



Department of Computer Science
UNIVERSITY OF COLORADO **BOULDER**



Support Vector Machines

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LECTURE 8

Slides adapted from Tom Mitchell, Eric Xing, and Lauren Hannah

Roadmap

- Classification: machines labeling data for us
- Previously: naïve Bayes and logistic regression
- This time: SVMs
 - (another) example of linear classifier
 - State-of-the-art classification
 - Good theoretical properties

Thinking Geometrically

- Suppose you have two classes: vacations and sports
- Suppose you have four documents

Sports

Doc₁: {ball, ball, ball, travel}

Doc₂: {ball, ball}

Vacations

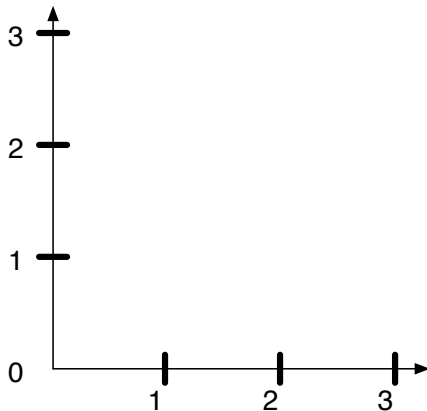
Doc₃: {travel, ball, travel}

Doc₄: {travel}

- What does this look like in vector space?

Put the documents in vector space

Travel



Ball

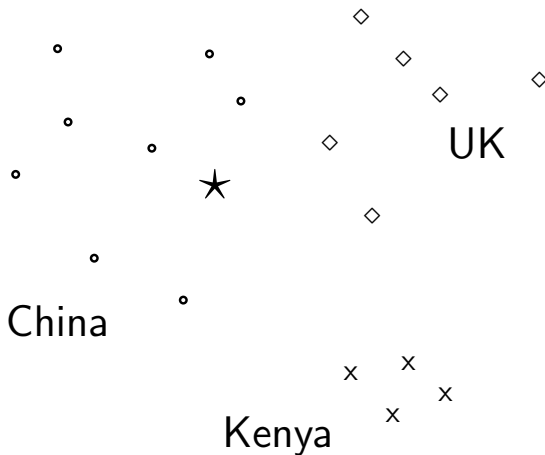
Vector space representation of documents

- Each document is a vector, one component for each term.
- Terms are axes.
- High dimensionality: 10,000s of dimensions and more
- How can we do classification in this space?

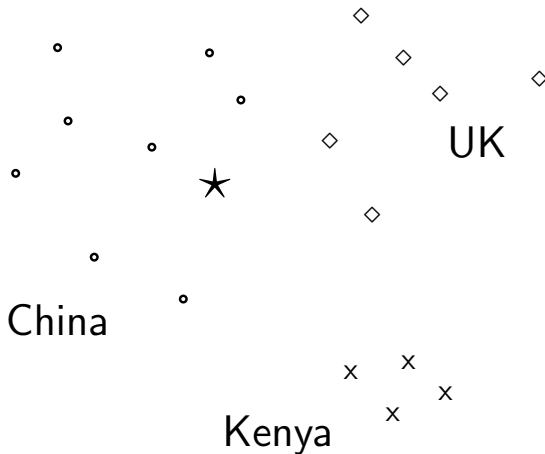
Vector space classification

- As before, the training set is a set of documents, each labeled with its class.
- In vector space classification, this set corresponds to a labeled set of points or vectors in the vector space.
- Premise 1: Documents in the same class form a **contiguous region**.
- Premise 2: Documents from different classes **don't overlap**.
- We define lines, surfaces, hypersurfaces to divide regions.

Classes in the vector space

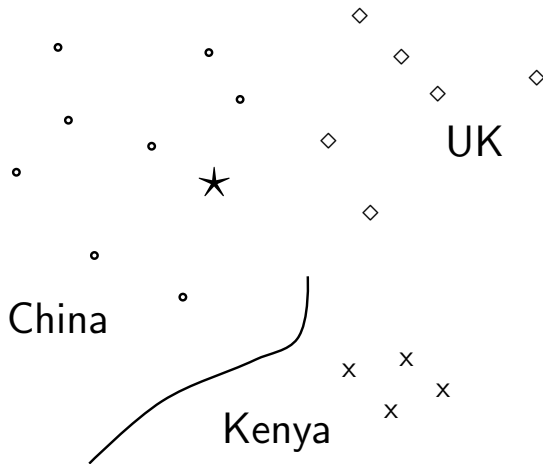


Classes in the vector space



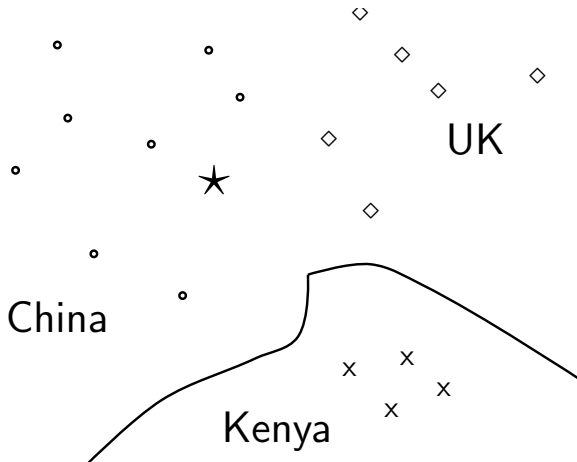
Should the document ★ be assigned to China, UK or Kenya?

Classes in the vector space



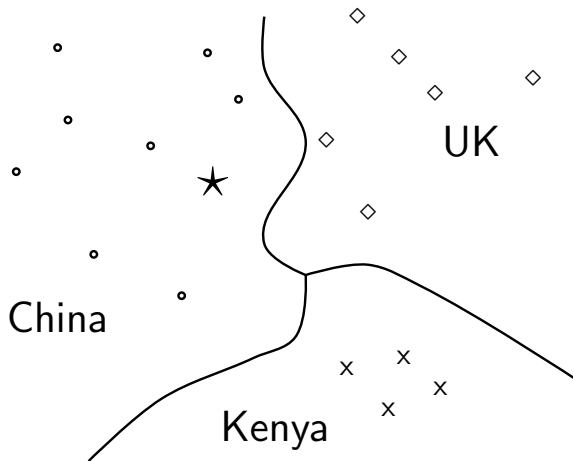
Find separators between the classes

Classes in the vector space



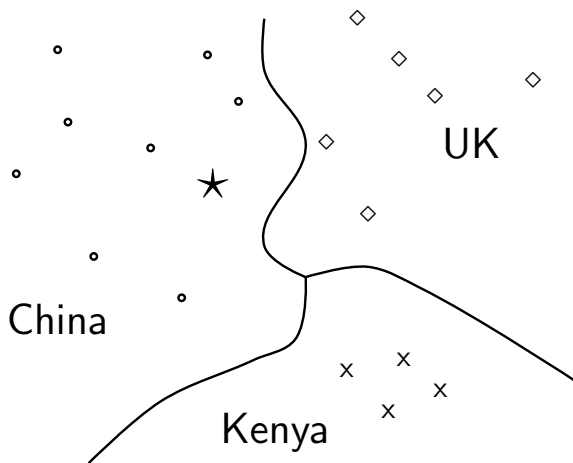
Find separators between the classes

Classes in the vector space



Based on these separators: ★ should be assigned to China

Classes in the vector space



How do we find separators that do a good job at classifying new documents like *? – Main topic of today

Plan

Linear Classifiers

Support Vector Machines

Formulation

Theoretical Guarantees

Recap

Linear classifiers

- Definition:
 - A linear classifier computes a linear combination or weighted sum $\sum_i w_i x_i$ of the feature values.
 - Classification decision: $\sum_i w_i x_i > \theta$?
 - ...where θ (the threshold) is a parameter.
- (First, we only consider binary classifiers.)
- Geometrically, this corresponds to a line (2D), a plane (3D) or a hyperplane (higher dimensionalities).
- We call this the **separator** or **decision boundary**.
- We find the separator based on training set.
- Methods for finding separator: logistic regression, naïve Bayes, linear SVM
- Assumption: The classes are **linearly separable**.

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- Assumption: The classes are **linearly separable**.
- Before, we just talked about equations. What's the geometric intuition?

A linear classifier in 1D



- A linear classifier in 1D is a point x described by the equation $w_1 d_1 = \theta$

A linear classifier in 1D



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- $x = \theta / w_1$

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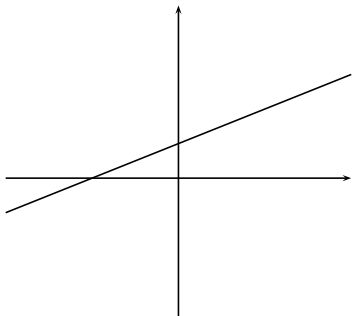
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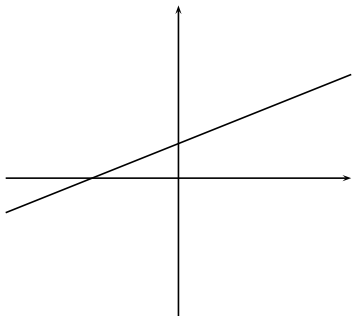
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A linear classifier in 2D



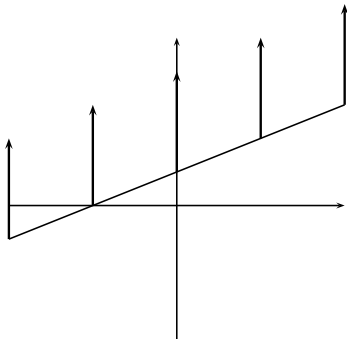
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A linear classifier in 2D



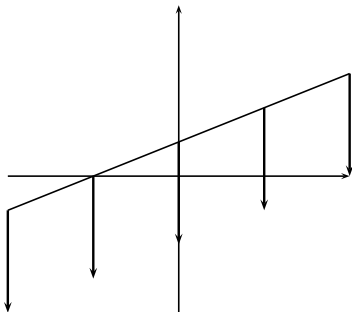
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- Example for a 2D linear classifier

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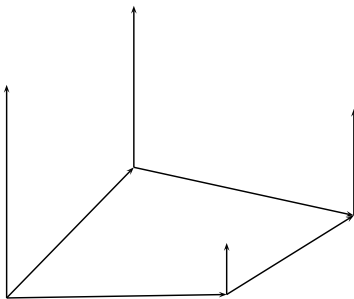
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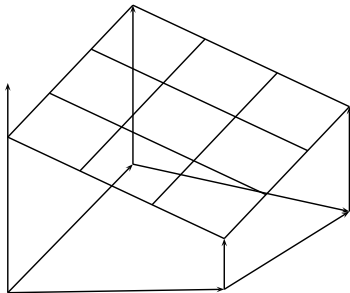
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A linear classifier in 3D



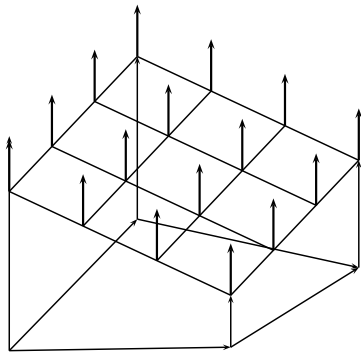
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$$w_1 d_1 + w_2 d_2 + w_3 d_3 = \theta$$

A linear classifier in 3D



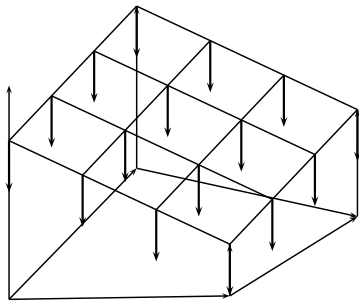
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Naive Bayes and Logistic Regression as linear classifiers

Multinomial Naive Bayes is a linear classifier (in log space) defined by:

$$\sum_{i=1}^M w_i d_i = \theta$$

where $w_i = \log[\hat{P}(t_i|c)/\hat{P}(t_i|\bar{c})]$, d_i = number of occurrences of t_i in d , and $\theta = -\log[\hat{P}(c)/\hat{P}(\bar{c})]$. Here, the index i , $1 \leq i \leq M$, refers to terms of the vocabulary.

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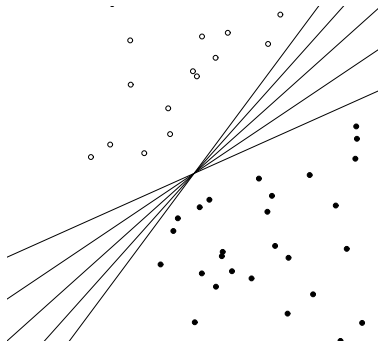
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Takeway

Naïve Bayes, logistic regression and SVM are all linear methods. They choose their hyperplanes based on different objectives: joint likelihood (NB), conditional likelihood (LR), and the margin (SVM).

Which hyperplane?



Which hyperplane?

- For linearly separable training sets: there are **infinitely** many separating hyperplanes.
- They all separate the training set perfectly ...
- ... but they behave differently on test data.
- Error rates on new data are low for some, high for others.
- How do we find a low-error separator?

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Linear Classifiers

Support Vector Machines

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Recap

Support vector machines

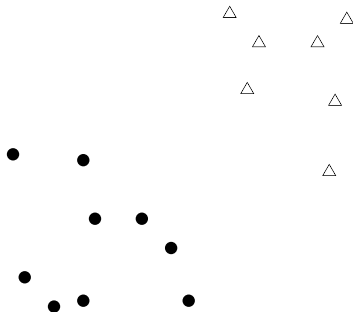
- Machine-learning research in the last two decades has improved classifier effectiveness.
- New generation of state-of-the-art classifiers: support vector machines (SVMs), boosted decision trees, regularized logistic regression, neural networks, and random forests
- Applications to IR problems, particularly text classification

SVMs: A kind of large-margin classifier

Vector space based machine-learning method aiming to find a decision boundary between two classes that is maximally far from any point in the training data (possibly discounting some points as outliers or noise)

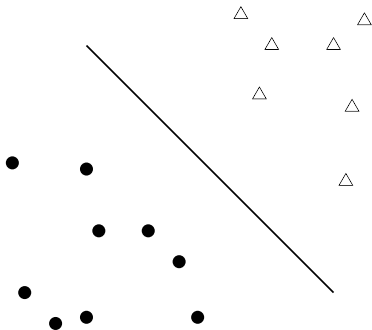
Support Vector Machines

- 2-class training data



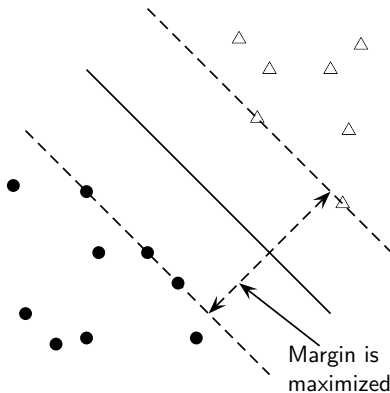
Support Vector Machines

- 2-class training data
- decision boundary →
linear separator



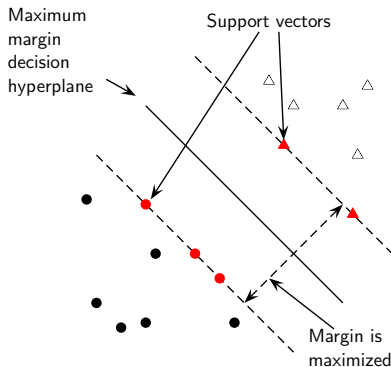
Support Vector Machines

- 2-class training data
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- criterion: being maximally far away from any data point \rightarrow determines classifier **margin**



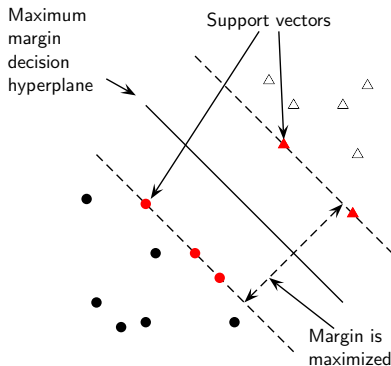
Support Vector Machines

- 2-class training data
- decision boundary \rightarrow **linear separator**
- criterion: being maximally far away from any data point \rightarrow determines classifier **margin**
- linear separator position defined by **support vectors**



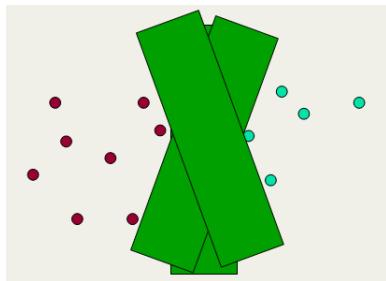
Why maximize the margin?

- Points near decision surface \rightarrow uncertain classification decisions
- A classifier with a large margin is always confident
- Gives classification safety margin (measurement or variation)



Why maximize the margin?

- SVM classifier: large margin around decision boundary
- compare to decision hyperplane: place fat separator between classes
 - unique solution
- decreased memory capacity
- increased ability to correctly generalize to test data



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Equation

- Equation of a hyperplane

$$\vec{w} \cdot x_i + b = 0 \quad (1)$$

- Distance of a point to hyperplane

$$\frac{|\vec{w} \cdot x_i + b|}{\|\vec{w}\|} \quad (2)$$

- The margin ρ is given by

$$\rho \equiv \min_{(x,y) \in S} \frac{|\vec{w} \cdot x_i + b|}{\|\vec{w}\|} = \frac{1}{\|\vec{w}\|} \quad (3)$$

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- This is because for any point on the marginal hyperplane,
 $\vec{w} \cdot x + b = \pm 1$

Optimization Problem

We want to find a weight vector \vec{w} and bias b that optimize

$$\min_{\vec{w}, b} \frac{1}{2} ||w||^2 \tag{4}$$

subject to $y_i(\vec{w} \cdot x_i + b) \geq 1, \forall i \in [1, m]$.

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Next week: algorithm

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Three Proofs that Suggest SVMs will Work

- Leave-one-out error
- VC Dimension
- Margin analysis

Leave One Out Error (sketch)

Leave one out error is the error by using one point as your test set (averaged over all such points).

$$\hat{R}_{LOO} = \frac{1}{m} \sum_{i=1}^m \mathbb{1} [h_{s-\{x_i\}} \neq y_i] \quad (5)$$

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This serves as an unbiased estimate of generalization error for samples of size $m - 1$:

$$\mathbb{E}_{S \sim D^m} [\hat{R}_{LOO}] = \mathbb{E}_{S' \sim D^{m-1}} [R(h_{S'})] \quad (6)$$

Leave One Out Error (sketch)

Let h_S be the hypothesis returned by SVMs for a separable sample S , and let $N_{SV}(S)$ be the number of support vectors that define h_S .

$$\mathbb{E}_{S \sim D^m} [R(h_S)] \leq \mathbb{E}_{S \sim D^{m+1}} \left[\frac{N_{SV}(S)}{m+1} \right] \quad (7)$$

Consider the held out error for x_i .

- If x_i was not a support vector, the answer doesn't change.
- If x_i was a support vector, it could change the answer; this is when we can have an error.

There are $N_{SV}(S)$ support vectors and thus $N_{SV}(S)$ possible errors.

VC Dimension Argument

Remember discussion VC dimension for d -dimensional hyperplanes?
That applies here:

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{2(d+1) \log \frac{\epsilon}{d+1}}{m}} + \sqrt{\frac{\log \frac{1}{\delta}}{2m}} \quad (8)$$

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But this is useless when d is large (e.g. for text).

Margin Theory

Margin Loss Function

To see where SVMs really shine, consider the margin loss ρ :

$$\Phi_{\rho}(x) = \begin{cases} 0 & \text{if } \rho \leq x \\ 1 - \frac{x}{\rho} & \text{if } 0 \leq x \leq \rho \\ 1 & \text{if } x \leq 0 \end{cases} \quad (9)$$

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The fraction of the points in the training sample S that have been misclassified or classified with confidence less than ρ .

Generalization

For linear classifiers $H = \{x \mapsto w \cdot x : \|w\| \leq \Lambda\}$ and data $X \in \{x : \|x\| \leq r\}$. Fix $\rho > 0$ then with probability at least $1 - \delta$, for any $h \in H$,

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- Data-dependent: must be separable with a margin
- Fortunately, many data do have good margin properties
- SVMs can find good classifiers in those instances

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Choosing what kind of classifier to use

When building a text classifier, first question: **how much training data is there currently available?**

- None?
- Very little?
- A fair amount?
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- Very little? **Naïve Bayes**
- A fair amount? **SVM**
- A huge amount **Doesn't matter, use whatever works**

SVM extensions: What's next

- Finding solutions
- Slack variables: not perfect line
- Kernels: different geometries

