IG-500N

Redefine motion limits...

GPS aided Orientation Sensor



The IG-500N is the world smallest GPS enhanced Attitude and Heading Reference System (AHRS). With its embedded Extended Kalman Filter, the IG-500N delivers unmatched precision for attitude and position measurements in very high dynamic conditions.

All in one: the IG-500N

The IG-500N includes a MEMS based Inertial Measurement Unit (IMU), a GPS receiver and a pressure sensor. It provides precise drift-free attitude and position, even in long time turns.

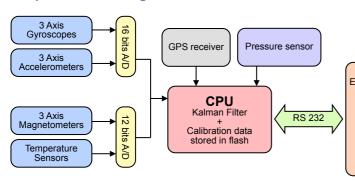
This miniature Inertial Navigation System (INS) runs a real time, on board, Extended Kalman Filter that computes orientation, position and velocity data at high update rates, up to 100 Hz.

The attitude accuracy is also improved, compared to traditional AHRS, by removing transient accelerations measured by the GPS receiver.

Easy and fast integration

SBG Systems has designed a powerful and easy to use Development Kit for this product. In just a few seconds, you can start evaluating and configuring your new device. Integrating the IG-500N in your application is even easier.

Simplified Block Diagram



Key Features

- GPS enhanced 3d velocity, position and orientation at high update rate (100 Hz)
- Accurate attitude even in high G maneuvers
- Precise UTC referenced output
- Embedded 4Hz GPS receiver & barometric sensor
- Wide inertial sensors range options
- Calibrated over full temperature range -40 to 85°C for bias, gain, misalignments, cross-axis and gyro-g
- Advanced and easy to use magnetometers compensation procedure for soft and hard iron
- Communication protocols: RS-232, CAN and USB
- Very compact and lightweight design (44 grams)
- Very low power design down to 550 mW
- Robust and high precision aluminum enclosure

Fields of use

- Unmanned vehicles
- Vehicle motion analysis
- Aerospace
- Robotics

3D Angular rate 3D Acceleration 3D Magnetic field

Marine industry





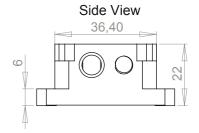
IG-500N

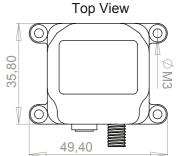
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Technical Specifications

Parameter	Specification			Remarks
Attitude				
Sensing range	360° in all axes			
Static accuracy	± 0.5° (Pitch, Roll) ± 1° (Heading)			Stabilized Kalman Filter Homogenous magnetic field
Dynamic accuracy	± 1.0° RMS			Under good GPS availability
Repeatability	< 0.2°			
Resolution	< 0.05°			
Output frequency	0 to 500 Hz 0 to 100 Hz			Calibrated sensors only Sensors, attitude, velocity, position
Standard Sensors	Accelerometers	Gyroscopes	Magnetometers	
Measurement range	± 5 g	± 300 °/s	± 1.2 Gauss	Refer to sensors options table
Non-linearity	< 0.2% of FS	< 0.1% of FS	< 0.2% of FS	·
Bias stability	± 5 mg	± 0.5 °/s < 0.1 °/s	± 0.5 mGauss	Over temperature range Kalman filter stabilized
Scale factor stability	< 0.1%	< 0.05%	< 0.5%	Over temperature range
Noise density	0.17% 0.25 mg/√Hz	0.05 °/s/√Hz	0.01 mG/√Hz	Over temperature range
Alignment error	< 0.1°	< 0.1°	< 0.1°	
Bandwidth	50 Hz	40 Hz	500 Hz	Additional software filter available
Sampling rate	10 000 Hz	10 000 Hz	1 000 Hz	, additional software filter available
Sampling rate	10 000 112	10 000 112	1 000 112	
GPS Receiver				
Receiver type	L1 frequency, C/	'A Code, 16-Cha	nnels, 4 Hz	
Position accuracy	2.0 meters 2.5 meters 5.0 meters			with SBAS support CEP (Horizontal accuracy) SEP (Vertical accuracy)
Acquisition time	< 3.5 s / 34 s			Hot start / Cold start
Tracking sensitivity	-158 dB			
_				
Pressure Sensor Resolution	6 Do			
Pressure accuracy	6 Pa ± 50 Pa			Relative
•	± 200 Pa			Absolute
Long term stability	100 Pa			Over 12 months
I I a data and a	0.11			
Update rate	9 Hz			
·	9 Hz			
Update rate Communication Output modes		or data,	,	Each output can be enabled or disabled by the user
Communication	Euler angles, Qu 3d velocity, 3d p Calibrated senso	osition, or data, a or TTL 3.3V) to 1 Mbit/s	,	
Communication Output modes	Euler angles, Qu 3d velocity, 3d p Calibrated sens Raw sensor data Serial (RS-232 of CAN 2.04/B up	osition, or data, a or TTL 3.3V) to 1 Mbit/s ded UsbToUart	,	
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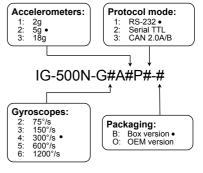
Mechanical drawing





All dimensions are in millimeters

Product code options



standard product options

Rev 1.9 Specifications are subject to change without notice.

