

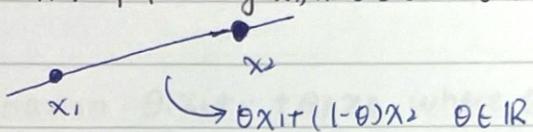
## Chapter 2 Convex Set

### 2.1 Affine and Convex set

#### 2.1.1 Affine

(1) A set is affine: if the line through any 2 distinct points in  $C$  lies in  $C$

i.e. if for any  $x_1, x_2 \in C$  and  $\theta \in \mathbb{R}$ , we have  $\underline{\theta x_1 + (1-\theta)x_2 \in C}$



linear combination of  $x_1, x_2$

(2) Affine Combination: of point  $x_1, x_2, \dots, x_k$  is  $\underline{\theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k}, \theta_1 + \theta_2 + \dots + \theta_k = 1$

(3) Affine Set: contains every affine combination of its points

if  $C$  is an affine set,  $x_1, \dots, x_k \in C$  and  $\sum_i \theta_i = 1$  then the point  $\theta_1 x_1 + \dots + \theta_k x_k \in C$

The solution set of a system of linear equations,  $C = \{x \mid Ax = b\}$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$   
is an affine set

Converse:  $\rightarrow$  affine combination  $\rightarrow$  still in the set

every affine set can be expressed as the solution set of a system of linear equations

(4) Affine Hull of  $C \Rightarrow \text{aff } C$

Affine hull of  $C$  is the smallest affine set that contains  $C$

$$\text{aff } C = \{ \theta_1 x_1 + \dots + \theta_k x_k \mid x_1, \dots, x_k \in C, \theta_1 + \dots + \theta_k = 1 \}$$

(5) Affine Dimension of set  $C$  is the dimension of its affine hull

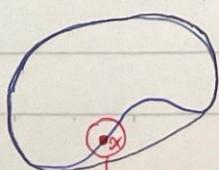
(6) relative interior 相对内部 of set  $C$  ( $\text{relint } C$ )

$$\text{relint } C = \{x \in C \mid B(x, r) \cap \text{aff } C \subseteq C \text{ for some } r > 0\}$$

$$B(x, r) = \{y \mid \|y - x\| \leq r\} \rightarrow \text{ball with radius } r$$

对于 set  $C$  中的一点  $x$ , 如果存在以  $x$  为圆心的任意大小的一个球, 使得该球与 affine set of  $C$  的交集仍在  $C$  中, 则  $x$  为  $C$  的 relative interior

$C$   
 $\text{aff } C$



⇒ 这么画不对. 但表意即可

→ 以  $x$  为圆心的球 (该例子中) 球  $\cap \text{aff } C \neq C$ ,  $x$  不位于  $C$  的 relative interior)

## 2.1.2 Convex

(1) A set is convex: if the line segment between any two points in  $C$  lies in  $C$   
 for any  $x_1, x_2 \in C$ , and any  $\theta \in [0, 1]$ ,  $\theta x_1 + (1-\theta)x_2 \in C$

Every affine set is also convex

(2) convex combination:  $\theta_1x_1 + \dots + \theta_kx_k$ , where  $\theta_1 + \dots + \theta_k = 1$  and  $\theta_i \geq 0, \forall i$

→ 与 affine combination  
 相比新增的条件

A set is convex if and only if it contains every convex combinations of its points  
联系 affine set contains every affine combinations of its points

(3) convex hull of set  $C$ , denoted by conv $C$ , is the set of all convex combinations of points in  $C$

$$\text{conv } C = \{\theta_1x_1 + \dots + \theta_kx_k \mid x_i \in C, \theta_i \geq 0, i=1, 2, \dots, k, \theta_1 + \dots + \theta_k = 1\}$$

→ smallest convex set that contains  $C$

→ convex combination 可认为是 infinite sums (of pdf, ...)

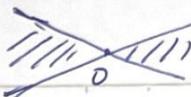
→ if  $x_i \in C$ ,  $C$  is convex,  $C \subseteq \mathbb{R}^n$  then  $\sum_{i=1}^{\infty} \theta_i x_i \in C$  when  $\theta_i \geq 0, \sum_{i=1}^{\infty} \theta_i = 1$

→ 進一步抽象为 integral: if  $p: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $p(x) \geq 0$ ,  $\int p(x) dx = 1$ ,  $x \in C$ ,  $C \subseteq \mathbb{R}^n$  is convex

then  $\int_C p(x) x dx \in C$  is also convex

→ 若样本集合为 convex, 则期望也为 convex

### 2.1.3 Cone / Negative Homogeneous



$\cancel{C}$  是 cone 但非 convex cone

(1) convex cone: If a set  $C$  is convex and cone

if  $\alpha$  for every  $x \in C$  and  $\theta \geq 0$ ,  $\theta x \in C$

for any  $x_1, x_2 \in C$ ,  $\theta_1, \theta_2 \geq 0$ , we have  $\theta_1 x_1 + \theta_2 x_2 \in C$

虽然 convex cone 中有 "convex". 但 convex 定义  $\theta \geq 0$

(2) conic combination:  $\theta_1 x_1 + \dots + \theta_k x_k$ , with  $\theta_1, \dots, \theta_k \geq 0$  且只有  $\theta_i \geq 0$  的条件  
原因在于 cone 导致 if  $x \in C$  then  $\theta x \in C$   $\forall \theta \geq 0$

(3) conic hull: is the set of all conic combinations of points in  $C$

$$\{\theta_1 x_1 + \dots + \theta_k x_k \mid x_i \in C, \theta_i \geq 0, i=1, \dots, k\}$$

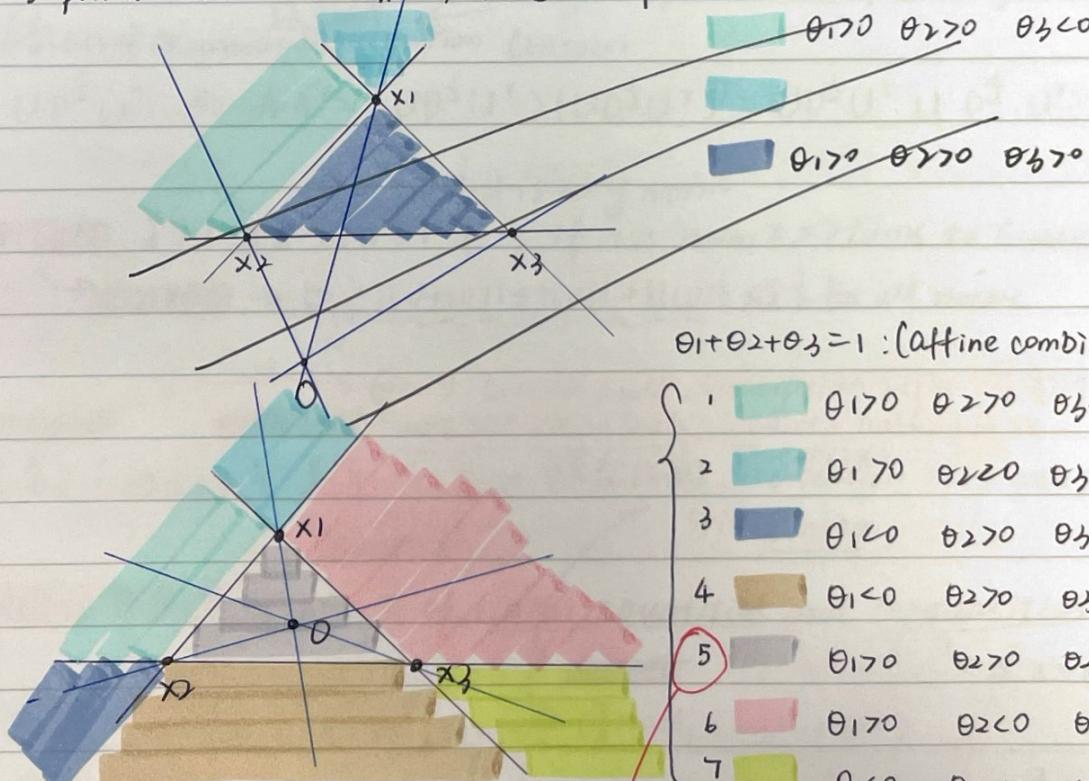
$$\theta_1 = \theta'_1 \cdot \theta_1' \quad \theta_2 = \theta'_2 \cdot \theta_2'$$

$$\text{with } \theta'_1 + \theta'_2 = 1$$

$$\begin{aligned} \theta_1 x_1 + \theta_2 x_2 &= \theta'_1 (\theta_1'' x_1) + \\ &\quad \theta'_2 (\theta_2'' x_2) \\ &= \theta'_1 x_1 + \theta'_2 x_2 \end{aligned}$$

类似 affine combination. convex combination and conic combination

consider 3 points  $x_1, x_2, x_3 \in \mathbb{R}^n$ , 如何理解  $x = \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3$  ?

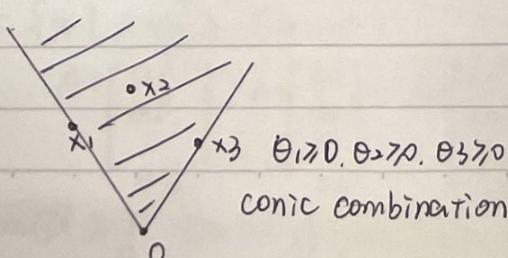


$\theta_1 + \theta_2 + \theta_3 = 1$  : (affine combination)

1	$\theta_1 > 0$	$\theta_2 > 0$	$\theta_3 < 0$	++-
2	$\theta_1 > 0$	$\theta_2 < 0$	$\theta_3 < 0$	+--
3	$\theta_1 < 0$	$\theta_2 > 0$	$\theta_3 < 0$	-+-
4	$\theta_1 < 0$	$\theta_2 > 0$	$\theta_3 > 0$	-++
5	$\theta_1 > 0$	$\theta_2 > 0$	$\theta_3 > 0$	+++
6	$\theta_1 > 0$	$\theta_2 < 0$	$\theta_3 > 0$	+--
7	$\theta_1 < 0$	$\theta_2 < 0$	$\theta_3 > 0$	--+

共 7 种情况. avoid  $\theta_1, \theta_2, \theta_3 < 0$

$\theta_1 + \theta_2 + \theta_3 = 1$  且  $\theta_1 \geq 0, \theta_2 \geq 0, \theta_3 \geq 0$  (convex combination)



## 2.2 Some Important Examples

(1) Hyperplane convex, affine

(2) Halfspace convex but not affine

(3) (Euclidean) Ball in  $\mathbb{R}^n$  convex  $\rightarrow$  由  $\|x\|_2 \leq \|v\| + \|w\| \leq \|v\| + \|w\|$  之證明

$$B(x_0, r) = \{x \mid \|x - x_0\|_2 \leq r\} = \{x \mid (x - x_0)^T(x - x_0) \leq r^2\}$$

$$= \{x_0 + ru \mid \|u\|_2 \leq 1\}$$

(4) Ellipsoids

$E = \{x \mid (x - x_0)^T P^{-1}(x - x_0) \leq 1\}$ ,  $P \in S_{++}^n$  symmetric positive definite  
 $= \{x_0 + Au \mid \|u\|_2 \leq 1\}$  determines how far the ellipsoid extends

$\hookrightarrow$  可推导得  $P = AAT$  例  $A = P^{\frac{1}{2}}$  in every direction from  $x_0$

$\forall P \in S_{++}^n$  is  $P = UDU^T$  where  $D$  is 对角 lengths of semi-axes of  $E$  are given by  $\sqrt{d_i}$  eigenvalues  
 有关于 ML 中 Gaussian Distribution Contour

$$\therefore P^{\frac{1}{2}} = U D^{\frac{1}{2}} U^T \Rightarrow A \cdot A^T = (UD^{\frac{1}{2}}U^T)(UD^{\frac{1}{2}}U^T)^T = UD^{\frac{1}{2}}U^T \cdot U \cdot D^{\frac{1}{2}} \cdot U^T = UDU^T = P$$

(5) norm ball  $\{x \mid \|x - x_0\| \leq r\}$  if it is norm 2  $\Rightarrow$  turns to Euclidean Ball  
 $\hookrightarrow$  convex  $\rightarrow$   $\|v + w\| \leq \|v\| + \|w\|$  之 for all norms

(6) norm cone convex finite set  $\{v_1, \dots, v_k\}$  is convex hull of  $V$   
 $C = \{(x) \mid \|x\| \leq t\}$  为所有向量的  $\hookrightarrow$  intersection of convex sets is convex  
 $\hookrightarrow$  still convex

(7) Polyhedra 多面体: finite # of linear equalities and inequalities

form ①  $P = \{x \mid a_j^T x \leq b_j, j=1, \dots, m, c_j^T x = d_j, j=1, \dots, p\}$   $\hookrightarrow a_i^T x \leq b_i$  (halfspace)

form ②  $P = \{x \mid Ax \leq b, Cx = d\}$   $\hookrightarrow$  as intersection of a finite # of hyperplanes and halfspaces

$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{bmatrix}, b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}, C = \begin{bmatrix} c_1^T \\ c_2^T \\ \vdots \\ c_p^T \end{bmatrix}, d = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_p \end{bmatrix} \rightarrow$$

vector inequality in  $\mathbb{R}^m$

$$\vec{v} \leq \vec{u} \text{ if } v_i \leq u_i \text{ for } i=1, \dots, m$$

form ③: 由  $Cx = d$  可写成  $\{Cx \leq d\}$   $\Rightarrow P = \{x \mid Ax \leq b\}$

No. if  $x \in S_+^n$  then  $x = UDU^T$ .  $D$  is a diagonal matrix. can be written as  $D = D^{\frac{1}{2}} \cdot D^{\frac{1}{2}}$

$$\hookrightarrow x = UD^{\frac{1}{2}} D^{\frac{1}{2}} U^T = (UD^{\frac{1}{2}} U^T)(UD^{\frac{1}{2}} U^T)^T = UD^{\frac{1}{2}} U^T U \cdot D^{\frac{1}{2}} U^T U^T = UD^{\frac{1}{2}} U^T = x$$

总结. if  $x \in S_+^n$  (即  $x$  经常转换为  $Z^T Z$  的形式, 其中  $Z = D^{\frac{1}{2}} U$  由于  $D$  是 diagonal)

进一步讲.  $Z^T Z = \langle Z, Z \rangle = \|Z\|^2$  经常与 ball 和 贝壳 set 连系在一起

非负限 nonnegative orthant  $\mathbb{R}_+^n = \{x \in \mathbb{R}^n \mid x_i \geq 0, i=1, \dots, n\} = \{x \in \mathbb{R}^n \mid x \succeq 0\}$  is polyhedron and a cone (a polyhedron cone)

(8) Simplexes  $\rightarrow$  a special polyhedra  $\Rightarrow$  convex

If  $k+1$  points  $v_0, v_1, \dots, v_k \in \mathbb{R}^n$  are affinely independent, which means  $v_1 - v_0, \dots, v_k - v_0$  are linearly independent

Simplexes  $C = \text{conv}\{v_0, \dots, v_k\} = \{y = \theta_0 v_0 + \dots + \theta_k v_k \mid \theta_i \geq 0, i=0, \dots, k, \sum_{i=0}^k \theta_i = 1\}$

$$= \text{conv}\{v_0, \dots, v_k\} = \{y = \theta_0 v_0 + \dots + \theta_k v_k \mid \theta \succeq 0, \sum \theta = 1\}$$

$\hookrightarrow$  convex hull

$\hookrightarrow$  vector with all entries one.

the convex hull of  $k+1$  affinely independent points

$\hookrightarrow k$  is the affine dimension of this simplexes

1-D Simplex: a line segment

①  $\succeq$  for vector is vector inequality

2-D Simplexes: a triangle

$\hookrightarrow$  vector 中每个元素之间比较

3-D Simplexes: a tetrahedron 四面体

②  $\succeq$  for symmetric matrix

$A \succeq 0$  表示 matrix  $A$  半正定

(9) Symmetric matrix  $S^n = \{x \in \mathbb{R}^{n \times n} \mid x = x^T\}$  即  $H\bar{x}$ ,  $x^T A x \geq 0$

$\hookrightarrow$  a vector space with dimension  $\frac{n(n+1)}{2}$

③  $\succeq$  for symmetric matrix

$\rightarrow$  矩阵  $x \succeq 0$  是什么意思  $\rightarrow$  已解决

Symmetric Positive Semidefinite matrices:  $S_+^n = \{x \in S^n \mid x \succeq 0\}$

$\hookrightarrow$  convex cone

$\hookrightarrow$   $Z^T X Z \geq 0$  for all  $Z$

$\hookrightarrow$  if  $A, B \in S_+^n, \theta_1, \theta_2 \geq 0 \Rightarrow \theta_1 A + \theta_2 B \in S_+^n$   $\rightarrow$  有理的思路

Symmetric Positive Definite matrices:  $S_{++}^n = \{x \in S^n \mid x > 0\}$  即 halfspaces  $\rightarrow$  convex

$Hx \neq 0 \quad x^T X x > 0$

同理正定矩阵  
eigenvalues  $> 0$

for  $n=2$   $S_+^2 = \begin{bmatrix} x & y \\ y & z \end{bmatrix} \Leftrightarrow x > 0, z > 0, xz - y^2 \geq 0$

推论: if  $A \succeq 0 \Rightarrow A$  的特征值非负

$$A = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$$

$$|A - \lambda I| = \begin{vmatrix} x - \lambda & y \\ y & z - \lambda \end{vmatrix} = (x - \lambda)(z - \lambda) - y^2$$

$\hookrightarrow$  for  $a\bar{x}^2 + b\bar{x} + c > 0$ . 在点  $x = \frac{-b}{2a}$  处

$\hookrightarrow$  在点  $\frac{x+z}{2}$  处  $> 0 \Rightarrow$  只要保证  $\lambda>0$  处该二次方程非负

$\lambda>0$  时  $LHS = xz - y^2 \Rightarrow$  if  $xz - y^2 \geq 0$ ,  $\begin{bmatrix} x & y \\ y & z \end{bmatrix}$  特征值非负  $\Rightarrow A \succeq 0$

## 2.3 Operations that preserve convexity

### (1) Intersection:

Convexity is preserved under intersection: if  $S_1$  and  $S_2$  are convex, then  $S_1 \cap S_2$  is convex.

Converse: Every closed convex set  $S$  is a (usually infinite) intersection of halfspaces.

### (2) Affine Mapping

A A function is affine:  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is affine if it is a sum of a linear function and a constant, i.e. if it has the form  $f(x) = Ax + b$ , where  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ .

$\Delta$  if  $S_1 \xrightarrow{f_1(x)} \{x\} \xrightarrow{f_2(\cdot)} S_2$   $f_1(\cdot)$  and  $f_2(\cdot)$  are affine functions

Affine mapping  $\Rightarrow$  ① if  $\{x\}$  is convex, then  $S_2 = f_2(x)$  is convex

$x \xrightarrow{f_2(\cdot)} S_2$ :  $S_2$  is the image of  $x$  under  $f_2(\cdot)$

即  $S_2 = f_2^{-1}(x)$  但描述

② if  $\{x\}$  is convex, then  $S_1 = f_1^{-1}(x)$  is convex

$\{S_1 \xrightarrow{f_1(\cdot)} x : S_1$  is the inverse image of  $x$  under  $f_1(\cdot)$

时写成 inverse image

of  $x$  under  $f_1(\cdot)$

没有  $\ominus$

→ 跟踪如果想检测一个集合  $\{x\}$  是否是 convex.

方法① 构造 affine function  $f_1(\cdot)$  使得  $S_1 = f_1(S_1) = x$  且  $S_1$  是 convex

方法② 构造 affine function  $f_2(\cdot)$  使得  $f_2(x) = S_2$  且  $S_2$  是 convex

Example:  $\{x | x_1 A_1 + x_2 A_2 + \dots + x_n A_n \leq B\}$   $\Leftarrow b, A_i \in \mathbb{R}^m, x \in \mathbb{R}^n$

想法1:  $x_1 A_1 + \dots + x_n A_n \leq B \Leftarrow a^T x = a_1 x_1 + \dots + a_n x_n \leq b$  类似

for convenience  $\hookrightarrow$  linear matrix inequality  $\hookrightarrow$  linear inequality of  $x$   
 $\hookrightarrow$   $A(x) \leq B$  of  $x$  (LMI of  $x$ )

而  $\{x | a^T x \leq b\}$  可看成 halfspaces 的交集.  $\because$  halfspace is convex  
 $\therefore \{x | a^T x \leq b\}$  is convex

同理:  $\{x | A_1 x_1 + \dots + A_n x_n \leq B\}$  is convex

想法2: 构造  $S$  convex set  $S'$  与 affine function  $f(\cdot)$  使得  $f(x) = S$  且  $f(S) = x$

想法: 有  $x$ . 已知  $A(x) \leq B$ . 如何构造  $f(\cdot)$  与 convex set  $S$ ?

$A(x) \leq B \Rightarrow B - A(x) \geq 0 \Rightarrow B - A(x) \in \mathbb{R}_+^m$ .  $\mathbb{R}_+^m$  is convex. 且  $f(x) = B - A(x)$

$\therefore \{x | A(x) \leq B\}$  可看成 the inverse image of the positive is affine function

semidefinite cone under the affine function  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  given by  
 $f(x) = B - A(x)$

### (3) Linear fractional and perspective functions.

Perspective function:  $P: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$   $P(x, t) = \frac{x}{t}$   $\text{dom } P = \{(x, t) \mid t > 0\}$

① if  $C \subseteq \text{dom } P$  is convex, then its  $\overline{\text{image}}$  is convex  $\Rightarrow P(C) = \{P(x) \mid x \in C\} = \mathbb{R}^n \times \mathbb{R}_+$

Physical perspective function: 看着 pin-hole camera. (in  $\mathbb{R}^3$ ) viewed through a pin-hole

An objective  $x$  at  $(x_1, x_2, x_3)$

camera, yields a line segment image

$$x_3 = 0$$

$$x' = \left( -\frac{x_1}{x_3}, -\frac{x_2}{x_3}, -1 \right) \quad x_3 = -1 \text{ (horizontal image plane)}$$

$$= \left( -\frac{x_1}{x_3}, \frac{x_2}{x_3}, 1 \right)$$

if we drop the last component (cause it is always -1)  
then the image of a point  $x$  appears at  $x' = -P(x)$

② The inverse image of a convex set under the perspective function is also convex.

if  $C \subseteq \mathbb{R}^n$  is convex, then  $P^{-1}(C) = \{(x, t) \in \mathbb{R}^{n+1} \mid \frac{x}{t} \in C, t > 0\}$

Linear fractional function: composing a perspective function with an affine function  
suppose affine function  $g: \mathbb{R}^m \rightarrow \mathbb{R}^{m+1}$ :

$$g(x) = \begin{bmatrix} A \\ c^T \end{bmatrix} x + \begin{bmatrix} b \\ d \end{bmatrix} \quad A \in \mathbb{R}^{m \times n}, c \in \mathbb{R}^n, b \in \mathbb{R}^m, d \in \mathbb{R}$$

function  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  given  $f = P \circ g$ , i.e.

$$f(x) = \frac{Ax + b}{c^T x + d} \quad \text{dom } f = \{x \mid c^T x + d > 0\} \text{ is linear-fractional}$$

$f(x)$  相当于先对  $x \in \mathbb{R}^n$  做 affine function  $g$ , 得到  $g(x) \in \mathbb{R}^{m+1}$ . function

再对  $g(x)$  做 perspective function, 得到  $f(x) \in \mathbb{R}^m$

$$\begin{array}{ccc} x & \xrightarrow{g} & g(x) & \xrightarrow{P} & f(x) \\ \mathbb{R}^n & & \mathbb{R}^{m+1} & & \mathbb{R}^m \end{array} \Rightarrow f: P \circ g$$

if  $x$  is convex  $\Leftrightarrow g(x)$  is convex (affine mapping)  $\Rightarrow f(x)$  is convex (perspective function preserves convexity)

## 2.4 Generalized inequality

(1) proper cone  $\rightarrow$  Example  $R^2$   $S^n_+$   
 for  $\forall x_1, x_2 \in C$ ,  $\theta_1, \theta_2 \geq 0$ , we have  $\theta_1 x_1 + \theta_2 x_2 \in C$

A convex cone  $K \subseteq R^n$  is called a proper cone if

- $K$  is convex
- $K$  is closed
- $K$  is solid (has no nonempty interior int( $S$ ))
- $K$  is pointed (has no line)  $\rightarrow$  not all cones have no line  
counter example: halfspace.

## (2) Generalize Inequality

A proper cone  $K$  is used to define a generalize inequality.

$$x \leq_K y \iff y - x \in K$$

$$(Ex \quad y \geq_K x)$$

strict partial ordering:  $x <_K y \iff y - x \in \text{int } K$

$\hookrightarrow$  two vectors  $x, y \in R^n$  if  $x \leq_K y$ ,  $K = R^2_+$  which means  $x_i \leq y_i \Rightarrow$  componentwise inequality  
 $\hookrightarrow$  usually drop the subscript  $R^2_+$  when symbol  $\leq$  or  $<$  appears between vectors

Matrix inequality  $X \leq_K Y$ ,  $K = S^n_+ \iff Y - X \in S^n_+$  is positive <sup>semi</sup>definite

$\hookrightarrow X$  is positive semidefinite if is written by  $X \geq 0$

$\hookrightarrow$  drop the subscript  $S^n_+$  for matrix inequality

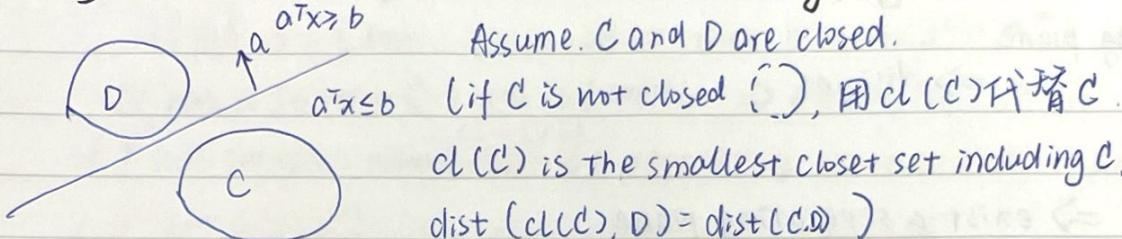
注意：没有closed的条件

## 2.5 Separating and supporting hyperplanes

条件 ① 条件 ② 条件 ③

(1) Separating hyperplane theorem: suppose  $C$  and  $D$  are nonempty disjoint convex sets, i.e.  $C \cap D = \emptyset$ , then there exist  $a \neq 0$  and  $b$ , such that  $a^T x \leq b$  for all  $x \in C$  and  $a^T x \geq b$  for all  $x \in D$ .

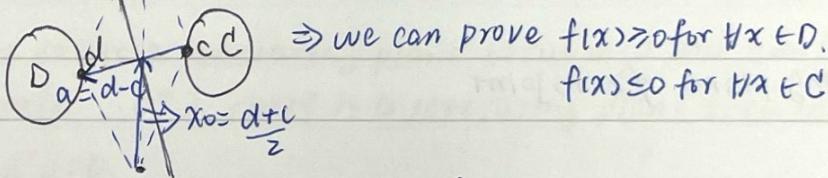
The hyperplane  $\{x \mid a^T x = b\}$  is called a separating hyperplane for the sets  $C$  and  $D$ .



① 证  $\text{dist}(C, D) = \inf \{ \|u - v\|_2 \mid u \in C, v \in D\} > 0$

可找到 a point  $c \in C$ ,  $d \in D$  such that  $\frac{\|c-d\|_2}{2} = \text{dist}(C, D)$

$\Rightarrow \|a = d - c\|_2 = \frac{1}{2}\|d - c\|_2$



hyperplane:  $f(x) = \frac{a}{\|a\|_2} (x - x_0)$

△ Separating of an affine and a convex set.

if  $D = \{f_u + g \mid u \in R^m\}$   $\Rightarrow$  there exist  $a \neq 0$  and  $b$  such that  $a^T x \geq b$  for all  $x \in D$   
 $\hookrightarrow a^T f_u \geq b - a^T g$  for all  $u \in R^m$

linear function is bounded  $\Rightarrow a^T F = 0$  &  $b \leq a^T g$

(2) strict separation

if  ~~$a^T x \leq b$~~   $a^T x < b$  for all  $x \in C$ ,  $a^T x > b$  for all  $x \in D \Rightarrow$  strict separation of set  $C$  and  $D$

$\hookrightarrow$  a point  $x_0 \notin C$  and a closed convex set  $C$  can be strictly separated.

可构造一个球  $B(x_0, \epsilon) = \{x_0 + u \mid \|u\|_2 \leq \epsilon\}$ , 寻找  $C$  与  $B$  之间的一个 separating hyperplane

$\hookrightarrow a^T(x_0 + u) \geq b$  for all  $\|u\|_2 \leq \epsilon \Rightarrow$  the  $u$  that minimize the LHS is  $u = \frac{-\epsilon a}{\|a\|_2}$

$\hookrightarrow$  affine function  $f(x) = a^T x - b - \epsilon \frac{\|a\|_2}{2}$  is positive on  $x_0$  and negative on  $C$

$\hookrightarrow$  A closest convex set is the intersection of all halfspaces that contain it.  $\frac{a^T(x+u)}{\|a\|_2}$

let  $C$  is a closest convex set.  $S$  is the intersection of all halfspaces that contain it.  $= a^T x - \epsilon \|a\|_2 \geq b$

that contain  $C \Rightarrow \langle pf \rangle C = S$

① Obviously if  $x \in C \Rightarrow x \in S$

② show if  $x \in S$  then  $x \in C$  suppose there exist  $x \in S, x \notin C$ .

由 the strict separation result, there exist a hyperplane that strictly separates  $x$  from  $C$   
 $\Rightarrow x \notin S$

## (3) Converse separating hyperplane theorems.

Converse of separating hyperplane theorem: if there exist a <sup>separating</sup> hyperplane then  $C, D$  are disjoint  $\rightarrow$  is not true!

$\hookrightarrow$  Add additional condition: Any 2 convex sets  $C$  and  $D$ , at least one of which is open, are disjoint if and only if there exist a separating plane.

$$\left\{ \begin{array}{l} \text{exist separating plane} \\ \text{convex sets} \\ \text{one is open} \end{array} \right. \Rightarrow \text{disjoint}$$

$$\left\{ \begin{array}{l} \text{disjoint} \\ \text{convex} \\ \text{one is open} \end{array} \right. \Rightarrow \text{exist a separating plane}$$

$$\left\{ \begin{array}{l} \text{disjoint} \\ \text{convex} \\ \text{nonempty} \end{array} \right. \Rightarrow \text{exist a separating plane}$$

exist a separating plane  $\nrightarrow$  disjoint

## (4) Supporting Hyperplane

for any <sup>条件①</sup> nonempty <sup>条件②</sup> convex set  $C$  and any  $x_0 \in \text{bd}(C)$ , there exists a supporting hyperplane to  $C$  at  $x_0$

$$\text{if } \overset{\circ}{C} \Rightarrow \text{bd}(C): \quad \text{bd}(C) \subseteq C \text{ 不成立}$$

$\hookrightarrow$  Partial converse of supporting plane theorem:

if a set is closed and has nonempty interior, and has a supporting hyperplane at every point in its boundary, then it is convex

$$\left\{ \begin{array}{l} \text{nonempty} \\ \text{convex} \\ x_0 \in \text{bd}(C) \end{array} \right. \Rightarrow \text{supporting plane from } x_0 \text{ and } C$$

$$\left\{ \begin{array}{l} \text{closed } C \\ \text{nonempty } \text{int}(C) \\ \text{Supporting plane exist } \forall x_0 \in \text{bd}(C) \end{array} \right. \Rightarrow \text{convex}$$

$\hookrightarrow$  闭包: intersection of supporting halfspaces.

## 2.6 Gordan Theorem & Farkas Theorem

### (1) Gordan Theorem

For any  $a^1, a^2, \dots, a^m \in \mathbb{R}^n$ , exactly one of the following systems has a solution

$$\textcircled{1} \quad \sum_{i=1}^m \lambda_i a_i = 0, \quad \sum_{i=1}^m \lambda_i = 1, \quad 0 \leq \lambda_1, \dots, \lambda_m \in \mathbb{R}$$

$$\textcircled{2} \quad a^i{}^T x < 0 \text{ for } i=1, \dots, m$$

If  $\textcircled{1}$  has solution  $\Leftrightarrow 0 \in \text{conv}(a^1, \dots, a^m)$

证明  $x = \sum \lambda_i a_i$ ,  $\sum \lambda_i = 1$ ,  $\lambda_i \geq 0$ , then  $x \in \text{conv}(a^1, \dots, a^m)$

$\textcircled{1}$  has a solution  $\Leftrightarrow x \geq 0$  is feasible  $\Rightarrow 0 \in \text{conv}(a^1, \dots, a^m)$

If  $\textcircled{2}$  has solution  $\Leftrightarrow$  there is a separating plane between  $0$  and  $\text{conv}(a^1, \dots, a^m)$

$\begin{cases} a^i{}^T x < 0 \\ a^i{}^T 0 = 0 \end{cases} \Rightarrow$  there exists a separating plane between

if  $\textcircled{2}$  has a solution  $x \Rightarrow$  can find a  $x$  such that  $a^i{}^T x < 0$

if  $0 \in \text{conv}(a^1, \dots, a^m)$  then  $a = \sum \theta_i a_i$ , we have  $a^i{}^T a > 0$ .

$$x^T a = a^T x = \sum \theta_i (a^i{}^T x) < 0 \text{ and } x^T 0 = 0$$

$\hookrightarrow$  means there exists a separating plane between  $0$  and  $\text{conv}(a^1, \dots, a^m)$

同样 if  $a \in \text{conv}(a^1, \dots, a^m)$ , there is a separating plane between  $0$  and  $\text{conv}(a)$

$\hookrightarrow$  we have  $\forall \lambda^T 0 = 0$

$$\lambda^T a \leq 0 \Rightarrow \lambda^T (\sum \theta_i a_i) \leq 0 \Rightarrow \sum \theta_i (\lambda^T a_i) \leq 0 \quad \text{且 } \sum \theta_i = 1$$

前到结果地有解 system  $\textcircled{2}$  没有对  $0$  有解  $\Rightarrow \lambda^T a_i \leq 0$

从, 怎么得到与  $\text{conv}(a)$  有关的解?  $\Rightarrow \forall a^i \in \text{conv}(a)$  has a solution

If  $\textcircled{2}$  has a solution  $\Rightarrow$  can find a  $x$  such that  $a^i{}^T x < 0$

$$\Rightarrow \sum \theta_i a^i{}^T x < 0 \quad \forall \theta_i \geq 0 \text{ 且 } \theta_i \neq 0$$

$$\Rightarrow x^T (\sum \theta_i a_i) < 0 \quad \forall \theta_i \geq 0 \text{ 且 } \theta_i \neq 0 \rightarrow \text{cone 要求 } \theta_i > 0 \text{ 且 cone 一定包含 } 0$$

$$\text{let } a = \sum \theta_i a_i, \theta_i > 0. \text{ we have } x^T a < 0, x^T 0 = 0$$

$\Rightarrow$  由  $\textcircled{2}$  有解的条件, 可推出  $0$  与  $\{\sum \theta_i a_i \mid \theta_i > 0\}$  之间存在一个 separating plane.

$\hookrightarrow$  即既非  $\text{conv}(a)$  也非  $\text{conic hull of } a$

由  $\text{conv}(a) \subseteq \{ \sum \theta_i a_i \mid \theta_i \geq 0 \}$   $\text{conv}(a) \subseteq \{ \sum \theta_i a_i \mid \theta_i \geq 0 \text{ 且 } \theta_i \neq 0 \}$

所以由  $\textcircled{2}$  有解也可以推出 There exists a separating plane between  $0$  and  $\text{conv}(a)$

同样由 (b) 也可以推出 (a).

所以 (a)  $\Leftrightarrow$  (b)

## (2) Farkas Lemma

for any  $a^1, \dots, a^m$  and  $c \in \mathbb{R}^n$  exactly one of the following systems has a solution:

$$\textcircled{1} \quad \sum_{i=1}^m \lambda_i a_i = c, \quad 0 \leq \lambda_i,$$

$$\textcircled{2} \quad (a^i)^T x \leq 0 \text{ for } i=1, \dots, m, \quad c^T x > 0, \quad x \in \mathbb{R}^n$$

注意.  $\sum_{i=1}^m \lambda_i a_i = c \in \mathbb{R}^n$  通常认为  $A = \begin{pmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{pmatrix}$ ,  $A^T = (a_1, a_2, \dots, a_m)$

$$A^T \lambda = (a_1, \dots, a_m) \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{pmatrix} = \sum_{i=1}^m \lambda_i a_i = c$$

即  $c$  看成  $A$  行向量的线性组合, 同样  $AX$  是  $A$  列向量的线性组合

if  $\textcircled{1}$  has solution  $\Leftrightarrow c$  是  $a_i$  的非负线性组合

$$\Leftrightarrow \exists c \in \text{conichull}(a_1, \dots, a_m)$$

if  $\textcircled{2}$  has solution  $\Rightarrow x^T (\sum \theta_i a_i) \leq 0$  for all  $\theta_i \geq 0$

$$\forall \alpha \in \mathbb{R}^m \quad \alpha = \sum \theta_i a_i \Leftrightarrow \alpha \in \text{cone}(a_1, \dots, a_m)$$

$$\left\{ \begin{array}{l} x^T \alpha \leq 0 \\ x^T c > 0 \end{array} \right.$$

$\Rightarrow$  there is a separating plane between  $c$  and  $\text{cone}(a_1, \dots, a_m)$