

(a) The graph on nodes v_1, \dots, v_5 with edges $(v_1, v_2), (v_1, v_3), (v_2, v_5), (v_3, v_4)$ and (v_4, v_5) is such an example. The algorithm will return 2 corresponding to the path of edges (v_1, v_2) and (v_2, v_5) , while the optimum is 3 using the path $(v_1, v_3), (v_3, v_4)$ and (v_4, v_5) .

(b) The idea is to use dynamic programming. The simplest version to think of uses the subproblems $OPT[i]$ for the length of the longest path from v_1 to v_i . One point to be careful of is that not all nodes v_i necessarily have a path from v_1 to v_i . We will use the value " $-\infty$ " for the $OPT[i]$ value in this case. We use $OPT(1) = 0$ as the longest path from v_1 to v_1 has 0 edges.

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Long-path(n)
  Array  $M[1 \dots n]$ 
   $M[1] = 0$ 
  For  $i = 2, \dots, n$ 
     $M = -\infty$ 
    For all edges  $(j, i)$  then
      if  $M[j] \neq -\infty$ 
        if  $M < M[j] + 1$  then
           $M = M[j] + 1$ 
        endif
      endif
    endfor
     $M[i] = M$ 
  endfor
  Return  $M[n]$  as the length of the longest path.

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The running time is $O(n^2)$ if you assume that all edges entering a node i can be listed in $O(n)$ time.