

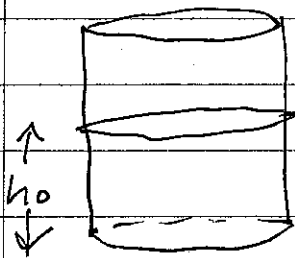
Existence & uniqueness Theorem for the initial value problem (*)

$$(*) \begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \end{cases} \quad \begin{array}{l} f: \mathbb{R}^n \rightarrow \mathbb{R}^n \\ x_0 \in \mathbb{R}^n \end{array}$$

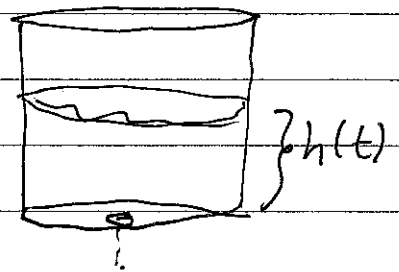
A soln. of (*) exists on some time interval containing $t=0$ provided f is continuous. (Does not need to exist for all time.)

For uniqueness of the soln. we need more than just continuity of f .

Example: showing that lack of uniqueness can be "physical" — not necessarily a sign that the model is flawed.

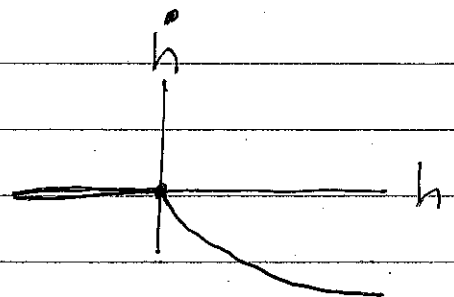


at $t=0$,
punch a hole
in the bucket



~~$\frac{dh}{dt} = -\sqrt{h}$~~

$$\frac{dh}{dt} = -\sqrt{h} \quad h \geq 0$$



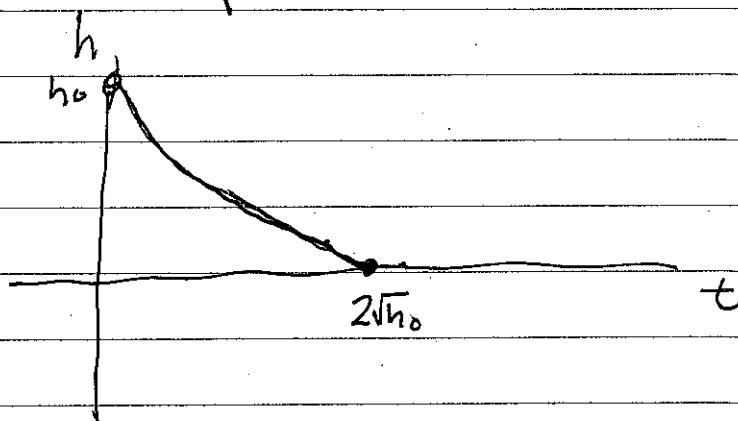
Construct soln. for $h_0 > 0$

$$\int_{h_0}^{h(t)} \frac{d\tilde{h}}{-\sqrt{\tilde{h}}} = \int_0^t d\tilde{t} = t$$

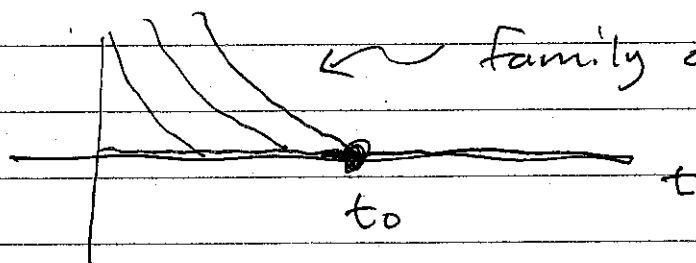
$$-2\sqrt{h(t)} + 2\sqrt{h_0} = t, \quad t \in [0, t_{\max}]$$

$$t_{\max} = 2\sqrt{h_0}$$

$$h(t) = \begin{cases} \left(\sqrt{h_0} - \frac{t}{2}\right)^2 & t \leq 2\sqrt{h_0} \\ 0 & t \geq 2\sqrt{h_0} \end{cases}$$



Notice that the soln. is not unique on a neighborhood of $t = t_0$ ($t > 2\sqrt{h_0}$), where $h(t) = 0$.



Family of solns. parameterized by h_0 up to some largest h_0 where bucket empties at t_0

Existence-uniqueness thm. (p. 82, Chapter 3)

$$(*) \begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \in \mathbb{R}^n \end{cases} \quad f: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

Suppose there are $a, b > 0$ s.t. $f: B_b(x_0) \rightarrow \mathbb{R}^n$

is Lipschitz with constant K . Then $(*)$

has a unique soln. $x(t)$ for $t \in J = [-a, a]$
provided $a = b/M$, where $M = \max_{x \in B_b(x_0)} |f(x)|$

$B_b(x_0)$ = ball of radius b about x_0
 $= \{x : |x - x_0| \leq b\}$

$t \in J = [-a, a]$, $a = b/M$

this ensures that the soln. doesn't
escape the ball in that time interval

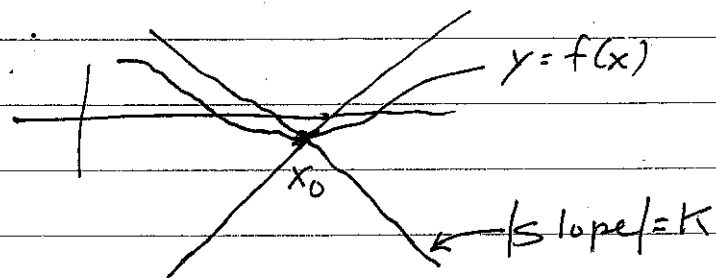
Lipschitz with constant K :

$$|f(x_2) - f(x_1)| \leq K |x_2 - x_1| \quad \forall x_1, x_2 \in B_b(x_0)$$

ie
$$\frac{|f(x_2) - f(x_1)|}{|x_2 - x_1|} \leq K \quad (x_1 \neq x_2)$$

↖ slope of secant line

single variable case:



Note that this condition doesn't hold for our bucket problem if $x_0 = 0$, i.e. there is no neighborhood of $x_0 = 0$ where we can bound the slope of the secant line since $f'(x)$ diverges as $x \rightarrow 0$.

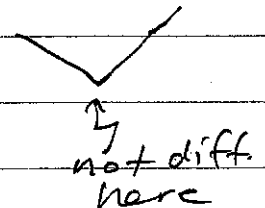
Note: if a function is differentiable (C^1) then it is Lipschitz.

if it is Lipschitz then it is continuous (C^0),

but it doesn't have to be differentiable

example $f(x) = |x|$

use $K=1$



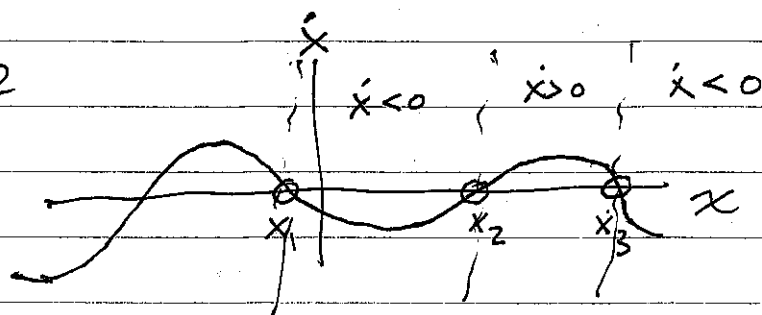
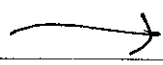
Before mentioning elements of proof

(Picard iteration, contraction mapping thm.)

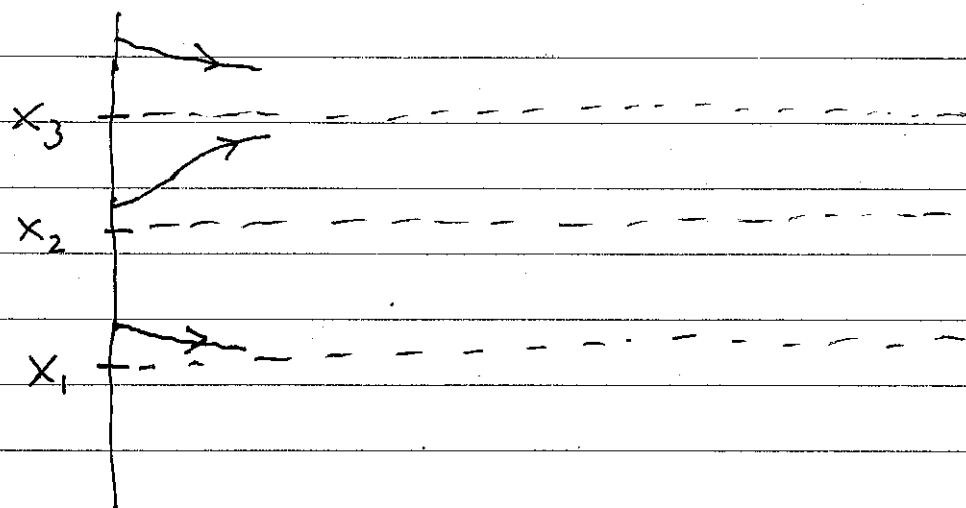
let's give a simple example of exploiting uniqueness to provide a qualitative analysis of solns.

$$\dot{x} = f(x) \quad x \in \mathbb{R}$$

graph of $f(x)$



Assume $x_0 > 0$ on above interval of x



f is smooth \Rightarrow uniqueness of solns holds

$x(t) \rightarrow x^*$, where x^* is one of x_1, x_2, x_3 ~~if $x_0 > 0$~~

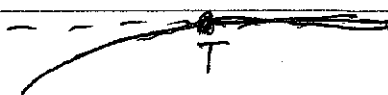
How long does it take to reach equilibrium?
(assuming it doesn't start at one)

~~Q~~

It must take an infinite amount of time

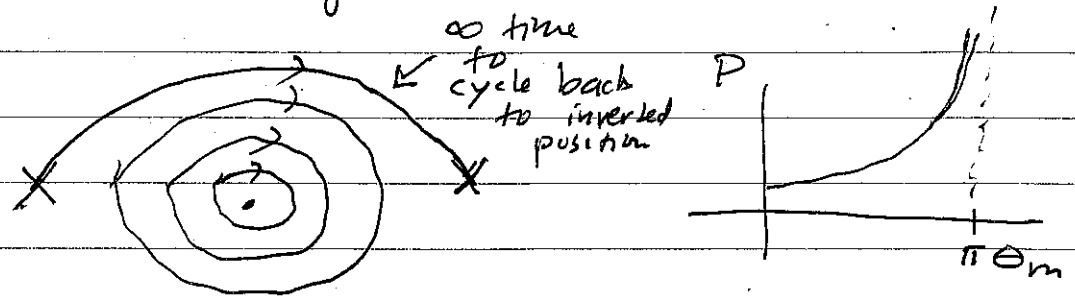
$$\lim_{t \rightarrow \infty} x(t) = x^*, \quad x(t) \neq x^* \text{ for any } t$$

can't have this



because it violates uniqueness thm.

This is how we know that the period of the pendulum diverges as $\theta_m \rightarrow \pi$ - ~~the~~



In this course we almost always assume $f(x)$ is C^1 & uniqueness thm applies.

Elements of proof (You are asked to identify role of K , Lipschitz constant, in proof on homework.)

$$(*) \begin{cases} \dot{x} = f(x) \\ x(0) = x_0 \end{cases} \Rightarrow \int_0^t \dot{x} d\tau = \int_0^t f(x) dt$$

$$(**) \boxed{x(t) = x_0 + \int_0^t f(x(s)) ds}$$

Soln. of $(**)$ satisfies $(*)$. We'll use $(**)$, i.e. we're interested in a function $x(t)$ for which $(**)$ holds.

"Picard Iteration" - consider the following map T :

$$Tu = x_0 + \int_0^t f(u(s)) ds$$

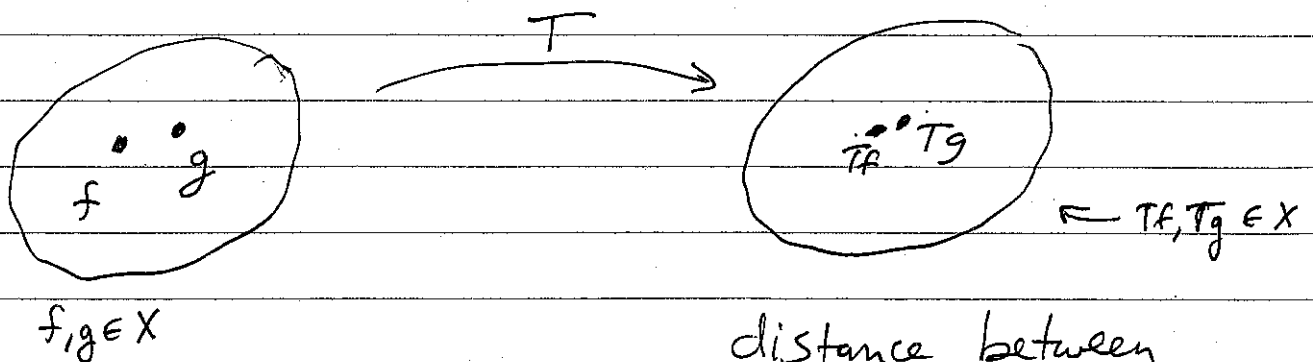
For example, you could start with some guess of the soln. $u_0(t)$ & iterate from there:

$$u_0(t) \xrightarrow{T} u_1(t) \xrightarrow{T} u_2(t) \rightarrow \dots$$

Note that a "fixed-pt." of this map, ~~is~~ ~~the~~ $Tx(t) = x(t)$ ~~is~~ ~~the~~ solves $(**)$

$$\begin{array}{c} x(t) = x_0 + \int_0^t f(x(s)) ds \\ \uparrow \qquad \qquad \qquad \uparrow \end{array}$$

Proof of existence-uniqueness relies on showing that T is a contraction mapping in which case it has a unique fixed pt



$X = \text{"metric space"}$

distance between
 Tf & Tg
is smaller than
distance between
 f & g

Contraction Mapping Thm

Let $T: X \rightarrow X$ be a map on a complete metric space X . The map is a contraction if there exists $c < 1$ s.t. for all $f, g \in X$,

$$\rho(T(f), T(g)) \leq c \rho(f, g)$$

In this case there is a unique fixed-pt.

We need to have a distance function $\rho(\cdot, \cdot)$ ~~and define~~ for our space X and then make sure there is a $c < 1$.

$X = C^0(J, B_b(x_0)) =$ set of continuous functions $u(t) \in B_b(x_0)$ for $t \in J = [-a, a]$

$$\rho(u_1(t), u_2(t)) = \sup_{t \in J} |u_1(t) - u_2(t)|$$

sup = supremum = least upper bound

(Note: $Tu(t)$ is continuous & stays in $B_b(x_0)$ via our restriction of $t \in J$)

need to find $c < 1$ s.t.

$$\rho(T(u_1(t)), T(u_2(t))) \leq c \rho(u_1(t), u_2(t))$$

$$\rho(T(u_1(t)), T(u_2(t))) = \sup_{t \in J} |T(u_1(t)) - T(u_2(t))|$$

$$|T(u_1(t)) - T(u_2(t))|$$

$$= \left| \left(x_0 + \int_0^t f(u_1(s)) ds \right) - \left(x_0 + \int_0^t f(u_2(s)) ds \right) \right|$$

$$= \left| \int_0^t f(u_1(s)) ds - \int_0^t f(u_2(s)) ds \right|$$

$$\leq \int_0^t \underbrace{|f(u_1(s)) - f(u_2(s))|}_{\leq K |u_1(s) - u_2(s)|} ds$$

by Lipschitz
assumption

$$\leq Ka \rho(u_1(t), u_2(t))$$

Let $Ka = c < 1$, $a < 1/K$
& $a < b/M$

Note: this additional restriction on a isn't
needed. See proofs in text to
eliminate it.

note

$$\rho(T(u_1(t)), T(u_2(t))) = \sup_{t \in J} |T(u_1(t)) - T(u_2(t))|$$

$$|T(u_1(t)) - T(u_2(t))| \leq \rho(T(u_1(t)), T(u_2(t)))$$