



# AT-XTR-903-A4 Multi-Channel Micro Embedded Transceiver Module

The AT-XTR-903-A4 radio transceiver represents a simple and economic solution to wireless data communications. The employment of an embedded microprocessor creates a transparent TTL RS-232 interface, and eliminates any need for packetizing and data encoding. The designer does not have to write complex software routines for the transmission management.

The input serial data speed (9600, 19200 ,38400 bps) is configured via two input lines (SP1 and SP2) Different degrees of encoding redundancy and data protection is automatically assigned to the forwarded RF packet depending on the selected speed:

- Hamming + Manchester at 9600 bps
- Manchester at 19200 bps
- Scrambling at 38400 bps

These schemes are designed to ensure a high level of data integrity.

The module is a multi-channel RF transceiver which features selection of **10 channels** between 433 and 434MHz. Channel selection is very straightforward and takes place through simple AT commands. RF output power may be selected (from –8 dBm to +10 dBm) and monitoring of channel occupation is also performed through simple AT commands.

The device implements frequency modulation (GFSK) which guarantees a better noise immunity compared to amplitude modulation. Open air range of up to 200 m with omni directional antennas can be achieved.

The AT-XTR-903 is extremely compact measuring only 33 x 23 mm. Timing guarantees a maximum latency of only 20 ms between sending data and its reception. This minimal delay includes the necessary time for the device to switch from RX to TX and transmit a synchronization header. Supply voltage is 3V regulated and a power down mode is available, reducing current consumption to less than 10  $\mu$ A. Even in the power down state, the AT-XTR-903 retains valid interface levels with the user's host application.



#### **Features**

- Transparent throughput of RS-232 data
- Also available on 900MHz and 868MHz
- No data encoding and no preamble required
- No data packaging
- Easy AT commands for channel selection, emitted power level and monitoring of channel occupation and signal strength
- HyperTerminal\* compatible
- 10 Selectable Operating Channels: 433-434 MHz model
- 169 Selectable Operating Channels:
   902–928 MHz model (AT-XTR-903-A9)
- Embedded microprocessor
- Small size (23x33 mm)
- Emitted power: user adjustable to 10mW

# **Typical Applications**

- Handheld Wireless
- Home automation
- Telemetry
- Access control
- Instruments monitoring
- Data acquisition
- POS terminals
- Robotics

<sup>\*</sup> Trademark registered by Hilgraeve

# **Pin Description**

O 1		18 O
O 2		17 O
O 3		16 O
		15 O
	XTR-903-A4	14 O
		13 O
		12 O
		11 O
O 9		10 🔘

Pin Number	Pin Designation
1,3	RF GND
2	ANT
9,10,18	GND
11	SP1
12	RSRX
13	485EN
14	RSTX
15	SP2
16	PWRDN
17	Vcc
4,5,6,7,8	Not used

RF GND - pins 1,3

RF ground plane connection.

ANT - pin 2

Antenna terminal.  $50\Omega$  impedance.

**GND - pins 9,10,18** 

Ground (0V).

SP1, SP2 - pins 11,15

These pins configure the serial data rate. Table 1 indicates the configuration voltage levels of SP1 and SP2 for the three different data rates.

# **Data Rate Configuration**

SP1	SP2	I/O Data Rate
Vcc	Vcc	9600
GND	Vcc	19200
Vcc	GND	38400
GND	GND	TEST Mode

Table 1

A different degree of redundancy and protection is associated with the RF packet according to the selected speed. This means that slower data rate results in a higher level of reliability and/or longer communication distance.

#### RSRX - pin 12

Data output of the receiver in TTL RS-232 logic levels with 1 start bit (0V), 8 data bits and 1 stop bit (3V). Output is normally high (3V).



#### 485EN - pin 13

Enable pin to control an external RS-485 transceiver chip.

#### RSTX - pin 14

Data input to the transmitter in TTL RS-232 logic levels with 1 start bit (0V), 8 data bits and 1 stop bit (3V). Input is normally high (3V).

#### PWRDN - pin 16

Enable pin to switch the power-saving feature ON or OFF . Applying 3V sets the module to Power Down mode, switching off all active circuitry and reducing consumption to less than 10  $\mu$ A. In the Power Down state, the logic levels of input/output data lines are still maintained at logic High levels (3V). Applying 0V to pin 16 configures the module for normal operating mode.

PWRDN	MODULE STATE
GND	ON
Vcc	OFF

### Vcc - pin 17

Positive supply voltage (3V). Should be properly filtered and regulated.

# **Technical Characteristics**

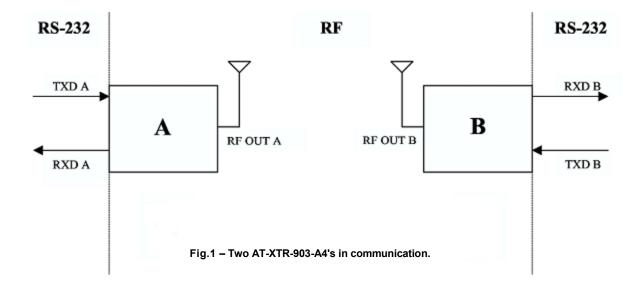
Absolute Limits	
	-20 °C to +70 °C -40 °C to +100 °C
Max. Supply Voltage	+6V
	-1.0 to Vcc + 0.3V
Output pin Voltage	-1.0 to Vcc + 0.3V

	Min.	Typ.	Max.	Units
DC values				
Supply Voltage	2.7	3	3.3	V
Current (rx mode)		30		mA
Current (tx mode @ -8 dBm)		25		mA
Current (tx mode @ 10 dBm)		40		mA
Current (stand-by mode)		8	10	μΑ
Input/output Logical 1 Level	0.7xVcc		Vcc	V
Input/output Logical 0 Level	0		0.3xVcc	V
RF				
Modulation Type		GFSK		
Frequency Band	2	133.05 to 434.8	37	MHz
Rx Sensitivity		-104		dBm
Tx Max Power Output	-8		10	dBm
Performance				
Input Bit Rate <sup>1</sup>	9600	), 19200 and 3	8400	bps
Outdoor range		200		m
Available Channels			10	
Channel Spacing		153.6		KHz
Timing				
PWRDN to RX	20			ms
PWRDN to TX				ms
TX to RX			20	ms
RX to TX			20	ms
Default Values (NO programming) <sup>2</sup>				·
Operating Channel		433.96		MHz
Tx Output Power		10		dBm

<sup>&</sup>lt;sup>1</sup> Input signal consists of 1 start bit, 8 data bits and 1 stop bit, no parity.
<sup>2</sup> Default values are factory configured. May be changed with AT command programming.

# **Application**

Integration of a powerful embedded microprocessor relieves the designer of the need to implement a synchronization protocol between the transmitting and receiving unit, thus significantly reducing the design cycle time. The AT-XTR-903 RF transceiver module allows the transfer of serial data in RS232-TTL logic, as output from a microprocessor host or from a PC serial port (with electrical level conversion), without the need for any further coding. The radio transmission is completely transparent, allowing the radio transfer of data packets of any length\* and with a latency of no longer then 20 ms between the data delivery and the actual reception. This time is required to "open" the communication connection. Thereafter, the data transfer occurs at the actual serial port speed (9600, 19200 or 38400 bps).

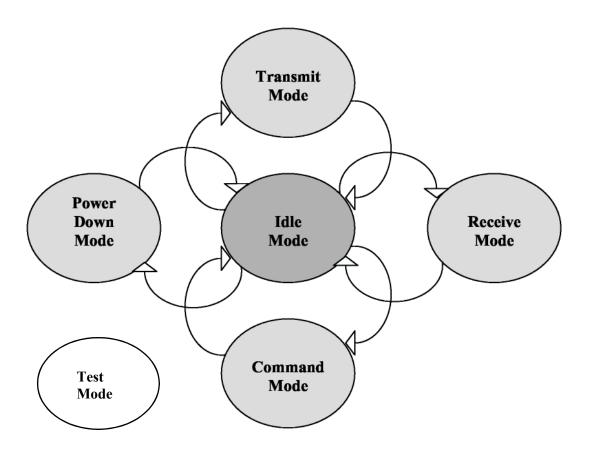


AT-XTR-903-A4 operation status may be summarized as follows:

- Test Mode
- Idle Mode
- RF Transmit Mode
- RF Receive Mode
- Command mode
- Power Down mode

The following pages discuss these modes in detail.

<sup>\*</sup>The maximum length of the input data packet is directly related to the precision of the bit rate of the signal. We recommend that data packet sizes should be kept to within 4Kbytes. A packetizing protocol should be implemented for applications that require the transfer of data exceeding 4Kbytes in size.



#### **Test Mode**

Test mode is entered into at power–up when SP1 and SP2 are at 0V (GND). In this mode, the carrier frequency is continuously modulated by a 20KHz pseudorandom data sequence. The test mode may be put to good use when setting up the link and may be used in conjunction with the RSSI read command. (see command mode for details on reading the RSSI value). To exit the test mode, SP1 and SP2 must be reconfigured under a power off state.

#### Idle mode

This is the rest state of the transceiver, when initially powered. In this mode the transceiver will be "listening", waiting for either RF synchronization sequence or data presence on the serial line input. If any of the two conditions occur, the transceiver will exit the idle mode, and switch to the new relevant status.

#### **Transmit mode**

From the rest state in idle mode, the transceiver will automatically go to transmit status (Transmit mode) as soon as it detects a start bit on the serial data input line (pin 14). RF data transfer is transparent to user, and the data packet will be delivered without any buffering, and with no limit on the packet length. No checksum is added or CRC performed. Error detection and correction is left to the designer to perform if required.

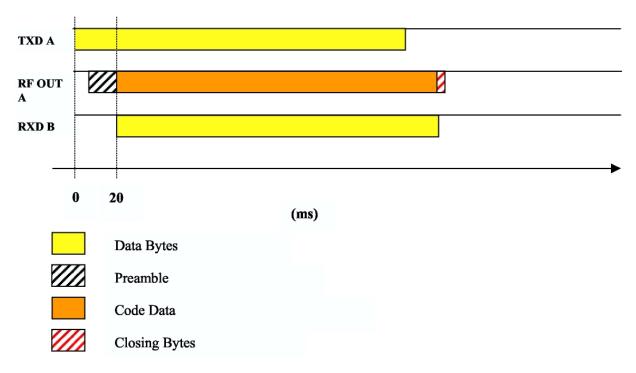


Fig. 3 – Timing Diagram of a data packet transmission

As shown in the Timing Diagram (Fig. 3) above, from the starting time (0 ms), when the first data bit arrives at the transmitting module's input, to the time when the same first data bit is received at the remote unit, is about 20ms. This delay accounts for the preamble transmission that the transmitting module automatically places before the packet of the data that is to be sent. This preamble is necessary to wake up and synchronize the receiver at the remote AT-XTR-903. A closing (end of packet) data sequence is also automatically appended to packet that is being sent.

The data rates at which the host may send data to the AT-XTR-903 on TXD, pin 14, is 9600 bps, 19200 bps or 38400 bps. The AT-XTR –903 is configured for the specific data rate via pin SP1 (pin 11) and SP2 (pin 15), in accordance with Table 1. Depending on the serial data rate configured, a different level of redundancy will be added in order to optimize RF transmission. These can be helpful in finding the most suitable configuration of the complete system according to all the possible conditions that can affect Radio Frequency propagation.

Data Rate	RF Data Encoding Scheme		
38400	Any single byte of the data packet to be sent is affected with pseudo-random balancing. There is no assurance that data received at remote module was not corrupted during radio transmission.		
19200	Any single byte of the data packet to be sent is balanced with the same number of '0's and '1' s (Manchester).  The system can recognize any single error per data bit and, if this occurs, the system will stop the data output on the receiving module's data line.		
9600	Manchester + Hamming. Hamming code allows correction of any single error occurring in any data nib- ble. This is the safest speed to send data, since the protocol implemented provides for error detection and correction.		

Table 2 - Redundancy options vs. serial data speed

#### RF Receive mode

Transfer from Idle to Receive mode will occur as soon as the module recognizes the synchronization preamble on the incoming RF signal. At this point the transceiver will stay in Receive mode up to the reception of packet closing sequence.

Any data in input from the serial line will be discarded while the module is in Receive mode.

#### Command mode

Command mode allows the designer /user to configure the main parameters which change the module's operating conditions, such as selecting a new operating frequency channel or setting the RF output power to desired value. This allows a high degree of flexibility to customize the AT-XTR-903 transceiver module for a specific application.

Programming is carried out via simple AT commands. To enter the Command mode from Idle mode, the following data string must be sent via serial RSTX line to the module:

• 3 consecutive ASCII plus characters (+++) without pauses

Within 35ms, the module will respond with **OK<CR><LF>** string to confirm it is in Command mode. (<CR> represents 'Carriage Return') (<LF> represents 'Line Feed')

Programming information is stored in 16 available registers (from 1 to 16). Some of these are available only for read operations, whilst others are available for read/write operations.

The syntax to read a value stored in a register is as follows:

Assuming that the command was issued correctly, the answer to this command is the value of the contents of the register. For a command issued with errors, the following answer is returned:

#### ERROR<CR><LF>

To change the value of parameter in a register, the following syntax is used:

A command issued correctly will receive **OK<CR><LF>** response. If the command contained a syntax error or if the value that was entered to be written is an unacceptable parameter for that register, an **ERROR<CR><LF>** response will be received.

All the values written into registers are volatile and will be lost when the module is powered OFF, unless they were previously saved into the EEPROM memory available in the embedded microprocessor. In this case, the modified values will be non-volatile and will be retained even if the module's power supply is cycled.

The command for non-volatile saving of ALL the values in register is:

#### ATWR<CR>

To exit Command Mode and return the transceiver to normal operating, the following command is issued:

#### ATCC<CR>

When in Command mode, it is possible to include multiple commands in a single command line by separating each command by a comma (,) operator. With following command line, for example, register 3 is set to value 2, the change is permanently saved and the Command Mode is exited:

# Example: ATS3=2,WR,CC <CR> OK<CR><LF>

As shown in the above example, the prefix -AT- is only used once in the beginning of the command of line and not required for the following commands which are separated with the comma operator.

Command chaining is possible only for write operations. If used in read operations, an "ERROR" message will be returned as in the following example:

Example: ats1,cc <CR>
ERROR <CR><LF>

Commands are not case sensitive, so either uppercase or lowercase characters may be used.

Refer to **Appendix A.** for details on register values and possible configurations.

#### **Power Down Mode**

Setting pin 16 (PWRDN) high (+3V) configures the transceiver to power saving mode, limiting its current consumption to less than 10  $\mu$ A. Whilst in Power Down the transceiver is not in a condition to receive or transmit but will continue to maintain the correct logic levels with the externally interfaced devices, for example, the received data line (RXD) will be kept HIGH (+3V) associated with a STOP bit. To bring the transceiver back to an operating state (Idle Mode), pin 16 must be taken low (0V).

## **Applications**

Fig.3 shows a typical AT-XTR-903 application, with the transceiver connected to a microprocessor that, in addition to data reception and transmission on the input and output lines (TXD & RXD), is also controlling two lines dedicated to serial interface speed selection (SP1 & SP2) plus the PWRDN line.

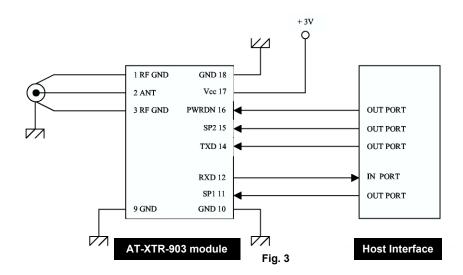


Fig.4, shows a typical connection between the AT-XTR-903-A4 module and PC serial port. The integrated circuit between the transceiver and the RS232 port is only used to convert the electrical level voltages between RS-232 and TTL logic. (eg. MAX 232)

With the use of the RTS line (pin 7 of DB9 connector) it is possible to drive the PWRDN line, while the serial data speed selection is set to 19200 bps.

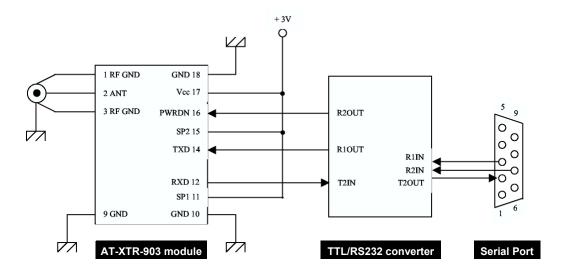


Fig.4 - Example connection of XTR-903-A4 and RS-232 serial port at 9600 bps.

#### **Application Suggestions**

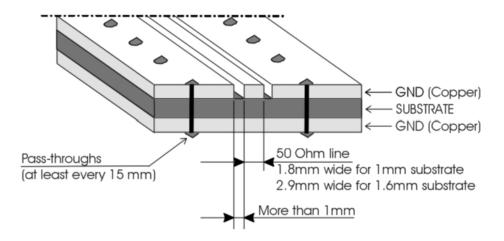
The following suggestions serve as guidelines in the final design and should not be considered as essential for prototyping purposes.

#### **GROUND Circuit**

- The module should be surrounded with ground plane. The circuit is best designed on double sided through plated PCB, with the ground planes on each side connected with via's (pass-through's) at least every 15 mm.
- Ground plane must be present around the antenna connection

#### 50 $\Omega$ Transmission lines (connection between pin 2 and Antenna)

- Should be as short as possible
- Trace width of 1.8 mm for FR4 PCB substrates with 1 mm cross section and 2.9 mm for substrates with 1.6 mm cross section. Trace distance from surrounding ground plane should be more than 1 mm (2 mm is better).
- The bottom side of the PCB should have a relatively large ground plane area.



#### **Antenna connection**

- Can be used to directly connect a radiating stylus (165 mm straight wire)
- Can be used to connect the central conductor of a coaxial cable to an off-board remote antenna. The cable's outer braid must be connected to GND near the antenna connection.

#### **Antenna**

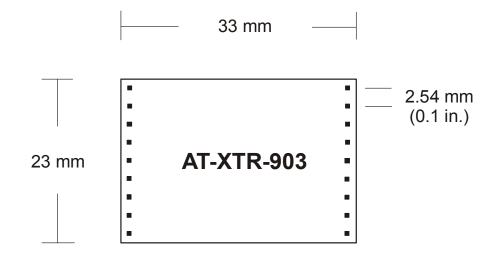
- An antenna must be connected to the transceiver antenna pin. A 16.5 cm whip antenna of 1mm diameter copper or brass may be used or 22 guage solid core insulated wire also works well. The body of the antenna should be as straight as possible and should be kept away from any other circuits or metal surface areas (at least 5 cm clearance is suggested)
- Antenna can be oriented either vertically or horizontally, with an abundant ground area around the connection feed point.

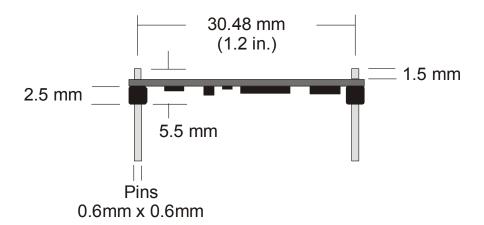
Note: ABACOM Technologies, Inc. offers a variety of manufactured antenna suitable for use with the AT-XTR-903 modules.

## Other components

- Position the RF module as far from other circuit components as possible (min. 5 mm)
- Keep microprocessor clock circuits as far away as possible. Apply GND shields.
- Do not install components around the  $50\Omega$  line(s). Keep at least 10mm clearance.
- If a PCB antenna is implemented, the area allocated for the antenna should not have any other circuits in close proximity .
- If the antenna connection is via coaxial cable, then other components may be placed around the connection point but approximately 5mm clearance away from the connection point should be given.

# **Mechanical dimensions**





# Appendix A - Register Programming

Different operating characteristics of the transceiver, such as RF channel selection, RF emitted power, etc..., can be programmed by the user through setting special parameters in 16 available registers.

The following information provides the meaning and programming possibilities for each register.

The current AT-XTR-903 transceiver modules implement 4 out of 16 registers - registers 1,2,3 and 16. Only these registers will be described, the remaining registers are reserved for possible future enhancements.

# Register 1 - Frequency Band

This register is READ ONLY and will supply information relating to the module's operating RF band. The AT-XTR-903 transceiver modules are available in three different models, 433MHz, 868MHz and 915MHz.

Command	Values	Read (R) / Write (W)
ATS1	0 =433-434 MHz	R
	1=868-870 MHz	
	2=902-928 MHz	

#### **Example 1:** Reading the operational band of the module

+++OK<CR><LF> ATS1<CR> 0 (0 = 433-434MHz band)

# Example 2:

+++OK<CR><LF> ATS1=2<CR> NO ACCESS<CR><LF>

Syntax Error: This register is available for Read only!

# Register 2 - RF CHANNEL

This register is available for read and write operations. It allows to get feed backs of the RF frequency (channel) setting for both receiving and transmitting circuits. Makes it possible to "write" a different frequency (channel).

Command	Values	Read (R)/ Write (W)
ATS2	0 = 433.19 MHz	RW
	1 = 433.34 MHz	
	2 = 433.50 MHz	
	3 = 433.65 MHz	
	4 = 433.80 MHz	
	5 = 433.96 MHz	
	6 = 434.11 MHz	
	7 = 434.27 MHz	
	8 = 434.42 MHz	
	9 = 434.57 MHz	

# **Example 1:** Reading the configured RF channel (433,5 MHz)

+++OK<CR><LF>

ATS2<CR>

2

# **Example 2:** Selecting channel 8 as the operating frequency (434,42 MHz)

+++OK<CR><LF>

ATS2=8<CR>

OK<CR>

# Register 3 - EMITTED RF POWER

This register is available for read and write operations. With the read command, feedback is given about the RF output power emitted from the module's transmitter section. The write command and enables the user to configure the transmitter section for the preferred RF output power.

Command	Values	Read (R)/ Write (W)
ATS3	0 = - 8 dBm	R/W
	1 = - 2 dBm	
	2 = + 4 dBm	
	3=+10 dBm	

# **Example 1:** Reading the configured RF output power (-2 dBm)

+++OK<CR><LF> ATS3<CR> 1

# Example 2: Setting RF output power to +10 dBm

+++OK<CR><LF> ATS3=3<CR> OK<CR><LF>

# Register 16 - RSSI (Received Strength Signal Indicator)

The register is read only and will supply a numeric value proportional to the RF Field Strength sensed from the receiving circuitry. The range of possible values returned from the register are 0 through 9. Reading register 16 starts a process of analysis of the RF channel that the module is programmed to operate on. This routine has a fixed duration of 200ms and the analysis result is given after this period. The analysis period should be allowed to run its course without interruption through issuing another command. The signal strength command is useful for determining possible channel occupation or for setting up the link in conjunction with the TEST mode.

Command	Values	Read (R)/ Write (W)
ATS16	0 = Minimum Field Strength	R
	1	
	2	
	3	
	4	
	5	
	6	
	7	
	8	
	9 = Maximum Field Strength	

# **Example 1: Reading Field Strength (strong received signal)**

+++OK<CR><LF> ATS16<CR> 9

#### **Example 2:** Reading Field Strength (very weak or no received signal)

+++OK<CR><LF> ATS16<CR> 0

**Example 3:** Syntax Error: register is read only!

+++OK<CR><LF> ATS16=3<CR> ERROR<CR><LF>