NAO

Programming a humanoid robot

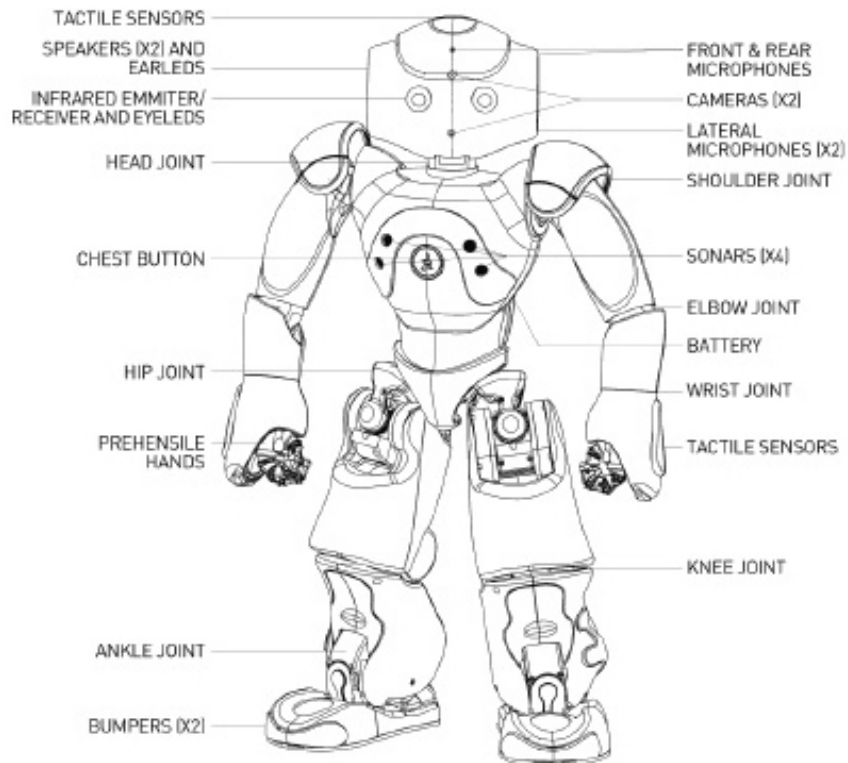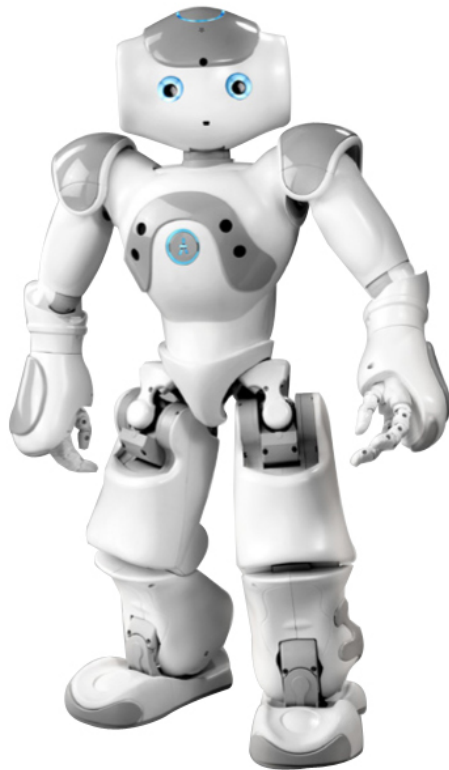# Introducing NAO

- But I'll let him introduce himself!

TACTILE SENSORS
SPEAKERS (X2) AND EARLEDS
INFRARED EMMITER/ RECEIVER AND EYELEDS
HEAD JOINT
CHEST BUTTON
HIP JOINT
PREHENSILE HANDS
ANKLE JOINT
BUMPERS (X2)

FRONT & REAR MICROPHONES
CAMERAS (X2)
LATERAL MICROPHONES (X2)
SHOULDER JOINT
SONARS (X4)
ELBOW JOINT
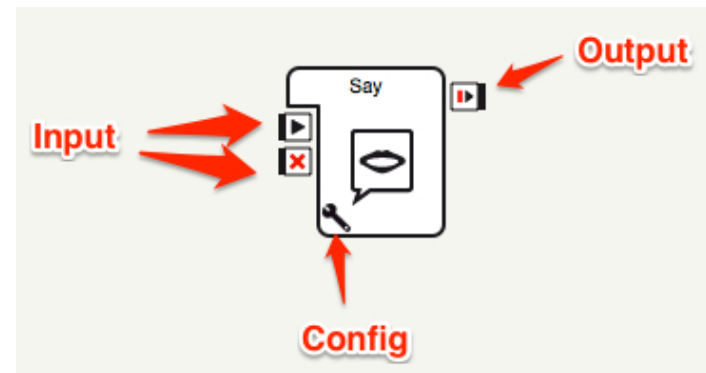BATTERY
WRIST JOINT
TACTILE SENSORS
KNEE JOINT

Choregraphe Software

- ## NAO Visual Programming
  - Allows users of NAO to create and edit simple movements and interactive behaviors.

- ## Demonstration

NAO's Mission

1. Make NAO walk towards you and stop in front of you.

2. NAO asks you to give him the ball and asks you where to put the ball.
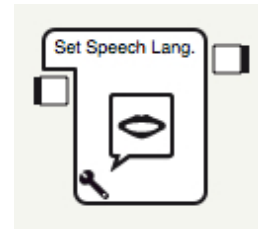
3. NAO looks around and finds the place you identified.

4. NAO goes there, and places the ball down.

Preparation

- Start Choregraphe
- Create a new project
- Load the Library: Devoxx4KIds_NAO_2_X.cbl
- Place and configure boxes
  - Set Speech Language
  - Set Reco. Lang.
  - Tactile Head
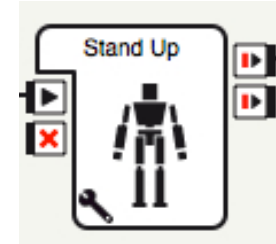

- Connect the boxes to the starting point.
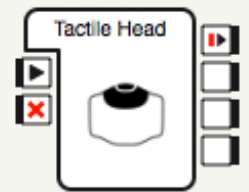
Exercise 1

- Make NAO walk towards you
  - Infrared Sensor (Eyes)
  - Sonar
  - Eye Color

1. Create a new box in the root plane
    1. Change the Name: Walk to Person
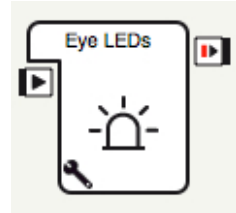   2. Change the Image: move.png
    3. Type: Flow Diagram

Exercise 1 (continued)

2. In the new box Walk to Person
   1. Make NAO stand (Stand Up)
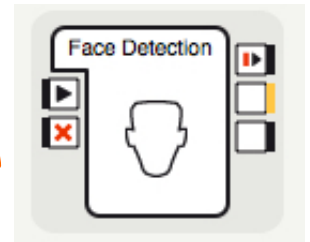   2. LookAround
      1. Green eyes when NAO finds you (Eye Leds)
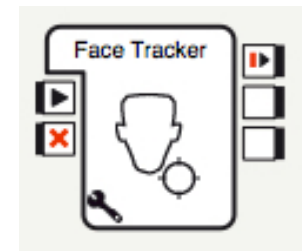   2. Red eyes when he doesn't find you (Eye Leds)
   3. Stop Looking Around upon Face Detection
   4. Use Face Tracker
      1. Edit Param: Mode = "Move"
      2. Stop by itself when target is reached

Exercise 2

- Ask the ball
  - Raise arm and open the hand
  - Make NAO speak
  - Make him understand what you say
    - NAO ask a question with 2 possible answers
  - Lower the arm and close the hand

Exercise 2 (continued)

1. Create a new box in this plane
   1. Change its name (up to you to choose)
   2. Type: Flow Diagram
2. Add 2 outputs
   1. Double-click on the new box
   2. Click on the ▯ (top right)
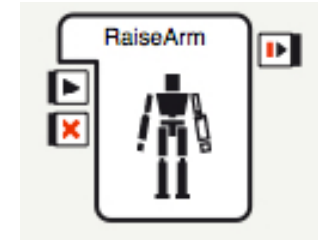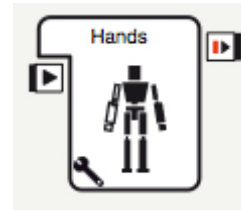   3. Name for output 1 : Chair
   4. Name for output 2: Box

3. Change the color of the eyes

4. Raise NAO's hand (library)

   1. Box : Raise Hand

   2. Box : Hands

      1. Edit Param: Left, Open

5. Make NAO speak with the Say box
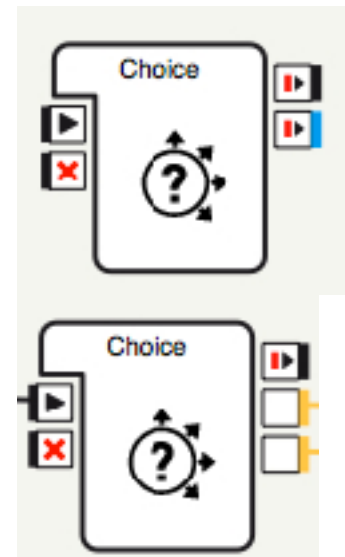
   1. NAO must ask for the ball

Exercise 2 (continued)

6. NAO asks where he should place the ball
   1. Create a nex box
      - Type : Flow Diagram
   2. Add a Choice box
      - Edit the output of the box
        - Rename the output answer into answer1
          » Type : Number : 1
          » Naturel : Punctual
        - Add a second output : answer2
          » Type : Number : 1
          » Naturel : Punctual
      - Double-click on the box to enter the question and the answers
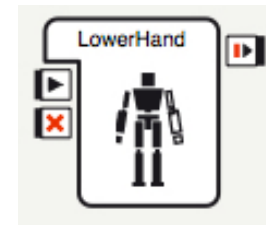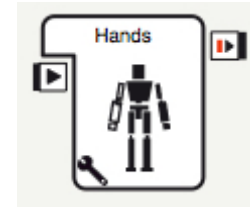   3. Make NAO repeat the answer you gave him

7. NAO lower his arm and close his hand
   - Go back to root plane.
   - Add a Hands box
     - Link both outputs to the box
     - Edit Param: Left, Close
   - Add a LowerHand box

Exercise 3

- NAO looks for the right place where to drop the ball
  - Turns his head
  - Looks for the right NAOMARK
  - Says he found the right place
  - Says he hasn't find the right place

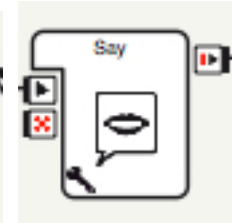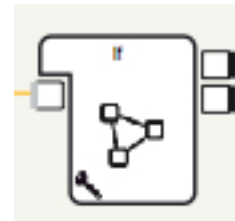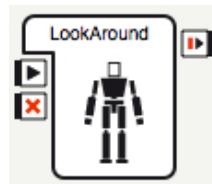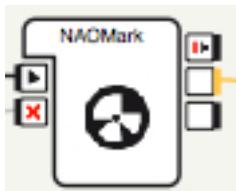1. Create a new box in the main place
    1. Change name : Research
    2. Type: Flow Diagram
2. Add 1 output
    1. Double-click on the new box
    2. Click the (top right corner)
    3. Name for the output : Found

3. In the new box, add:
    1. A NAOMark box
    2. A LookAround box
    3. An IF box
    4. Two Say boxes
    5. Three Wait boxes (Change timeout to 4,000000)

Exercise 3 (continued)

4. Connect the starting input of Research box to:
   1. LookAround
   2. NAOMark
   3. A wait box

5. Make NAO's head look around

6. Connect the NAOMark to the IF box
   1. Configure the IF box :
      1. Condition Operator : =
      2. Value to compare : 68

Exercise 3 (continued)

7. Conect the output output_then of the IF box to the Input :

    1. onStop ▣ of boxes Wait, LookAround
    2. onStart ▣ of a Say box
        1. Use Say box to say that NAO has found a box to drop the ball
        2. Don't forget to make NAO say he hasn't find any box where to drop the ball. It's up to you to find out how to do!

8. Then get back to main plane and do the same thing for the chair (copy/paste + modifications).

Exercise 4

- NAO goes to the required place to drop the ball
  - Walk to the box or the chair using LandMark Tracker
  - Bumper Sensor to avoid collision with box or chair
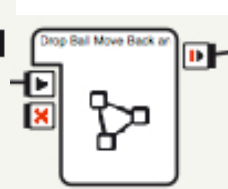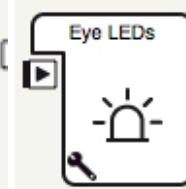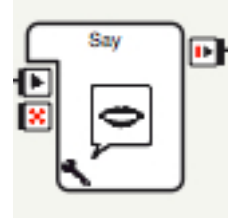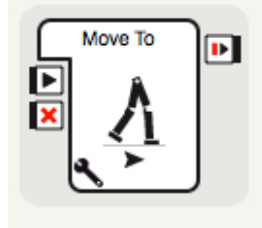 - Drop the ball

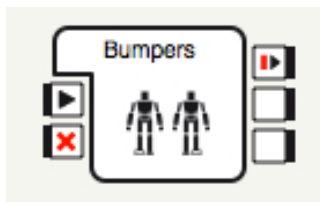# Exercise 4 (continued)

1. Create a new box in root plane:
    1. Edit name: Walk to NAOMark
    2. Type: Flow Diagram

Exercise 4 (continued)

2. In the new box, add:
    1. A LandMarkTracker box
    2. A Bumpers box
    3. A Move To box
    4. A Say box
    5. 2 Wait boxes (Change timeout to 0,500000)
    6. 2 Eye LEDs boxes
    7. A Drop Ball Move Back and Sit box

Exercise 4 (continued)

3. Connect the starting point of Walk to NAOMark box to the input of NAO facing Mark

4. Connect the output of NAO facing Mark àto the input onStart of:
   1. Bumpers :
      1. NAO must walk 2 steps backward
      2. Stop all other boxes
      3. NAO must say he found the place « Im in! »
   2. Mark Walk Tracker
      1. Eyes turn to blue if NAOMark is no longer detected
         1. Output: onLost connected to Input onStop
         2. NAO take a step
         3. NAO must say he has arrived « Im in »
      2. Green eyes if NAOMark is detected

5. In the root plane, add the Drop Ball Move Back and Sit box and connect it to the Walk to NAOMark box