



Decision Trees and SVMs

Jordan Boyd-Graber University of Colorado Boulder

Slides adapted from Tom Mitchell, Eric Xing, and Lauren Hannah

Roadmap

- Classification: machines labeling data for us
- Last time: naïve Bayes and logistic regression
- This time:
 - Decision Trees
 - Simple, nonlinear, interpretable
 - SVMs
 - (another) example of linear classifier
 - State-of-the-art classification
 - Examples in Rattle (Logistic, SVM, Trees)
 - Discussion: Which classifier should I use for my problem?

Plan

Decision Trees

Learning Decision Trees

Vector space classification

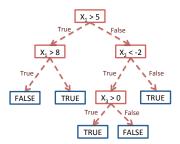
Linear Classifiers

Support Vector Machines

Recap

Suppose that we want to construct a set of rules to represent the data

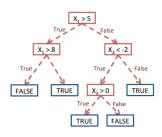
- can represent data as a series of if-then statements
- · here, "if" splits inputs into two categories
- "then" assigns value
- when "if" statements are nested, structure is called a tree



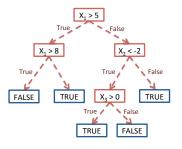
Ex: data (X_1, X_2, X_3, Y) with X_1, X_2, X_3 are real, Y Boolean

First, see if $X_1 > 5$:

- if TRUE, see if $X_1 > 8$
 - if TRUE, return FALSE
 - o if FALSE, return TRUE
- if FALSE, see if $X_2 < -2$
 - if TRUE, see if $X_3 > 0$
 - if TRUE, return TRUE
 - if FALSE, return FALSE
 - o if FALSE, return TRUE

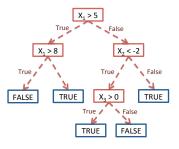


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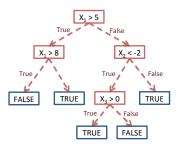
Example 1:
$$(X_1, X_2, X_3) = (1, 1, 1)$$

Example 2:
$$(X_1, X_2, X_3) = (10, -3, 0)$$



Example 1: $(X_1, X_2, X_3) = (1, 1, 1) \rightarrow TRUE$

Example 2: $(X_1, X_2, X_3) = (10, -3, 0)$



Example 1:
$$(X_1, X_2, X_3) = (1, 1, 1) \rightarrow TRUE$$

Example 2: $(X_1, X_2, X_3) = (10, -3, 0) \rightarrow FALSE$

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Terminology:

- branches: one side of a split
- leaves: terminal nodes that return values

Why trees?

- trees can be used for regression or classification
 - regression: returned value is a real number
 - classification: returned value is a class
- unlike linear regression, SVMs, naive Bayes, etc, trees fit local models
 - in large spaces, global models may be hard to fit
 - results may be hard to interpret
- fast, interpretable predictions

Example: Predicting Electoral Results

2008 Democratic primary:

- Hillary Clinton
- Barack Obama

Given historical data, how will a count vote?

- can extrapolate to state level data
- might give regions to focus on increasing voter turnout
- would like to know how variables interact

Example: Predicting Electoral Results

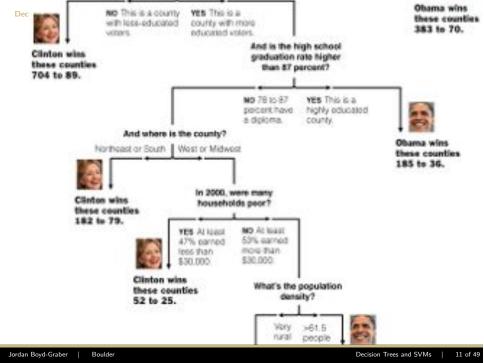
Decision Tree: The Obama-Clinton Divide more than Barack Oboma has won the 20 percent black? with large black or highly NO There are not **VES** This county Senator Hillary Rodham Clinton has a commanding lead in less-educated counties dominated by whites. Follow the arrows for a more detailed split. And is the high school graduation rate higher than 75 percent? Ohama wins NO This is a county YES This is a with loss-educated county with more 383 to 70. And is the high school Clinton wins graduation rate higher these counties 704 to 89. than 87 percent? NO 78 to 87 YES This is a percent have highly educated And where is the county? Obama wins Northcast or South | West or Midwest these counties 185 to 36. In 2000, were many Clinton wins households peor? _----NO At least 53% earned more than \$30,000 YES ALREAD lines than Clinton wins What's the population these counties density? 52 to 25. eary >61.5 rural people per sq Obama wins In 2004, did Bush beat Kerry badly? these counties 201 to 83. VES NO Clinton wins these counties 48 to 13.

Example: Predicting Electoral Results

Decision Tree: The Obama-Clinton Divide

In the nominating is a county contests so far, Senator more than Borack Oboms has won the 20 percent black? vast majority of counties with large black or highly educated populations. NO There are not **VES** This county Senator Hillary Rodham many Altscantwo a large Clinton has a commanding Amoricans in this Alnoan-American lead in less-educated. doubly. population counties dominated by whites. Follow the arrows for a more detailed split. And is the high school graduation rate higher than 78 percent? Ohama wins NO This is a county WIRE TING IO D these counties with loss-educated county with more 383 to 70. educated volers.

And is the high school





Note: Chart exclutes Florida are thinkings. Course sees results are not sensible or Asieka, riswasi, Koreasi, Neboska, riswasi, Koreasi, Dakota of Morre, Yesica, Counties are included heros, once for primary viders and order for pulsars preforants.

Sources: Election results visi The Associated Press; Census Boreau; Dave Late's Attas of U.S. Presidential Elections

MANUAL DISCOVERY TORK THES

Decision Trees

Decision tree representation:

- Each internal node tests an attribute
- Each branch corresponds to attribute value
- Each leaf node assigns a classification

How would we represent as a function of X, Y:

- X AND Y (both must be true)
- X OR Y (either can be true)
- X XOR Y (one and only one is true)

When to Consider Decision Trees

- Instances describable by attribute-value pairs
- Target function is discrete valued
- Disjunctive hypothesis may be required
- Possibly noisy training data

Examples:

- Equipment or medical diagnosis
- Credit risk analysis
- Modeling calendar scheduling preferences

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Vector space classification

Linear Classifiers

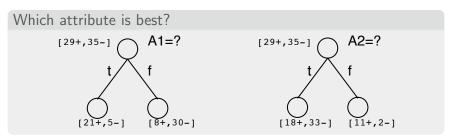
Support Vector Machines

Recap

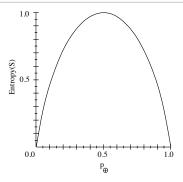
Top-Down Induction of Decision Trees

Main loop:

- 1. $A \leftarrow$ the "best" decision attribute for next *node*
- 2. Assign A as decision attribute for node
- 3. For each value of A, create new descendant of node
- 4. Sort training examples to leaf nodes
- 5. If training examples perfectly classified, Then STOP, Else iterate over new leaf nodes



Entropy: Reminder



- S is a sample of training examples
- p_{\oplus} is the proportion of positive examples in S
- p_{\ominus} is the proportion of negative examples in S
- ullet Entropy measures the impurity of S

$$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$$

Entropy

How spread out is the distribution of S:

$$p_{\oplus}(-\log_2 p_{\oplus}) + p_{\ominus}(-\log_2 p_{\ominus})$$

$$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$$

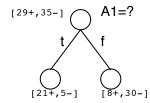
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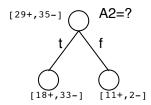
Information Gain

Which feature A would be a more useful rule in our decision tree?

Gain(S, A) = expected reduction in entropy due to sorting on A

$$Gain(S, A) \equiv Entropy(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} Entropy(S_v)$$





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$$H(S) = -\frac{29}{54} \lg \left(\frac{29}{54}\right) - \frac{35}{64} \lg \left(\frac{35}{64}\right)$$

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$$H(S) = -\frac{29}{54} \lg \left(\frac{29}{54}\right) - \frac{35}{64} \lg \left(\frac{35}{64}\right)$$
$$= 0.96$$

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$$Gain(S, A_1) = 0.96 - \frac{26}{64} \left[-\frac{5}{26} \lg \left(\frac{5}{26} \right) - \frac{21}{26} \lg \left(\frac{21}{26} \right) \right]$$
$$-\frac{38}{64} \left[-\frac{8}{38} \lg \left(\frac{8}{38} \right) - \frac{30}{38} \lg \left(\frac{30}{38} \right) \right]$$
$$=$$

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$$= 0.96 - 0.28 - 0.44 = 0.24$$

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$$Gain(S, A_2) = 0.96 - \frac{51}{64} \left[-\frac{18}{51} \lg \left(\frac{18}{51} \right) - \frac{33}{51} \lg \left(\frac{33}{51} \right) \right]$$
$$- \frac{13}{64} \left[-\frac{11}{13} \lg \left(\frac{11}{13} \right) - \frac{2}{13} \lg \left(\frac{2}{13} \right) \right]$$

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$$-\frac{13}{64} \left[-\frac{11}{13} \lg \left(\frac{11}{13} \right) - \frac{2}{13} \lg \left(\frac{2}{13} \right) \right]$$
$$= 0.96 - 0.75 - 0.13 = 0.08$$

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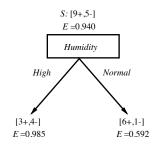
Training Examples

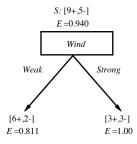
Day	Outlook	Temperature	Humidity	Wind	PlayTennis
D1	Sunny	Hot	High	Weak	No
D2	Sunny	Hot	High	Strong	No
D3	Overcast	Hot	High	Weak	Yes
D4	Rain	Mild	High	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	High	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	High	Strong	Yes
D13	Overcast	Hot	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

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Selecting the Next Attribute

Which attribute is the best classifier?





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ID3 Algorithm

- Start at root, look for best attribute
- Repeat for subtrees at each attribute outcome
- Stop when information gain is below a threshold
- Bias: prefers shorter trees (Occam's Razor)
 - \rightarrow a short hyp that fits data unlikely to be coincidence
 - → a long hyp that fits data might be coincidence
 - Prevents overfitting (more later)

Plan

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Learning Decision Trees

Vector space classification

Linear Classifiers

Support Vector Machines

Recap

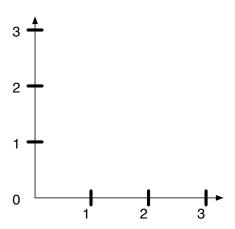
Thinking Geometrically

- Suppose you have two classes: vacations and sports
- Suppose you have four documents

• What does this look like in vector space?

Put the documents in vector space

Travel



Ball

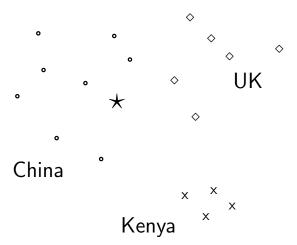
Vector space representation of documents

- Each document is a vector, one component for each term.
- Terms are axes.
- High dimensionality: 10,000s of dimensions and more
- How can we do classification in this space?

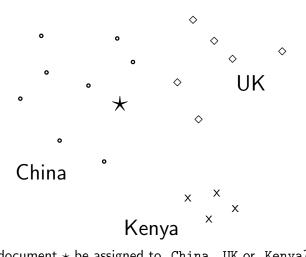
Vector space classification

- As before, the training set is a set of documents, each labeled with its class.
- In vector space classification, this set corresponds to a labeled set of points or vectors in the vector space.
- Premise 1: Documents in the same class form a contiguous region.
- Premise 2: Documents from different classes don't overlap.
- We define lines, surfaces, hypersurfaces to divide regions.

Classes in the vector space

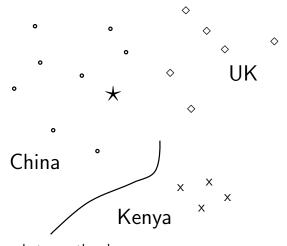


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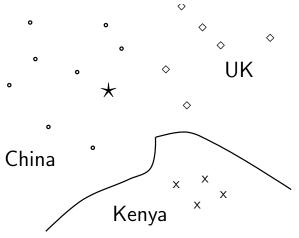
Should the document ★ be assigned to China, UK or Kenya?

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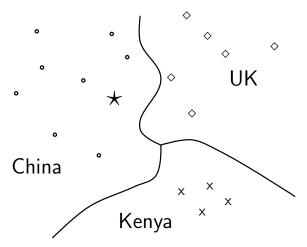
Find separators between the classes

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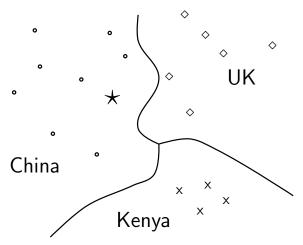
Find separators between the classes

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Based on these separators: ★ should be assigned to China

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How do we find separators that do a good job at classifying new documents like \star ? – Main topic of today

Plan

Linear Classifiers

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Linear classifiers

- Definition:
 - A linear classifier computes a linear combination or weighted sum $\sum_i w_i x_i$ of the feature values.
 - Classification decision: $\sum_i w_i x_i > \theta$?
 - \circ . . . where θ (the threshold) is a parameter.
- (First, we only consider binary classifiers.)
- Geometrically, this corresponds to a line (2D), a plane (3D) or a hyperplane (higher dimensionalities).
- We call this the separator or decision boundary.
- We find the separator based on training set.
- Methods for finding separator: logistic regression, naïve Bayes, linear SVM
- Assumption: The classes are linearly separable.

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- Assumption: The classes are linearly separable.
- Before, we just talked about equations. What's the geometric intuition?



• A linear classifier in 1D is a point x described by the equation $w_1d_1=\theta$

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- A linear classifier in 1D is a point x described by the equation $w_1 d_1 = \theta$
- $x = \theta/w_1$

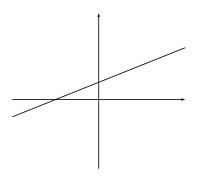
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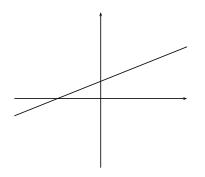
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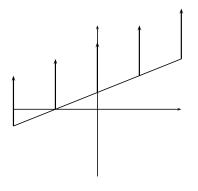
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- Points (d_1) with $w_1d_1 \geq \theta$ are in the class c.
- Points (d_1) with $w_1d_1 < \theta$ are in the complement class \overline{c} .



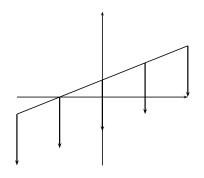
• A linear classifier in 2D is a line described by the equation $w_1d_1 + w_2d_2 = \theta$



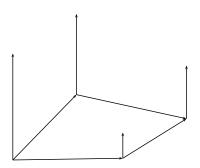
- A linear classifier in 2D is a line described by the equation $w_1d_1 + w_2d_2 = \theta$
- Example for a 2D linear classifier



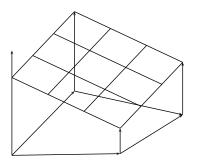
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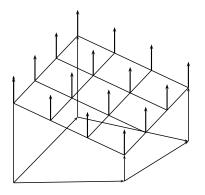
- A linear classifier in 2D is a line described by the equation $w_1 d_1 + w_2 d_2 = \theta$
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- Points $(d_1 \ d_2)$ with $w_1 d_1 + w_2 d_2 > \theta$ are in the class c.
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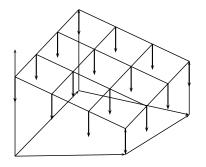
• A linear classifier in 3D is a plane described by the equation $w_1 d_1 + w_2 d_2 + w_3 d_3 = \theta$



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Naive Bayes and Logistic Regression as linear classifiers

Multinomial Naive Bayes is a linear classifier (in log space) defined by:

$$\sum_{i=1}^{M} w_i d_i = \theta$$

where $w_i = \log[\hat{P}(t_i|c)/\hat{P}(t_i|\bar{c})]$, $d_i = \text{number of occurrences of } t_i \text{ in } d$, and $\theta = -\log[\hat{P}(c)/\hat{P}(\bar{c})]$. Here, the index i, $1 \leq i \leq M$, refers to terms of the vocabulary.

Logistic regression is the same (we only put it into the logistic function to turn it into a probability).

Naive Bayes and Logistic Regression as linear classifiers

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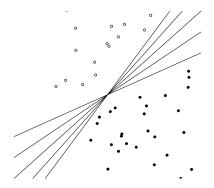
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Takeway

Naïve Bayes, logistic regression and SVM are all linear methods. They choose their hyperplanes based on different objectives: joint likelihood (NB), conditional likelihood (LR), and the margin (SVM).

Which hyperplane?



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Which hyperplane?

- For linearly separable training sets: there are infinitely many separating hyperplanes.
- They all separate the training set perfectly . . .
- ... but they behave differently on test data.
- Error rates on new data are low for some, high for others.
- How do we find a low-error separator?

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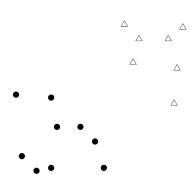
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- Machine-learning research in the last two decades has improved classifier effectiveness.
- New generation of state-of-the-art classifiers: support vector machines (SVMs), boosted decision trees, regularized logistic regression, neural networks, and random forests
- Applications to IR problems, particularly text classification

SVMs: A kind of large-margin classifier

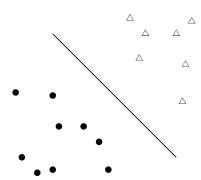
Vector space based machine-learning method aiming to find a decision boundary between two classes that is maximally far from any point in the training data (possibly discounting some points as outliers or noise)

• 2-class training data

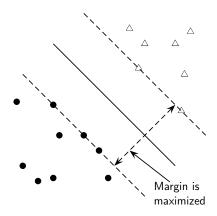


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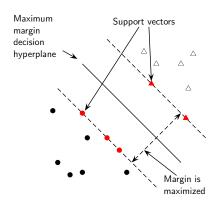
- 2-class training data
- decision boundary → linear separator



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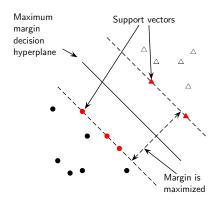


- 2-class training data
- decision boundary → linear separator
- criterion: being maximally far away from any data point → determines classifier margin
- linear separator position defined by support vectors



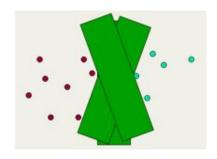
Why maximize the margin?

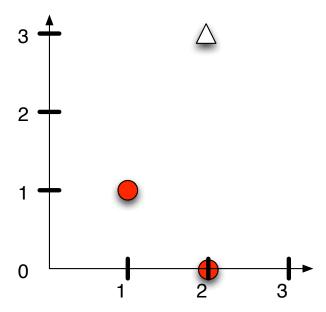
- Points near decision surface → uncertain classification decisions
- A classifier with a large margin is always confident
- Gives classification safety margin (measurement or variation)



Why maximize the margin?

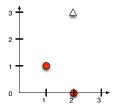
- SVM classifier: large margin around decision boundary
- compare to decision hyperplane: place fat separator between classes
 - unique solution
- decreased memory capacity
- increased ability to correctly generalize to test data





Jordan Boyd-Graber | Boulder Decision Trees and SVMs

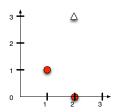
Working geometrically:



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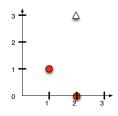
Working geometrically:

• The maximum margin weight vector will be parallel to the shortest line connecting points of the two classes, that is, the line between (1,1) and (2,3), giving a weight vector of (1,2).



Working geometrically:

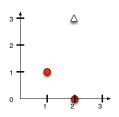
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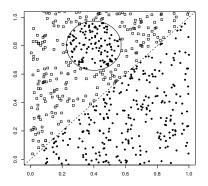
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- The optimal decision surface is orthogonal to that line and intersects it at the halfway point. Therefore, it passes through (1.5, 2).
- The SVM decision boundary is:

$$0 = \frac{1}{2}x + y - \frac{11}{4} \Leftrightarrow 0 = \frac{2}{5}x + \frac{4}{5}y - \frac{11}{5}$$



SVM extensions

- Slack variables: not perfect line
- Kernels: different geometries



Loss functions: Different penalties for getting the answer wrong

Plan

Recap

Jordan Boyd-Graber Boulder

Text classification

- Many commercial applications
- There are many applications of text classification for corporate Intranets, government departments, and Internet publishers.
- Often greater performance gains from exploiting domain-specific text features than from changing from one machine learning method to another. (Homework 2)

When building a text classifier, first question: how much training data is there currently available?

- None?
- Very little?
- A fair amount?
- A huge amount

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When building a text classifier, first question: how much training data is there currently available?

- None? Hand write rules or use active learning
- Very little? Naïve Bayes
- A fair amount? SVM
- A huge amount Doesn't matter, use whatever works

Recap

- Is there a learning method that is optimal for all text classification problems?
- No, because there is a tradeoff between bias and variance.
- Factors to take into account:
 - How much training data is available?
 - How simple/complex is the problem? (linear vs. nonlinear decision boundary)
 - How noisy is the problem?
 - How stable is the problem over time?
 - For an unstable problem, it's better to use a simple and robust classifier.
 - You'll be investigating the role of features in HW2!