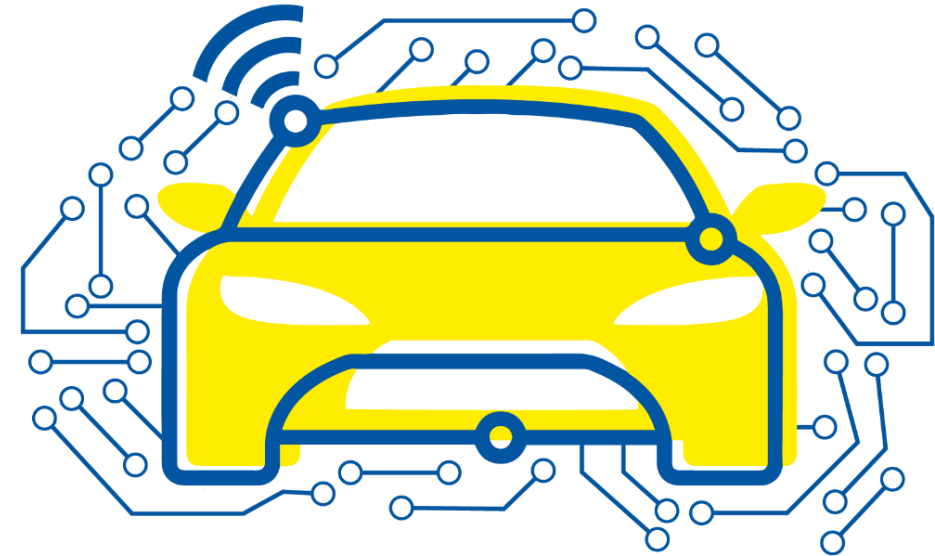**Automated and Connected Driving Challenges**

Section 2 – Sensor Data Processing

Object Detection

Tasks

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Exercises of this Subsection

3D Object Detection

- **Assignment:
  "3D Object Detection Training"**
  - Jupyter Notebook
  - Preprocessing of LiDAR data
  - Building training pipeline
  - Training
  - Inference and postprocessing

Image: ika

- **Assignment:
  "3D Object Detection Inference in ROS"**
  - ROS Node
  - Using real point cloud data from test vehicle in ROS
  - Performing 3D object detection with trained model
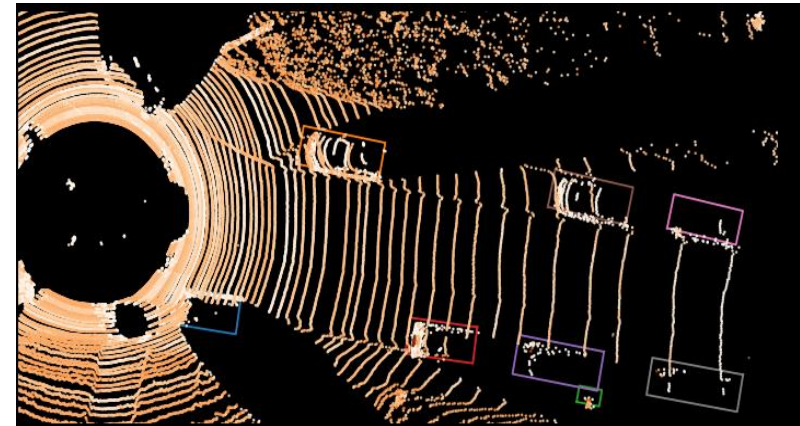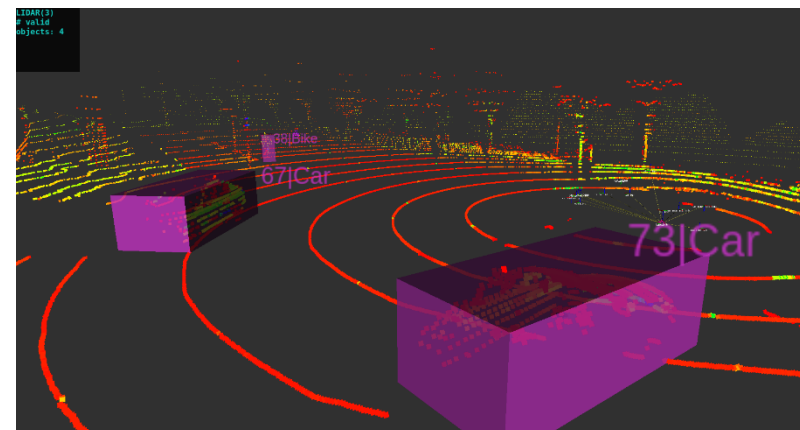 - Visualizing predictions in RVIZ

Image: ika