

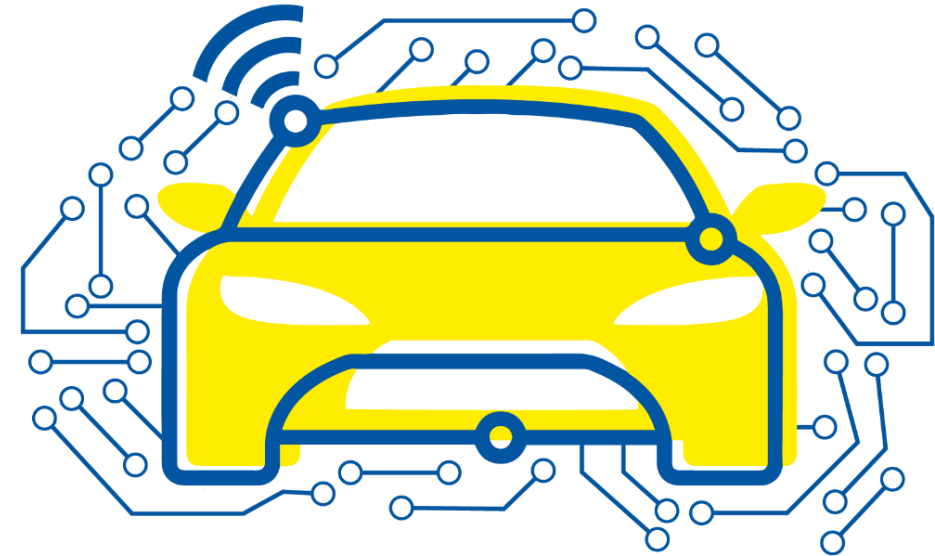
Automated and Connected Driving Challenges

Section 2 – Sensor Data Processing

Localization Challenges

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Localization – Challenges

Challenges in Vehicle Localization

Increasing accuracy requirements on different Guidance Levels for Automated Driving

Navigation

Guidance

Stabilization

10 m

0,01 m

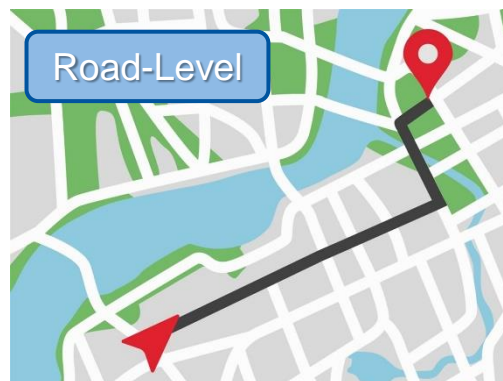


Image: businessrole.us

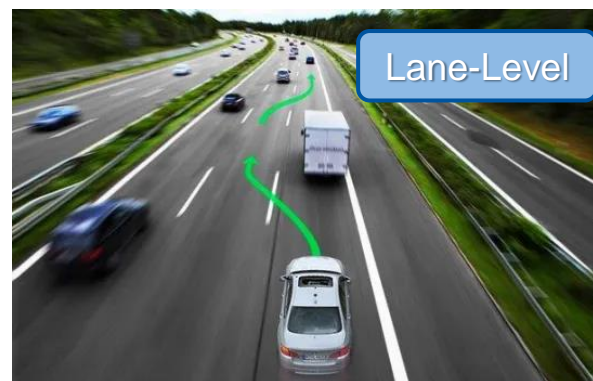


Image: towardsdatascience.com



Image: univdatos.com



Localization – Challenges

Challenges in Vehicle Localization

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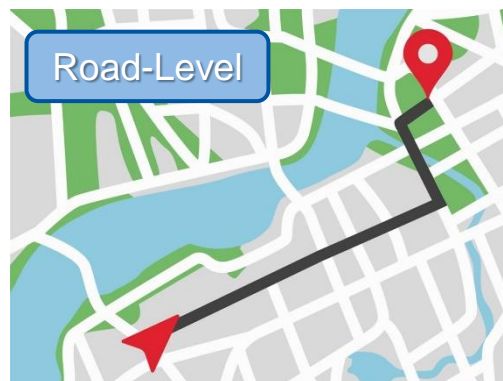


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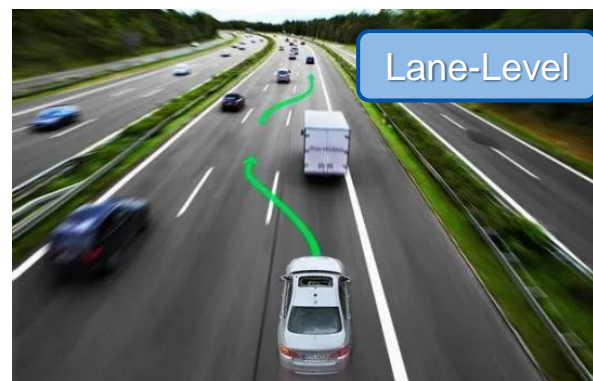


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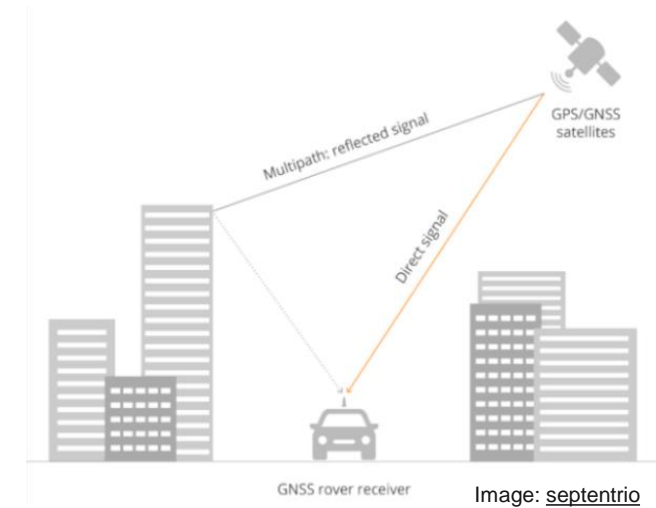
Image: univdatos.com



Localization – Challenges

Challenges in Vehicle Localization

Availability and quality of GNSS signals





Localization – Challenges

Challenges in Vehicle Localization

Availability and quality of GNSS signals

- Sender-specific Satellite outages
Orbital errors
- Signal propagation Atmospheric effects
Refraction, diffraction, absorption
Multipath effects
- Receiver-specific Situational occlusions
Antenna effects
Hardware delay

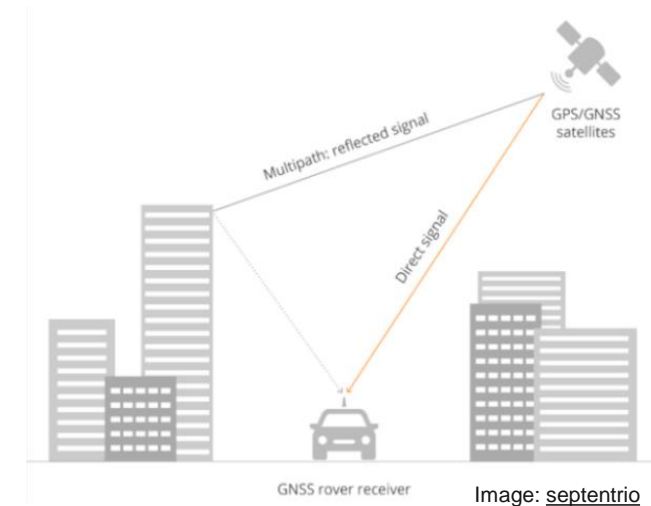


Image: [septentrio](#)



Image: [gpsworld.com](#)



Localization – Challenges

Challenges in Vehicle Localization

Impaired landmark detection with visual sensors

- Weather conditions Fog, rain, snow
- Lighting conditions Glare in low sun conditions
- Impaired sensors Dirt, ice
- Occlusions Dynamic objects
- Changing landmarks: Damages



Image: [valeo](#)



Image: [ulm-news](#)



Image: [forbes.com](#)



Image: [ADAC](#)



Localization – Challenges

Mitigation of Challenges

Orthogonal performance capabilities

- Different approaches often complement each other well
- Impairment of one method is positively correlated with good performance of another

Examples

- Clear sky in the countryside with only few landmarks
- Numerous landmarks when sky is occluded in cities

→ Fusion of information from different sensors and approaches helps mitigate individual weaknesses



Image: [Wikimedia](#)



Image: [Wikimedia](#)