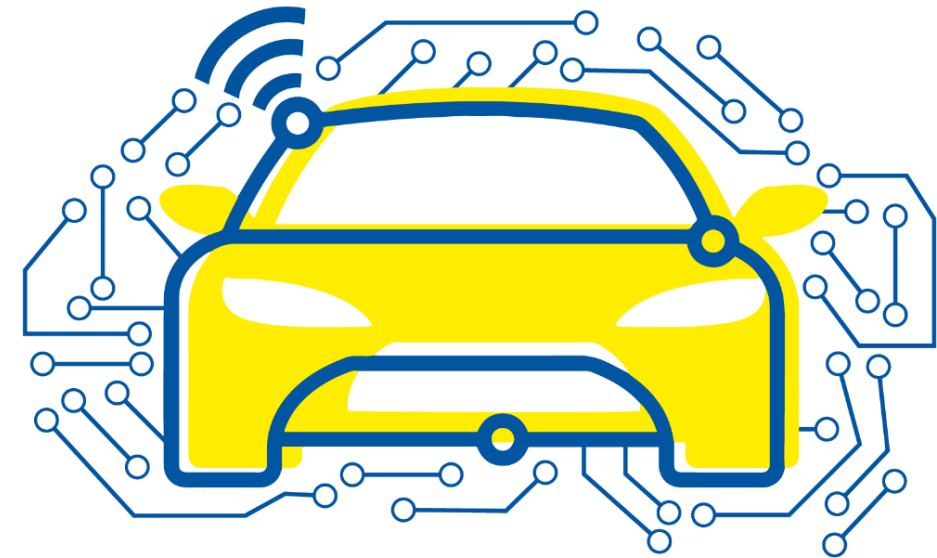**Automated and Connected Driving Challenges**

Section 3 – Object Fusion and Tracking
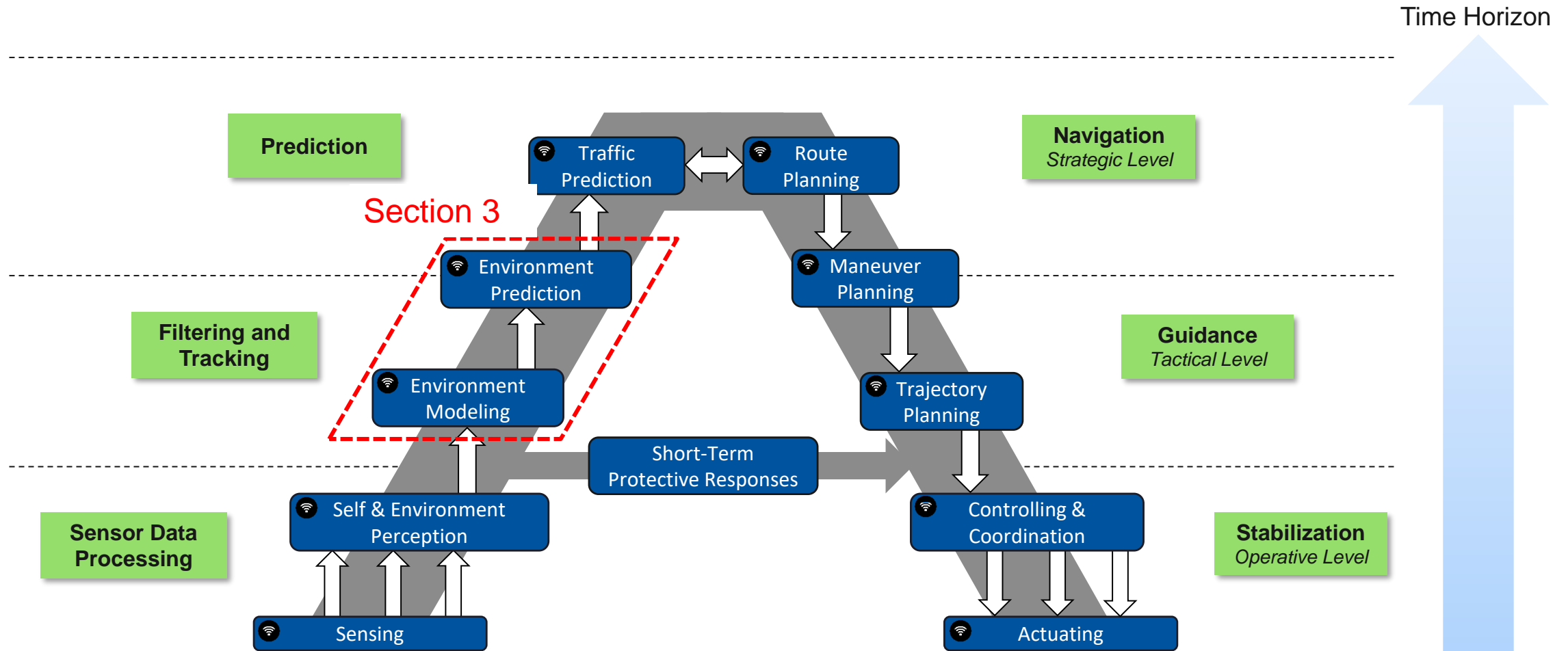
Introduction

Overview

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Structuring Automated Driving

The A-Model

Environment Modeling

Comprehensive Environment Model

Example of a comprehensive environment model

Object list (dynamic / online)
- road users / dynamic objects
- here cars blue, pedestrians pink
- output of tracking algorithm

Occupancy grid map (dynamic / online)
- static objects
- here: occupied cells displayed with fixed height

Digital HD map (static / offline)
- static environment
- created *prior* to driving task

Parametrized area for drivable space

Image: Zoox