



V8后端代码生成：常量池及其实现

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提纲

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 - 常量池产生流程和关键函数
- 一个例子

常量池是什么？

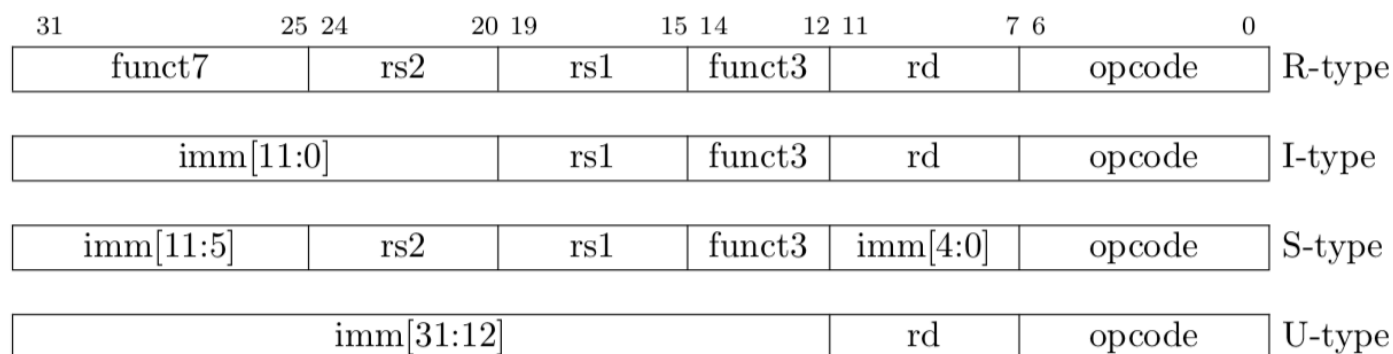
- 在程序指令流中插入的，保存程序编译时和链接时的常量的数据结构
- ARM编译器最先使用了literal pool：
 - ARM的指令只有12bi的立即数域
 - 当指令所需的立即数超过12bit的表示范围时，在每4K边界的范围内，插入一个查找表来保存该立即数，并将程序中的立即数加载指令（LDR Rd, =const）改成PC-relative的load指令
 - 查找表：
 - 输入：PC
 - 输出：立即数
 - 用途一：保存程序所需的编译时常量，避免使用多条指令进行拼接：c=a+0x12345678
 - 用途二：保存程序所需的较大的跳转偏移 jump 0x12345678，这个偏移可能要在链接时才能计算得到

常量池用途

- 用途一：保存程序所需的编译时常量，避免使用多条指令进行拼接：
c=a+0x12345678
 - before：li rd,0x12345678->lui/andi/lsl/andi...
 - after: load rd, offset(pc)
- 用途二：保存程序所需的较大的跳转偏移 jump 0x12345678，这个偏移可能要在链接时才能计算得到
 - before: li rd, 0x12345678, jump rd (位置相关)
 - after: jump offset(pc) (offset和pc可以在链接时决定)

V8的RISCV64后端为什么需要常量池-1

●RISCV指令的立即数域：



●lui : imm20

●auipc : imm20

●load/store : imm12

●addi/slti(u)/xori/ori/andi: imm12

●beq/bne/blt(u)/bge(u): imm12

<https://riscv.org/technical/specifications/>
Volume 1, Unprivileged Spec v. 20191213

V8的RISCV64后端为什么需要常量池-2

伪指令li的几个例子：在64bit地址空间下，大部分li需要4~8条指令

立即数位数	所需的加载指令	数量
imm<12bit	addi rd, x0, imm	1
12bit<imm<32bit	lui rd , imm[31:12] addi rd,x0, imm[11:0]	2
imm>32bit general case with temp register	lui rd , imm[31:12] addi rd,x0, imm[11:0] Lui rtemp, imm[63:42] addi rtemp, rtemp, imm[41:32] slli rtemp.rtemp,32 add rd,rd,rtemp	6

立即数位 数	所需的加载指令	数量
li_constant	<pre> lui(rd, (imm + (1LL << 47) + (1LL << 35) + (1LL << 23) + (1LL << 11)) >>48); // Bits 63:48 addiw(rd, rd, (imm + (1LL << 35) + (1LL << 23) + (1LL << 11)) << 16 >>52); // Bits 47:36 slli(rd, rd, 12); addi(rd, rd, (imm + (1LL << 23) + (1LL << 11)) << 28 >> 52); // Bits 35:24 slli(rd, rd, 12); addi(rd, rd, (imm + (1LL << 11)) << 40 >> 52); // Bits 23:12 slli(rd, rd, 12); addi(rd, rd, imm << 52 >> 52); // Bits 11:0 </pre>	8
li_ptr	<pre> int64_t a6 = imm & 0x3f; // bits 0:5. 6 bits int64_t b11 = (imm >> 6) & 0x7ff; // bits 6:11. 11 bits int64_t high_31 = (imm >> 17) & 0x7fffffff; // 31 bits int64_t high_20 = ((high_31 + 0x800) >> 12); // 19 bits int64_t low_12 = high_31 & 0xfff; // 12 bits lui(rd, (int32_t)high_20); addi(rd, rd, low_12); // 31 bits in rd. slli(rd, rd, 11); // Space for next 11 bis ori(rd, rd, b11); // 11 bits are put in. 42 bit in rd slli(rd, rd, 6); // Space for next 6 bits ori(rd, rd, a6); // 6 bits are put in. 48 bis in rd </pre>	6

V8的RISCV64后端为什么需要常量池-3

- 在32bit定长指令的编码下，立即数编码域是有限的，加载机器指针长度的立即数，需要多条机器指令
- RISCV64这个问题尤其明显：li伪指令大部分情况下需要产生4条以上的机器指令
- 对比：MIPS的立即数域有16bit，可以减少一些指令
- 常量池可以在编译器时将立即数域提前放在指令流中，在使用这个立即数的地方，使用auipc/ld指令来完成常量加载，节省指令，这也是代码重定位的基础

V8常量池涉及的文件和数据结构-1

- 文件

- src/constant-pool.cc/h
- src/codegen/riscv64/assembler-riscv64.cc

- 相关的Class和成员变量

- ConstantPoolKey: 记录Key值, (value32/value64, Reloc mode, pc)
- ConstantPool: std::multipamp<ConstantPoolKey, int> entries;
- Assmebler::ConstantPool constpool_

V8常量池插入的流程:三大步



V8常量池的记录 : RecordEntry: 对li和jr指令记录

```
void TurboAssembler::li(Register rd, Operand j, LiFlags mode) {  
...   int count = li_estimate(j.immediate(), temps.hasAvailable());  
      int reverse_count = li_estimate(~j.immediate(), temps.hasAvailable());  
      if (FLAG_riscv_constant_pool && count >= 4 && reverse_count >= 4) {  
        // Ld a Address from a constant pool.  
        RecordEntry((uint64_t)j.immediate(), j.rmode());  
        auipc(rd, 0);  
        // Record a value into constant pool.  
        ld(rd, rd, 0);  
      } else {...
```

```
void MacroAssembler::JumpToInstructionStream(Address entry) {  
...  
      RecordEntry(entry, RelocInfo::OFF_HEAP_TARGET);  
      RecordRelocInfo(RelocInfo::OFF_HEAP_TARGET, entry);  
      auipc(kOffHeapTrampolineRegister, 0);  
      ld(kOffHeapTrampolineRegister, kOffHeapTrampolineRegister, 0);  
      Jump(kOffHeapTrampolineRegister);  
...}
```

V8常量池插入的检查:

时机：无条件跳转指令之后&编译单元结束之时

check point	routine
TurboAssembler::Jump()	cc_always : ForceConstantPoolEmissionWithoutJump(); EmitConstPoolWithJumpIfNeeded();
TurboAssembler::Ret()	ForceConstantPoolEmissionWithoutJump();
TurboAssembler::Branch()	EmitConstPoolWithJumpIfNeeded();
TurboAssembler::BranchLong()	EmitConstPoolWithJumpIfNeeded();
TurboAssembler::BranchShortHelper()	cc_always: EmitConstPoolWithJumpIfNeeded();
Assembler::GetCode()	ForceConstantPoolEmissionWithoutJump();

V8常量池插入的重点函数 :检查时机例一

TurboAssembler::Jump() && Ret()

```
void TurboAssembler::Jump(Register target, Condition cond, Register rs,
                          const Operand& rt) {
    if (cond == cc_always) {
        jr(target);
        ForceConstantPoolEmissionWithoutJump();
    } else {
        BRANCH_ARGS_CHECK(cond, rs, rt);
        Branch(kInstrSize * 2, NegateCondition(cond), rs, rt);
        jr(target);
    }
}
```

```
void TurboAssembler::Ret(Condition cond, Register rs, const Operand& rt) {
    Jump(ra, cond, rs, rt);
    if (cond == al) {
        ForceConstantPoolEmissionWithoutJump();
    }
}
```

V8常量池插入的重点函数：检查时机例二

Assembler::GetCode()

```
void Assembler::GetCode(Isolate* isolate, CodeDesc* desc,  
                        SafepointTableBuilder* safepoint_table_builder,  
                        int handler_table_offset) {  
    ...  
    ForceConstantPoolEmissionWithoutJump();  
    ...  
}
```

V8常量池插入的重点函数：启动check

```
void ForceConstantPoolEmissionWithoutJump() {  
    constpool_.Check(Emission::kForced, Jump::kOmitted);  
}  
  
void ForceConstantPoolEmissionWithJump() {  
    constpool_.Check(Emission::kForced, Jump::kRequired);  
}  
  
void EmitConstPoolWithJumpIfNeeded(size_t margin = 0) {  
    constpool_.Check(Emission::kIfNeeded, Jump::kRequired, margin);  
}  
  
void EmitConstPoolWithoutJumpIfNeeded(size_t margin = 0) {  
    constpool_.Check(Emission::kIfNeeded, Jump::kOmitted, margin);  
}
```

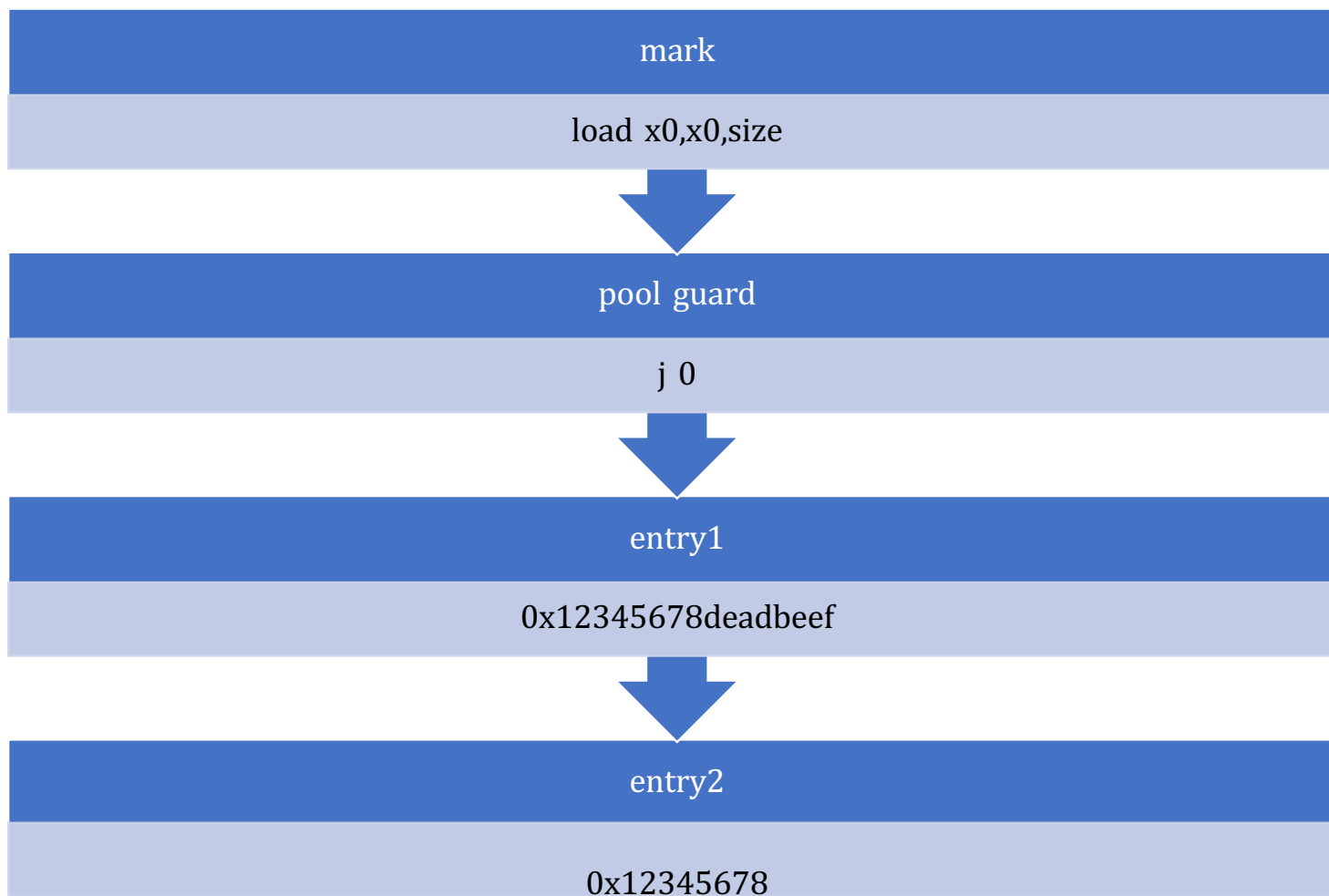
V8常量池插入的重点函数：check是否应该开始Emit

```
void ConstantPool::Check(Emission force_emit, Jump require_jump,
                        size_t margin) {
    if (IsBlocked()) {
        // Something is wrong if emission is forced and blocked at the same time.
        DCHECK_EQ(force_emit, Emission::kIfNeeded);
        return;
    }
    if (!IsEmpty() && (force_emit == Emission::kForced ||
                      ShouldEmitNow(require_jump, margin))) {
        int worst_case_size = ComputeSize(Jump::kRequired, Alignment::kRequired);
        int needed_space = worst_case_size + assem->kGap;
        while (assem->buffer_space() <= needed_space) {
            assem->GrowBuffer();
        }
        EmitAndClear(require_jump);
    }
    SetNextCheckIn(ConstantPool::kCheckInterval);
}
```


V8常量池插入的重点函数：插入常量池

ConstantPool::EmitAndClear()

```
Label after_pool;  
if (require_jump == Jump::kRequired) asm_>b(&after_pool);  
  
asm_>RecordComment("[ Constant Pool");  
EmitPrologue(require_alignment);  
if (require_alignment == Alignment::kRequired) asm_>Align(kInt64Size);  
EmitEntries();  
asm_>RecordComment("]");  
  
if (after_pool.is_linked()) asm_>bind(&after_pool);
```



V8常量池插入的重点函数：EmitEntries

```
void ConstantPool::EmitEntries() {  
    for (auto iter = entries_.begin(); iter != entries_.end(); ) {  
        DCHECK(iter->first.is_value32() || IsAligned(asm_->pc_offset(), 8));  
        auto range = entries_.equal_range(iter->first);  
        bool shared = iter->first.AllowsDeduplication();  
        for (auto it = range.first; it != range.second; ++it) {  
            SetLoadOffsetToConstPoolEntry(it->second, asm_->pc(), it->first);  
            if (!shared) Emit(it->first);  
        }  
        if (shared) Emit(iter->first);  
        iter = range.second;  
    }  
}
```

V8常量池插入的重点函数：Emit

```
void ConstantPool::Emit(const ConstantPoolKey& key) {  
    if (key.is_value32()) {  
        asm->dd(key.value32()); //dump raw double bytes  
    } else {  
        asm->dq(key.value64());// dump raw quad bytes  
    }  
}
```

V8常量池插入的重点函数：SetLoadOffsetToConstPoolEntry

```
void ConstantPool::SetLoadOffsetToConstPoolEntry(int load_offset,
                                                    Instruction* entry_offset,
                                                    const ConstantPoolKey& key) {
    Instr instr_auipc = assm_->instr_at(load_offset);
    Instr instr_ld = assm_->instr_at(load_offset + 4);
    // Instruction to patch must be 'ld rd, offset(rd)' with 'offset == 0'.
    DCHECK(asm_->IsAuipc(instr_auipc));
    DCHECK(asm_->IsLd(instr_ld));
    DCHECK_EQ(asm_->LdOffset(instr_ld), 0);
    DCHECK_EQ(asm_->AuipcOffset(instr_auipc), 0);
    int32_t distance = static_cast<int32_t>(
        reinterpret_cast<Address>(entry_offset) -
        reinterpret_cast<Address>(asm_->toAddress(load_offset)));
    int32_t Hi20 = (((int32_t)distance + 0x800) >> 12);
    int32_t Lo12 = (int32_t)distance << 20 >> 20;
    CHECK(is_int32(distance));
    asm_->instr_at_put(load_offset, SetAuipcOffset(Hi20, instr_auipc));
    asm_->instr_at_put(load_offset + 4, SetLdOffset(Lo12, instr_ld));
}
```



auipc rd, imm20
ld rd, imm12(rd)

V8常量池：一个例子

- ./d9 --print-code --code-comments --riscv-debug ./sunspider/3d-morph.js 2>&1 |tee logcstp.txt
- log内容：

```
[ Constant Pool
0x7f9de4c46154 574 00803003    constant pool begin
(num_const = 8) ;; constant pool #ld x0, 0x8(x0)
0x7f9de4c46158 578 0000006f    constant #jal 0(x0)
0x7f9de4c4615c 57c cccccccc    constant
0x7f9de4c46160 580 f37bebd5    constant
0x7f9de4c46164 584 3fcacee9    constant
0x7f9de4c46168 588 54442d18    constant
0x7f9de4c4616c 58c 400921fb    constant
0x7f9de4c46170 590 ac4258f5    constant
0x7f9de4c46174 594 bfca9cd9    constant
]
```

总结

- 常量池是在程序指令流中插入的，保存程序编译时和链接时的常量的数据结构
- 常量池用于减小代码尺寸和重定位
- RISC-V64指令集的I-type指令只有12bit imm域，汇编li伪指令时，某些立即数需要4条以上机器指令实现，需要使用常量池进行优化
- 目前的V8 RISC-V64后端已经实现了常量池

谢谢

欢迎交流合作

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