dh - eg) \\ = aei + bfg + cdh - gec - hfa - idb.$$

Properties of Determinants:

(i) If two rows of a determinant are interchanged, then the determinant changes sign:

$$\begin{vmatrix} d & e & f \\ a & b & c \\ g & h & i \end{vmatrix} = - \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix}.$$

(ii) If two rows of the determinant are equal, the determinant has value 0:

$$\begin{vmatrix} a & b & c \\ a & b & c \\ g & h & i \end{vmatrix} = 0.$$

(iii) If the multiple of one row of the determinant is added to another row, the values of the determinant remains unchanged:

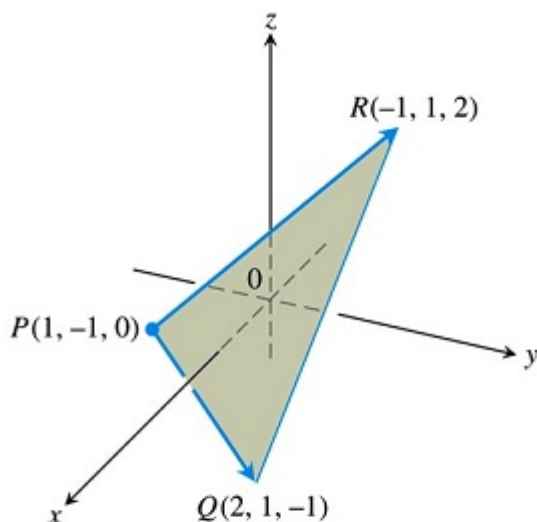
$$\begin{vmatrix} a & b & c \\ d+ta & e+tb & f+tc \\ g & h & i \end{vmatrix} = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix}.$$

The Cross Product as a Determinant:

The formula for the cross product of $\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k}$ and $\vec{v} = v_1 \vec{i} + v_2 \vec{j} + v_3 \vec{k}$ presented in the above theorem can be expressed symbolically as a determinant (about the first row) with basis vectors as the elements of the first row :

$$\vec{u} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} \vec{i} - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} \vec{j} + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \vec{k}.$$

Example 2. Find the area of the triangle with vertices at three points $P = (1, -1, 0)$, $R = (-1, 1, 2)$ and $Q = (2, 1, -1)$.



The vector $\vec{PQ} \times \vec{PR}$ is perpendicular to the plane of triangle PQR (Example 2). The area of triangle PQR is half of $|\vec{PQ} \times \vec{PR}|$

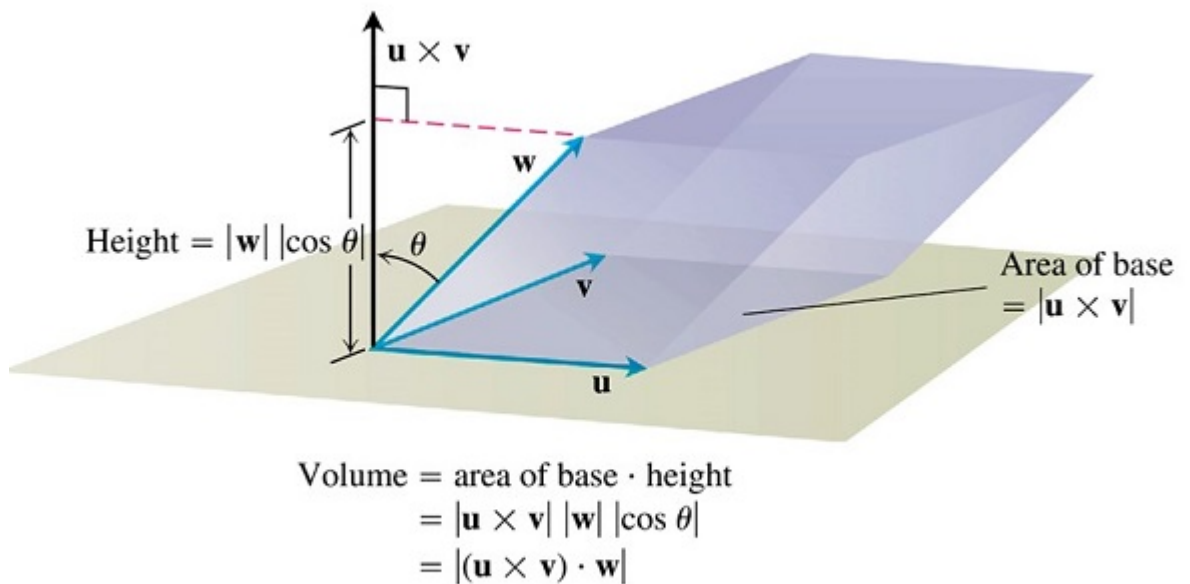
Two sides of the triangle as in the figure are given by the vectors:

$$\overrightarrow{PQ} = \langle 1, 2, -1 \rangle \text{ and } \overrightarrow{PR} = \langle -2, 2, 2 \rangle.$$

$$\frac{1}{2}|\overrightarrow{PQ} \times \overrightarrow{PR}| = \frac{1}{2} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & -1 \\ -2 & 2 & 2 \end{vmatrix} = \frac{1}{2} | \langle 6, 0, 6 \rangle | = \frac{1}{2} \sqrt{36 + 36} = 3\sqrt{2} \text{ square units.}$$

Definition. The quantity $\vec{u} \bullet (\vec{v} \times \vec{w})$ is called **the scalar triple product** of the vectors \vec{u} , \vec{v} and \vec{w} .

The volume of the parallelepiped spanned by the vectors \vec{u} , \vec{v} and \vec{w} can be found as in the following figure.



The number $|(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w}|$ is the volume of a parallelepiped.