Notebook - Maratona de Programação

Heladito??

Contents

1 Algoritmos

1.1 Cdq

```cpp
// LIS 3D problem

struct Segtree{
    vi t;
    int n;

    Segtree(int n){
        this->n = n;
        t.assign(2*n, 0);
    }

    int merge(int a, int b){
        return max(a, b);
    }

    void build(){
        for(int i=n-1;i>0;i--)
            t[i] = merge(t[i<<1], t[i<<1|1]);
    }

    int query(int l, int r){
        int resl = -INF, resr = -INF;
        for(l+=n, r+=n+1; l<r; l>>=1, r>>=1){
            if(l&1) resl = merge(resl, t[l++]);
            if(r&1) resr = merge(t[--r], resr);
        }
        return merge(resl, resr);
    }

    void update(int p, int value){
        p+=n;
        for(t[p]=max(t[p], value); p >>= 1;)
            t[p] = merge(t[p<<1], t[p<<1|1]);
    }
};

struct point{
    int x, y, z, id;
    bool left;
    point(int x=0, int y=0, int z=0): x(x), y(y), z(z){
        left = false;
    }
    bool operator<(point &o){
        if(x != o.x) return x < o.x;
        if(y != o.y) return y > o.y;
        return z < o.z;
    }
};


void cdq(int l, int r, vector<point> &a, vi &dp){
    if(l==r) return;

    int mid = (l+r) / 2;

    cdq(l, mid, a, dp);

    // compress z
    set<int> uz; map<int, int> idz;
    for(int i=l;i<=r;i++) uz.insert(a[i].z);
    int id = 0;
    for(auto z: uz) idz[z] = id++;

    vector<point> tmp;
    for(int i=l;i<=r;i++){
        tmp.pb(a[i]);
        tmp.back().x = 0;
        tmp.back().z = idz[tmp.back().z];
        if(i<=mid)
            tmp.back().left = true;
    }

    Segtree st(id);

    sort(tmp.rbegin(), tmp.rend());

    for(auto t: tmp){
        if(t.left){
            st.update(t.z, dp[t.id]);
        }else{
            dp[t.id] = max(dp[t.id], st.query(0, t.z-1)+1);
        }
    }

    cdq(mid+1, r, a, dp);
}


int32_t main()
{sws;

    int n; cin >> n;

    vector<point> vet(n);
    for(int i=0;i<n;i++){
        cin >> vet[i].x >> vet[i].y >> vet[i].z;
    }

    sort(vet.begin(), vet.end());

    for(int i=0;i<n;i++)
        vet[i].id = i;

    vi dp(n, 1);

    cdq(0, n-1, vet, dp);

    int ans = 0;
    for(int i=0;i<n;i++)
        ans = max(ans, dp[i]);

    cout << ans << endl;


    return 0;
}
```

1.2 Histogram Rectangle

```cpp
ll bestRectangle(vector<int> hist){
    int n = hist.size();
    stack<ll> s;
    s.push(-1);
    ll ans = hist[0];
    vector<ll> left_smaller(n, -1), right_smaller(n, n);
    for(int i=0;i<n;i++){
        while(!s.empty() and s.top()!=-1 and hist[s.top()]>hist[i]){
            right_smaller[s.top()] = i;
            s.pop();
        }
        if(i>0 and hist[i]==hist[i-1])
            left_smaller[i] = left_smaller[i-1];
        else
            left_smaller[i] = s.top();
        s.push(i);
    }

    for(int j=0;j<n;j++){
        ll area = hist[j]*(right_smaller[j]-left_smaller[j]-1);
        ans = max(ans, area);
    }
    return ans;
}
```

1.3 Mst Xor

```
// omg why just 2 seconds
#include <bits/stdc++.h>
// #define int long long
#define ff first
#define ss second
#define ll long long
#define ld long double
#define pb push_back
#define eb emplace_back
#define pii pair<int, int>
#define pll pair<ll, ll>
#define ti tuple<int, int, int>
#define vi vector<int>
#define vl vector<ll>
#define vii vector<pii>
#define sws ios_base::sync_with_stdio(false);cin.tie(NULL);cout.tie(NULL);
#define endl '\n'
#define teto(a, b) (((a)+(b)-1)/(b))
#define all(x) x.begin(), x.end()
#define forn(i, n) for(int i = 0; i < (int)n; i++)
#define forne(i, a, b) for(int i = a; i <= b; i++)
#define dbg(msg, var) cerr << msg << " " << var << endl;

using namespace std;

const int MAX = 6e6+10;
const ll MOD = 1e9+7;
const int INF = 0x3f3f3f3f;
const ll LLINF = 0x3f3f3f3f3f3f3f3f;
const ld EPS = 1e-6;
const ld PI = acos(-1);

// End Template //

const int N = 2e5+10;

struct DSU {
    int n;
    map<int, int> parent;
    map<int, vi> comp;

    int find(int v) {
        if(v==parent[v])
            return v;
        return parent[v]=find(parent[v]);
    }

    void join(int a, int b) {
        a = find(a);
        b = find(b);
        if(a!=b) {
            if((int)comp[a].size()<(int)comp[b].size())
                swap(a, b);

            for(auto v: comp[b])
                comp[a].pb(v);
            comp[b].clear();
            parent[b]=a;
        }

    }
};

int trie[MAX][2];
set<int> idx[MAX];
int finish[MAX];
int nxt = 1;

void add(int s){
    int node = 0;
    for(int i=30;i>=0;i--){
        bool c = (s & (1<<i));
        if(trie[node][c] == 0)
            node = trie[node][c] = nxt++;
        else
            node = trie[node][c];
        finish[node]++;
    }
}

void remove(int s){
    int node = 0;
    for(int i=30;i>=0;i--){
        bool c = (s & (1<<i));
        node = trie[node][c];
        finish[node]--;
    }
}

int min_xor(int s){
    int node = 0;
    int ans = 0;
    for(int i=30;i>=0;i--){
        bool c = (s & (1<<i));
        if(finish[trie[node][c]] != 0)
            node = trie[node][c];
        else{
            ans ^= 1 << i;
            node = trie[node][!c];
        }
    }
    return ans;
}


int32_t main()
{sws;

    int n;
    cin >> n;
    vi x(n);
    for(int i=0;i<n;i++)
        cin >> x[i];

    sort(x.begin(), x.end());
    x.erase(unique(x.begin(), x.end()), x.end());
    n = x.size();

    DSU dsu;

    ll mstsum = 0;

    vi pais;
    for(int i=0;i<n;i++){
        add(x[i]);
        dsu.parent[x[i]] = x[i];
        dsu.comp[x[i]].pb(x[i]);
        pais.pb(x[i]);
    }

    while((int)pais.size()!=1){
        vector<ti> edges;
        for(auto p: pais){
            vi &nodes = dsu.comp[p];
            // erase
            for(auto u: nodes) remove(u);

            // query
            ti ed = {LLINF, 0, 0};
            for(auto u: nodes){
                int xr = min_xor(u);
                ed = min(ed, {xr, u, xr^u});
            }
            edges.pb(ed);

            // add back
            for(auto u: nodes) add(u);
        }

        for(auto [xr, u, v]: edges){
            if(dsu.find(u)!=dsu.find(v)){
                // u, v -> mst
                // cout << "mst = " << u << " " << v << endl;
                mstsum += xr;
                dsu.join(u, v);
            }
        }
        vi pais2;
        for(auto p: pais)
            if(p==dsu.find(p))
                pais2.pb(p);
        swap(pais, pais2);
    }

    cout << mstsum << endl;


    return 0;
}
```

1.4 Ternary Search

```
// Ternary
ld l = -1e4, r = 1e4;
int iter = 100;
while(iter--){
    ld m1 = (2*l + r) / 3;
    ld m2 = (l + 2*r) / 3;
    if(check(m1) > check(m2))
        l = m1;
    else
        r = m2;
}
```

2 DP

2.1 Aliens

```
// Solves https://codeforces.com/contest/1279/problem/F

// dado um vetor de inteiros, escolha k subsegmentos disjuntos de soma ámxima
// em vez de rodar a dp[i][k] = melhor soma éat i usando k segmentos,
// vc roda uma dp[i] adicionando um custo W toda vez que usa um novo subsegmento,
// e faz busca ábinria nesse W pra achar o custo ímnimo que usa exatamente K intervalos

ll n, k, L;
pll check(ll w, vl& v){
    vector<pll> dp(n+1);
    dp[0] = {0,0};
    for(int i=1;i<=n;i++){
        dp[i] = dp[i-1];
        dp[i].ff += v[i];
        if(i-L>=0){
            pll t = {dp[i-L].ff + w, dp[i-L].ss + 1};
            dp[i] = min(dp[i], t);
        }
    }

    return dp[n];
}

ll solve(vl v){
    ll l=-1, r=n+1, ans=-1;
    while(l<=r){
        ll mid = (l+r)/2;
        pll c = check(mid, v);
        if(c.ss <= k){
            r = mid - 1;
            ans = mid;
        }else{
            l = mid + 1;
        }
    }

    pll c = check(ans, v);

    if(ans < 0) return 0;

    // we can simply use k insted of c.ss ~magic~
    return c.ff - ans*k;
}

int32_t main()
{sws;

    string s;
    cin >> n >> k >> L;
    cin >> s;

    vl upper(n+1, 0), lower(n+1, 0);
    for(int i=0;i<n;i++)
        if('A'<= s[i] and s[i] <= 'Z')
            upper[i+1] = 1;
    for(int i=0;i<n;i++)
        if('a'<= s[i] and s[i] <= 'z')
            lower[i+1] = 1;

    cout << min(solve(lower),
                solve(upper)) << endl;

    return 0;
}
```

2.2 Divide Conquer

```
ll cost(int l, int r) {
    return ?;
}

void process(int l, int r, int optl, int optr) {
    if (l > r) return;
    int opt = optl;
    int mid = (l + r) / 2;
    for (int i=optl;i<=min(mid-1, optr);i++) {
        if (dp[i] + cost(i+1, mid) < dp2[mid]) {
            opt = i;
            dp2[mid] = dp[i] + cost(i+1, mid);
        }
    }
    process(l, mid-1, optl, opt);
    process(mid+1, r, opt, optr);
```

```cpp
}

int main() {
    for (int i=0;i<n;i++) {
        dp[i] = cost(0, i);
        dp2[i] = LLINF;
    }

    for (int i=0;i<k-1;i++) {
        process(0, n-1, 0, n-1);
        swap(dp, dp2);
        dp2.assign(N, LLINF);
    }
}
```

2.3 Dp Digitos

```cpp
// dp de quantidade de numeros <= r com ate qt digitos diferentes de 0
ll dp(int idx, string& r, bool menor, int qt, vector<vector<vi>>& tab) {
    if(qt > 3) return 0;
    if(idx >= r.size()) {
        return 1;
    }
    if(tab[idx][menor][qt] != -1)
        return tab[idx][menor][qt];

    ll res = 0;
    for(int i = 0; i <= 9; i++) {
        if(menor or i <= r[idx]-'0') {
            res += dp(idx+1, r, menor or i < (r[idx]-'0') , qt+(i>0), tab);
        }
    }

    return tab[idx][menor][qt] = res;
}
```

2.4 Knuth

```cpp
for (int i=1;i<=n;i++) {
    opt[i][i] = i;
    dp[i][i] = ?; // initialize
}
auto cost = [&](int l, int r) {
    return ?;
};

for (int l=n-1;l>=1;l--) {
    for (int r=l+1;r<=n;r++) {
        ll ans = LLINF;
        for (int k=opt[l][r-1]; k<=min(r-1, opt[l+1][r]); k++) {
            ll best = dp[l][k] + dp[k+1][r];
            if (ans > best) {
                ans = best;
                opt[l][r] = k;
            }
        }
        dp[l][r] = ans + cost(l, r);
    }
}

cout << dp[1][n] << endl;
```

2.5 Largest Ksubmatrix

```cpp
int n, m;
int a[MAX][MAX];
// Largest K such that exists a block K*K with equal numbers
int largestKSubmatrix(){
    int dp[n][m];
    memset(dp, 0, sizeof(dp));

    int result = 0;
    for(int i = 0 ; i < n ; i++){
        for(int j = 0 ; j < m ; j++){
            if(!i or !j)
                dp[i][j] = 1;
            else if(a[i][j] == a[i-1][j] and
                    a[i][j] == a[i][j-1] and
                    a[i][j] == a[i-1][j-1])
                dp[i][j] = min(min(dp[i-1][j], dp[i][j-1]),
                               dp[i-1][j-1]) + 1;
            else dp[i][j] = 1;

            result = max(result, dp[i][j]);
        }
    }

    return result;
}
```

2.6 Lis

```cpp
multiset<int> S;
for(int i=0;i<n;i++){
    auto it = S.upper_bound(vet[i]); // low for inc
    if(it != S.end())
        S.erase(it);
    S.insert(vet[i]);
}
// size of the lis
int ans = S.size();

//////////////////////////// see that later
// https://codeforces.com/blog/entry/13225?#comment-180208

vi LIS(const vi &elements){
    auto compare = [&](int x, int y) {
        return elements[x] < elements[y];
    };
    set< int, decltype(compare) > S(compare);

    vi previous( elements.size(), -1 );
    for(int i=0; i<int( elements.size() ); ++i){
        auto it = S.insert(i).first;
        if(it != S.begin())
            previous[i] = *prev(it);
        if(*it == i and next(it) != S.end())
            S.erase(next(it));
    }

    vi answer;
    answer.push_back( *S.rbegin() );
    while ( previous[answer.back()] != -1 )
        answer.push_back( previous[answer.back()] );
    reverse( answer.begin(), answer.end() );
    return answer;
}
```

2.7 Partition Problem

```cpp
// Partition Problem DP O(n2)
bool findPartition(vi &arr){
    int sum = 0;
    int n = arr.size();

    for(int i=0;i<n;i++)
        sum += arr[i];

    if(sum&1) return false;

    bool part[sum/2+1][n+1];

    for(int i=0;i<=n;i++)
        part[0][i] = true;

    for(int i=1;i<=sum/2;i++)
        part[i][0] = false;

    for(int i=1;i<=sum/2;i++){
        for(int j=1;j<=n;j++){
            part[i][j] = part[i][j-1];
            if(i >= arr[j-1])
                part[i][j] |= part[i - arr[j-1]][j-1];
        }
    }
    return part[sum / 2][n];
}
```

3 ED

3.1 Bit

```cpp
struct FT {
    vi bit;  // indexado em 1
    int n;

    FT(int sz) {
        this->n = n;
        bit.assign(n+1, 0);
    }

    int sum(int idx) {
        int ret = 0;
        for(; idx >= 1; idx -= idx & -idx)
            ret += bit[idx];
        return ret;
    }

    int sum(int l, int r) { // [l, r]
        return sum(r) - sum(l - 1);
    }

    void add(int idx, int delta) {
        for(; idx <= n; idx += idx & -idx)
            bit[idx] += delta;
    }
};
```

3.2 Bit Kth

```cpp
struct FT {
    vector<int> bit;  // indexado em 1
    int n;

    FT(int n) {
        this->n = n + 1;
        bit.assign(n + 1, 0);
    }

    int kth(int x){
        int resp = 0;
        x--;
        for(int i=26;i>=0;i--){
            if(resp + (1<<i) >= n) continue;
            if(bit[resp + (1<<i)] <= x){
                x -= bit[resp + (1<<i)];
                resp += (1<<i);
            }
        }
        return resp + 1;
    }

    void upd(int pos, int val){
        for(int i = pos; i < n; i += (i&-i))
            bit[i] += val;
    }
};
```

3.3 Cht

```cpp
const ll is_query = -LLINF;
struct Line{
    ll m, b;
    mutable function<const Line*()> succ;
    bool operator<(const Line& rhs) const{
        if(rhs.b != is_query) return m < rhs.m;
        const Line* s = succ();
        if(!s) return 0;
        ll x = rhs.m;
        return b - s->b < (s->m - m) * x;
    }
};
struct Cht : public multiset<Line>{ // maintain max m*x+b
    bool bad(iterator y){
        auto z = next(y);
        if(y == begin()){
            if(z == end()) return 0;
            return y->m == z->m && y->b <= z->b;
        }
        auto x = prev(y);
        if(z == end()) return y->m == x->m && y->b <= x->b;
        return (ld)(x->b - y->b)*(z->m - y->m) >= (ld)(y->b - z->b)*(y->m - x->m);
    }
    void insert_line(ll m, ll b){ // min -> insert (-m,-b) -> -eval()
        auto y = insert({ m, b });
        y->succ = [=]{ return next(y) == end() ? 0 : &*next(y); };
        if(bad(y)){ erase(y); return; }
        while(next(y) != end() && bad(next(y))) erase(next(y));
        while(y != begin() && bad(prev(y))) erase(prev(y));
    }
    ll eval(ll x){
        auto l = *lower_bound((Line) { x, is_query });
        return l.m * x + l.b;
    }
};
```

3.4 Color Update

```cpp
#define ti tuple<int, int, int>
struct Color{
    set<ti> inter; // l, r, color
    vector<ti> update(int l, int r, int c){
        if(inter.empty()){ inter.insert({l, r, c}); return {}; }
        vector<ti> removed;
        auto it = inter.lower_bound({l+1, 0, 0});
        it = prev(it);
        while(it != inter.end()){
            auto [l1, r1, c1] = *it;
            if((l<=l1 and l1<=r) or (l<=r1 and r1<=r) or (l1<=l and r<=r1)){
                removed.pb({l1, r1, c1});
            }else if(l1 > r)
                break;
            it = next(it);
        }
        for(auto [l1, r1, c1]: removed){
            inter.erase({l1, r1, c1});
            if(l1<l) inter.insert({l1, min(r1, l-1), c1});
            if(r<r1) inter.insert({max(l1, r+1), r1, c1});
        }
        if(c != 0) inter.insert({l, r, c});
        return removed;
    }

    ti query(int i){
        if(inter.empty()) return {INF, INF, INF};
        return *prev(inter.lower_bound({i+1, 0, 0}));
    }
};
```

3.5 Dsu Queue

```cpp
// DSU with queue rollback
// Normal DSU implementation with queue-like rollback, pop removes the oldest join.
// find(x) - O(logn)
// join(a, b) - O(logn)
// pop() - (log^2n) amortized

struct event {
    int a, b;    // original operation
    int fa, fb; // fa turned into fb's father
    bool type; // 1 = inverted, 0 = normal
};

struct DSU {
    int n;
    vector<int> parent, size;
    vector<event> st; int qnt_inv;
    DSU(int n): n(n), parent(n), size(n, 1), qnt_inv(0) {
        for (int i=0;i<n;i++) parent[i] = i;
    }

    int find(int a) {
        if (parent[a] == a) return a;
        return find(parent[a]);
    }

    void join(int a, int b, bool inverted=false) {
        int fa = find(a), fb = find(b);
        if (size[fa] < size[fb]) swap(fa, fb);
        st.push_back({a, b, fa, fb, inverted});
        if (inverted == 1) qnt_inv++;
        if (fa != fb) {
            parent[fb] = fa;
            size[fa] += size[fb];
        }
    }

    void roll_back() {
        auto [a, b, fa, fb, type] = st.back(); st.pop_back();
        if (type == 1) qnt_inv--;
        if (fa != fb) {
            parent[fb] = fb;
            size[fa] -= size[fb];
        }
    }

    void pop() {
        auto lsb = [](int x) { return x&-x; };
        if (qnt_inv == 0) { // invert all elements
            vector<event> normal;
            while (!st.empty()) {
                normal.push_back(st.back());
                roll_back();
            }
            for (auto [a, b, fa, fb, type]: normal) {
                join(a, b, true);
            }
        } else if (st.back().type == 0) { // need to realocate
            int qnt = lsb(qnt_inv);
            vector<event> normal, inverted;
            while (qnt > 0) {
                event e = st.back();
                if (e.type == 1) {
                    inverted.push_back(e);
                    qnt--;
                } else {
                    normal.push_back(e);
                }
                roll_back();
            }
            while (!normal.empty()) {
                auto [a, b, fa, fb, type] = normal.back(); normal.pop_back();
                join(a, b);
            }
            while (!inverted.empty()) {
                auto [a, b, fa, fb, type] = inverted.back(); inverted.pop_back();
                join(a, b, true);
            }
        }

        // remove the last element
        roll_back();
    }
};
```

3.6 Minqueue

```cpp
struct MinQ {
    stack<pair<ll,ll>> in;
    stack<pair<ll,ll>> out;

    void add(ll val) {
        ll minimum = in.empty() ? val : min(val, in.top().ss);
        in.push({val, minimum});
    }

    ll pop() {
        if(out.empty()) {
            while(!in.empty()) {
                ll val = in.top().ff;
                in.pop();
                ll minimum = out.empty() ? val : min(val, out.top().ss);
                out.push({val, minimum});
            }
        }
        ll res = out.top().ff;
        out.pop();
        return res;
    }

    ll minn() {
        ll minimum = LLINF;
        if(in.empty() || out.empty())
            minimum = in.empty() ? (ll)out.top().ss : (ll)in.top().ss;
        else
            minimum = min((ll)in.top().ss, (ll)out.top().ss);

        return minimum;
    }

    ll size() {
        return in.size() + out.size();
    }
};
```

3.7 Segtree Implicita

```
// SegTree Implicita O(nlogMAX)

struct node{
    int val;
    int l, r;
    node(int a=0, int b=0, int c=0){
        l=a;r=b;val=c;
    }
};

int idx=2; // 1-> root / 0-> zero element
node t[8600010];
int N;

int merge(int a, int b){
    return a + b;
}

void update(int pos, int x, int i=1, int j=N, int no=1){
    if(i==j){
        t[no].val+=x;
        return;
    }
    int meio = (i+j)/2;

    if(pos<=meio){
        if(t[no].l==0) t[no].l=idx++;
        update(pos, x, i, meio, t[no].l);
    }
    else{
        if(t[no].r==0) t[no].r=idx++;
        update(pos, x, meio+1, j, t[no].r);
    }

    t[no].val=merge(t[t[no].l].val, t[t[no].r].val);
}

int query(int A, int B, int i=1, int j=N, int no=1){
    if(B<i or j<A)
        return 0;
    if(A<=i and j<=B)
        return t[no].val;

    int mid = (i+j)/2;

    int ansl = 0, ansr = 0;

    if(t[no].l!=0) ansl = query(A, B, i, mid, t[no].l);
    if(t[no].r!=0) ansr = query(A, B, mid+1, j, t[no].r);

    return merge(ansl, ansr);
}
```

3.8 Segtree Implicita Lazy

```
struct node{
    pll val;
    ll lazy;
    ll l, r;
    node(){
        l=-1;r=-1;val={0,0};lazy=0;
    }
};

node tree[40*MAX];
int id = 2;
ll N=1e9+10;

pll merge(pll A, pll B){
    if(A.ff==B.ff) return {A.ff, A.ss+B.ss};
    return (A.ff<B.ff ? A:B);
}

void prop(ll l, ll r, int no){
    ll mid = (l+r)/2;
    if(l!=r){
        if(tree[no].l==-1){
            tree[no].l = id++;
            tree[tree[no].l].val = {0, mid-l+1};
        }
        if(tree[no].r==-1){
            tree[no].r = id++;
            tree[tree[no].r].val = {0, r-(mid+1)+1};
        }
        tree[tree[no].l].lazy += tree[no].lazy;
        tree[tree[no].r].lazy += tree[no].lazy;
    }
    tree[no].val.ff += tree[no].lazy;
    tree[no].lazy=0;
}

void update(int a, int b, int x, ll l=0, ll r=2*N, ll no=1){
    prop(l, r, no);
    if(a<=l and r<=b){
        tree[no].lazy += x;
        prop(l, r, no);
        return;
    }
    if(r<a or b<l) return;
    int m = (l+r)/2;
    update(a, b, x, l, m, tree[no].l);
    update(a, b, x, m+1, r, tree[no].r);

    tree[no].val = merge(tree[tree[no].l].val, tree[tree[no].r].val);
}

pll query(int a, int b, int l=0, int r=2*N, int no=1){
    prop(l, r, no);
    if(a<=l and r<=b) return tree[no].val;
    if(r<a or b<l) return {INF, 0};
    int m = (l+r)/2;
    int left = tree[no].l, right = tree[no].r;

    return tree[no].val = merge(query(a, b, l, m, left),
                                query(a, b, m+1, r, right));
}
```

3.9 Segtree Iterative

```
struct Segtree{
    int n; vector<int> t;
    Segtree(int n): n(n), t(2*n, 0) {}

    int f(int a, int b) { return max(a, b); }

    void build(){
        for(int i=n-1; i>0; i--)
            t[i] = f(t[i<<1], t[i<<1|1]);
    }

    int query(int l, int r) { // [l, r]
        int resl = -INF, resr = -INF;
        for(l+=n, r+=n+1; l<r; l>>=1, r>>=1) {
            if(l&1) resl = f(resl, t[l++]);
            if(r&1) resr = f(t[--r], resr);
        }
        return f(resl, resr);
    }

    void update(int p, int value) {
        for(t[p+=n]=value; p >>= 1;)
            t[p] = f(t[p<<1], t[p<<1|1]);
    }
};
```

3.10 Segtree Maxsubarray

```
// Subarray with maximum sum
struct no{
    ll p, s, t, b; // prefix, suffix, total, best
    no(ll x=0): p(x), s(x), t(x), b(x){}
};

struct Segtree{
    vector<no> t;
    int n;

    Segtree(int n){
        this->n = n;
        t.assign(2*n, no(0));
    }

    no merge(no l, no r){
        no ans;
        ans.p = max(0LL, max(l.p, l.t+r.p));
        ans.s = max(0LL, max(r.s, l.s+r.t));
        ans.t = l.t+r.t;
        ans.b = max(max(l.b, r.b), l.s+r.p);
        return ans;
    }

    void build(){
        for(int i=n-1; i>0; i--)
            t[i]=merge(t[i<<1], t[i<<1|1]);
    }

    no query(int l, int r){ // idx 0
        no a(0), b(0);
        for(l+=n, r+=n+1; l<r; l>>=1, r>>=1){
            if(l&1)
                a=merge(a, t[l++]);
            if(r&1)
                b=merge(t[--r], b);
        }
        return merge(a, b);
    }

    void update(int p, int value){
        for(t[p+=n] = no(value); p >>= 1;)
            t[p] = merge(t[p<<1], t[p<<1|1]);
    }

};
```

3.11 Segtree Pa

```
int N;
vl t(4*MAX, 0);
vl v(MAX, 0);
vector<pll> lazy(4*MAX, {0,0});
// [x, x+y, x+2y...] //

inline ll merge(ll a, ll b){
    return a + b;
}

void build(int l=0, int r=N-1, int no=1){
    if(l == r){ t[no] = v[l]; return; }
    int mid = (l + r) / 2;
    build(l, mid, 2*no);
    build(mid+1, r, 2*no+1);
    t[no] = merge(t[2*no], t[2*no+1]);
}

inline pll sum(pll a, pll b){ return {a.ff+b.ff, a.ss+b.ss}; }

inline void prop(int l, int r, int no){
    auto [x, y] = lazy[no];
    if(x==0 and y==0) return;
    ll len = (r-l+1);
    t[no] += (x + x + y*(len-1))*len / 2;
    if(l != r){
        int mid = (l + r) / 2;
        lazy[2*no] = sum(lazy[2*no], lazy[no]);
        lazy[2*no+1] = sum(lazy[2*no+1], {x + (mid-l+1)*y, y});
    }
    lazy[no] = {0,0};
}

ll query(int a, int b, int l=0, int r=N-1, int no=1){
    prop(l, r, no);
    if(r<a or b<l) return 0;
    if(a<=l and r<=b) return t[no];
    int mid = (l + r) / 2;
    return merge(
        query(a, b, l, mid, 2*no),
        query(a, b, mid+1, r, 2*no+1)
    );
}

void update(int a, int b, ll x, ll y, int l=0, int r=N-1, int no=1){
    prop(l, r, no);
    if(r<a or b<l) return;
    if(a<=l and r<=b){
        lazy[no] = {x, y};
        prop(l, r, no);
        return;
    }
    int mid = (l + r) / 2;
    update(a, b, x, y, l, mid, 2*no);
    update(a, b, x + max((mid-max(l, a)+1)*y, 0LL), y, mid+1, r, 2*no+1);
    t[no] = merge(t[2*no], t[2*no+1]);
}
```

3.12 Segtree Recursive

```
vector<ll> t(4*N, 0);
vector<ll> lazy(4*N, 0);

inline ll f(ll a, ll b) {
    return a + b;
}

void build(vector<int> &v, int lx=0, int rx=N-1, int x=1) {
```

```cpp
    if (lx == rx) { if (lx < v.size()) t[x] = v[lx]; return; }
    int mid = (lx + rx) / 2;
    build(v, lx, mid, 2*x);
    build(v, mid+1, rx, 2*x+1);
    t[x] = f(t[2*x], t[2*x+1]);
}

void prop(int lx, int rx, int x) {
    if (lazy[x] != 0) {
        t[x] += lazy[x] * (rx-lx+1);
        if (lx != rx) {
            lazy[2*x] += lazy[x];
            lazy[2*x+1] += lazy[x];
        }
        lazy[x] = 0;
    }
}

ll query(int l, int r, int lx=0, int rx=N-1, int x=1) {
    prop(lx, rx, x);
    if (r < lx or rx < l) return 0;
    if (l <= lx and rx <= r) return t[x];
    int mid = (lx + rx) / 2;
    return f(
        query(l, r, lx, mid, 2*x),
        query(l, r, mid+1, rx, 2*x+1)
    );
}

void update(int l, int r, ll val, int lx=0, int rx=N-1, int x=1) {
    prop(lx, rx, x);
    if (r < lx or rx < l) return;
    if (l <= lx and rx <= r) {
        lazy[x] += val;
        prop(lx, rx, x);
        return;
    }
    int mid = (lx + rx) / 2;
    update(l, r, val, lx, mid, 2*x);
    update(l, r, val, mid+1, rx, 2*x+1);
    t[x] = f(t[2*x], t[2*x+1]);
}
```

3.13 Sparse Table

```cpp
int logv[N+1];
void make_log() {
    logv[1] = 0; // pre-computar tabela de log
    for (int i = 2; i <= N; i++)
        logv[i] = logv[i/2] + 1;
}
struct Sparse {
    int n;
    vector<vector<int>> st;

    Sparse(vector<int>& v) {
        n = v.size();
        int k = logv[n];
        st.assign(n+1, vector<int>(k+1, 0));

        for (int i=0;i<n;i++) {
            st[i][0] = v[i];
        }

        for(int j = 1; j <= k; j++) {
            for(int i = 0; i + (1 << j) <= n; i++) {
                st[i][j] = f(st[i][j-1], st[i + (1 << (j-1))][j-1]);
            }
        }
    }

    int f(int a, int b) {
        return min(a, b);
    }

    int query(int l, int r) {
        int k = logv[r-l+1];
        return f(st[l][k], st[r - (1 << k) + 1][k]);
    }
};


struct Sparse2d {
    int n, m;
    vector<vector<vector<int>>> st;

    Sparse2d(vector<vector<int>> mat) {
        n = mat.size();
        m = mat[0].size();
        int k = logv[min(n, m)];

        st.assign(n+1, vector<vector<int>>(m+1, vector<int>(k+1)));
        for(int i = 0; i < n; i++)
            for(int j = 0; j < m; j++)
                st[i][j][0] = mat[i][j];

        for(int j = 1; j <= k; j++) {
            for(int x1 = 0; x1 < n; x1++) {
                for(int y1 = 0; y1 < m; y1++) {
                    int delta = (1 << (j-1));
                    if(x1+delta >= n or y1+delta >= m) continue;

                    st[x1][y1][j] = st[x1][y1][j-1];
                    st[x1][y1][j] = f(st[x1][y1][j], st[x1+delta][y1][j-1]);
                    st[x1][y1][j] = f(st[x1][y1][j], st[x1][y1+delta][j-1]);
                    st[x1][y1][j] = f(st[x1][y1][j], st[x1+delta][y1+delta][j-1]);
                }
            }
        }
    }

    // so funciona para quadrados
    int query(int x1, int y1, int x2, int y2) {
        assert(x2-x1+1 == y2-y1+1);
        int k = logv[x2-x1+1];
        int delta = (1 << k);

        int res = st[x1][y1][k];
        res = f(res, st[x2 - delta+1][y1][k]);
        res = f(res, st[x1][y2 - delta+1][k]);
        res = f(res, st[x2 - delta+1][y2 - delta+1][k]);
        return res;
    }

    int f(int a, int b) {
        return a | b;
    }

};
```

3.14 Treap

```cpp
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count()); // mt19937_64
uniform_int_distribution<int> distribution(1, INF);

```

```
const int N = 2e5+10;
int nxt = 0;
int X[N], Y[N], L[N], R[N], sz[N], idx[N];
bool flip[N];

//! Call this before anything else
void build() {
    iota(Y+1, Y+N, 1);
    shuffle(Y+1, Y+N, rng); // rng :: mt19937
}

int new_node(int x, int id) {
    int u = ++nxt;
    idx[u] = id;
    sz[u] = 1;
    X[u] = x;
    return u;
}

void push(int u) { // also known as unlaze
    if(!u) return;
    if (flip[u]) {
        flip[u] = false;
        flip[L[u]] ^= 1;
        flip[R[u]] ^= 1;
        swap(L[u], R[u]);
    }
}

void pull(int u) { // also known as fix
    if (!u) return;
    sz[u] = sz[L[u]] + 1 + sz[R[u]];
}

// root = merge(l, r);
int merge(int l, int r) {
    push(l); push(r);
    int u;
    if (!l || !r) {
        u = l ? l : r;
    } else if (Y[l] < Y[r]) {
        u = l;
        R[u] = merge(R[u], r);
    } else {
        u = r;
        L[u] = merge(l, L[u]);
    }
    pull(u);
    return u;
}

// (s elements, N - s elements)
pair<int, int> splitsz(int u, int s) {
    if (!u) return {0, 0};
    push(u);
    if (sz[L[u]] >= s) {
        auto [l, r] = splitsz(L[u], s);
        L[u] = r;
        pull(u);
        return { l, u };
    } else {
        auto [l, r] = splitsz(R[u], s - sz[L[u]] - 1);
        R[u] = l;
        pull(u);
        return { u, r };
    }
}

// (<= x, > x)
pair<int, int> splitval(int u, int x) {
    if (!u) return {0, 0};
    push(u);
    if (X[u] > x) {
        auto [l, r] = splitval(L[u], x);
        L[u] = r;
        pull(u);
        return { l, u };
    } else {
        auto [l, r] = splitval(R[u], x);
        R[u] = l;
        pull(u);
        return { u, r };
    }
}

int insert(int u, int node) {
    push(u);
    if (!u) return node;
    if (Y[node] < Y[u]) {
        tie(L[node], R[node]) = splitval(u, X[node]);
        u = node;
    }
    else if (X[node] < X[u]) L[u] = insert(L[u], node);
    else R[u] = insert(R[u], node);
    pull(u);
    return u;
}

int find(int u, int x) {
    return u == 0    ? 0 :
           x == X[u] ? u :
           x <  X[u] ? find(L[u], x) :
                       find(R[u], x);
}

void free(int u) { /* node u can be deleted, maybe put in a pool of free IDs */ }

int erase(int u, int key) {
    push(u);
    if (!u) return 0;
    if (X[u] == key) {
        int v = merge(L[u], R[u]);
        free(u);
        u = v;
    } else u = erase(key < X[u] ? L[u] : R[u], key);
    pull(u);
    return u;
}
```

3.15 Virtual Tree

```
bool initialized = false;
int original_root = 1;
const int E = 2 * N;
vector<int> vt[N]; // virtual tree edges
int in[N], out[N], T, t[E<<1];
void dfs_time(int u, int p = 0) {
    in[u] = ++T;
    t[T + E] = u;
    for (int v : g[u]) if (v != p) {
        dfs_time(v, u);
        t[++T + E] = u;
    }
    out[u] = T;
}

int take(int u, int v) { return in[u] < in[v] ? u : v; }
bool cmp_in(int u, int v) { return in[u] < in[v]; }
void build_st() {
    in[0] = 0x3f3f3f3f;
    for (int i = E-1; i > 0; i--)
        t[i] = take(t[i<<1], t[i<<1|1]);
}

int query(int l, int r) {
    int ans = 0;
    for (l+=E, r+=E; l < r; l>>=1, r>>=1) {
        if (l&1) ans = take(ans, t[l++]);
        if (r&1) ans = take(ans, t[--r]);
    }
    return ans;
}

int get_lca(int u, int v) {
    if (in[u] > in[v]) swap(u, v);
    return query(in[u], out[v]+1);
}

int covers(int u, int v) { // does u cover v?
    return in[u] <= in[v] && out[u] >= out[v];
}

int build_vt(vector<int>& vnodes) {
    assert(initialized);

    sort(all(vnodes), cmp_in);
    int n = vnodes.size();
    for (int i = 0; i < n-1; i++) {
        int u = vnodes[i], v = vnodes[i+1];
        vnodes.push_back(get_lca(u, v));
    }
    sort(all(vnodes), cmp_in);
    vnodes.erase(unique(all(vnodes)), vnodes.end());

    for (int u : vnodes)
        vt[u].clear();

    stack<int> s;
    for (int u : vnodes) {
        while (!s.empty() && !covers(s.top(), u))
            s.pop();
        if (!s.empty()) vt[s.top()].push_back(u);
        s.push(u);
    }
    return vnodes[0]; // root
}

void initialize() {
    initialized = true;
    dfs_time(original_root);
    build_st();
}
```

4 Geometria

4.1 2d

```
#define vp vector<point>
#define ld long double
const ld EPS = 1e-6;
const ld PI = acos(-1);

typedef ld T;
bool eq(T a, T b){ return abs(a - b) <= EPS; }

struct point{
    T x, y;
    int id;
    point(T x=0, T y=0): x(x), y(y){}

    point operator+(const point &o) const{ return {x + o.x, y + o.y}; }
    point operator-(const point &o) const{ return {x - o.x, y - o.y}; }
    point operator*(T t) const{ return {x * t, y * t}; }
    point operator/(T t) const{ return {x / t, y / t}; }
    T operator*(const point &o) const{ return x * o.x + y * o.y; }
    T operator^(const point &o) const{ return x * o.y - y * o.x; }
    bool operator<(const point &o) const{
        return (eq(x, o.x) ? y < o.y : x < o.x);
    }
    bool operator==(const point &o) const{
        return eq(x, o.x) and eq(y, o.y);
    }
    friend ostream& operator<<(ostream& os, point p) {
        return os << "(" << p.x << "," << p.y << ")"; }
};

int ccw(point a, point b, point e){ // -1=dir; 0=collinear; 1=esq;
    T tmp = (b-a) ^ (e-a); // vector from a to b
    return (tmp > EPS) - (tmp < -EPS);
}

ld norm(point a){ // Modulo
    return sqrt(a * a);
}
T norm2(point a){
    return a * a;
}
bool nulo(point a){
    return (eq(a.x, 0) and eq(a.y, 0));
}
point rotccw(point p, ld a){
    // a = PI*a/180; // graus
    return point((p.x*cos(a)-p.y*sin(a)), (p.y*cos(a)+p.x*sin(a)));
}
point rot90cw(point a) { return point(a.y, -a.x); };
point rot90ccw(point a) { return point(-a.y, a.x); };

ld proj(point a, point b){ // a sobre b
    return a*b/norm(b);
}
ld angle(point a, point b){ // em radianos
    ld ang = a*b / norm(a) / norm(b);
    return acos(max(min(ang, (ld)1), (ld)-1));
}
ld angle_vec(point v){
    // return 180/PI*atan2(v.x, v.y); // graus
    return atan2(v.x, v.y);
}
ld order_angle(point a, point b){ // from a to b ccw (a in front of b)
    ld aux = angle(a,b)*180/PI;
    return ((a^b)<=0 ? aux:360-aux);
}
bool angle_less(point a1, point b1, point a2, point b2){ // ang(a1,b1) <= ang(a2,b2)
    point p1((a1*b1), abs((a1^b1)));
    point p2((a2*b2), abs((a2^b2)));
    return (p1^p2) <= 0;
}

ld area(vp &p){ // (points sorted)
    ld ret = 0;
    for(int i=2;i<(int)p.size();i++)
        ret += (p[i]-p[0])^(p[i-1]-p[0]);
    return abs(ret/2);
}
ld areaT(point &a, point &b, point &c){
    return abs((b-a)^(c-a))/2.0;
}

point center(vp &A){
    point c = point();
    int len = A.size();
    for(int i=0;i<len;i++)
        c=c+A[i];
    return c/len;
}

point forca_mod(point p, ld m){
    ld cm = norm(p);
    if(cm<EPS) return point();
    return point(p.x*m/cm,p.y*m/cm);
}

ld param(point a, point b, point v){
    // v = t*(b-a) + a // return t;
    // assert(line(a, b).inside_seg(v));
    return ((v-a) * (b-a)) / ((b-a) * (b-a));
}

bool simetric(vp &a){ //ordered
    int n = a.size();
    point c = center(a);
    if(n&1) return false;
    for(int i=0;i<n/2;i++)
        if(ccw(a[i], a[i+n/2], c) != 0)
            return false;
    return true;
}

point mirror(point m1, point m2, point p){
    // mirror point p around segment m1m2
    point seg = m2-m1;
    ld t0 = ((p-m1)*seg) / (seg*seg);
    point ort = m1 + seg*t0;
    point pm = ort-(p-ort);
    return pm;
}


///////////
//  Line  //
///////////

struct line{
    point p1, p2;
    T a, b, c; // ax+by+c = 0;
    // y-y1 = ((y2-y1)/(x2-x1))(x-x1)
    line(point p1=0, point p2=0): p1(p1), p2(p2){
        a = p1.y - p2.y;
        b = p2.x - p1.x;
        c = p1 ^ p2;
    }
    line(T a=0, T b=0, T c=0): a(a), b(b), c(c){
        // Gera os pontos p1 p2 dados os coeficientes
        // isso aqui eh um lixo mas quebra um galho kkkkkk
        if(b==0){
            p1 = point(1, -c/a);
            p2 = point(0, -c/a);
        }else{
            p1 = point(1, (-c-a*1)/b);
            p2 = point(0, -c/b);
        }
    }

    T eval(point p){
        return a*p.x+b*p.y+c;
    }
    bool inside(point p){
        return eq(eval(p), 0);
    }
    point normal(){
        return point(a, b);
    }

    bool inside_seg(point p){
        return (
            ((p1-p) ^ (p2-p)) == 0 and
            ((p1-p) * (p2-p)) <= 0
        );
    }

};

// be careful with precision error
vp inter_line(line l1, line l2){
    ld det = l1.a*l2.b - l1.b*l2.a;
    if(det==0) return {};
    ld x = (l1.b*l2.c - l1.c*l2.b)/det;
    ld y = (l1.c*l2.a - l1.a*l2.c)/det;
    return {point(x, y)};
}

// segments not collinear
vp inter_seg(line l1, line l2){
    vp ans = inter_line(l1, l2);
    if(ans.empty() or !l1.inside_seg(ans[0]) or !l2.inside_seg(ans[0]))
        return {};
    return ans;
}
bool seg_has_inter(line l1, line l2){
    return ccw(l1.p1, l1.p2, l2.p1) * ccw(l1.p1, l1.p2, l2.p2) < 0 and
           ccw(l2.p1, l2.p2, l1.p1) * ccw(l2.p1, l2.p2, l1.p2) < 0;
}

ld dist_seg(point p, point a, point b){ // point - seg
    if((p-a)*(b-a) < EPS) return norm(p-a);
    if((p-b)*(a-b) < EPS) return norm(p-b);
    return abs((p-a)^(b-a)) / norm(b-a);
}

ld dist_line(point p, line l){ // point - line
    return abs(l.eval(p))/sqrt(l.a*l.a + l.b*l.b);
}

line bisector(point a, point b){
    point d = (b-a)*2;
    return line(d.x, d.y, a*a - b*b);
}

line perpendicular(line l, point p){ // passes through p
    return line(l.b, -l.a, -l.b*p.x + l.a*p.y);
}


///////////
// Circle //
///////////

struct circle{
    point c; T r;
    circle() : c(0, 0), r(0){}
    circle(const point o) : c(o), r(0){}
    circle(const point a, const point b){
        c = (a+b)/2;
        r = norm(a-c);
    }
    circle(const point a, const point b, const point cc){
        assert(ccw(a, b, cc) != 0);
        c = inter_line(bisector(a, b), bisector(b, cc))[0];
        r = norm(a-c);
    }
    bool inside(const point &a) const{
        return norm(a - c) <= r + EPS;
    }
};

pair<point, point> tangent_points(circle cr, point p) {
    ld d1 = norm(p-cr.c), theta = asin(cr.r/d1);
    point p1 = rotccw(cr.c-p, -theta);
    point p2 = rotccw(cr.c-p, theta);
    assert(d1 >= cr.r);
    p1 = p1 * (sqrt(d1*d1-cr.r*cr.r) / d1) + p;
    p2 = p2 * (sqrt(d1*d1-cr.r*cr.r) / d1) + p;
    return {p1, p2};
}


circle incircle(point p1, point p2, point p3){
    ld m1 = norm(p2-p3);
    ld m2 = norm(p1-p3);
    ld m3 = norm(p1-p2);
    point c = (p1*m1 + p2*m2 + p3*m3)*(1/(m1+m2+m3));
    ld s = 0.5*(m1+m2+m3);
    ld r = sqrt(s*(s-m1)*(s-m2)*(s-m3)) / s;
    return circle(c, r);
}

circle circumcircle(point a, point b, point c) {
    circle ans;
    point u = point((b-a).y, -(b-a).x);
    point v = point((c-a).y, -(c-a).x);
    point n = (c-b)*0.5;
    ld t = (u^n)/(v^u);
    ans.c = ((a+c)*0.5) + (v*t);
    ans.r = norm(ans.c-a);
    return ans;
}

vp inter_circle_line(circle C, line L){
    point ab = L.p2 - L.p1, p = L.p1 + ab * ((C.c-L.p1)*(ab) / (ab*ab));
    ld s = (L.p2-L.p1)^(C.c-L.p1), h2 = C.r*C.r - s*s / (ab*ab);
    if (h2 < -EPS) return {};
    if (eq(h2, 0)) return {p};
    point h = (ab/norm(ab)) * sqrt(h2);
    return {p - h, p + h};
}

vp inter_circle(circle c1, circle c2){
    if (c1.c == c2.c) { assert(c1.r != c2.r); return {}; }
    point vec = c2.c - c1.c;
    ld d2 = vec * vec, sum = c1.r + c2.r, dif = c1.r - c2.r;
    ld p = (d2 + c1.r * c1.r - c2.r * c2.r) / (2 * d2);
    ld h2 = c1.r * c1.r - p * p * d2;
    if (sum * sum < d2 or dif * dif > d2) return {};
    point mid = c1.c + vec * p, per = point(-vec.y, vec.x) * sqrt(fmax(0, h2) / d2);
    if (eq(per.x, 0) and eq(per.y, 0)) return {mid};
    return {mid + per, mid - per};
}

// minimum circle cover O(n) amortizado
circle min_circle_cover(vp v){
    random_shuffle(v.begin(), v.end());
    circle ans;
    int n = v.size();
    for(int i=0;i<n;i++) if(!ans.inside(v[i])){
        ans = circle(v[i]);
        for(int j=0;j<i;j++) if(!ans.inside(v[j])){
            ans = circle(v[i], v[j]);
            for(int k=0;k<j;k++) if(!ans.inside(v[k])){
                ans = circle(v[i], v[j], v[k]);
            }
        }
    }
    return ans;
}
```

4.2 3d

```
// typedef ll cod;
// bool eq(cod a, cod b){ return (a==b); }

const ld EPS = 1e-6;
#define vp vector<point>
typedef ld cod;
bool eq(cod a, cod b){ return fabs(a - b) <= EPS; }

struct point
{
    cod x, y, z;
    point(cod x=0, cod y=0, cod z=0): x(x), y(y), z(z) {}

    point operator+(const point &o) const {
        return {x+o.x, y+o.y, z+o.z};
    }
    point operator-(const point &o) const {
        return {x-o.x, y-o.y, z-o.z};
    }
    point operator*(cod t) const {
        return {x*t, y*t, z*t};
    }
    point operator/(cod t) const {
        return {x/t, y/t, z/t};
    }
    bool operator==(const point &o) const {
        return eq(x, o.x) and eq(y, o.y) and eq(z, o.z);
    }
    cod operator*(const point &o) const { // dot
        return x*o.x + y*o.y + z*o.z;
    }
    point operator^(const point &o) const { // cross
        return point(y*o.z - z*o.y,
                     z*o.x - x*o.z,
                     x*o.y - y*o.x);
    }
};

ld norm(point a) { // Modulo
    return sqrt(a * a);
}
cod norm2(point a) {
    return a * a;
}
bool nulo(point a) {
    return (eq(a.x, 0) and eq(a.y, 0) and eq(a.z, 0));
}
ld proj(point a, point b) { // a sobre b
    return (a*b)/norm(b);
}
ld angle(point a, point b) { // em radianos
```

```
    return acos((a*b) / norm(a) / norm(b));
}

cod triple(point a, point b, point c) {
    return (a * (b^c)); // Area do paralelepipedo
}

point normilize(point a) {
    return a/norm(a);
}

struct plane {
    cod a, b, c, d;
    point p1, p2, p3;
    plane(point p1=0, point p2=0, point p3=0): p1(p1), p2(p2), p3(p3) {
        point aux = (p1-p3)^(p2-p3);
        a = aux.x; b = aux.y; c = aux.z;
        d = -a*p1.x - b*p1.y - c*p1.z;
    }
    plane(point p, point normal) {
        normal = normilize(normal);
        a = normal.x; b = normal.y; c = normal.z;
        d = -(p*normal);
    }

    // ax+by+cz+d = 0;
    cod eval(point &p) {
        return a*p.x + b*p.y + c*p.z + d;
    }
};

cod dist(plane pl, point p) {
    return fabs(pl.a*p.x + pl.b*p.y + pl.c*p.z + pl.d) / sqrt(pl.a*pl.a + pl.b*pl.b + pl.c*pl.c);
}

point rotate(point v, point k, ld theta) {
    // Rotaciona o vetor v theta graus em torno do eixo k
    // theta *= PI/180; // graus
    return (
        v*cos(theta)) +
        ((k^v)*sin(theta)) +
        (k*(k*v))*(1-cos(theta)
    );
}

// 3d line inter / mindistance
cod d(point p1, point p2, point p3, point p4) {
    return (p2-p1) * (p4-p3);
}
vector<point> inter3d(point p1, point p2, point p3, point p4) {
    cod mua = ( d(p1, p3, p4, p3) * d(p4, p3, p2, p1) - d(p1, p3, p2, p1) * d(p4, p3, p4, p3) )
            / ( d(p2, p1, p2, p1) * d(p4, p3, p4, p3) - d(p4, p3, p2, p1) * d(p4, p3, p2, p1) );
    cod mub = ( d(p1, p3, p4, p3) + mua * d(p4, p3, p2, p1) ) / d(p4, p3, p4, p3);
    point pa = p1 + (p2-p1) * mua;
    point pb = p3 + (p4-p3) * mub;
    if (pa == pb) return {pa};
    return {};
}
```

4.3 Convex Hull

```
vp convex_hull(vp P)
{
    sort(P.begin(), P.end());
    vp L, U;
    for(auto p: P){
        while(L.size()>=2 and ccw(L.end()[-2], L.back(), p)!=1)
            L.pop_back();
        L.push_back(p);
    }
    reverse(P.begin(), P.end());
    for(auto p: P){
        while(U.size()>=2 and ccw(U.end()[-2], U.back(), p)!=1)
            U.pop_back();
        U.push_back(p);
    }
    L.pop_back();
    L.insert(L.end(), U.begin(), U.end()-1);
    return L;
}
```

4.4 Delaunay

```
cod areaT2(point &a, point &b, point &c){
    return abs((b-a)^(c-a));
}

typedef struct QuadEdge* Q;
struct QuadEdge {
    int id;
    point o;
    Q rot, nxt;
    bool used;

    QuadEdge(int id_ = -1, point o_ = point(INF, INF)) :
        id(id_), o(o_), rot(nullptr), nxt(nullptr), used(false) {}

    Q rev() const { return rot->rot; }
    Q next() const { return nxt; }
    Q prev() const { return rot->next()->rot; }
    point dest() const { return rev()->o; }
};

Q edge(point from, point to, int id_from, int id_to) {
    Q e1 = new QuadEdge(id_from, from);
    Q e2 = new QuadEdge(id_to, to);
    Q e3 = new QuadEdge;
    Q e4 = new QuadEdge;
    tie(e1->rot, e2->rot, e3->rot, e4->rot) = {e3, e4, e2, e1};
    tie(e1->nxt, e2->nxt, e3->nxt, e4->nxt) = {e1, e2, e4, e3};
    return e1;
}

void splice(Q a, Q b) {
    swap(a->nxt->rot->nxt, b->nxt->rot->nxt);
    swap(a->nxt, b->nxt);
}

void del_edge(Q& e, Q ne) { // delete e and assign e <- ne
    splice(e, e->prev());
    splice(e->rev(), e->rev()->prev());
    delete e->rev()->rot, delete e->rev();
    delete e->rot; delete e;
    e = ne;
}

Q conn(Q a, Q b) {
    Q e = edge(a->dest(), b->o, a->rev()->id, b->id);
    splice(e, a->rev()->prev());
    splice(e->rev(), b);
    return e;
}

bool in_c(point a, point b, point c, point p) { // p ta na circunf. (a, b, c) ?
    __int128 p2 = p*p, A = a*a - p2, B = b*b - p2, C = c*c - p2;
    return areaT2(p, a, b) * C + areaT2(p, b, c) * A + areaT2(p, c, a) * B > 0;
}

pair<Q, Q> build_tr(vector<point>& p, int l, int r) {
    if (r-l+1 <= 3) {
        Q a = edge(p[l], p[l+1], l, l+1), b = edge(p[l+1], p[r], l+1, r);
        if (r-l+1 == 2) return {a, a->rev()};
        splice(a->rev(), b);
        ll ar = areaT2(p[l], p[l+1], p[r]);
        Q c = ar ? conn(b, a) : 0;
        if (ar >= 0) return {a, b->rev()};
        return {c->rev(), c};
    }
    int m = (l+r)/2;
    auto [la, ra] = build_tr(p, l, m);
    auto [lb, rb] = build_tr(p, m+1, r);
    while (true) {
        if (ccw(lb->o, ra->o, ra->dest())) ra = ra->rev()->prev();
        else if (ccw(lb->o, ra->o, lb->dest())) lb = lb->rev()->next();
        else break;
    }
    Q b = conn(lb->rev(), ra);
    auto valid = [&](Q e) { return ccw(e->dest(), b->dest(), b->o); };
    if (ra->o == la->o) la = b->rev();
    if (lb->o == rb->o) rb = b;
    while (true) {
        Q L = b->rev()->next();
        if (valid(L)) while (in_c(b->dest(), b->o, L->dest(), L->next()->dest()))
            del_edge(L, L->next());
        Q R = b->prev();
        if (valid(R)) while (in_c(b->dest(), b->o, R->dest(), R->prev()->dest()))
            del_edge(R, R->prev());
        if (!valid(L) and !valid(R)) break;
        if (!valid(L) or (valid(R) and in_c(L->dest(), L->o, R->o, R->dest())))
            b = conn(R, b->rev());
        else b = conn(b->rev(), L->rev());
    }
    return {la, rb};
}

vector<vector<int>> delaunay(vp v) {
    int n = v.size();
    auto tmp = v;
    vector<int> idx(n);
    iota(idx.begin(), idx.end(), 0);
    sort(idx.begin(), idx.end(), [&](int l, int r) { return v[l] < v[r]; });
    for (int i = 0; i < n; i++) v[i] = tmp[idx[i]];
    assert(unique(v.begin(), v.end()) == v.end());
    vector<vector<int>> g(n);
    bool col = true;
    for (int i = 2; i < n; i++) if (areaT2(v[i], v[i-1], v[i-2])) col = false;
    if (col) {
        for (int i = 1; i < n; i++)
            g[idx[i-1]].push_back(idx[i]), g[idx[i]].push_back(idx[i-1]);
        return g;
    }
    Q e = build_tr(v, 0, n-1).first;
    vector<Q> edg = {e};
    for (int i = 0; i < edg.size(); e = edg[i++]) {
        for (Q at = e; !at->used; at = at->next()) {
            at->used = true;
            g[idx[at->id]].push_back(idx[at->rev()->id]);
            edg.push_back(at->rev());
        }
    }
    return g;
}
```

4.5 Halfplane Inter

```
struct Halfplane {
    point p, pq;
    ld angle;
    Halfplane() {}
    Halfplane(const point &a, const point &b) : p(a), pq(b - a) {
        angle = atan2l(pq.y, pq.x);
    }

    bool out(const point &r) { return (pq ^ (r - p)) < -EPS; }
    bool operator<(const Halfplane &e) const { return angle < e.angle; }

    friend point inter(const Halfplane &s, const Halfplane &t) {
        ld alpha = ((t.p - s.p) ^ t.pq) / (s.pq ^ t.pq);
        return s.p + (s.pq * alpha);
    }
};

vp hp_intersect(vector<Halfplane> &H) {

    point box[4] = {
        point(LLINF, LLINF),
        point(-LLINF, LLINF),
        point(-LLINF, -LLINF),
        point(LLINF, -LLINF)
    };

    for(int i = 0; i < 4; i++) {
        Halfplane aux(box[i], box[(i+1) % 4]);
        H.push_back(aux);
    }

    sort(H.begin(), H.end());
    deque<Halfplane> dq;
    int len = 0;
    for(int i = 0; i < (int)H.size(); i++) {

        while (len > 1 && H[i].out(inter(dq[len-1], dq[len-2]))) {
            dq.pop_back();
            --len;
        }

        while (len > 1 && H[i].out(inter(dq[0], dq[1]))) {
            dq.pop_front();
            --len;
        }

        if (len > 0 && fabsl((H[i].pq ^ dq[len-1].pq)) < EPS) {
            if ((H[i].pq * dq[len-1].pq) < 0.0)
                return vp();

            if (H[i].out(dq[len-1].p)) {
                dq.pop_back();
                --len;
            }
            else continue;
        }

        dq.push_back(H[i]);
        ++len;
    }

    while (len > 2 && dq[0].out(inter(dq[len-1], dq[len-2]))) {
        dq.pop_back();
        --len;
    }

    while (len > 2 && dq[len-1].out(inter(dq[0], dq[1]))) {
        dq.pop_front();
        --len;
    }

    if (len < 3) return vp();

    vp ret(len);
    for(int i = 0; i+1 < len; i++) {
        ret[i] = inter(dq[i], dq[i+1]);
    }
    ret.back() = inter(dq[len-1], dq[0]);
    return ret;
}

// O(n3)
vp half_plane_intersect(vector<line> &v){
    vp ret;
    int n = v.size();
    for(int i=0; i<n; i++){
        for(int j=i+1; j<n; j++){
            point crs = inter(v[i], v[j]);
            if(crs.x == INF) continue;
            bool bad = 0;
            for(int k=0; k<n; k++)
                if(v[k].eval(crs) < -EPS){
                    bad = 1;
                    break;
                }

            if(!bad) ret.push_back(crs);
        }
    }
    return ret;
}
```

4.6 Inside Polygon

```
// Convex O(logn)

bool insideT(point a, point b, point c, point e){
    int x = ccw(a, b, e);
    int y = ccw(b, c, e);
    int z = ccw(c, a, e);
    return !((x==1 or y==1 or z==1) and (x==-1 or y==-1 or z==-1));
}

bool inside(vp &p, point e){ // ccw
    int l=2, r=(int)p.size()-1;
    while(l<r){
        int mid = (l+r)/2;
        if(ccw(p[0], p[mid], e) == 1)
            l=mid+1;
        else{
            r=mid;
        }
    }
    // bordo
    // if(r==(int)p.size()-1 and ccw(p[0], p[r], e)==0) return false;
    // if(r==2 and ccw(p[0], p[1], e)==0) return false;
    // if(ccw(p[r], p[r-1], e)==0) return false;
    return insideT(p[0], p[r-1], p[r], e);
}


// Any O(n)

int inside(vp &p, point pp){
    // 1 - inside / 0 - boundary / -1 - outside
    int n = p.size();
    for(int i=0;i<n;i++){
        int j = (i+1)%n;
        if(line({p[i], p[j]}).inside_seg(pp))
            return 0;
    }
    int inter = 0;
    for(int i=0;i<n;i++){
        int j = (i+1)%n;
        if(p[i].x <= pp.x and pp.x < p[j].x and ccw(p[i], p[j], pp)==1)
            inter++; // up
        else if(p[j].x <= pp.x and pp.x < p[i].x and ccw(p[i], p[j], pp)==-1)
            inter++; // down
    }

    if(inter%2==0) return -1; // outside
    else return 1; // inside
}
```

4.7 Intersect Polygon

```
bool intersect(vector<point> A, vector<point> B) // Ordered ccw
{
    for(auto a: A)
        if(inside(B, a))
            return true;
    for(auto b: B)
        if(inside(A, b))
            return true;

    if(inside(B, center(A)))
        return true;

    return false;
}
```

4.8 Kdtree

```
bool on_x(const point& a, const point& b) { return a.x < b.x; }
bool on_y(const point& a, const point& b) { return a.y < b.y; }
bool on_z(const point& a, const point& b) { return a.z < b.z; }

struct Node {
    point pt; // if this is a leaf, the single point in it
    cod x0 = LLINF, x1 = -LLINF, y0 = LLINF, y1 = -LLINF, z0 = LLINF, z1 = -LLINF; // bounds
    Node *first = 0, *second = 0;

    cod distance(const point &p) { // min squared distance to a point
        cod x = (p.x < x0 ? x0 : p.x > x1 ? x1 : p.x);
        cod y = (p.y < y0 ? y0 : p.y > y1 ? y1 : p.y);
        cod z = (p.z < z0 ? z0 : p.z > z1 ? z1 : p.z);
        return norm(point(x,y,z) - p);
    }

    Node(vp&& p) : pt(p[0]) {
        for (point pi : p) {
            x0 = min(x0, pi.x); x1 = max(x1, pi.x);
            y0 = min(y0, pi.y); y1 = max(y1, pi.y);
            z0 = min(z0, pi.z); z1 = max(z1, pi.z);
        }
        if (p.size() > 1) {
            auto cmp = (x1-x0 >= y1-y0 and x1-x0 >= z1-z0 ? on_x : (y1-y0 >= z1-z0 ? on_y:on_z));
            sort(p.begin(), p.end(), cmp);
            // divide by taking half the array for each child (not
            // best performance with many duplicates in the middle)
            int half = p.size() / 2;
            first = new Node({p.begin(), p.begin() + half});
            second = new Node({p.begin() + half, p.end()});
        }
    }
};

struct KDTree {
    Node* root;
    KDTree(const vp& p) : root(new Node({p.begin(), p.end()})) {}

    pair<cod, point> search(Node *node, const point& p) {
        if (!node->first) {
            // uncomment if we should not find the point itself:
            if (p == node->pt) return {LLINF, point()};
            return make_pair(norm(p - node->pt), node->pt);
        }

        Node *f = node->first, *s = node->second;
        cod bfirst = f->distance(p), bsec = s->distance(p);
        if (bfirst > bsec) swap(bsec, bfirst), swap(f, s);

        auto best = search(f, p);
        if (bsec < best.first)
            best = min(best, search(s, p));
        return best;
    }

    // find nearest point to a point, and its squared distance
    // (requires an arbitrary operator< for Point)
    pair<cod, point> nearest(const point& p) {
        return search(root, p);
    }
};
```

4.9 Lichao

```
struct Lichao { // min
    struct line {
        ll a, b;
        array<int, 2> ch;
        line(ll a_ = 0, ll b_ = LLINF) : a(a_), b(b_), ch({-1, -1}) {}
        ll operator ()(ll x) { return a * x + b; }
    };
    vector<line> ln;

    int ch(int p, int d) {
        if (ln[p].ch[d] == -1) {
            ln[p].ch[d] = ln.size();
            ln.emplace_back();
        }
        return ln[p].ch[d];
    }
    Lichao() { ln.emplace_back(); }

    void add(line s, ll l=-N, ll r=N, int p=0) {
        ll m = (l+r)/2;
        bool L = s(l) < ln[p](l);
        bool M = s(m) < ln[p](m);
        bool R = s(r) < ln[p](r);
        if (M) swap(ln[p], s), swap(ln[p].ch, s.ch);
        if (s.b == LLINF) return;
        if (L != M) add(s, l, m-1, ch(p, 0));
        else if (R != M) add(s, m+1, r, ch(p, 1));
    }
    ll query(int x, ll l=-N, ll r=N, int p=0) {
        ll m = (l + r) / 2, ret = ln[p](x);
        if (ret == LLINF) return ret;
        if (x < m) return min(ret, query(x, l, m-1, ch(p, 0)));
        return min(ret, query(x, m+1, r, ch(p, 1)));
    }
};
```

4.10 Linear Transformation

```
// Apply linear transformation (p -> q) to r.
point linear_transformation(point p0, point p1, point q0, point q1, point r) {
    point dp = p1-p0, dq = q1-q0, num((dp^dq), (dp^dq));
    return q0 + point((r-p0)^(num), (r-p0)*(num))/(dp*dp);
}
```

4.11 Mindistpair

```
ll MinDistPair(vp &vet){
    int n = vet.size();
    sort(vet.begin(), vet.end());
    set<point> s;

    ll best_dist = LLINF;
    int j=0;
    for(int i=0;i<n;i++){
        ll d = ceil(sqrt(best_dist));
        while(j<n and vet[i].x-vet[j].x >= d){
            s.erase(point(vet[j].y, vet[j].x));
            j++;
        }

        auto it1 = s.lower_bound({vet[i].y - d, vet[i].x});
        auto it2 = s.upper_bound({vet[i].y + d, vet[i].x});

        for(auto it=it1; it!=it2; it++){
            ll dx = vet[i].x - it->y;
            ll dy = vet[i].y - it->x;
            if(best_dist > dx*dx + dy*dy){
                best_dist = dx*dx + dy*dy;
                // vet[i] e inv(it)
            }
        }

        s.insert(point(vet[i].y, vet[i].x));
    }
    return best_dist;
}
```

4.12 Minkowski Sum

```
vp minkowski(vp p, vp q){
    int n = p.size(), m = q.size();
    auto reorder = [&](vp &p) {
        // set the first vertex must be the lowest
        int id = 0;
        for(int i=1;i<p.size();i++){
            if(p[i].y < p[id].y or (p[i].y == p[id].y and p[i].x < p[id].x))
                id = i;
        }
        rotate(p.begin(), p.begin() + id, p.end());
    };

    reorder(p); reorder(q);
    p.push_back(p[0]);
    q.push_back(q[0]);
    vp ans; int i = 0, j = 0;
    while(i < n or j < m){
        ans.push_back(p[i] + q[j]);
        cod cross = (p[i+1] - p[i]) ^ (q[j+1] - q[j]);
        if(cross >= 0) i ++;
        if(cross <= 0) j ++;
    }
    return ans;
}
```

4.13 Numintersectionline

```
int main()
{
    int lim = 1e6;
    Segtree st(lim+100);
    int n, m, y, x, l, r;
    cin >> n >> m;

    int open=-1, close=INF; // open -> check -> close
    vector< pair<int, pii> > sweep;

    ll ans = 0;
    for(int i=0;i<n;i++){ // horizontal
        cin >> y >> l >> r;
        sweep.pb({l, {open, y}});
        sweep.pb({r, {close, y}});
    }
    for(int i=0;i<m;i++){ // vertical
        cin >> x >> l >> r;
        sweep.pb({x, {l, r}});
    }
    sort(sweep.begin(), sweep.end());

    // set<int> on;
    for(auto s: sweep){
        if(s.ss.ff==open){
            st.update(s.ss.ss, 1);
            // on.insert(s.ss.ss);
        }
        else if(s.ss.ff==close){
            st.update(s.ss.ss, -1);
            // on.erase(s.ss.ss);
        }
        else{
            ans += st.query(s.ss.ff, s.ss.ss);
            // auto it1 = on.lower_bound(s.ss.ff);
            // auto it2 = on.upper_bound(s.ss.ss);
            // for(auto it = it1; it!=it2; it++){
            //     intersection -> (s.ff, it);
            // }
        }
    }

    cout << ans << endl;


    return 0;
}
```

4.14 Polygon Cut Length

```
// Polygon Cut length
ld solve(vp &p, point a, point b){ // ccw
    int n = p.size();
    ld ans = 0;

    for(int i=0;i<n;i++){
        int j = (i+1) % n;

        int signi = ccw(a, b, p[i]);
        int signj = ccw(a, b, p[j]);

        if(signi == 0 and signj == 0){
            if((b-a) * (p[j]-p[i]) > 0){
                ans += param(a, b, p[j]);
                ans -= param(a, b, p[i]);
            }
        }else if(signi <= 0 and signj > 0){
            ans -= param(a, b, inter_line({a, b}, {p[i], p[j]})[0]);
        }else if(signi > 0 and signj <= 0){
            ans += param(a, b, inter_line({a, b}, {p[i], p[j]})[0]);
        }
    }

    return abs(ans * norm(b-a));
}
```

4.15 Polygon Diameter

```
pair<point, point> polygon_diameter(vp p) {
    p = convex_hull(p);
    int n = p.size(), j = n<2 ? 0:1;
    pair<ll, vp> res({0, {p[0], p[0]}});
    for (int i=0;i<j;i++){
        for (;; j = (j+1) % n) {
            res = max(res, {norm2(p[i] - p[j]), {p[i], p[j]}});
            if ((p[(j + 1) % n] - p[j]) ^ (p[i + 1] - p[i]) >= 0)
                break;
        }
    }
    return res.second;
}

double diameter(const vector<point> &p) {
    vector<point> h = convexHull(p);
    int m = h.size();
    if (m == 1)
        return 0;
    if (m == 2)
```

```
        return dist(h[0], h[1]);
    int k = 1;
    while (area(h[m - 1], h[0], h[(k + 1) % m]) > area(h[m - 1], h[0], h[k]))
        ++k;
    double res = 0;
    for (int i = 0, j = k; i <= k && j < m; i++) {
        res = max(res, dist(h[i], h[j]));
        while (j < m && area(h[i], h[(i + 1) % m], h[(j + 1) % m]) > area(h[i], h[(i + 1) % m], h[j])) {
            res = max(res, dist(h[i], h[(j + 1) % m]));
            ++j;
        }
    }
    return res;
}
```

4.16 Rotating Callipers

```
int N;

int sum(int i, int x){
    if(i+x>N-1) return (i+x-N);
    return i+x;
}

ld rotating_callipers(vp &vet){
    N = vet.size();
    ld ans = 0;
    // 2 triangulos (p1, p3, p4) (p1, p2, p3);
    for(int i=0;i<N;i++){ // p1
        int p2 = sum(i, 1); // p2
        int p4 = sum(i, 3); // p4
        for(int j=sum(i, 2);j!=i;j=sum(j, 1)){ // p3
            if(j==p2) p2 = sum(p2, 1);
            while(sum(p2, 1)!=j and areaT(vet[p2], vet[i], vet[j]) < areaT(vet[sum(p2, 1)], vet[i], vet[j]))
                p2 = sum(p2, 1);
            while(sum(p4, 1)!=i and areaT(vet[p4], vet[i], vet[j]) < areaT(vet[sum(p4, 1)], vet[i], vet[j]))
                p4 = sum(p4, 1);

            ans = max(ans, area(vet[i], vet[p2], vet[j], vet[p4]));
        }
    }

    return ans;
}
```

4.17 Sort By Angle

```
// Comparator funcion for sorting points by angle

int ret[2][2] = {{3, 2},{4, 1}};
inline int quad(point p) {
    return ret[p.x >= 0][p.y >= 0];
}

bool comp(point a, point b) { // ccw
    int qa = quad(a), qb = quad(b);
    return (qa == qb ? (a ^ b) > 0 : qa < qb);
}

// only vectors in range [x+0, x+180)
bool comp(point a, point b){
    return (a ^ b) > 0; // ccw
    // return (a ^ b) < 0; // cw
}
```

4.18 Tetrahedron Distance3d

```
bool nulo(point a){
    return (eq(a.x, 0) and eq(a.y, 0) and eq(a.z, 0));
}

ld misto(point p1, point p2, point p3){
    return (p1^p2)*p3;
}

ld dist_pt_face(point p, vp v){
    assert(v.size()==3);

    point v1 = v[1]-v[0];
    point v2 = v[2]-v[0];
    point n = (v1^v2);

    for(int i=0;i<3;i++){
        point va = p-v[i];
        point vb = v[(i+1)%3]-v[i];
        point ve = vb^n;
        ld d = ve*v[i];
        //se ponto coplanar com um dos lados do prisma (va^vb eh nulo),
        //ele esta dentro do prisma (poderia desconsiderar pois distancia
        //vai ser a msm da distancia do ponto ao segmento)
        if(!nulo(va^vb) and (v[(i+2)%3]*ve>d) ^ (p*ve>d)) return LLINF;
    }

    //se ponto for coplanar ao triangulo (e dentro do triangulo)
    //vai retornar zero corretamente
    return fabs(misto(p-v[0],v1,v2)/norm(n));
}

ld dist_pt_seg(point p, vp li){
    return norm((li[1]-li[0])^(p-li[0]))/norm(li[1]-li[0]);
}

ld dist_line(vp l1, vp l2){
    point n = (l1[1]-l1[0])^(l2[1]-l2[0]);
    if(nulo(n)) //retas paralelas - dist ponto a reta
        return dist_pt_seg(l2[0],l1);

    point o1o2 = l2[0]-l1[0];
    return fabs((o1o2*n)/norm(n));
}
// retas paralelas e intersecao nao nula
ld dist_seg(vp l1, vp l2){

    assert(l2.size()==2);
    assert(l1.size()==2);

    //pontos extremos do segmento
    ld ans = LLINF;
    for(int i=0;i<2;i++)
        for(int j=0;j<2;j++)
            ans = min(ans, norm(l1[i]-l2[j]));

    //verificando distancia de ponto extremo com ponto interno dos segs
    for(int t=0;t<2;t++){
        for(int i=0;i<2;i++){
            bool c=true;
            for(int k=0;k<2;k++){
                point va = l1[i]-l2[k];
```

```cpp
                point vb = l2[!k]-l2[k];
                ld ang = atan2(norm((vb^va)), vb*va);
                if(ang>PI/2) c = false;
            }
            if(c)
                ans = min(ans,dist_pt_seg(l1[i],l2));
        }
        swap(l1,l2);
    }

    //ponto interno com ponto interno dos segmentos
    point v1 = l1[1]-l1[0], v2 = l2[1]-l2[0];
    point n = v1^v2;
    if(!nulo(n)){
        bool ok = true;
        for(int t=0;t<2;t++){
            point n2 = v2^n;
            point o1o2 = l2[0]-l1[0];
            ld escalar = (o1o2*n2)/(v1*n2);
            if(escalar<0 or escalar>1) ok = false;
            swap(l1,l2);
            swap(v1,v2);
        }
        if(ok) ans = min(ans,dist_line(l1,l2));
    }

    return ans;
}

ld ver(vector<vp> &vet){
    ld ans = LLINF;
    // vertice - face
    for(int k=0;k<2;k++)
        for(int pt=0;pt<4;pt++)
            for(int i=0;i<4;i++){
                vp v;
                for(int j=0;j<4;j++){
                    if(i!=j) v.pb(vet[!k][j]);
                }
                ans = min(ans, dist_pt_face(vet[k][pt], v));
            }

    // edge - edge
    for(int i1=0;i1<4;i1++)
        for(int j1=0;j1<i1;j1++)
            for(int i2=0;i2<4;i2++)
                for(int j2=0;j2<i2;j2++)
                    ans = min(ans, dist_seg({vet[0][i1], vet[0][j1]},
                                            {vet[1][i2], vet[1][j2]}));

    return ans;
}
```

4.19 Voronoi

```cpp
bool polygonIntersection(line &seg, vp &p) {
    long double l = -1e18, r = 1e18;
    for(auto ps : p) {
        long double z = seg.eval(ps);
        l = max(l, z);
        r = min(r, z);
    }
    return l - r > EPS;
}

int w, h;

line getBisector(point a, point b) {
    line ans(a, b);
    swap(ans.a, ans.b);
    ans.b *= -1;
    ans.c = ans.a * (a.x + b.x) * 0.5 + ans.b * (a.y + b.y) * 0.5;
    return ans;
}

vp cutPolygon(vp poly, line seg) {
    int n = (int) poly.size();
    vp ans;
    for(int i = 0; i < n; i++) {
        double z = seg.eval(poly[i]);
        if(z > -EPS) {
            ans.push_back(poly[i]);
        }
        double z2 = seg.eval(poly[(i + 1) % n]);
        if((z > EPS && z2 < -EPS) || (z < -EPS && z2 > EPS)) {
            ans.push_back(inter_line(seg, line(poly[i], poly[(i + 1) % n]))[0]);
        }
    }
    return ans;
}

// BE CAREFUL!
// the first point may be any point
// O(N^3)
vp getCell(vp pts, int i) {
    vp ans;
    ans.emplace_back(0, 0);
    ans.emplace_back(1e6, 0);
    ans.emplace_back(1e6, 1e6);
    ans.emplace_back(0, 1e6);
    for(int j = 0; j < (int) pts.size(); j++) {
        if(j != i) {
            ans = cutPolygon(ans, getBisector(pts[i], pts[j]));
        }
    }
    return ans;
}

// O(N^2) expected time
vector<vp> getVoronoi(vp pts) {
    // assert(pts.size() > 0);
    int n = (int) pts.size();
    vector<int> p(n, 0);
    for(int i = 0; i < n; i++) {
        p[i] = i;
    }
    shuffle(p.begin(), p.end(), rng);
    vector<vp> ans(n);
    ans[0].emplace_back(0, 0);
    ans[0].emplace_back(w, 0);
    ans[0].emplace_back(w, h);
    ans[0].emplace_back(0, h);
    for(int i = 1; i < n; i++) {
        ans[i] = ans[0];
    }
    for(auto i : p) {
        for(auto j : p) {
            if(j == i) break;
            auto bi = getBisector(pts[j], pts[i]);
            if(!polygonIntersection(bi, ans[j])) continue;
            ans[j] = cutPolygon(ans[j], getBisector(pts[j], pts[i]));
            ans[i] = cutPolygon(ans[i], getBisector(pts[i], pts[j]));
        }
    }
    return ans;
}
```

5 Grafos

5.1 2sat

```cpp
#define rep(i,l,r) for (int i = (l); i < (r); i++)
struct TwoSat { // copied from kth-competitive-programming/kactl
    int N;
    vector<vi> gr;
    vi values; // 0 = false, 1 = true
    TwoSat(int n = 0) : N(n), gr(2*n) {}
    int addVar() { // (optional)
        gr.emplace_back();
        gr.emplace_back();
        return N++;
    }
    void either(int f, int j) {
        f = max(2*f, -1-2*f);
        j = max(2*j, -1-2*j);
        gr[f].push_back(j^1);
        gr[j].push_back(f^1);
    }
    void atMostOne(const vi& li) { // (optional)
        if ((int)li.size() <= 1) return;
        int cur = ~li[0];
        rep(i,2,(int)li.size()) {
            int next = addVar();
            either(cur, ~li[i]);
            either(cur, next);
            either(~li[i], next);
            cur = ~next;
        }
        either(cur, ~li[1]);
    }
    vi _val, comp, z; int time = 0;
    int dfs(int i) {
        int low = _val[i] = ++time, x; z.push_back(i);
        for(int e : gr[i]) if (!comp[e])
            low = min(low, _val[e] ?: dfs(e));
        if (low == _val[i]) do {
            x = z.back(); z.pop_back();
            comp[x] = low;
            if (values[x>>1] == -1)
                values[x>>1] = x&1;
        } while (x != i);
        return _val[i] = low;
    }
    bool solve() {
        values.assign(N, -1);
        _val.assign(2*N, 0); comp = _val;
        rep(i,0,2*N) if (!comp[i]) dfs(i);
        rep(i,0,N) if (comp[2*i] == comp[2*i+1]) return 0;
        return 1;
    }
};
```

5.2 Block Cut Tree

```cpp
// Block-Cut Tree do brunomaletta
// art[i] responde o numero de novas componentes conexas
// criadas apos a remocao de i do grafo g
// Se art[i] >= 1, i eh ponto de articulacao
//
// Para todo i <= blocks.size()
// blocks[i] eh uma componente 2-vertce-conexa maximal
// edgblocks[i] sao as arestas do bloco i
// tree[i] eh um vertice da arvore que corresponde ao bloco i
//
// pos[i] responde a qual vertice da arvore vertice i pertence
// Arvore tem no maximo 2n vertices

struct block_cut_tree {
    vector<vector<int>> g, blocks, tree;
    vector<vector<pair<int, int>>> edgblocks;
    stack<int> s;
    stack<pair<int, int>> s2;
    vector<int> id, art, pos;

    block_cut_tree(vector<vector<int>> g_) : g(g_) {
        int n = g.size();
        id.resize(n, -1), art.resize(n), pos.resize(n);
        build();
    }

    int dfs(int i, int& t, int p = -1) {
        int lo = id[i] = t++;
        s.push(i);

        if (p != -1) s2.emplace(i, p);
        for (int j : g[i]) if (j != p and id[j] != -1) s2.emplace(i, j);

        for (int j : g[i]) if (j != p) {
            if (id[j] == -1) {
                int val = dfs(j, t, i);
                lo = min(lo, val);

                if (val >= id[i]) {
                    art[i]++;
                    blocks.emplace_back(1, i);
                    while (blocks.back().back() != j)
                        blocks.back().push_back(s.top()), s.pop();

                    edgblocks.emplace_back(1, s2.top()), s2.pop();
                    while (edgblocks.back().back() != pair(j, i))
                        edgblocks.back().push_back(s2.top()), s2.pop();
                }
                // if (val > id[i]) aresta i-j eh ponte
            }
            else lo = min(lo, id[j]);
        }

        if (p == -1 and art[i]) art[i]--;
        return lo;
    }

    void build() {
        int t = 0;
        for (int i = 0; i < g.size(); i++) if (id[i] == -1) dfs(i, t, -1);

        tree.resize(blocks.size());
        for (int i = 0; i < g.size(); i++) if (art[i])
            pos[i] = tree.size(), tree.emplace_back();

        for (int i = 0; i < blocks.size(); i++) for (int j : blocks[i]) {
            if (!art[j]) pos[j] = i;
            else tree[i].push_back(pos[j]), tree[pos[j]].push_back(i);
        }
    }
};
```

5.3 Centroid Decomp

```
vector<int> g[N];
int sz[N], rem[N];

void dfs(vector<int>& path, int u, int d=0, int p=-1) {
    path.push_back(d);
    for (int v : g[u]) if (v != p and !rem[v]) dfs(path, v, d+1, u);
}

int dfs_sz(int u, int p=-1) {
    sz[u] = 1;
    for (int v : g[u]) if (v != p and !rem[v]) sz[u] += dfs_sz(v, u);
    return sz[u];
}

int centroid(int u, int p, int size) {
    for (int v : g[u]) if (v != p and !rem[v] and sz[v] > size / 2)
        return centroid(v, u, size);
    return u;
}

ll decomp(int u, int k) {
    int c = centroid(u, u, dfs_sz(u));
    rem[c] = true;

    ll ans = 0;
    vector<int> cnt(sz[u]);
    cnt[0] = 1;
    for (int v : g[c]) if (!rem[v]) {
        vector<int> path;
        dfs(path, v);
        // d1 + d2 + 1 == k
        for (int d : path) if (0 <= k-d-1 and k-d-1 < sz[u])
            ans += cnt[k-d-1];
        for (int d : path) cnt[d+1]++;
    }

    for (int v : g[c]) if (!rem[v]) ans += decomp(v, k);
    return ans;
}
```

5.4 Dfs Tree

```
int desce[N], sobe[N], vis[N], h[N];
int backedges[N], pai[N];

// backedges[u] = backedges que comecam embaixo de (ou =) u e sobem pra cima de u; backedges[u] == 0 => u eh ponte
void dfs(int u, int p) {
    if(vis[u]) return;
    pai[u] = p;
    h[u] = h[p]+1;
    vis[u] = 1;

    for(auto v : g[u]) {
        if(p == v or vis[v]) continue;
        dfs(v, u);
        backedges[u] += backedges[v];
    }
    for(auto v : g[u]) {
        if(h[v] > h[u]+1)
            desce[u]++;
        else if(h[v] < h[u]-1)
            sobe[u]++;
    }
    backedges[u] += sobe[u] - desce[u];
}
```

5.5 Dinic

```
const int N = 300;

struct Dinic {
    struct Edge{
        int from, to; ll flow, cap;
    };
    vector<Edge> edge;

    vector<int> g[N];
    int ne = 0;
    int lvl[N], vis[N], pass;
    int qu[N], px[N], qt;

    ll run(int s, int sink, ll minE) {
        if(s == sink) return minE;

        ll ans = 0;

        for(; px[s] < (int)g[s].size(); px[s]++) {
            int e = g[s][ px[s] ];
            auto &v = edge[e], &rev = edge[e^1];
            if(lvl[v.to] != lvl[s]+1 || v.flow >= v.cap)
                continue;           // v.cap - v.flow < lim
            ll tmp = run(v.to, sink,min(minE, v.cap-v.flow));
            v.flow += tmp, rev.flow -= tmp;
            ans += tmp, minE -= tmp;
            if(minE == 0) break;
        }
        return ans;
    }
    bool bfs(int source, int sink) {
        qt = 0;
        qu[qt++] = source;
        lvl[source] = 1;
        vis[source] = ++pass;
        for(int i = 0; i < qt; i++) {
            int u = qu[i];
            px[u] = 0;
            if(u == sink) return true;
            for(auto& ed : g[u]) {
                auto v = edge[ed];
                if(v.flow >= v.cap || vis[v.to] == pass)
                    continue; // v.cap - v.flow < lim
                vis[v.to] = pass;
                lvl[v.to] = lvl[u]+1;
                qu[qt++] = v.to;
            }
        }
        return false;
    }
    ll flow(int source, int sink) {
        reset_flow();
        ll ans = 0;
        //for(lim = (1LL << 62); lim >= 1; lim /= 2)
        while(bfs(source, sink))
            ans += run(source, sink, LLINF);
        return ans;
    }
    void addEdge(int u, int v, ll c, ll rc) {
        Edge e = {u, v, 0, c};
        edge.pb(e);
        g[u].push_back(ne++);

        e = {v, u, 0, rc};
        edge.pb(e);
        g[v].push_back(ne++);
    }
    void reset_flow() {
        for(int i = 0; i < ne; i++)
            edge[i].flow = 0;
        memset(lvl, 0, sizeof(lvl));
        memset(vis, 0, sizeof(vis));
        memset(qu, 0, sizeof(qu));
        memset(px, 0, sizeof(px));
        qt = 0; pass = 0;
    }
    vector<pair<int, int>> cut() {
        vector<pair<int, int>> cuts;
        for (auto [from, to, flow, cap]: edge) {
            if (flow == cap and vis[from] == pass and vis[to] < pass and cap>0) {
                cuts.pb({from, to});
            }
        }
        return cuts;
    }
};
```

5.6 Dominator Tree

```
// Dominator Tree
// idom[x] = immediate dominator of x

vector<int> g[N], gt[N], T[N];
vector<int> S;
int dsu[N], label[N];
int sdom[N], idom[N], dfs_time, id[N];

vector<int> bucket[N];
vector<int> down[N];

void prep(int u){
    S.push_back(u);
    id[u] = ++dfs_time;
    label[u] = sdom[u] = dsu[u] = u;

    for(int v : g[u]){
        if(!id[v])
            prep(v), down[u].push_back(v);
        gt[v].push_back(u);
    }
}

int fnd(int u, int flag = 0){
    if(u == dsu[u]) return u;
    int v = fnd(dsu[u], 1), b = label[ dsu[u] ];
    if(id[ sdom[b] ] < id[ sdom[ label[u] ] ])
        label[u] = b;
    dsu[u] = v;
    return flag ? v : label[u];
}

void build_dominator_tree(int root, int sz){
    // memset(id, 0, sizeof(int) * (sz + 1));
    // for(int i = 0; i <= sz; i++) T[i].clear();
    prep(root);
    reverse(S.begin(), S.end());

    int w;
    for(int u : S){
        for(int v : gt[u]){
            w = fnd(v);
            if(id[ sdom[w] ] < id[ sdom[u] ])
                sdom[u] = sdom[w];
        }
        gt[u].clear();

        if(u != root) bucket[ sdom[u] ].push_back(u);

        for(int v : bucket[u]){
            w = fnd(v);
            if(sdom[w] == sdom[v]) idom[v] = sdom[v];
            else idom[v] = w;
        }
        bucket[u].clear();

        for(int v : down[u]) dsu[v] = u;
        down[u].clear();
    }

    reverse(S.begin(), S.end());
    for(int u : S) if(u != root){
        if(idom[u] != sdom[u]) idom[u] = idom[ idom[u] ];
        T[ idom[u] ].push_back(u);
    }
    S.clear();
}
```

5.7 Ford

```
const int N = 2000010;

struct Ford {
    struct Edge {
        int to, f, c;
    };

    int vis[N];
    vector<int> adj[N];
    vector<Edge> edges;
    int cur = 0;

    void addEdge(int a, int b, int cap, int rcap) {
        Edge e;
        e.to = b; e.c = cap; e.f = 0;
        edges.pb(e);
        adj[a].pb(cur++);

        e = Edge();
        e.to = a; e.c = rcap; e.f = 0;
        edges.pb(e);
        adj[b].pb(cur++);
    }

    int dfs(int s, int t, int f, int tempo) {
        if(s == t)
            return f;
        vis[s] = tempo;

        for(int e : adj[s]) {
            if(vis[edges[e].to] < tempo and (edges[e].c - edges[e].f) > 0) {
                if(int a = dfs(edges[e].to, t, min(f, edges[e].c-edges[e].f) , tempo)) {
                    edges[e].f += a;
                    edges[e^1].f -= a;
                    return a;
                }
            }
        }
        return 0;
    }

    int flow(int s, int t) {
        int mflow = 0, tempo = 1;
        while(int a = dfs(s, t, INF, tempo)) {
            mflow += a;
            tempo++;
        }
        return mflow;
    }
};
```

5.8 Hld Aresta

```
// Use it together with recursive_segtree
const int N = 3e5+10;
vector<vector<pair<int, int>>> g(N, vector<pair<int, int>>());
vector<int> in(N), inv(N), sz(N);
vector<int> peso(N), pai(N);
vector<int> head(N), tail(N), h(N);

int tin;

void dfs(int u, int p=-1, int depth=0){
    sz[u] = 1; h[u] = depth;
    for(auto &i: g[u]) if(i.ff != p){
        auto [v, w] = i;
        dfs(v, u, depth+1);
        pai[v] = u; sz[u] += sz[v]; peso[v] = w;
        if (sz[v] > sz[g[u][0].ff] or g[u][0].ff == p) swap(i, g[u][0]);
    }
}
void build_hld(int u, int p = -1) {
    v[in[u] = tin++] = peso[u]; tail[u] = u;
    inv[tin-1] = u;
    for(auto &i: g[u]) if(i.ff != p) {
        int v = i.ff;
        head[v] = (i == g[u][0] ? head[u] : v);
        build_hld(v, u);
    }
    if(g[u].size() > 1) tail[u] = tail[g[u][0].ff];
}
void init_hld(int root = 0) {
    dfs(root);
    tin = 0;
    build_hld(root);
    build();
}
void reset(){
    g.assign(N, vector<pair<int,int>>());
    in.assign(N, 0), sz.assign(N, 0);
    peso.assign(N, 0), pai.assign(N, 0);
    head.assign(N, 0); tail.assign(N, 0);
    h.assign(N, 0); inv.assign(N, 0);

    t.assign(4*N, 0); v.assign(N, 0);
    lazy.assign(4*N, 0);
}
ll query_path(int a, int b) {
    if (a == b) return 0;
    if(in[a] < in[b]) swap(a, b);

    if(head[a] == head[b]) return query(in[b]+1, in[a]);
    return merge(query(in[head[a]], in[a]), query_path(pai[head[a]], b));
}
void update_path(int a, int b, int x) {
    if (a == b) return;
    if(in[a] < in[b]) swap(a, b);

    if(head[a] == head[b]) return (void)update(in[b]+1, in[a], x);
    update(in[head[a]], in[a], x); update_path(pai[head[a]], b, x);
}
ll query_subtree(int a) {
    if(sz[a] == 1) return 0;
    return query(in[a]+1, in[a]+sz[a]-1);
}
void update_subtree(int a, int x) {
    if(sz[a] == 1) return;
    update(in[a]+1, in[a]+sz[a]-1, x);
}
int lca(int a, int b) {
    if(in[a] < in[b]) swap(a, b);
    return head[a] == head[b] ? b : lca(pai[head[a]], b);
}
```

5.9 Hld Vertice

```
// Use it together with recursive_segtree
const int N = 3e5+10;
vector<vector<int>> g(N, vector<int>());
vector<int> in(N), inv(N), sz(N);
vector<int> peso(N), pai(N);
vector<int> head(N), tail(N), h(N);

int tin;

void dfs(int u, int p=-1, int depth=0){
    sz[u] = 1; h[u] = depth;
    for(auto &v: g[u]) if(v != p){
        dfs(v, u, depth+1);
        pai[v] = u; sz[u] += sz[v];
        if (sz[v] > sz[g[u][0]] or g[u][0] == p) swap(v, g[u][0]);
    }
}
void build_hld(int u, int p = -1) {
    v[in[u] = tin++] = peso[u]; tail[u] = u;
    inv[tin-1] = u;
    for(auto &v: g[u]) if(v != p) {
        head[v] = (v == g[u][0] ? head[u] : v);
        build_hld(v, u);
    }
    if(g[u].size() > 1) tail[u] = tail[g[u][0]];
}
void init_hld(int root = 0) {
    dfs(root);
    tin = 0;
    build_hld(root);
    build();
}
void reset(){
    g.assign(N, vector<int>());
    in.assign(N, 0), sz.assign(N, 0);
    peso.assign(N, 0), pai.assign(N, 0);
    head.assign(N, 0); tail.assign(N, 0);
    h.assign(N, 0); inv.assign(N, 0);

    t.assign(4*N, 0); v.assign(N, 0);
    lazy.assign(4*N, 0);
}
ll query_path(int a, int b) {
    if(in[a] < in[b]) swap(a, b);

    if(head[a] == head[b]) return query(in[b], in[a]);
    return merge(query(in[head[a]], in[a]), query_path(pai[head[a]], b));
}
void update_path(int a, int b, int x) {
    if(in[a] < in[b]) swap(a, b);

    if(head[a] == head[b]) return (void)update(in[b], in[a], x);
    update(in[head[a]], in[a], x); update_path(pai[head[a]], b, x);
}
ll query_subtree(int a) {
    return query(in[a], in[a]+sz[a]-1);
}
void update_subtree(int a, int x) {
    update(in[a], in[a]+sz[a]-1, x);
}
int lca(int a, int b) {
    if(in[a] < in[b]) swap(a, b);
    return head[a] == head[b] ? b : lca(pai[head[a]], b);
}
```

5.10 Hungarian

```
// Hungarian Algorithm
//
// Assignment problem
// Put the edges in the ’a’ matrix (negative or positive)
// assignment() returns a pair with the min assignment,
// and the column choosen by each row
// assignment() - O(n^3)

template<typename T>
struct hungarian {
    int n, m;
    vector<vector<T>> a;
    vector<T> u, v;
    vector<int> p, way;
    T inf;

    hungarian(int n_, int m_) : n(n_), m(m_), u(m+1), v(m+1), p(m+1), way(m+1) {
        a = vector<vector<T>>(n, vector<T>(m));
        inf = numeric_limits<T>::max();
    }
    pair<T, vector<int>> assignment() {
        for (int i = 1; i <= n; i++) {
            p[0] = i;
            int j0 = 0;
            vector<T> minv(m+1, inf);
            vector<int> used(m+1, 0);
            do {
                used[j0] = true;
                int i0 = p[j0], j1 = -1;
                T delta = inf;
                for (int j = 1; j <= m; j++) if (!used[j]) {
                    T cur = a[i0-1][j-1] - u[i0] - v[j];
                    if (cur < minv[j]) minv[j] = cur, way[j] = j0;
                    if (minv[j] < delta) delta = minv[j], j1 = j;
                }
                for (int j = 0; j <= m; j++)
                    if (used[j]) u[p[j]] += delta, v[j] -= delta;
                    else minv[j] -= delta;
                j0 = j1;
            } while (p[j0] != 0);
            do {
                int j1 = way[j0];
                p[j0] = p[j1];
                j0 = j1;
            } while (j0);
        }
        vector<int> ans(m);
        for (int j = 1; j <= n; j++) ans[p[j]-1] = j-1;
        return make_pair(-v[0], ans);
    }
};
```

5.11 Kosaraju

```
vector<int> g[N], gi[N]; // grafo invertido
int vis[N], comp[N]; // componente conexo de cada vertice
stack<int> S;

void dfs(int u){
    vis[u] = 1;
    for(auto v: g[u]) if(!vis[v]) dfs(v);
    S.push(u);
}

void scc(int u, int c){
    vis[u] = 1; comp[u] = c;
    for(auto v: gi[u]) if(!vis[v]) scc(v, c);
}

void kosaraju(int n){
    for(int i=0;i<n;i++) vis[i] = 0;
    for(int i=0;i<n;i++) if(!vis[i]) dfs(i);
    for(int i=0;i<n;i++) vis[i] = 0;
    while(S.size()){
        int u = S.top();
        S.pop();
        if(!vis[u]) scc(u, u);
    }
}
```

5.12 Lca

```
template<typename T> struct rmq {
    vector<T> v;
    int n; static const int b = 30;
    vector<int> mask, t;

    int op(int x, int y) { return v[x] < v[y] ? x : y; }
    int msb(int x) { return __builtin_clz(1)-__builtin_clz(x); }
    rmq() {}
    rmq(const vector<T>& v_) : v(v_), n(v.size()), mask(n), t(n) {
        for (int i = 0, at = 0; i < n; mask[i++] = at |= 1) {
            at = (at<<1)&((1<<b)-1);
            while (at and op(i, i-msb(at&-at)) == i) at ^= at&-at;
        }
        for (int i = 0; i < n/b; i++) t[i] = b*i+b-1-msb(mask[b*i+b-1]);
        for (int j = 1; (1<<j) <= n/b; j++) for (int i = 0; i+(1<<j) <= n/b; i++)
            t[n/b*j+i] = op(t[n/b*(j-1)+i], t[n/b*(j-1)+i+(1<<(j-1))]);
    }
    int small(int r, int sz = b) { return r-msb(mask[r]&((1<<sz)-1)); }
    T query(int l, int r) {
        if (r-l+1 <= b) return small(r, r-l+1);
        int ans = op(small(l+b-1), small(r));
        int x = l/b+1, y = r/b-1;
        if (x <= y) {
            int j = msb(y-x+1);
            ans = op(ans, op(t[n/b*j+x], t[n/b*j+y-(1<<j)+1]));
```

```cpp
        }
        return ans;
    }
};

namespace lca {
    vector<int> g[MAX];
    int v[2*MAX], pos[MAX], dep[2*MAX];
    int t;
    rmq<int> RMQ;

    void dfs(int i, int d = 0, int p = -1) {
        v[t] = i, pos[i] = t, dep[t++] = d;
        for (int j : g[i]) if (j != p) {
            dfs(j, d+1, i);
            v[t] = i, dep[t++] = d;
        }
    }
    void build(int n, int root) {
        t = 0;
        dfs(root);
        RMQ = rmq<int>(vector<int>(dep, dep+2*n-1));
    }
    int lca(int a, int b) {
        a = pos[a], b = pos[b];
        return v[RMQ.query(min(a, b), max(a, b))];
    }
    int dist(int a, int b) {
        return dep[pos[a]] + dep[pos[b]] - 2*dep[pos[lca(a, b)]];
    }
}

// binary lift

const int LOG = 22;
vector<vector<int>> g(N);
int t, n;
vector<int> in(N), height(N);
vector<vector<int>> up(LOG, vector<int>(N));
void dfs(int u, int h=0, int p=-1) {
    up[0][u] = p;
    in[u] = t++;
    height[u] = h;
    for (auto v: g[u]) if (v != p) dfs(v, h+1, u);
}

void blift() {
    up[0][0] = 0;
    for (int i=1;i<LOG;i++) {
        for (int j=0;j<n;j++) {
            up[i][j] = up[i-1][up[i-1][j]];
        }
    }
}

int lca(int u, int v) {
    if (u == v) return u;
    if (in[u] < in[v]) swap(u, v);
    for (int i=LOG-1;i>=0;i--) {
        int u2 = up[i][u];
        if (in[u2] > in[v])
            u = u2;
    }
    return up[0][u];
}

t = 0;
dfs(0);
blift();
```

5.13 Mcmf

```cpp
template <class T = int>
class MCMF {
public:
    struct Edge {
        Edge(int a, T b, T c) : to(a), cap(b), cost(c) {}
        int to;
        T cap, cost;
    };

    MCMF(int size) {
        n = size;
        edges.resize(n);
        pot.assign(n, 0);
        dist.resize(n);
        visit.assign(n, false);
    }

    std::pair<T, T> mcmf(int src, int sink) {
        std::pair<T, T> ans(0, 0);
        if(!SPFA(src, sink)) return ans;
        fixPot();
        // can use dijkstra to speed up depending on the graph
        while(SPFA(src, sink)) {
            auto flow = augment(src, sink);
            ans.first += flow.first;
            ans.second += flow.first * flow.second;
            fixPot();
        }
        return ans;
    }

    void addEdge(int from, int to, T cap, T cost) {
        edges[from].push_back(list.size());
        list.push_back(Edge(to, cap, cost));
        edges[to].push_back(list.size());
        list.push_back(Edge(from, 0, -cost));
    }
private:
    int n;
    std::vector<std::vector<int>> edges;
    std::vector<Edge> list;
    std::vector<int> from;
    std::vector<T> dist, pot;
    std::vector<bool> visit;

    /*bool dij(int src, int sink) {
        T INF = std::numeric_limits<T>::max();
        dist.assign(n, INF);
        from.assign(n, -1);
        visit.assign(n, false);
        dist[src] = 0;
        for(int i = 0; i < n; i++) {
            int best = -1;
            for(int j = 0; j < n; j++) {
                if(visit[j]) continue;
                if(best == -1 || dist[best] > dist[j]) best = j;
            }
            if(dist[best] >= INF) break;
            visit[best] = true;
            for(auto e : edges[best]) {
                auto ed = list[e];
                if(ed.cap == 0) continue;
                T toDist = dist[best] + ed.cost + pot[best] - pot[ed.to];
                assert(toDist >= dist[best]);
                if(toDist < dist[ed.to]) {
                    dist[ed.to] = toDist;
                    from[ed.to] = e;
                }
            }
        }
        return dist[sink] < INF;
    }*/

    std::pair<T, T> augment(int src, int sink) {
        std::pair<T, T> flow = {list[from[sink]].cap, 0};
        for(int v = sink; v != src; v = list[from[v]^1].to) {
            flow.first = std::min(flow.first, list[from[v]].cap);
            flow.second += list[from[v]].cost;
        }
        for(int v = sink; v != src; v = list[from[v]^1].to) {
            list[from[v]].cap -= flow.first;
            list[from[v]^1].cap += flow.first;
        }
        return flow;
    }

    std::queue<int> q;
    bool SPFA(int src, int sink) {
        T INF = std::numeric_limits<T>::max();
        dist.assign(n, INF);
        from.assign(n, -1);
        q.push(src);
        dist[src] = 0;
        while(!q.empty()) {
            int on = q.front();
            q.pop();
            visit[on] = false;
            for(auto e : edges[on]) {
                auto ed = list[e];
                if(ed.cap == 0) continue;
                T toDist = dist[on] + ed.cost + pot[on] - pot[ed.to];
                if(toDist < dist[ed.to]) {
                    dist[ed.to] = toDist;
                    from[ed.to] = e;
                    if(!visit[ed.to]) {
                        visit[ed.to] = true;
                        q.push(ed.to);
                    }
                }
            }
        }
        return dist[sink] < INF;
    }

    void fixPot() {
        T INF = std::numeric_limits<T>::max();
        for(int i = 0; i < n; i++) {
            if(dist[i] < INF) pot[i] += dist[i];
        }
    }
};
```

5.14 Mcmf Quirino

```
struct Dinitz {
  struct Edge {
    int v, u, cap, flow=0, cost;
    Edge(int v, int u, int cap, int cost) : v(v), u(u), cap(cap), cost(cost) {}
  };

  int n, s, t;
  Dinitz(int n, int s, int t) : n(n), s(s), t(t) {
    adj.resize(n);
  }

  vector<Edge> edges;
  vector<vector<int>> adj;
  void add_edge(int v, int u, int cap, int cost) {
    edges.eb(v, u, cap, cost);
    adj[v].pb(sz(edges)-1);
    edges.eb(u, v, 0, -cost);
    adj[u].pb(sz(edges)-1);
  }

  vector<int> dist;
  bool spfa() {
    dist.assign(n, LLINF);

    queue<int> Q;
    vector<bool> inqueue(n, false);

    dist[s] = 0;
    Q.push(s);
    inqueue[s] = true;

    vector<int> cnt(n);

    while (!Q.empty()) {
      int v = Q.front(); Q.pop();
      inqueue[v] = false;

      for (auto eid : adj[v]) {
        auto const& e = edges[eid];
        if (e.cap - e.flow <= 0) continue;
        if (dist[e.u] > dist[e.v] + e.cost) {
          dist[e.u] = dist[e.v] + e.cost;
          if (!inqueue[e.u]) {
            Q.push(e.u);
            inqueue[e.u] = true;
          }
        }
      }
    }

    return dist[t] != LLINF;
  }

  int cost = 0;
  vector<int> ptr;
  int dfs(int v, int f) {
    if (v == t || f == 0) return f;
    for (auto &cid = ptr[v]; cid < sz(adj[v]);) {
      auto eid = adj[v][cid];
      auto &e = edges[eid];
      cid++;
      if (e.cap - e.flow <= 0) continue;
      if (dist[e.v] + e.cost != dist[e.u]) continue;
      int newf = dfs(e.u, min(f, e.cap-e.flow));
      if (newf == 0) continue;
      e.flow += newf;
      edges[eid^1].flow -= newf;
      cost += e.cost * newf;
      return newf;
    }
    return 0;
  }

  int total_flow = 0;
  int flow() {
    while (spfa()) {
      ptr.assign(n, 0);
      while (int newf = dfs(s, LLINF))
        total_flow += newf;
    }
    return total_flow;
  }
};
```

6 Math

6.1 Berlekamp Massey

```cpp

#define SZ 233333

ll qp(ll a,ll b)
{
    ll x=1; a%=MOD;
    while(b)
    {
        if(b&1) x=x*a%MOD;
        a=a*a%MOD; b>>=1;
    }
    return x;
}
namespace linear_seq {

inline vector<int> BM(vector<int> x)
{
    //ls: (shortest) relation sequence (after filling zeroes) so far
    //cur: current relation sequence
    vector<int> ls,cur;
    //lf: the position of ls (t')
    //ldt: delta of ls (v')
    int lf=0,ldt=0;
    for(int i=0;i<int(x.size());++i)
    {
        ll t=0;
        //evaluate at position i
        for(int j=0;j<int(cur.size());++j)
            t=(t+x[i-j-1]*(ll)cur[j])%MOD;
        if((t-x[i])%MOD==0) continue; //good so far
        //first non-zero position
        if(!cur.size())
        {
            cur.resize(i+1);
            lf=i; ldt=(t-x[i])%MOD;
            continue;
        }
        //cur=cur-c/ldt*(x[i]-t)
        ll k=-(x[i]-t)*qp(ldt,MOD-2)%MOD/*1/ldt*/;
        vector<int> c(i-lf-1); //add zeroes in front
        c.pb(k);
        for(int j=0;j<int(ls.size());++j)
            c.pb(-ls[j]*k%MOD);
        if(c.size()<cur.size()) c.resize(cur.size());
        for(int j=0;j<int(cur.size());++j)
            c[j]=(c[j]+cur[j])%MOD;
        //if cur is better than ls, change ls to cur
        if(i-lf+(int)ls.size()>=(int)cur.size())
            ls=cur,lf=i,ldt=(t-x[i])%MOD;
        cur=c;
    }
    for(int i=0;i<int(cur.size());++i)
        cur[i]=(cur[i]%MOD+MOD)%MOD;
    return cur;
}
int m; //length of recurrence
//a: first terms
//h: relation
ll a[SZ],h[SZ],t_[SZ],s[SZ],t[SZ];
//calculate p*q mod f
inline void mull(ll*p,ll*q)
{
    for(int i=0;i<m+m;++i) t_[i]=0;
    for(int i=0;i<m;++i) if(p[i])
        for(int j=0;j<m;++j)
            t_[i+j]=(t_[i+j]+p[i]*q[j])%MOD;
    for(int i=m+m-1;i>=m;--i) if(t_[i])
        //miuns t_[i]x^{i-m}(x^m-\sum_{j=0}^{m-1} x^{m-j-1}h_j)
        for(int j=m-1;~j;--j)
            t_[i-j-1]=(t_[i-j-1]+t_[i]*h[j])%MOD;
    for(int i=0;i<m;++i) p[i]=t_[i];
}
inline ll calc(ll K)
{
    for(int i=m;~i;--i)
        s[i]=t[i]=0;
    //init
    s[0]=1; if(m!=1) t[1]=1; else t[0]=h[0];
    //binary-exponentiation
    while(K)
    {
        if(K&1) mull(s,t);
        mull(t,t); K>>=1;
    }
    ll su=0;
    for(int i=0;i<m;++i) su=(su+s[i]*a[i])%MOD;
    return (su%MOD+MOD)%MOD;
}
inline int work(vector<int> x,ll n)
{
    if(n<int(x.size())) return x[n];
    vector<int> v=BM(x); m=v.size(); if(!m) return 0;
    for(int i=0;i<m;++i) h[i]=v[i],a[i]=x[i];
    return calc(n);
}

}
using linear_seq::work;
```

6.2 Bigmod

```cpp
ll mod(string a, ll p) {
    ll res = 0, b = 1;
    reverse(all(a));

    for(auto c : a) {
        ll tmp = (((ll)c-'0')*b) % p;
        res = (res + tmp) % p;

        b = (b * 10) % p;
    }

    return res;
}
```

6.3 Crt

```cpp
tuple<ll, ll, ll> ext_gcd(ll a, ll b) {
    if (!a) return {b, 0, 1};
    auto [g, x, y] = ext_gcd(b%a, a);
    return {g, y - b/a*x, x};
}

struct crt {
    ll a, m;

    crt() : a(0), m(1) {}
    crt(ll a_, ll m_) : a(a_), m(m_) {}
    crt operator * (crt C) {
        auto [g, x, y] = ext_gcd(m, C.m);
        if ((a - C.a) % g) a = -1;
        if (a == -1 or C.a == -1) return crt(-1, 0);
        ll lcm = m/g*C.m;
        ll ans = a + (x*(C.a-a)/g % (C.m/g))*m;
        return crt((ans % lcm + lcm) % lcm, lcm);
    }
};
```

6.4 Division Trick

```cpp
for(int l = 1, r; l <= n; l = r + 1) {
    r = n / (n / l);
    // n / i has the same value for l <= i <= r
}
```

6.5 Fft Mod Tfg

```cpp
// usar vector<int> p(ms, 0);

const int me = 20;
const int ms = 1 << me;

ll fexp(ll x, ll e, ll mod = MOD) {
    ll ans = 1;
    x %= mod;
    for(; e > 0; e /= 2) {
        if(e & 1) {
            ans = ans * x % mod;
        }
        x = x * x % mod;
    }
    return ans;
}

//is n primitive root of p ?
bool test(ll x, ll p) {
    ll m = p - 1;
    for(int i = 2; i * i <= m; ++i) if(m % i == 0) {
        if(fexp(x, i, p) == 1) return false;
        if(fexp(x, m / i, p) == 1) return false;
    }
    return true;
}

//find the largest primitive root for p
int search(int p) {
    for(int i = p - 1; i >= 2; --i) if(test(i, p)) return i;
    return -1;
}

#define add(x, y, mod) (x+y>=mod?x+y-mod:x+y)

const int gen = search(MOD);
int bits[ms], r[ms + 1];

void pre(int n) {
    int LOG = 0;
    while(1 << (LOG + 1) < n) {
        LOG++;
    }
    for(int i = 1; i < n; i++) {
        bits[i] = (bits[i >> 1] >> 1) | ((i & 1) << LOG);
    }
}

void pre(int n, int root, int mod) {
    pre(n);
    r[0] = 1;
    for(int i = 1; i <= n; i++) {
        r[i] = (ll) r[i - 1] * root % mod;
    }
}

vector<int> fft(vector<int> a, int mod, bool inv = false) {
    int root = gen;
    if(inv) {
        root = fexp(root, mod - 2, mod);
    }
    int n = a.size();
    root = fexp(root, (mod - 1) / n, mod);
    pre(n, root, mod);
    for(int i = 0; i < n; i++) {
        int to = bits[i];
        if(i < to) {
            swap(a[i], a[to]);
        }
    }
    for(int len = 1; len < n; len *= 2) {
        for(int i = 0; i < n; i += len * 2) {
            int cur_root = 0;
            int delta = n / (2 * len);
            for(int j = 0; j < len; j++) {
                int u = a[i + j], v = (ll) a[i + j + len] * r[cur_root] % mod;
                a[i + j] = add(u, v, mod);
                a[i + j + len] = add(u, mod - v, mod);
                cur_root += delta;
            }
        }
    }
    if(inv) {
        int rev = fexp(n, mod-2, mod);
        for(int i = 0; i < n; i++)
            a[i] = (ll) a[i] * rev % mod;
    }
    return a;
}
```

6.6 Fft Simple

```cpp
#define ld long double
const ld PI = acos(-1);

struct num{
    ld a {0.0}, b {0.0};
    num(){}
    num(ld na) : a{na}{}
    num(ld na, ld nb) : a{na}, b{nb} {}
    const num operator+(const num &c) const{
        return num(a + c.a, b + c.b);
    }
    const num operator-(const num &c) const{
        return num(a - c.a, b - c.b);
    }
    const num operator*(const num &c) const{
        return num(a*c.a - b*c.b, a*c.b + b*c.a);
    }
    const num operator/(const int &c) const{
         return num(a/c, b/c);
    }
};

void fft(vector<num> &a, bool invert){
    int n = a.size();
    for(int i=1,j=0;i<n;i++){
        int bit = n>>1;
        for(; j&bit; bit>>=1)
            j^=bit;
        j^=bit;
        if(i<j)
            swap(a[i], a[j]);
    }
    for(int len = 2; len <= n; len <<= 1){
        ld ang = 2 * PI / len * (invert ? -1 : 1);
        num wlen(cos(ang), sin(ang));
        for(int i=0;i<n;i+=len){
            num w(1);
            for (int j=0;j<len/2;j++){
                num u = a[i+j], v = a[i+j+len/2] * w;
                a[i+j] = u + v;
                a[i+j+len/2] = u - v;
                w = w * wlen;
            }
        }
    }
    if(invert)
      for(num &x: a)
          x = x/n;

}

vector<ll> multiply(vector<int> const& a, vector<int> const& b){
    vector<num> fa(a.begin(), a.end());
    vector<num> fb(b.begin(), b.end());
    int n = 1;
    while(n < int(a.size() + b.size()) )
        n <<= 1;
    fa.resize(n);
    fb.resize(n);
    fft(fa, false);
    fft(fb, false);
    for(int i=0;i<n;i++)
        fa[i] = fa[i]*fb[i];
    fft(fa, true);
    vector<ll> result(n);
    for(int i=0;i<n;i++)
        result[i] = round(fa[i].a);
    while(result.back()==0) result.pop_back();
    return result;
}
```

6.7 Fft Tourist

```
struct num{
    ld x, y;
    num() { x = y = 0; }
    num(ld x, ld y) : x(x), y(y) {}
};

inline num operator+(num a, num b) { return num(a.x + b.x, a.y + b.y); }
inline num operator-(num a, num b) { return num(a.x - b.x, a.y - b.y); }
inline num operator*(num a, num b) { return num(a.x * b.x - a.y * b.y, a.x * b.y + a.y * b.x); }
inline num conj(num a) { return num(a.x, -a.y); }

int base = 1;
vector<num> roots = {{0, 0}, {1, 0}};
vector<int> rev = {0, 1};
const ld PI = acos(-1);

void ensure_base(int nbase){
    if(nbase <= base)
        return;

    rev.resize(1 << nbase);
    for(int i = 0; i < (1 << nbase); i++)
        rev[i] = (rev[i >> 1] >> 1) + ((i & 1) << (nbase - 1));

    roots.resize(1 << nbase);

    while(base < nbase){
        ld angle = 2*PI / (1 << (base + 1));
        for(int i = 1 << (base - 1); i < (1 << base); i++){
            roots[i << 1] = roots[i];
            ld angle_i = angle * (2 * i + 1 - (1 << base));
            roots[(i << 1) + 1] = num(cos(angle_i), sin(angle_i));
        }
        base++;
    }
}

void fft(vector<num> &a, int n = -1){
    if(n == -1)
        n = a.size();

    assert((n & (n-1)) == 0);
    int zeros = __builtin_ctz(n);
    ensure_base(zeros);
    int shift = base - zeros;
    for(int i = 0; i < n; i++)
        if(i < (rev[i] >> shift))
            swap(a[i], a[rev[i] >> shift]);

    for(int k = 1; k < n; k <<= 1)
        for(int i = 0; i < n; i += 2 * k)
            for(int j = 0; j < k; j++){
                num z = a[i+j+k] * roots[j+k];
                a[i+j+k] = a[i+j] - z;
                a[i+j] = a[i+j] + z;
            }
}

vector<num> fa, fb;
vector<ll> multiply(vector<ll> &a, vector<ll> &b){
    int need = a.size() + b.size() - 1;
    int nbase = 0;
    while((1 << nbase) < need) nbase++;
    ensure_base(nbase);
    int sz = 1 << nbase;
    if(sz > (int) fa.size())
        fa.resize(sz);

    for(int i = 0; i < sz; i++){
        int x = (i < (int) a.size() ? a[i] : 0);
        int y = (i < (int) b.size() ? b[i] : 0);
        fa[i] = num(x, y);
    }
    fft(fa, sz);
    num r(0, -0.25 / sz);
    for(int i = 0; i <= (sz >> 1); i++){
        int j = (sz - i) & (sz - 1);
        num z = (fa[j] * fa[j] - conj(fa[i] * fa[i])) * r;
        if(i != j) {
            fa[j] = (fa[i] * fa[i] - conj(fa[j] * fa[j])) * r;
        }
        fa[i] = z;
    }
    fft(fa, sz);
    vector<ll> res(need);
    for(int i = 0; i < need; i++)
        res[i] = round(fa[i].x);

    return res;
}


vector<ll> multiply_mod(vector<ll> &a, vector<ll> &b, int m, int eq = 0){
    int need = a.size() + b.size() - 1;
    int nbase = 0;
    while((1 << nbase) < need) nbase++;
    ensure_base(nbase);
    int sz = 1 << nbase;
    if(sz > (int) fa.size())
        fa.resize(sz);
```

```cpp

    for(int i=0;i<(int)a.size();i++){
        int x = (a[i] % m + m) % m;
        fa[i] = num(x & ((1 << 15) - 1), x >> 15);
    }
    fill(fa.begin() + a.size(), fa.begin() + sz, num {0, 0});
    fft(fa, sz);
    if(sz > (int) fb.size())
        fb.resize(sz);
    if(eq)
        copy(fa.begin(), fa.begin() + sz, fb.begin());
    else{
        for(int i = 0; i < (int) b.size(); i++){
            int x = (b[i] % m + m) % m;
            fb[i] = num(x & ((1 << 15) - 1), x >> 15);
        }
        fill(fb.begin() + b.size(), fb.begin() + sz, num {0, 0});
        fft(fb, sz);
    }
    ld ratio = 0.25 / sz;
    num r2(0, -1);
    num r3(ratio, 0);
    num r4(0, -ratio);
    num r5(0, 1);
    for(int i=0;i<=(sz >> 1);i++) {
        int j = (sz - i) & (sz - 1);
        num a1 = (fa[i] + conj(fa[j]));
        num a2 = (fa[i] - conj(fa[j])) * r2;
        num b1 = (fb[i] + conj(fb[j])) * r3;
        num b2 = (fb[i] - conj(fb[j])) * r4;
        if(i != j){
            num c1 = (fa[j] + conj(fa[i]));
            num c2 = (fa[j] - conj(fa[i])) * r2;
            num d1 = (fb[j] + conj(fb[i])) * r3;
            num d2 = (fb[j] - conj(fb[i])) * r4;
            fa[i] = c1 * d1 + c2 * d2 * r5;
            fb[i] = c1 * d2 + c2 * d1;
        }
        fa[j] = a1 * b1 + a2 * b2 * r5;
        fb[j] = a1 * b2 + a2 * b1;
    }
    fft(fa, sz);
    fft(fb, sz);
    vector<ll> res(need);
    for(int i=0;i<need;i++){
        ll aa = round(fa[i].x);
        ll bb = round(fb[i].x);
        ll cc = round(fa[i].y);
        res[i] = (aa + ((bb % m) << 15) + ((cc % m) << 30)) % m;
    }
    return res;
}
```

6.8 Frac

```cpp
struct frac {
    ll num, den;
    frac(ll num=0, ll den=1) : num(num), den(den) {}
    frac operator+(const frac &o) const { return {num*o.den + o.num*den, den*o.den}; }
    frac operator-(const frac &o) const { return {num*o.den - o.num*den, den*o.den}; }
    frac operator*(const frac &o) const { return {num*o.num, den*o.den}; }
    frac operator/(const frac &o) const { return {num*o.den, den*o.num}; }
    bool operator<(const frac &o) const { return num*o.den < den*o.num; }
};
```

6.9 Fwht

```cpp
// Fast Walsh Hadamard Transform
//
// FWHT<'|'>(f) eh SOS DP
// FWHT<'&'>(f) eh soma de superset DP
// Se chamar com ^, usar tamanho potencia de 2!!
//
// O(n log(n))

template<char op, class T> vector<T> FWHT(vector<T> f, bool inv = false) {
    int n = f.size();
    for (int k = 0; (n-1)>>k; k++) for (int i = 0; i < n; i++) if (i>>k&1) {
        int j = i^(1<<k);
        if (op == '^') f[j] += f[i], f[i] = f[j] - 2*f[i];
        if (op == '|') f[i] += (inv ? -1 : 1) * f[j];
        if (op == '&') f[j] += (inv ? -1 : 1) * f[i];
    }
    if (op == '^' and inv) for (auto& i : f) i /= n;
    return f;
}
```

6.10 Gaussxor

```cpp
struct Gauss {
    array<ll, LOG_MAX> vet;
    int size;
    Gauss() : size(0) {
        fill(vet.begin(), vet.end(), 0);
    }
    Gauss(vector<ll> vals) : size(0) {
        fill(vet.begin(), vet.end(), 0);
        for(ll val : vals) add(val);
    }
    bool add(ll val) {
        for(int i = LOG_MAX-1; i >= 0; i--) if(val & (1LL << i)) {
            if(vet[i] == 0) {
                vet[i] = val;
                size++;
                return true;
            }
            val ^= vet[i];
        }
        return false;
    }
};
```

6.11 Inverso Mult

```cpp
// gcd(a, m) = 1 para existir solucao
// ax + my = 1, ou a*x = 1 (mod m)
ll inv(ll a, ll m) { // com gcd
    ll x, y;
    gcd(a, m, x, y);
    return (((x % m) +m) %m);
}

ll inv(ll a, ll phim) { // com phi(m), se m for primo entao phi(m) = p-1
    ll e = phim-1;
    return fexp(a, e);
}
```

6.12 Kitamasa

```cpp
using poly = vector<mint>; // mint = int mod P with operators +, - and *
```

```
inline int len(const poly& a) { return a.size(); } // get rid of the annoying "hey a.size() is unsigned" warning

poly pmul(const poly& a, const poly& b) {
    poly c(len(a) + len(b) - 1, 0);
    for (int i = 0; i < len(a); i++)
        for (int j = 0; j < len(b); j++)
            c[i+j] = c[i+j] + a[i] * b[j];
    return c;
}

// only works if b.back() == 1
poly pmod(const poly& a, const poly& b) {
    poly c(a.begin(), a.end());
    for (int i = len(c) - 1; i >= len(b) - 1; i--) {
        int k = i - (len(b) - 1); // index of the quotient term
        for (int j = 0; j < len(b); j++)
            c[j+k] = c[j+k] - c[i] * b[j];
    }
    c.resize(len(b) - 1);
    return c;
}

poly ppwr(poly x, ll e, poly f) {
    poly ans = { 1 };
    for (; e > 0; e /= 2) {
        if (e & 1) ans = pmod(pmul(ans, x), f);
        x = pmod(pmul(x, x), f);
    }
    return ans;
}

// values = { A0, A1, ..., An }. recurrence = C0 × A0 + C1 × A1 + ... + Cn × An generates A{n+1}
mint kitamasa(const poly& values, const poly& recurrence, ll n) {
    poly f(len(recurrence) + 1);
    f.back() = 1;
    for (int i = 0; i < len(recurrence); i++)
        f[i] = mint(0) - recurrence[i];

    auto d = ppwr(poly{0, 1}, n, f); // x^N mod f(x)

    mint ans = 0;
    for (int i = 0; i < len(values); i++)
        ans = ans + d[i] * values[i];
    return ans;
}
```

6.13 Linear Diophantine Equation

```
// Linear Diophantine Equation
int gcd(int a, int b, int &x, int &y)
{
    if (a == 0)
    {
        x = 0; y = 1;
        return b;
    }
    int x1, y1;
    int d = gcd(b%a, a, x1, y1);
    x = y1 - (b / a) * x1;
    y = x1;
    return d;
}

bool find_any_solution(int a, int b, int c, int &x0, int &y0, int &g)
{
    g = gcd(abs(a), abs(b), x0, y0);
    if (c % g)
        return false;

    x0 *= c / g;
    y0 *= c / g;
    if (a < 0) x0 = -x0;
    if (b < 0) y0 = -y0;
    return true;
}

//  All solutions
//  x = x0 + k*b/g
//  y = y0 - k*a/g
```

6.14 Matrix Exponentiation

```
struct Matrix {
    vector<vl> m;
    int r, c;

    Matrix(vector<vl> mat) {
        m = mat;
        r = mat.size();
        c = mat[0].size();
    }

    Matrix(int row, int col, bool ident=false) {
        r = row; c = col;
        m = vector<vl>(r, vl(c, 0));
        if(ident) {
            for(int i = 0; i < min(r, c); i++) {
                m[i][i] = 1;
            }
        }
    }

    Matrix operator*(const Matrix &o) const {
        assert(c == o.r); // garantir que da pra multiplicar
        vector<vl> res(r, vl(o.c, 0));

        for(int i = 0; i < r; i++) {
            for(int k = 0; k < c; k++) {
                for(int j = 0; j < o.c; j++) {
                    res[i][j] = (res[i][j] + m[i][k]*o.m[k][j]) % MOD;
                }
            }
        }

        return Matrix(res);
    }
};

Matrix fexp(Matrix b, int e, int n) {
    if(e == 0) return Matrix(n, n, true); // identidade
    Matrix res = fexp(b, e/2, n);
    res = (res * res);
    if(e%2) res = (res * b);

    return res;
}
```

6.15 Miller Habin

```
ll mul(ll a, ll b, ll m) {
    return (a*b-ll(a*(long double)b/m+0.5)*m+m)%m;
}

ll expo(ll a, ll b, ll m) {
    if (!b) return 1;
    ll ans = expo(mul(a, a, m), b/2, m);
    return b%2 ? mul(a, ans, m) : ans;
}

bool prime(ll n) {
    if (n < 2) return 0;
    if (n <= 3) return 1;
    if (n % 2 == 0) return 0;

    ll d = n - 1;
    int r = 0;
    while (d % 2 == 0) {
        r++;
        d /= 2;
    }

    // com esses primos, o teste funciona garantido para n <= 2^64
    // funciona para n <= 3*10^24 com os primos ate 41
    for (int i : {2, 325, 9375, 28178, 450775, 9780504, 795265022}) {
        if (i >= n) break;
        ll x = expo(i, d, n);
        if (x == 1 or x == n - 1) continue;

        bool deu = 1;
        for (int j = 0; j < r - 1; j++) {
            x = mul(x, x, n);
            if (x == n - 1) {
                deu = 0;
                break;
            }
        }
        if (deu) return 0;
    }
    return 1;
}
```

6.16 Mint

```
struct mint {
    int x;
    mint(int _x = 0) : x(_x) { }
    mint operator +(const mint &o) const { return x + o.x >= MOD ? x + o.x - MOD : x + o.x; }
    mint operator *(const mint &o) const { return mint((ll)x * o.x % MOD); }
    mint operator -(const mint &o) const { return *this + (MOD - o.x); }
    mint inv() { return pwr(MOD - 2); }
    mint pwr(ll e) {
        mint ans = 1;
        for (mint b=x; e; e >>= 1, b = b * b)
            if (e & 1) ans = ans * b;
        return ans;
    }
};

mint fac[N], ifac[N];
void build_fac() {
    fac[0] = 1;
    for (int i=1;i<N;i++)
        fac[i] = fac[i-1] * i;
    ifac[N-1] = fac[N-1].inv();
    for (int i=N-2;i>=0;i--)
        ifac[i] = ifac[i+1] * (i+1);
}
mint c(ll n, ll k) {
    if (k > n) return 0;
    return fac[n] * ifac[k] * ifac[n-k];
}
```

6.17 Mobius

```
vi mobius(int n) {
    // g(n) = sum{f(d)} => f(n) = sum{mu(d)*g(n/d)}
    vi mu(n+1);
    mu[1] = 1; mu[0] = 0;
    for(int i = 1; i <= n; i++)
        for(int j = i + i; j <= n; j += i)
            mu[j] -= mu[i];

    return mu;
}
```

6.18 Mulmod

```
ll mulmod(ll a, ll b) {
    if(a == 0) {
        return 0LL;
    }
    if(a%2 == 0) {
        ll val = mulmod(a/2, b);
        return (val + val) % MOD;
    }
    else {
        ll val = mulmod((a-1)/2, b);
        val = (val + val) % MOD;
        return (val + b) % MOD;
    }
}
```

6.19 Pollard Rho

```
ll mul(ll a, ll b, ll m) {
    ll ret = a*b - (ll)((ld)1/m*a*b+0.5)*m;
    return ret < 0 ? ret+m : ret;
}

ll pow(ll a, ll b, ll m) {
    ll ans = 1;
    for (; b > 0; b /= 2ll, a = mul(a, a, m)) {
        if (b % 2ll == 1)
            ans = mul(ans, a, m);
    }
    return ans;
}

bool prime(ll n) {
    if (n < 2) return 0;
    if (n <= 3) return 1;
    if (n % 2 == 0) return 0;

    ll r = __builtin_ctzll(n - 1), d = n >> r;
    for (int a : {2, 325, 9375, 28178, 450775, 9780504, 795265022}) {
        ll x = pow(a, d, n);
        if (x == 1 or x == n - 1 or a % n == 0) continue;

        for (int j = 0; j < r - 1; j++) {
            x = mul(x, x, n);
            if (x == n - 1) break;
        }
        if (x != n - 1) return 0;
    }
    return 1;
}

ll rho(ll n) {
    if (n == 1 or prime(n)) return n;
    auto f = [n](ll x) {return mul(x, x, n) + 1;};

    ll x = 0, y = 0, t = 30, prd = 2, x0 = 1, q;
    while (t % 40 != 0 or gcd(prd, n) == 1) {
        if (x==y) x = ++x0, y = f(x);
        q = mul(prd, abs(x-y), n);
        if (q != 0) prd = q;
        x = f(x), y = f(f(y)), t++;
    }
    return gcd(prd, n);
}

vector<ll> fact(ll n) {
    if (n == 1) return {};
    if (prime(n)) return {n};
    ll d = rho(n);
    vector<ll> l = fact(d), r = fact(n / d);
    l.insert(l.end(), r.begin(), r.end());
    return l;
}
```

6.20 Poly

```
const int MOD = 998244353;
const int me = 15;
const int ms = 1 << me;

#define add(x, y) x+y>=MOD?x+y-MOD:x+y

const int gen = 3; // use search() from PrimitiveRoot.cpp if MOD isn't 998244353
int bits[ms], root[ms];

void initFFT() {
    root[1] = 1;
    for(int len = 2; len < ms; len += len) {
        int z = (int) fexp(gen, (MOD - 1) / len / 2);
        for(int i = len / 2; i < len; i++) {
            root[2 * i] = root[i];
            root[2 * i + 1] = (int)((long long) root[i] * z % MOD);
        }
    }
}

void pre(int n) {
    int LOG = 0;
    while(1 << (LOG + 1) < n) {
        LOG++;
    }
    for(int i = 1; i < n; i++) {
        bits[i] = (bits[i >> 1] >> 1) | ((i & 1) << LOG);
    }
}

std::vector<int> fft(std::vector<int> a, bool inv = false) {
    int n = (int) a.size();
    pre(n);
    if(inv) {
        std::reverse(a.begin() + 1, a.end());
    }
    for(int i = 0; i < n; i++) {
        int to = bits[i];
        if(i < to) { std::swap(a[i], a[to]); }
    }
    for(int len = 1; len < n; len *= 2) {
        for(int i = 0; i < n; i += len * 2) {
            for(int j = 0; j < len; j++) {
                int u = a[i + j], v = (int)((long long) a[i + j + len] * root[len + j] % MOD);
                a[i + j] = add(u, v);
                a[i + j + len] = add(u, MOD - v);
            }
        }
    }
    if(inv) {
        long long rev = fexp(n, MOD-2, MOD);
        for(int i = 0; i < n; i++)
            a[i] = (int)(a[i] * rev % MOD);
    }
    return a;
}

std::vector<int> shift(const std::vector<int> &a, int s) {
    int n = std::max(0, s + (int) a.size());
    std::vector<int> b(n, 0);
    for(int i = std::max(-s, 0); i < (int) a.size(); i++) {
        b[i + s] = a[i];
    }
    return b;
}

std::vector<int> cut(const std::vector<int> &a, int n) {
    std::vector<int> b(n, 0);
    for(int i = 0; i < (int) a.size() && i < n; i++) {
        b[i] = a[i];
    }
    return b;
}

std::vector<int> operator +(std::vector<int> a, const std::vector<int> &b) {
    int sz = (int) std::max(a.size(), b.size());
    a.resize(sz, 0);
    for(int i = 0; i < (int) b.size(); i++) {
        a[i] = add(a[i], b[i]);
    }
    return a;
}

std::vector<int> operator -(std::vector<int> a, const std::vector<int> &b) {
    int sz = (int) std::max(a.size(), b.size());
    a.resize(sz, 0);
    for(int i = 0; i < (int) b.size(); i++) {
        a[i] = add(a[i], MOD - b[i]);
    }
    return a;
}

std::vector<int> operator *(std::vector<int> a, std::vector<int> b) {
    while(!a.empty() && a.back() == 0) a.pop_back();
    while(!b.empty() && b.back() == 0) b.pop_back();
    if(a.empty() || b.empty()) return std::vector<int>(0, 0);
    int n = 1;
    while(n-1 < (int) a.size() + (int) b.size() - 2) n += n;
    a.resize(n, 0);
    b.resize(n, 0);
    a = fft(a, false);
    b = fft(b, false);
    for(int i = 0; i < n; i++) {
        a[i] = (int) ((long long) a[i] * b[i] % MOD);
    }
    return fft(a, true);
}

std::vector<int> inverse(const std::vector<int> &a, int k) {
    assert(!a.empty() && a[0] != 0);
    if(k == 0) {
        return std::vector<int>(1, (int) fexp(a[0], MOD - 2));
    } else {
        int n = 1 << k;
        auto c = inverse(a, k-1);
        return cut(c * cut(std::vector<int>(1, 2) - cut(a, n) * c, n), n);
    }
}

std::vector<int> operator /(std::vector<int> a, std::vector<int> b) {
    // NEED TO TEST!
    while(!a.empty() && a.back() == 0) a.pop_back();
    while(!b.empty() && b.back() == 0) b.pop_back();
    assert(!b.empty());
    if(a.size() < b.size()) return std::vector<int>(1, 0);
    std::reverse(a.begin(), a.end());
    std::reverse(b.begin(), b.end());
    int n = (int) a.size() - (int) b.size() + 1;
    int k = 0;
    while((1 << k) - 1 < n) k++;
    a = cut(a * inverse(b, k), (int) a.size() - (int) b.size() + 1);
    std::reverse(a.begin(), a.end());
    return a;
}

std::vector<int> log(const std::vector<int> &a, int k) {
    assert(!a.empty() && a[0] != 0);
    int n = 1 << k;
    std::vector<int> b(n, 0);
    for(int i = 0; i+1 < (int) a.size() && i < n; i++) {
        b[i] = (int)((i + 1LL) * a[i+1] % MOD);
    }
    b = cut(b * inverse(a, k), n);
    assert((int) b.size() == n);
    for(int i = n - 1; i > 0; i--) {
        b[i] = (int) (b[i-1] * fexp(i, MOD - 2) % MOD);
    }
    b[0] = 0;
    return b;
}

std::vector<int> exp(const std::vector<int> &a, int k) {
    assert(!a.empty() && a[0] == 0);
    if(k == 0) {
        return std::vector<int>(1, 1);
    } else {
        auto b = exp(a, k-1);
        int n = 1 << k;
        return cut(b * cut(std::vector<int>(1, 1) + cut(a, n) - log(b, k), n), n);
    }
}
```

6.21 Primitiveroot

```
long long fexp(long long x, long long e, long long mod = MOD) {
    long long ans = 1;
    x %= mod;
    for(; e > 0; e /= 2, x = x * x % mod) {
        if(e & 1) ans = ans * x % mod;
    }
    return ans;
}
//is n primitive root of p ?
bool test(long long x, long long p) {
    long long m = p - 1;
    for(int i = 2; i * i <= m; ++i) if(!(m % i)) {
        if(fexp(x, i, p) == 1) return false;
        if(fexp(x, m / i, p) == 1) return false;
    }
    return true;
}
//find the smallest primitive root for p
int search(int p) {
    for(int i = 2; i < p; i++) if(test(i, p)) return i;
    return -1;
}
```

6.22 Raiz Primitiva

```
ll fexp(ll b, ll e, ll mod) {
    if(e == 0) return 1LL;
    ll res = fexp(b, e/2LL, mod);
    res = (res*res)%mod;
    if(e%2LL)
        res = (res*b)%mod;

    return res%mod;
}

vl fatorar(ll n) { // fatora em primos
    vl fat;
    for(int i = 2; i*i <= n; i++) {
        if(n%i == 0) {
            fat.pb(i);
            while(n%i == 0)
                n /= i;
        }
    }
    return fat;
}

// O(log(n) ^ 2)
bool raiz_prim(ll a, ll mod, ll phi, vl fat) {
    if(__gcd(a, mod) != 1 or fexp(a, phi/2, mod) == 1) // phi de euler sempre eh PAR
        return false;

    for(auto f : fat) {
        if(fexp(a, phi/f, mod) == 1)
            return false;
    }

    return true;
}

// mods com raizes primitivas: 2, 4, p^k, 2*p^k, p eh primo impar, k inteiro --- O(n log^2(n))
ll achar_raiz(ll mod, ll phi) {
    if(mod == 2) return 1;
    vl fat, elementos;
    fat = fatorar(phi);

    for(ll i = 2; i <= mod-1; i++) {
        if(raiz_prim(i, mod, phi, fat))
            return i;
    }

    return -1; // retorna -1 se nao existe
}

vl todas_raizes(ll mod, ll phi, ll raiz) {
    vl raizes;
    if(raiz == -1) return raizes;
    ll r = raiz;
    for(ll i = 1; i <= phi-1; i++) {
        if(__gcd(i, phi) == 1) {
            raizes.pb(r);
        }
        r = (r * raiz) % mod;
    }

    return raizes;
}
```

6.23 Randommod

```
int randommod() {
    auto primo = [](int num) {
        for(int i = 2; i*i <= num; i++) {
            if(num%i == 0) return false;
        }
        return true;
    };
    uniform_int_distribution<int> distribution(1000000007, 1500000000);
    int num = distribution(rng);
    while(!primo(num)) num++;
    return num;
}
```

6.24 Totient

```
// phi(p^k) = (p^(k-1))*(p-1) com p primo
// O(sqrt(m))
ll phi(ll m){
    ll res = m;
    for(ll d=2;d*d<=m;d++){
        if(m % d == 0){
            res = (res/d)*(d-1);
            while(m%d == 0)
                m /= d;
        }
    }
    if(m > 1) {
        res /= m;
        res *= (m-1);
    }
    return res;
}

// modificacao do crivo, O(n*log(log(n)))
vector<ll> phi_to_n(ll n){
    vector<bool> isprime(n+1, true);
    vector<ll> tot(n+1);
    tot[0] = 0; tot[1] = 1;
    for(ll i=1;i<=n; i++){
        tot[i] = i;
    }

    for(ll p=2;p<=n;p++){
        if(isprime[p]){
            tot[p] = p-1;
            for(ll i=p+p;i<=n;i+=p){
                isprime[i] = false;
                tot[i] = (tot[i]/p)*(p-1);
            }
        }
    }
    return tot;
}
```

7 Misc

7.1 Bitwise

```
// Least significant bit (lsb)
    int lsb(int x) { return x&-x; }
    int lsb(int x) { return __builtin_ctz(x); } // bit position
// Most significant bit (msb)
    int msb(int x) { return 32-1-__builtin_clz(x); } // bit position

// Power of two
    bool isPowerOfTwo(int x){ return x && (!(x&(x-1))); }

// floor(log2(x))
int flog2(int x)  { return 32-1-__builtin_clz(x); }
int flog2ll(ll x) { return 64-1-__builtin_clzll(x); }

// Built-in functions
// Number of bits 1
__builtin_popcount()
__builtin_popcountll()

// Number of leading zeros
__builtin_clz()
__builtin_clzll()

// Number of trailing zeros
__builtin_ctz()
__builtin_ctzll()
```

7.2 Ordered Set

```
#include <bits/extc++.h>
using namespace __gnu_pbds; // or pb_ds;
template<typename T, typename B = null_type>
using ordered_set = tree<T, B, less<T>, rb_tree_tag, tree_order_statistics_node_update>;

// order_of_key(k)  : Number of items strictly smaller than k
// find_by_order(k) : K-th element in a set (counting from zero)

// to swap two sets, use a.swap(b);
```

7.3 Rand

```
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count()); // mt19937_64
uniform_int_distribution<int> distribution(1,n);

num = distribution(rng); // num no range [1, n]
shuffle(vec.begin(), vec.end(), rng); // shuffle

using ull = unsigned long long;
ull mix(ull o){
    o+=0x9e3779b97f4a7c15;
    o=(o^(o>>30))*0xbf58476d1ce4e5b9;
    o=(o^(o>>27))*0x94d049bb133111eb;
    return o^(o>>31);
}
ull hash(pii a) {return mix(a.first ^ mix(a.second));}
```

7.4 Submask

```
// O(3^n)
for (int m = 0; m < (1<<n); m++) {
    for (int s = m; s; s = (s-1) & m) {
        // s is every submask of m
    }
}

// O(2^n * n) SOS dp like
```

```
for (int b = n-1; b >= 0; b--) {
    for (int m = 0; m < (1 << n); m++) {
        if (j & (1 << b)) {
            // propagate info through submasks
            amount[j ^ (1 << b)] += amount[j];
        }
    }
}
```

7.5 Template

```
#include <bits/stdc++.h>
#define ll long long
#define ff first
#define ss second
#define ld long double
#define pb push_back
#define sws cin.tie(0)->sync_with_stdio(false);
#define endl '\n'

using namespace std;

const int N = 0;
const ll MOD = 998244353;
const int INF = 0x3f3f3f3f;
const ll LLINF = 0x3f3f3f3f3f3f3f3f;

int32_t main() {
    #ifndef LOCAL
    sws;
    #endif

    return 0;
}

// ulimit -s unlimited
// alias comp="g++ -std=c++20 -fsanitize=address -O2 -o out"
// #pragma GCC optimize("O3,unroll-loops")
// #pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
```

8 Numeric

8.1 Lagrange Interpolation

```
// Lagrange's interpolation O(n^2)
ld interpolate(vector<pair<int, int>> d, ld x){
    ld y = 0;
    int n = d.size();
    for(int i=0;i<n;i++){
        ld yi = d[i].ss;
        for(int j=0;j<n;j++)
            if(j!=i)
                yi = yi*(x - d[j].ff)/(ld)(d[i].ff - d[j].ff);

        y += yi;
    }
    return y;
}

// O(n)

template<typename T = mint>
struct Lagrange {
    vector<T> y, den, l, r;
    int n;
    Lagrange(const vector<T>& _y) : y(_y), n(_y.size()) {
        den.resize(n, 0);
        l.resize(n, 0); r.resize(n, 0);

        for (int i = 0; i < n; i++) {
            den[i] = ifac[i] * ifac[n - 1 - i];
            if ((n - 1 - i) % 2 == 1) den[i] = -den[i];
        }
    }

    T eval(T x) {
        l[0] = 1;
        for (int i = 1; i < n; i++)
            l[i] = l[i-1] * (x + -T(i-1));

        r[n - 1] = 1;
        for (int i = n - 2; i >= 0; i--)
            r[i] = r[i+1] * (x + -T(i+1));

        T ans = 0;
        for (int i = 0; i < n; i++) {
            T num = l[i] * r[i];
            ans = ans + y[i] * num * den[i];
        }
        return ans;
    }
};
```

8.2 Newton Raphson

```
// Newton Raphson

ld f(x){ return x*2 + 2; }
ld fd(x){ return 2; } // derivada

ld root(ld x){
    // while(f(x)>EPS)
    for(int i=0;i<20;i++){
        if(fd(x)<EPS)
            x = LLINF;
        else
            x = x - f(x)/fd(x);
    }
    return x;
}
```

8.3 Simpson's Formula

```
inline ld simpson(ld fl, ld fr, ld fmid, ld l, ld r){
    return (fl+fr+4*fmid)*(r-l)/6;
}

ld rsimpson(ld slr, ld fl, ld fr, ld fmid, ld l, ld r)
{
    ld mid = (l+r)/2;
    ld fml = f((l+mid)/2), fmr = f((mid+r)/2);
    ld slm = simpson(fl,fmid,fml,l,mid);
    ld smr = simpson(fmid,fr,fmr,mid,r);
    if(fabsl(slr-slm-smr) < EPS) return slm+smr; // aprox. good enough
    return rsimpson(slm,fl,fmid,fml,l,mid)+rsimpson(smr,fmid,fr,fmr,mid,r);
}

ld integrate(ld l, ld r)
{
    ld mid = (l+r)/2;
    ld fl = f(l), fr = f(r);
    ld fmid = f(mid);
    return rsimpson(simpson(fl,fr,fmid,l,r),fl,fr,fmid,l,r);
}
```

9 Strings

9.1 Aho Corasick

```
// https://github.com/joseleite19/icpc-notebook/blob/master/code/string/aho_corasick.cpp
const int A = 26;
int to[N][A];
int ne = 2, fail[N], term[N];
void add_string(string str, int id){
    int p = 1;
    for(auto c: str){
        int ch = c - 'a'; // !
        if(!to[p][ch]) to[p][ch] = ne++;
        p = to[p][ch];
    }
    term[p]++;
}
void init(){
    for(int i = 0; i < ne; i++) fail[i] = 1;
    queue<int> q; q.push(1);
    int u, v;
    while(!q.empty()){
        u = q.front(); q.pop();
        for(int i = 0; i < A; i++){
            if(to[u][i]){
                v = to[u][i]; q.push(v);
                if(u != 1){
                    fail[v] = to[ fail[u] ][i];
                    term[v] += term[ fail[v] ];
                }
            }
            else if(u != 1) to[u][i] = to[ fail[u] ][i];
            else to[u][i] = 1;
        }
    }
}
```

9.2 Edit Distance

```
int edit_distance(int a, int b, string& s, string& t) {
    // indexado em 0, transforma s em t
    if(a == -1) return b+1;
    if(b == -1) return a+1;
    if(tab[a][b] != -1) return tab[a][b];

    int ins = INF, del = INF, mod = INF;
    ins = edit_distance(a-1, b, s, t) + 1;
    del = edit_distance(a, b-1, s, t) + 1;
    mod = edit_distance(a-1, b-1, s, t) + (s[a] != t[b]);

    return tab[a][b] = min(ins, min(del, mod));
}
```

9.3 Eertree

```
// heavily based on https://ideone.com/YQX9jv,
// which adamant cites here https://codeforces.com/blog/entry/13959?#comment-196033
struct Eertree {
    int s[N];
    int n, last, sz;

    int len[N], link[N];
    int to[N][A];

    Eertree() {
        s[n++] = -1;
        len[1] = -1, link[1] = 1; // "backspace" root is 1
        len[0] = 0, link[0] = 1;  // empty root is 0 (to[backspace root][any char] = empty root)
        last = 2;
        sz = 2;
    }

    int get_link(int u) {
        while (s[n - len[u] - 2] != s[n - 1]) u = link[u];
        return u;
    }

    void push(int c) {
        s[n++] = c;
        int p = get_link(last);
        if (!to[p][c]) {
            int u = ++sz;
            len[u] = len[p] + 2;
            link[u] = to[get_link(link[p])][c]; // may be 0 (empty), but never 1 (backspace)
            to[p][c] = u;
        }
        last = to[p][c];
    }
};
```

9.4 Hash

```
// String Hash template
// constructor(s) - O(|s|)
// query(l, r) - returns the hash of the range [l,r] from left to right - O(1)
// query_inv(l, r) from right to left - O(1)

struct Hash {
    const ll P = 31;
    int n; string s;
    vector<ll> h, hi, p;
    Hash() {}
    Hash(string s): s(s), n(s.size()), h(n), hi(n), p(n) {
        for (int i=0;i<n;i++) p[i] = (i ? P*p[i-1]:1) % MOD;
        for (int i=0;i<n;i++)
            h[i] = (s[i] + (i ? h[i-1]:0) * P) % MOD;
        for (int i=n-1;i>=0;i--)
            hi[i] = (s[i] + (i+1<n ? hi[i+1]:0) * P) % MOD;
    }
    int query(int l, int r) {
        ll hash = (h[r] - (l ? h[l-1]*p[r-l+1]%MOD : 0));
        return hash < 0 ? hash + MOD : hash;
    }
    int query_inv(int l, int r) {
        ll hash = (hi[l] - (r+1 < n ? hi[r+1]*p[r-l+1] % MOD : 0));
        return hash < 0 ? hash + MOD : hash;
    }
};
```

9.5 Kmp

```
string p;
int neighbor[N];
int walk(int u, char c) { // leader after inputting `c`
    while (u != -1 && (u+1 >= (int)p.size() || p[u + 1] != c)) // leader doesn't match
        u = neighbor[u];
    return p[u + 1] == c ? u+1 : u;
}
void build() {
    neighbor[0] = -1; // -1 is the leftmost state
    for (int i = 1; i < (int)p.size(); i++)
        neighbor[i] = walk(neighbor[i-1], p[i]);
}
```

9.6 Lcs

```
string LCSubStr(string X, string Y)
{
    int m = X.size();
    int n = Y.size();

    int result = 0, end;
    int len[2][n];
    int currRow = 0;

    for(int i=0;i<=m;i++){
        for(int j=0;j<=n;j++){
            if(i==0 || j==0)
                len[currRow][j] = 0;
            else if(X[i-1] == Y[j-1]){
                len[currRow][j] = len[1-currRow][j-1] + 1;
                if(len[currRow][j] > result){
                    result = len[currRow][j];
                    end = i - 1;
                }
            }
            else
                len[currRow][j] = 0;
        }

        currRow = 1 - currRow;
    }

    if(result==0)
        return string();

    return X.substr(end - result + 1, result);
}
```

9.7 Lcsubseq

```
// Longest Common Subsequence
string lcs(string x, string y){
    int n = x.size(), m = y.size();
    vector<vi> dp(n+1, vi(m+1, 0));

    for(int i=0;i<=n;i++){
        for(int j=0;j<=m;j++){
            if(!i or !j)
                dp[i][j]=0;
            else if(x[i-1] == y[j-1])
                dp[i][j]=dp[i-1][j-1]+1;
            else
                dp[i][j]=max(dp[i-1][j], dp[i][j-1]);
        }
    }

    // int len = dp[n][m];
    string ans="";

    // recover string
    int i = n-1, j = m-1;
    while(i>=0 and j>=0){
        if(x[i] == y[j]){
            ans.pb(x[i]);
            i--; j--;
        }else if(dp[i][j+1]>dp[i+1][j])
            i--;
        else
            j--;
    }

    reverse(ans.begin(), ans.end());

    return ans;
}
```

9.8 Manacher

```
// O(n), d1 -> palindromo impar, d2 -> palindromo par (centro da direita)
void manacher(string &s, vector<int> &d1, vector<int> &d2) {
    int n = s.size();
    for(int i = 0, l = 0, r = -1; i < n; i++) {
        int k = (i > r) ? 1 : min(d1[l + r - i], r - i + 1);
        while(0 <= i - k && i + k < n && s[i - k] == s[i + k]) {
            k++;
        }
        d1[i] = k--;
        if(i + k > r) {
            l = i - k;
            r = i + k;
        }
    }

    for(int i = 0, l = 0, r = -1; i < n; i++) {
        int k = (i > r) ? 0 : min(d2[l + r - i + 1], r - i + 1);
        while(0 <= i - k - 1 && i + k < n && s[i - k - 1] == s[i + k]) {
            k++;
        }
        d2[i] = k--;
        if(i + k > r) {
            l = i - k - 1;
            r = i + k ;
        }
    }
}
```

9.9 Suffix Array

```
vector<int> suffix_array(string s) {
    s += "!";
    int n = s.size(), N = max(n, 260);
    vector<int> sa(n), ra(n);
    for (int i = 0; i < n; i++) sa[i] = i, ra[i] = s[i];

    for (int k = 0; k < n; k ? k *= 2 : k++) {
        vector<int> nsa(sa), nra(n), cnt(N);

        for (int i = 0; i < n; i++) nsa[i] = (nsa[i]-k+n)%n, cnt[ra[i]]++;
        for (int i = 1; i < N; i++) cnt[i] += cnt[i-1];
        for (int i = n-1; i+1; i--) sa[--cnt[ra[nsa[i]]]] = nsa[i];

        for (int i = 1, r = 0; i < n; i++) nra[sa[i]] = r += ra[sa[i]] !=
            ra[sa[i-1]] or ra[(sa[i]+k)%n] != ra[(sa[i-1]+k)%n];
        ra = nra;
        if (ra[sa[n-1]] == n-1) break;
    }
```

```cpp
    return vector<int>(sa.begin()+1, sa.end());
}

vector<int> kasai(string s, vector<int> sa) {
    int n = s.size(), k = 0;
    vector<int> ra(n), lcp(n);
    for (int i = 0; i < n; i++) ra[sa[i]] = i;

    for (int i = 0; i < n; i++, k -= !!k) {
        if (ra[i] == n-1) { k = 0; continue; }
        int j = sa[ra[i]+1];
        while (i+k < n and j+k < n and s[i+k] == s[j+k]) k++;
        lcp[ra[i]] = k;
    }
    return lcp;
}
```

9.10 Suffix Array Radix

```cpp
#define pii pair<int, int>

void radix_sort(vector<pii>& rnk, vi& ind) {
    auto counting_sort = [](vector<pii>& rnk, vi& ind) {
        int n = ind.size(), maxx = -1;
        for(auto p : rnk) maxx = max(maxx, p.ff);

        vi cnt(maxx+1, 0), pos(maxx+1), ind_new(n);
        for(auto p : rnk) cnt[p.ff]++;
        pos[0] = 0;

        for(int i = 1; i <= maxx; i++) {
            pos[i] = pos[i-1] + cnt[i-1];
        }

        for(auto idx : ind) {
            int val = rnk[idx].ff;
            ind_new[pos[val]] = idx;
            pos[val]++;
        }

        swap(ind, ind_new);
    };

    for(int i = 0; i < (int)rnk.size(); i++) swap(rnk[i].ff, rnk[i].ss);
    counting_sort(rnk, ind);
    for(int i = 0; i < (int)rnk.size(); i++) swap(rnk[i].ff, rnk[i].ss);
    counting_sort(rnk, ind);
}

vi suffix_array(const string& s) {
    int n = s.size();
    vector<pii> rnk(n, {0, 0});
    vi ind(n);
    for(int i=0;i<n;i++) {
        rnk[i].ff = (s[i] == '$') ? 0 : s[i]-'a'+1; // manter '$' como 0
        ind[i] = i;
    }

    for(int k = 1; k <= n; k = (k << 1)) {
        for(int i = 0; i < n; i++) {
            if(ind[i]+k >= n) {
                rnk[ind[i]].ss = 0;
            }
            else {
                rnk[ind[i]].ss = rnk[ind[i]+k].ff;
            }
        }
        radix_sort(rnk, ind); // sort(all(rnk), cmp) pra n*log(n), cmp com rnk[i] < rnk[j]

        vector<pii> tmp = rnk;
        tmp[ind[0]] = {1, 0}; // rnk.ff comecar em 1 pois '$' eh o 0
        for(int i = 1; i < n; i++) {
            tmp[ind[i]].ff = tmp[ind[i-1]].ff;
            if(rnk[ind[i]] != rnk[ind[i-1]]) {
                tmp[ind[i]].ff++;
            }
        }
        swap(rnk, tmp);
    }
    return ind;
}


vi lcp_array(const string& s, const vi& sarray) {
    vi inv(s.size());
    for(int i = 0; i < (int)s.size(); i++) {
        inv[sarray[i]] = i;
    }
    vi lcp(s.size());
    int k = 0;
    for(int i = 0; i < (int)s.size()-1; i++) {
        int pi = inv[i];
        if(pi-1 < 0) continue;
        int j = sarray[pi-1];

        while(s[i+k] == s[j+k]) k++;
        lcp[pi] = k;
        k = max(k-1, 0);
    }

    return vi(lcp.begin()+1, lcp.end()); // LCP(i, j) = min(lcp[i], ..., lcp[j-1])
}
```

9.11 Suffix Automaton

```cpp
const int SA = 2*N; // Node 1 is the initial node of the automaton
int last = 1;
#define link my_link
int len[SA], link[SA];
array<int, 26> to[SA]; // maybe map<int, int>
int lastID = 1;
void push(int c) {
    int u = ++lastID;
    len[u] = len[last] + 1;

    int p = last;
    last = u; // update last immediately
    for (; p > 0 && !to[p][c]; p = link[p])
        to[p][c] = u;

    if (p == 0) { link[u] = 1; return; }

    int q = to[p][c];
    if (len[q] == len[p] + 1) { link[u] = q; return; }

    int clone = ++lastID;
    len[clone] = len[p] + 1;
    link[clone] = link[q];
    link[q] = link[u] = clone;
    to[clone] = to[q];
    for (int pp = p; to[pp][c] == q; pp = link[pp])
        to[pp][c] = clone;
}
```

9.12 Z Func

```
vector<int> Z(string s) {
    int n = s.size();
    vector<int> z(n);
    int x = 0, y = 0;
    for (int i = 1; i < n; i++) {
        z[i] = max(0, min(z[i - x], y - i + 1));
        while (i + z[i] < n and s[z[i]] == s[i + z[i]]) {
            x = i; y = i + z[i]; z[i]++;
        }
    }
    return z;
}
```