

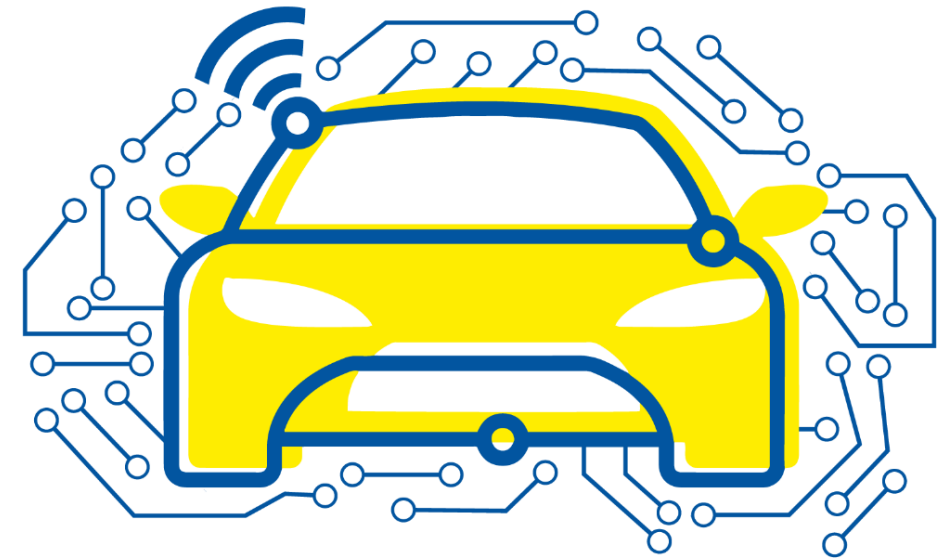
# Automated and Connected Driving Challenges

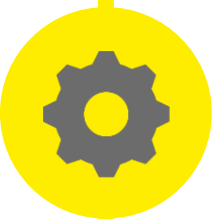
Section 1 – Introduction & Tools

## Robot Operating System Tasks

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# Robot Operating System – Introduction

## *ROS Tasks*

- **Introduction – Tools – Setup Coding Environment**

- clone ACDC Repository
- install Docker
- pull docker image
- start container

- **Practical ROS tasks**

- **ROS Foundations:** Master, Nodes, Parameters, Messages, Topics, Services, Launch
- **ROS GUI Tools:** RQT, RVIZ
- **ROS Coding:** C++ Nodes
- **ROS Bag:** Record, Info, Play, GUI
- **ROS Application:** Vehicle Controller
- **ROS2:** Introduction and ROS Bridge



Video: ika