

# E-values: Calibration, combination, and applications

Sam Rosenberg University of Pennsylvania rosesamk@sas.upenn.edu

April 7, 2022



## Outline



#### Motivations

## Background

Basic definitions Calibrating e- and p-values Merging e-values

## Testing multiple hypotheses

Definitions
FWV arbitrary e-value adjustment
FWV independent e-value adjustment

#### Conclusion

## Bibliography

# The multiple comparisons problem



- Consider a meta-analysis in which we want to test a hypothesis common to a number of past studies
- What happens if we cannot access each of the original datasets?
  - Can we combine information from published results to perform the analysis?
- ► In practice, often combine p-values for multiple testing or testing multiple hypotheses
  - Class of functions for merging p-values complicated<sup>1</sup>
  - Class of functions for merging e-values, an alternative, is much nicer<sup>2</sup>



<sup>&</sup>lt;sup>1</sup>Vovk, B. Wang, and R. Wang 2022.

<sup>&</sup>lt;sup>2</sup>Vovk and R. Wang 2021.

# Setting



- Consider a probability space  $(\Omega, \mathcal{A}, Q)$  with sample space  $\Omega$  (a set), event space  $\mathcal{A}$  (a  $\sigma$ -algebra on  $\Omega$ ), and probability measure Q
- ► For a random variable  $X: \Omega \to S \subseteq \overline{\mathbb{R}}$  on our probability space, denote its expectation with respect to Q by  $\mathbb{E}^Q[X] := \int_{\Omega} X \, dQ$ 
  - ▶ We write  $\mathbb{E}[X]$  when Q is obvious from context



- ▶ An e-variable  $E:\Omega \to [0,\infty]$  is an extended random variable with  $\mathbb{E}^Q[E] \leq 1$ 
  - Any value taken by an e-variable (a realization of the random variable) is called an e-value
  - lacktriangle The set of all e-variables for our probability space is denoted  $\mathcal{E}_Q$
  - Larger values of E are stronger evidence against the null hypothesis Q (e.g. since  $Q(E \ge e) \le e^{-1}$  by Markov's inequality)
- ▶ Why do we let  $E = \infty$ ?
  - ▶ When testing a null hypothesis measure Q with a pre-specified e-variable E, an observed e-value of  $E(\omega) = \infty$  allows us to reject Q

## P-values



▶ A p-variable is a  $P: \Omega \rightarrow [0,1]$  s.t.

$$\forall \epsilon \in (0,1), \ Q(P \le \epsilon) \le \epsilon$$

- P-values are defined similarly to e-values
- PQ denotes the set of all p-variables for our probability space

## Calibrators: P-values to e-values



- ► Calibrators convert between p-values and e-values (and vice versa):
  - ▶ A p-to-e calibrator is a decreasing function  $f:[0,1] \to [0,\infty]$  if for any probability space  $(\Omega, \mathcal{A}, Q)$  and any p-variable  $P \in \mathcal{P}_Q$ ,  $f(P) \in \mathcal{E}_Q$ 
    - i.e. for any probability space, the p-variables on that space are transformed to e-variables on that space by f
  - A calibrator f dominates another calibrator g if  $f \ge g$  and strictly dominates if  $f \ne g$
  - A calibrator is admissible if it isn't strictly dominated by another calibrator

## P-to-e calibrators characterization



We have the following characterization of (admissible) p-to-e calibrators:

#### Theorem 1

A decreasing function  $f:[0,1]\to [0,\infty]$  is a p-to-e calibrator iff  $\int_0^1 f(p)\,dp \le 1$ . It is admissible iff f is upper semicontinuous,  $f(0)=\infty$ , and

 $\int_0^1 f(p) dp = 1.$ 

Since  $\int_0^1 \kappa p^{\kappa-1} = 1$  for  $\kappa \in (0,1)$ , an example family of calibrators immediately following from this result is:

$$\Big\{f_{\kappa}(p):=\kappa p^{\kappa-1}\,|\,\kappa\in(0,1)\Big\}.$$



**f** is a p-to-e calibrator  $\Rightarrow \int_0^1 f \leq 1$ : This follows immediately, taking  $(\Omega, \mathcal{A}, Q) = ([0,1], \sigma([0,1]), \mu)$  and  $P = \mathrm{id}_{[0,1]}$ , where  $\mu$  is the uniform measure on [0,1].

 $\int_0^1 f \le 1 \Rightarrow f$  is a p-to-e calibrator: Suppose P is a p-variable and P' is uniform on [0,1]. Then  $Q(P < x) \le x =: Q(P' < x)$  for any  $x \in (0,1)$  since P is a p-variable and by definition of P' as uniform.

So  $Q(f(P) > y) \le Q(f(P') > y)$  for any  $y \in (0,1)$  since f is decreasing. Then  $\mathbb{E}[f(P)] \le \mathbb{E}[f(P')] = \int_0^1 f(p) dp \le 1$ , where the equality holds since P' is uniform on [0,1].

We omit the proof of the latter statement for brevity, but it follows readily from the definitions.

# Calibrators: E-values to p-values



- ▶ The case for converting from e-values to p-values is similar:
  - An e-to-p calibrator is a decreasing function  $f:[0,\infty] \to [0,1]$  iff for any probability space  $(\Omega,\mathcal{A},Q)$  and any e-variable  $E \in \mathcal{E}_Q$ ,  $f(E) \in \mathcal{P}_Q$
  - (Strict) domination and admissibility are defined analogously to before

# E-to-p calibrators characterization



Similar to Theorem 1, we can characterize (admissible) e-to-p calibrators:

#### Theorem 2

The function  $f:[0,\infty] \to [0,1]$  given by  $f(t) := \min(1,t^{-1})$  is an e-to-p calibrator. In fact, it dominates every other e-to-p calibrator and is the only admissible e-to-p calibrator.

So, there are effectively many admissible p-to-e calibrators, but only a single admissible e-to-p calibrator.



 $m{f(t)}$  is an e-to-p calibrator: For  $E \in \mathcal{E}_Q$  and  $\epsilon \in (0,1)$ ,

$$Q(f(E) \le \epsilon) = Q(\epsilon^{-1} \le f(E)^{-1}) = Q(\epsilon^{-1} \le E) \le \frac{\mathbb{E}^{Q}[E]}{\epsilon^{-1}} \le \epsilon,$$

where the second equality is because  $\epsilon^{-1} > 1$  so  $f(E)^{-1} = E$  when  $\epsilon^{-1} \le f(E)^{-1}$ , the first inequality uses Markov's inequality, and the last inequality is true because E is an e-variable.



f(t) dominates any e-to-p calibrator: Let g be another e-to-p calibrator. Note that it is sufficient to show that f dominates g. Suppose that for some  $t_0 \in [0,\infty]$ ,  $g(t_0) < f(t_0) = \min(1,t_0^{-1})$ . We have two cases:

- ▶ When  $g(t_0) < f(t_0) = t_0^{-1}$  for some  $t_0 > 1$ , consider an e-variable E that equals  $t_0$  with probability  $1/t_0$  and is 0 otherwise. Note that  $g(E) = g(t_0) < t_0^{-1}$  with probability  $t_0^{-1}$ . But if g(E) was a p-variable, then  $P(g(E) \le g(t_0)) \le g(t_0) < t_0^{-1}$ , indicating a contradiction (since  $t_0^{-1} = P(g(E) = g(t_0)) \le P(G(E) \le g(t_0))$ .
- When  $g(t_0) < f(t_0) = 1$  for some  $t_0 \in [0,1]$ , consider an e-variable E that equals 1 a.s. We have  $g(E) = g(t_0) < 1$  a.s., so  $P(g(E) < t_0) = 1 > t_0$  and g(E) cannot be a p-variable.



An e-merging function of  $K \geq 2$  e-values is an increasing Borel function  $F: [0, \infty)^K \to [0, \infty)$  s.t. for any probability space  $(\Omega, \mathcal{A}, Q)$  and random variables  $E_1, \ldots, E_K$  on the space,

$$E_1,\ldots,E_K\in\mathcal{E}_Q\Rightarrow F(E_1,\ldots,E_K)\in\mathcal{E}_Q$$

- ▶ An e-merging function F dominates another G if  $F \ge G$  and is strict if F(e) > G(e) for some  $e \in [0, \infty)^K$ 
  - ▶ F essentially dominates G if for any  $e \in [0, \infty)^K$ ,

$$G(e) > 1 \Rightarrow F(e) \geq G(e)$$

(i.e. F is at least as good as G when G is useful)

- An e-merging function is admissible if it is not dominated by another e-merging function
  - i.e. it is maximal in the partial order defined by the relation of domination



#### Theorem 3

The arithmetic mean  $M_K: [0,\infty)^K \to [0,\infty)$ , given by

$$M_K(e_1,\ldots,e_K):=\frac{e_1+\cdots+e_K}{K},$$

essentially dominates any symmetric e-merging function.

#### Theorem 4

Suppose that F is a symmetric e-merging function. Then F is dominated by a function in the class

$$M_{K,\lambda} := \Big\{ \lambda + (1-\lambda)M_k : \lambda \in [0,1] \Big\}.$$

Specifically, F is admissible iff  $F \in M_{K,\lambda}$  with  $F(0) = \lambda$ .



We will provide a proof of Theorem 3, but omit that of Theorem 4 for expositional brevity (see Vovk and R. Wang 2021).

#### Proof.

Suppose F is a symmetric e-merging function. Suppose for contradiction that there is some  $(e_1, \ldots, e_K) \in [0, \infty)^K$  s.t.

$$b:=F(e_1,\ldots,e_K)>\max\Big(M_K(e_1,\ldots,e_K),1\Big)=:a.$$

Let  $\pi$  by uniformly selected from  $\mathcal{S}_{\mathcal{K}}$  and

 $(D_1,\ldots,D_K):=(e_{\pi(1)},\ldots,e_{\pi(K)})$  (i.e. a random permutation of our e-values).

Take  $(D'_1, \ldots, D'_K) := (D_1, \ldots, D_K)1_A$ , where A is independent of  $\pi$  and  $P(A) = a^{-1}$ .

For each k,  $\mathbb{E}[D_k] = M_K(e_1, \dots, e_K)$  since  $\pi$  was uniform on  $S_K$  implies that  $D_k$  equals  $e_1, \dots, e_K$  with equal probability.

Then  $\mathbb{E}[D_k'] = M_K(e_1, \dots, e_K)/a \le 1$  by construction.

Since  $D'_k$  is nonnegative, we must have  $D'_k \in \mathcal{E}_Q$ .

Then  $F(D'_1, \ldots, D'_K) \in \mathcal{E}_Q$  since F is an e-merging function, so

 $\mathbb{E}[F(D_1',\ldots,D_K')] \leq 1.$ 

But by symmetry,

$$\mathbb{E}[F(D_1', \dots, D_K')] = Q(A)F(e_1, \dots, e_K) + (1 - Q(A))F(0, \dots, 0)$$

$$\geq b/a$$

$$> 1.$$

a contradiction.

So, no such  $(e_1, \ldots, e_K)$  exists and  $M_K$  essentially dominates F.



- Can also consider merging functions specifically for independent e-values
- An ie-merging function of  $K \geq 2$  e-values is an increasing Borel function  $F: [0,\infty)^K \to [0,\infty)$  s.t. for any probability space  $(\Omega, \mathcal{A}, Q)$ ,

$$E_1, \ldots, E_k \in \mathcal{E}_Q$$
 are independent  $\Rightarrow F(E_1, \ldots, E_K) \in \mathcal{E}_Q$ 

- ► Define domination, strict domination, and admissibility for ie-merging functions analogously to case of e-merging functions
- ▶ Define  $i\mathcal{E}_Q^K \subseteq \mathcal{E}_Q^K$  to be the set of component-wise independent random vectors in  $\mathcal{E}_Q^K$  and  $\mathbf{1} := (1, \dots, 1) \in \mathbb{R}^K$
- ▶ Say an ie-merging function F weakly dominates another ie-merging function G if for all  $e_1, \ldots, e_K$ ,

$$(e_1,\ldots,e_K)\in[1,\infty)^K\Rightarrow F(e_1,\ldots,e_K)\geq G(e_1,\ldots,e_K)$$

▶ i.e. F is at least as good as G when all e-value inputs are useful

# (i)e-merging functions characterization



We have the following sufficient condition for being an (i)e-merging function:

#### Theorem 5

For an increasing Borel function  $F:[0,\infty)^K \to [0,\infty)$ , if  $\mathbb{E}[F(E)]=1$  for all  $E \in \mathcal{E}_Q^K$  s.t.  $\mathbb{E}[(E_1,\ldots,E_K)]=1$  (resp. for all  $E \in i\mathcal{E}_Q^K$  s.t.  $\mathbb{E}[(E_1,\ldots,E_K)]=1$ ), then F is an admissible e-merging (resp. ie-merging) function.

So, the  $M_K$  is an admissible e-merging function and the U-statistics

$$U_n(e_1,\ldots,e_K) := \frac{1}{\binom{K}{n}} \sum_{\{k_1,\ldots,k_n\} \subseteq \{1,\ldots,K\}} e_{k_1} \ldots e_{k_n}, \ n \in \{0,\ldots,K\}$$

and their convex mixtures are admissible ie-merging functions

- ▶ Contains the product (n = K), arithmetic average  $M_K$  (n = 1), and constant function 1 (n = 0)
- ► Family is not complete class of admissible ie-merging functions

Clearly,  $F(E) \in \mathcal{E}_Q^K$  (resp.  $F(E) \in i\mathcal{E}_Q^K$ ), so F is an e-merging (resp. ie-merging function).

Suppose for contradiction that there is an (i)e-merging function F such that  $G \ge F$  and  $G(e_1, \ldots, e_K) > F(e_1, \ldots, e_K)$  for some  $(e_1, \ldots, e_K) \in [0, \infty)^K$ .

Take  $(E_1, \ldots, E_K) \in \mathcal{E}_Q^K$  (resp.  $i\mathcal{E}_Q^K$ ) with  $\mathbb{E}[(E_1, \ldots, E_K)] = \mathbf{1}$  s.t.  $Q((E_1, \ldots, E_K) = (e_1, \ldots, e_K)) > 0$  (e.g. by considering a distribution with a positive mass on  $e_1, \ldots, e_K$ ).

Then

$$Q(G(E_1,\ldots,E_K)>F(E_1,\ldots,E_K))>0$$

since  $(E_1,\ldots,E_K)=(e_1,\ldots,e_K)\Rightarrow G(E_1,\ldots,E_K)>F(E_1,\ldots,E_K).$  So.

$$\mathbb{E}[G(E_1,\ldots,E_K)] > \mathbb{E}[F(E_1,\ldots,E_K)] = 1,$$

contradicting that G is an (i)e-merging function.

Thus, F is admissible.

# Domination of ie-merging functions



We have an additional nice property of the product merging function:

#### Theorem 6

The product  $(e_1, \ldots, e_K) \mapsto e_1 \ldots e_K$  weakly dominates any ie-merging function.



Suppose for contradiction that there exists  $(e_1,\ldots,e_K)\in [1,\infty)^K$  s.t.  $F(e_1,\ldots,e_K)>e_1\ldots e_K$  for some ie-merging function F. Let  $E_1,\ldots,E_K$  be independent random variables such that for  $k\in\{1,\ldots,K\}$ ,  $E_k=e_k$  with probability  $e_k^{-1}$  and  $E_k=0$  otherwise. Clearly, each  $E_k$  is an e-variable, but

$$\mathbb{E}[F(E_1, \dots, E_K)] \ge F(e_1, \dots, e_K) Q(E_1 = e_1, \dots, E_K = e_K)$$
 $> (e_1 \dots e_K) (e_1^{-1} \dots e_K^{-1})$ 
 $= 1.$ 

So, F is not an ie-merging function and the product weakly dominates any ie-merging function.



- Let  $(\Omega, \mathcal{A})$  be a measurable space (the sample space and event space, resp.) and  $\mathcal{B}(\Omega)$  be the family of all probability measures on the space
- ▶ Say E is an e-variable w.r.t. a composite null hypothesis  $H \subseteq \mathcal{B}(\Omega)$  if  $\mathbb{E}^Q[E] \leq 1$  for any measure  $Q \in H$
- ▶ In multiple testing, have a set of composite null hypotheses  $\{H_k : 1 \le k \le K\}$
- For each k, have an e-variable  $E_k$  w.r.t.  $H_k$



A conditional e-variable is a family of extended nonnegative random variables  $E_Q$ ,  $Q \in \mathcal{B}(\Omega)$  satisfying

$$\forall Q \in \mathcal{B}(Q), \mathbb{E}^Q[E_Q] \leq 1$$

(i.e. each  $E_Q \in \mathcal{E}_Q$ )

Say that extended random variables  $E_1^*, \ldots, E_K^*$  are family-wise valid (FWV) for testing  $H_1, \ldots, H_K$  if there exists a conditional e-variable  $(E_Q)_{Q \in \mathcal{B}(\Omega)}$  s.t.

$$\forall k \in \{1, \dots, K\} , \forall Q \in H_k : E_Q \ge E_k^*$$

From the definition of a conditional e-variable, we see that this equivalent to

$$orall Q \in \mathcal{B}(\Omega): \mathbb{E}^Q \Big[\max_{k:Q \in \mathcal{H}_k} E_k^* \Big] \leq 1$$

(i.e. joint validity of the e-variables  $E_k^*$ )

▶ Say that  $(E_Q)_{Q \in \mathcal{B}(\Omega)}$  witnesses that  $E_1^*, \dots E_K^*$  are FWV



## **Algorithm 1** Adjusting arbitrary e-values for multiple testing

```
Require: Arbitrary e-values e_1, \ldots, e_K.
 1: Find the ordering permutation \pi \in S_k s.t. e_{\pi(1)} \leq \cdots \leq e_{\pi(K)}
 2: Define the order statistics e_{(k)} := e_{\pi(k)} for k \in \{1, \dots, K\}
 3: Set S_0 := 0
 4: for i \in \{1, ..., K\} do
 5: S_i := S_{i-1} + e_{(i)} (cumulative sum of ordered values)
 6: for k \in \{1, ..., K\} do
    e_{\pi(k)}^* := e_{\pi(k)}
 8: for i \in \{1, ..., k-1\} do
             e := \frac{e_{\pi(k)} + S_i}{i+1} (average of first i and k-th ordered values)
 9:
             if e < e_{\pi(k)}^* then
10:
                 e_{\pi(k)}^* := e
11:
12: return e_{\pi(1)}^*, \ldots, e_{\pi(K)}^*
```

# FWV arbitrary e-value adjustment



#### Theorem 7

Algorithm 1 is family-wise valid. It has a computational complexity of  $O(K^2)$ .



Note that the computational complexity immediately follows from the nested for-loops, so we need only show FWV.

It suffices to check that the e-variables  $E_1^*,\ldots,E_k^*$  from Algorithm 1 are FWV. For any subset  $I\subseteq\{1,\ldots,K\}$ , the composite hypothesis  $H_I$  is

$$H_I := \left(\bigcap_{k \in I} H_k\right) \bigcap \left(\bigcap_{k \in \{1, \dots, K\} \setminus I} H_k^c\right),$$

with  $H_k^c$  defined as the complement of  $H_k$ . The conditional e-variable witnessing the FWV of  $E_1^*, \ldots, E_K^*$  is the arithmetic mean

$$E_Q := \frac{1}{|I_Q|} \sum_{k \in I_Q} E_k,$$

with  $I_Q := \{k | Q \in H_k\}$  and  $E_Q$  defined as 1 when  $I_Q = \emptyset$ .



We use the following (conservative) definition for our adjusted e-variables  $E_k^*$ :

$$E_k^* := \min_{I \subseteq \{1, \dots, K\} : k \in I} \frac{1}{|I|} \sum_{i \in I} E_i.$$

Note that for each  $k \in \{1, ..., K\}$ ,

$$E_{\pi(k)}^* = \min_{i \in \{0, \dots, k-1\}} \frac{E_{\pi(k)} + E_{(1)} + \dots + E_{(i)}}{i+1}.$$



In lines 3-5 of Algorithm 1, we compute

$$S_i := e_{(1)} + \cdots + e_{(i)}, i \in \{1, \ldots, K\}$$

and in lines 8-9 we calculate

$$e_{k,i} := \frac{e_{\pi(k)} + e_{(1)} + \dots + e_{(i)}}{i+1}, i \in \{1, \dots, k-1\}$$

Then

$$e_{\pi(k)}^* = \min_{i \in \{1, \dots, k-1\}} e_{k,i} = \min_{i \in \{0, \dots, k-1\}} \frac{e_{\pi(k)} + e_{(1)} + \dots + e_{(i)}}{i+1},$$

so the algorithm is in fact FWV since these are e-values associated with the adjusted e-variables  $E_k^*$ .



## Algorithm 2 Adjusting independent e-values for multiple testing

**Require:** Independent e-values  $e_1, \ldots, e_K$ .

- 1: Let  $a:=\prod_{k\in\{1,\ldots,K\}:e_k<1}e_k$  (with empty product defined as 1)
- 2: **for**  $k \in \{1, ..., K\}$  **do**
- 3:  $e_k^* := ae_k$
- 4: **return**  $e_1^*, \ldots, e_K^*$

# FWV independent e-value adjustment



#### Theorem 8

Algorithm 2 is family-wise valid. It has a computational complexity of O(K).

Note that Algorithm 2 is actually FWV for sequential e-variables, but we focus on independent e-variables for brevity.



Again, the computational complexity immediately follows from the algorithm pseudocode so we focus on proving FWV.

As before, take  $I_Q := \{k | Q \in H_k\}$ . Our conditional e-variable that witnesses that  $e_1^*, \dots, e_K^*$  are FWV are the ones given by the product ie-merging function, i.e.

$$E_Q := \prod_{k \in I_Q} E_k,$$

where our adjusted e-variables are

$$E_k^* := \min_{I \subseteq \{1,\ldots,K\}: k \in I} \prod_{i \in I} E_i.$$

By inspection, we can see that  $e_1^*, \ldots, e_K^*$  in Algorithm 2 are realizations of  $E_1^*, \ldots, E_K^*$ , so the Algorithm is FWV.



- ► E-values as an alternative to p-values
- Conversion between p- and e-values with calibrators that have known domination structure
- Combine e-values together with e-merging functions that have complicated domination structure
- FWV valid algorithms for adjusting (independent) e-values
- Applications to multiple testing



- Vovk, Vladimir, Bin Wang, and Ruodu Wang (2022). "Admissible ways of merging p-values under arbitrary dependence". In: The Annals of Statistics 50.1, pp. 351–375. DOI: 10.1214/21-AOS2109. URL: https://doi.org/10.1214/21-AOS2109.

Vovk, Vladimir and Ruodu Wang (2021). "E-values: Calibration, combination and applications". In: The Annals of Statistics 49.3. pp. 1736-1754. DOI: 10.1214/20-AOS2020. URL: https://doi.org/10.1214/20-AOS2020.