RECALL

- Theorem: Let V be a vector space with operation + and .

  and let W be a non-empty subset of V. Then W is a

  subspace of V if and only if the following conditions

  hold:
  - a) It u and v are any vectors in W, then utv win W.
  - b) If e is any real number and u is any vector in W then c. u is in W.

$$E_X: Let W = S[X] \in \mathbb{R}^3 \mid Z = 0$$
. Is W a subspace of  $\mathbb{R}^3$ ?

Solution: Observe that W is nonempty, since [0] EW

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 \end{bmatrix}$$

Where X1+X2ER M1+Y2ER

12+3 call x1+x2=x3 ER -41+42=43 ER

Thus W is a non-empty subset of IR3, closed under addition and scaler multiplication of vectors, so W is a subspace of R3.

a subspace of 123 or not?

Solution: Let 
$$W = S \begin{bmatrix} 9 \\ 5 \end{bmatrix} \in \mathbb{R}^3 \mid c = 1$$
 be the set of all vectors of the form  $\begin{bmatrix} 9 \\ 5 \end{bmatrix}$ .

Observe that it is not empty since [ o] EW

$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} + \begin{bmatrix} a_2 \\ b_2 \end{bmatrix} = \begin{bmatrix} a_1 + a_2 \in \mathbb{R} & \text{lets call } a_1 + a_2 = a_3 \\ b_1 + b_2 \in \mathbb{R} & \text{b}_1 + b_2 = b_3 \end{bmatrix}$$

Definition. The vectors v1, -- , vk in a vector space V are said to be "linearly dependent" if there exist constant ap--, ak not all zero, such that

$$\frac{2-1}{\sum} \sigma^{2} \Lambda^{2} = \sigma^{1} \Lambda^{1} + \cdots + \sigma^{\nu} \Lambda^{\nu} = 0$$

Otherwise 11, - . 1/k are called "Linearly independent".

That is VIs. . . VK are linearly independent if whenever

0/1/ + 11 + 0 / 1/2 0

Ex: Determine whether S= \$(1,0), 10,113 is linearly independent

Solution: Write

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$$\begin{bmatrix} c_1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$[c_1] = [c_0] = 1 c_1 = c_2 = 0$$

Hence { (1,0), (0,1)} is linearly independent.

Ex: Is S= { (1,0), (0,1), (1,-1)} Unearly independent?

Solution: Consider

C\_1(1/0) + c\_2(0,1)+c\_3(1,-1)=(0,0) (if c\_1=c\_2=c\_3=0) then it is linearly independent)

(c1+c3) c2-c3)=(0,0)

S = 1 + c3 = 0

 $\begin{cases} c_1 = -c_3 \\ c_2 = c_3 \end{cases}$ 

This means = 1 = k, = 2 = -k, = 3 = -k

This system has solution ciek, cz = -k, cz = -k if k = 0

then we have a non-trivial solution.

For example (=2, =2 -2) =3=-2;

2(1,0)-2(0,1)-2(1,-1)=(2-2,-2+2)=(0,0)

Hence S= {(1,0), (0,1), (1,-1)} is linearly dependent,

not independent!

Ex: Write  $(7,-2,2) \in \mathbb{R}^3$  as a linear combination of (4,-1,0), (0,1,1) and (2,0,1)

Solution: We want to find =1, =2, =3 so that

 $(7 - 2 - 2) = c_1 (1 - 1 - 0) + c_2 (0, 1, 1) + c_3 (2, 0, 1)$ 

(7,-2,2) = (c1,-c1,0)+(0,c2,c2)+(2c3,0,c3)

 $(7, -2, 2) = (c_1 + 2c_3) - c_1 + c_2) c_2 + c_3)$ 

 $=) \begin{cases} c_1 + 2c_3 = 7 \\ -c_1 + c_2 = -2 \end{cases} = 7 \begin{cases} c_1 = +1 \\ c_2 + c_3 = 2 \end{cases}$   $=) \begin{cases} c_1 + 2c_3 = 7 \\ c_2 = -1 \end{cases}$   $=) \begin{cases} c_1 + 2c_3 = 7 \\ c_2 = -1 \end{cases}$   $= c_3 = 3 / 7$ 

Thus  $(7, -2, 2) = \pm (1, -1, 0) - \pm (0, 1, 1) + 3(2, 0, 1)$ = (1, -1, 0) + (0, -1, -1) + (0, 0, 2)

Ex: Show the spanf (1,0,1), (-1,2,3), 10,1,-1)} is all of R3.

Solution: We must show that any vector (a,b,e) ER3 can be written as a linear combination of the three given vectors.

 $(c_1, 0, \pm 1) + (c_2(-1, 2, 3) + (c_3(0, 1, -1) = (a_1b_1c))$  $(c_1, 0, \epsilon_2) + (-c_2(2c_2, 3c_2) + (0, \epsilon_3, -\epsilon_3) = (a_1b_1c)$ 

$$\begin{cases} a = c_1 - c_2 \\ b = 2c_2 + c_3 \end{cases}$$

$$c = c_1 + 3c_2 - c_3$$

$$c_1 = \frac{5a + b + c}{6}$$
  $c_2 = \frac{b + c - a}{6}$   $c_3 = \frac{a + 2b - c}{3}$ 

Hence (a,b,c) = span \( (4,0,1),(-1,2,3),(0,1,-1)\) and the span is all of R3.

Definition! The vectors VID-. JVK in a vector space V are said to form a basis for V if

a) V1, V2, - , VK are linearly independent

b) V1, Ve, .. Vk sper V

Ex: Show that the set  $\left\{\begin{bmatrix} 2\\1\\0\end{bmatrix},\begin{bmatrix} 2\\1\\1\end{bmatrix},\begin{bmatrix} 2\\1\end{bmatrix}\right\}$  is a basis

for IR3.

Solution: We will show that 1) Linearly independent 2) spor

1) Write

$$c_1\begin{bmatrix}2\\7\\0\end{bmatrix}+c_2\begin{bmatrix}2\\7\\1\end{bmatrix}+c_3\begin{bmatrix}2\\2\\1\end{bmatrix}=\begin{bmatrix}0\\0\end{bmatrix}$$
 if  $c_1=c_2=c_3=0$  then it is lineary independent

$$\begin{bmatrix} 2c_1 \\ z_1 \\ 0 \end{bmatrix} + \begin{bmatrix} 2c_2 \\ c_2 \\ c_2 \end{bmatrix} + \begin{bmatrix} 2c_3 \\ 2c_3 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2c_1 + 2c_2 + 2c_3 \\ c_1 + c_2 + 2c_3 \\ c_2 + c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} 2c_1 + 2c_2 = 0 & c_1 + c_2 + c_3 = 0 \\ c_1 + c_2 + 2c_3 = 0 & c_1 + c_2 + 2c_3 = 0 \end{cases} = c_1 + c_2 + c_3 = 0$$

$$c_2 + c_3 = 0$$

$$c_3 = 0$$

$$c_4 + c_3 = 0$$

$$c_4 + c_3 = 0$$

$$c_4 + c_3 = 0$$

$$c_5 + c_3 = 0$$

Hence  $c_1 = c_2 = c_3 = 0$ . Therefore these vectors are linearly independents.

We try to write (a,b,c) as a linear combination of three vectors:

$$c_1 \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\begin{bmatrix} 2c_1 \\ c_1 \end{bmatrix} + \begin{bmatrix} 2c_2 \\ c_2 \end{bmatrix} + \begin{bmatrix} 2c_3 \\ 2c_3 \end{bmatrix} = \begin{bmatrix} \alpha \\ b \end{bmatrix}$$

$$\begin{bmatrix} 2c_1 + 2c_2 + 2c_3 \\ c_1 + c_2 + 2c_3 \\ c_2 + c_3 \end{bmatrix} = \begin{bmatrix} \alpha \\ b \\ c \end{bmatrix}$$

$$\begin{cases} 2c_1 + 2c_2 + 2c_3 = a \\ c_1 + c_2 + 2c_3 = b \end{cases}$$

$$\begin{cases} c_2 + c_3 = c \end{cases}$$

$$c_2 = \frac{2c - 2b + \alpha}{2}$$
 $c_3 = \frac{2b - \alpha}{2}$ 

Hence we can write (a,b,E) as a linear combination of three vectors with soefficient c1,52,53.

Hence 
$$\left\{ \begin{bmatrix} 2\\7 \end{bmatrix}, \begin{bmatrix} 2\\1 \end{bmatrix} \right\}$$
 is a basis for  $\mathbb{R}^3$ .

Ex: Which of the following sets of vectors are basis for R3?

Solution: Recall that since dimCR3)=3, all besis of R3 mas exactly three Linearly independent vectors.

So No! Here we have two vectors, we need three linearly independent vectors.

Solution: No! Here we have four vectors and dim(R3)=3 so at least one of them is a linear combination of the others.

$$=$$
  $\left\{ \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ 

Solution: There are 3 vectors, now we need to verify if they are
1) linearly independent
2) spor

So c1=c2=c3=0. Hence these vectors are linearly independent.

2) Take (a,b,e) ER3

We try to write (a,b,c) as a linear combination of three vectors

$$C_1 \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} + C_2 \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} + C_3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3c_1-c_2\\ 2c_1+2c_2+c_3 \end{bmatrix} = \begin{bmatrix} d\\ b\\ c \end{bmatrix}$$

$$3c_{1}-c_{2}=a$$

$$2c_{1}+2c_{2}+c_{3}=b$$

$$2c_{1}+c_{2}=c$$

$$c+c_{2}+c_{3}=b$$

$$\frac{2c_1+c_2=c}{5c_1+c_2=c}$$

$$5c_1 = a + c$$

$$c_2 = c - \left(\frac{2a + 2c}{5}\right)$$

$$c_2 = \frac{3z - 2q}{5}$$

$$c + \frac{3c - 2a}{5} + c_3 = b = 7$$
  $c_3 = b - c - \left(\frac{3c - 2a}{5}\right)$ 

Hence we can write (a,b,c) as a linear combination of three vectors with coefficient a, c2, c3.

Hence 
$$\left\{ \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$
 is a basis for  $\mathbb{R}^3$ .

Definition! Let V and W be two vector spaces. A function

 $T:V \longrightarrow W$ 

is called a "Linear transformation" of Vinto W, it following two properties are true for all u, vEV and scalers e.

1) T(u+v) = T(u) + T(v)

2) T( = u) = = = T(u)

Ex: Let T(V1, V2, V3) = (2V1+V2, 2V2-3V1, V1-V3)

a) compute T(-4,5,1).

Solution: We know that

T (11,12,13) = (21,+12,212-311,11-13) So

T(-45,1)=(2,(-4)+5,2,5-3にい,-4-1)

= (-3,22,-5)//

b) compute the praimage of W=(4,1,-1)

Solution: Suppose (4,1/2,13) is in the preimage of (4,1,-1).

Then

(24,+42,242-341,41-13)=(4,1,-1)

 $\begin{cases} 2v_1 + v_2 = 4 & v_1 = 1 + v_3 = 1 \\ 2v_2 - v_1 = 1 & = 1 \end{cases} v_1 = \frac{2v_2 - 1}{2} = \frac{v_1 - v_2}{2}$   $\begin{cases} v_1 - v_2 = 4 & v_2 = 1 \\ v_1 - v_2 = 4 & v_2 = 6 \end{cases} v_2 = \frac{v_2 - v_2}{2}$ 

$$v_1 = 2v_2 - 1 = 2$$
,  $\frac{1}{5} - 1 = \frac{1}{5} = 1 = \frac{1}{5} = \frac{1}{5} = \frac{1}{5}$ 

$$V_1 = 1 + V_3 = 7$$
  $\frac{7}{5} = 1 + V_3 = 7 V_3 = \frac{2}{5} / 1$ 

Ex: Let T: R3 > R3 be a linear transformation such that

$$T(\pm_{1}0,0) = (2,4,-1)$$

$$T(0,0,1) = (0,-2,2)$$

Compute T(-2,4,-1).

Solution: We have

$$(-2, 4, -1) = -2(4, 0, 0) + 4(0, 1, 0) - +(0, 0, +)$$

Hence 
$$T(-2,4,-1) = -2T(1,0,0) + 4T(0,1,0) - T(0,0,1)$$

$$(2,4,-1) \qquad (4,3,-2) \qquad (0,+2,2)$$

Definition: Let V, W be two vector spaces and T; V > W a linear transformation

1) Then the kernel of T, ker(T), is the set of VEV such that T(V) = 0.

2) The range of T, range (T) is given by

range (T) = { WEW | W = T(V) for some VEV}

EX: Find ker(T) where T: R3 - R2 is defined by

T((V1, V2, V3)) = (V1+V2, V2-V3)

Solution: Since Ker (T) = \( \gamma \colon \text{R}^3 \colon \text{T(V)} = 0 \\ \gamma \colon \text{ we must show

T((111/2)/3))=(0,0)

(V1+V2) 12-V3) = (0,0)

 $\begin{cases} V_1 + V_2 = 0 \\ V_2 - V_3 = 0 \end{cases} \begin{cases} V_1 = -V_2 \\ V_2 = V_3 \end{cases} V_1 = -V_2$   $V_2 = V_3$   $V_3 = -V_4$ 

Hence

Ker (T) = \(\gamma\) \(\mathreal\) \(\mathre

Ex: Define T: R2 - R3 such that

T((a,b,e)) = (a-b+e, 2a+b-e, -a-2b+2e)

Determine range (T).

Solution: Let W= (W1, W2, W3) be in range (T).

Thus W= T ((a,b,e)) for some vector (a,b,e) = 123.

Thus

T((a,b, c)) = (a-b+c, 2a+b-c, -a-2b+2c) = (W1, W2, W3)

a-p+c = W1

20 +b-c=W2

 $-0-2b+2c=W_{3}$ 

 $a - b + c = W_2 + W_3 = W_1 = W_2 + W_3$ 

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So if W=(W1, W2, W3) is to be the range (T), there

W1 = W2 + W3. That is

range (T) = { W= (W1, W2, W3) E1R3 | W1 = W2 + W3 }

Ex: Let T:R > R. Define T(x) = mx where TEXMINIMAN m is a fixed real number. Show that T is a linear transformation.

Solution: We must show the following two conductions:

$$v_{x} = v_{x} = v_{x} = v_{x}$$

$$= v_{x} + v_{y}$$

$$= v_{x} + v_{y}$$

$$2) T(r \times) = m(r \times) = (mr)(x) = (rm)(x) = r(mx)$$
$$= rT(x)$$

Hence T is a linear transformation.

Ex: Let T:R ->R. Define T(x)=mx+b where m and b are real numbers and b≠0. Show that T is not a linear transformation.

Solution: We must show the following two conditions:

T(x+y) = m(x+y) + b = mx + my + b

T(x+y)=mx+my+b

Now lets check

T(x) + T(y) = mx + b + my + b

= mx +my +2b

Hence

T(x+y)=mx+my+b

T(x) +T(y)=mx +my +2b ) = since b = 0

Hence T is not a linear transformation

Ex: Is  $U = \{ [x] \in \mathbb{R}^2 \mid x+y=0, x-y=1 \}$  a subspace of  $\mathbb{R}^2$ ?

Solution: No!

Remember that in order for u to be a subspace of  $\mathbb{R}^2$ ,

It must contain the zero vector, which in this zase is  $\begin{bmatrix} 0 \end{bmatrix}$ . But  $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$  is not a solution to the system

$$x - \lambda = 7$$

$$x + \lambda = 0$$

Hence [0] ∉ 4 implying that U is not a subspace.