### An Ensemble of Neural Nets

Rahul Ramesh

STAT-991

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$$e(h) = \mathbb{P}[h(x) \neq y],$$

and is well-calibrated.

$$\gamma = \mathbb{P}(Y|p_h(Y|X) = q)$$
$$c(h) = \mathbb{E}_q [d(\gamma, q)]$$

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Accuracy

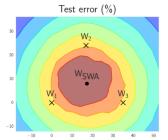


Figure: See Izmailov et al. (2018)

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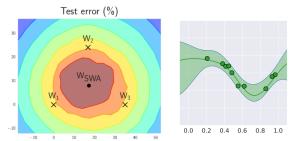


Figure: See Izmailov et al. (2018) and Ovadia et al. (2019)

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Ensembles have emerged as useful approximations of the Bayes posterior.

We explore some recent results that make use of ensembles.

# The Bayes posterior

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Instead, we hedge our bets and consider a distribution over parameters

$$p(\theta|D) \propto p(D|\theta)p(\theta) = \exp(-U(\theta))$$

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In practice, we use a Monte Carlo approximation. First sample

$$\theta_1, \theta_2, \cdots \theta_k \sim p(\theta|D),$$

and use them to make predictions.

$$p(y|x, D) \approx \frac{1}{k} \sum_{i=1}^{k} p(y|x, \theta_i)$$

#### How do we train a model?

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#### Existing methods:

- 1. Variational approximation  $(q_w(\theta) \approx p(\theta|D))$
- 2. Markov-chain Monte-carlo (MCMC)

The ELBO forms the basis of VI methods (Blundell et al., 2015; Wen et al., 2018; Louizos and Welling, 2016)

$$\log p(y|x) \ge \mathbb{E}_{q_w(\theta)}[\log p(y|x,\theta)] - \mathbb{E}_{q_w(\theta)}\left[\log \frac{q_w(\theta)}{p(\theta)}\right]$$

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is the gradient with dropout.

The second term is usually absent in an implementation of dropout

$$\mathbb{E}_{q_{\mu}(\theta)}[\log \frac{q_{\mu}(\theta)}{p(\theta)}]$$

but approximately corresponds to the L2-penalty.

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Parameters with low losses are sampled more frequently.

### **MCMC - Langevin Equation**

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Hence, if we simulate the SDE, we will converge to the stationary distribution

$$\underline{d\theta(t)} = -\nabla U(\theta(t))\underline{dt} + \sqrt{2T}\underline{dB_t}$$

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$$\theta_{t+1} = \theta_t - \eta \nabla [U(\theta(t))]_i + \sqrt{2T}\xi_t$$

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Introduce a "velocity" variable and attempt to conserve the Hamiltonian of the system.

## A closer look at Bayesian posteriors

#### How Good is the Bayes Posterior in Deep Neural Networks Really?

Florian Wenzel<sup>\*1</sup> Kevin Roth<sup>\*+2</sup> Bastiaan S. Veeling<sup>\*+31</sup> Jakub Świątkowski <sup>4+</sup> Linh Tran<sup>5+</sup> Stephan Mandt<sup>6+</sup> Jasper Snoek<sup>1</sup> Tim Salimans<sup>1</sup> Rodolphe Jenatton<sup>1</sup> Sebastian Nowozin<sup>7+</sup>

#### What Are Bayesian Neural Network Posteriors Really Like?

Pavel Izmailov 1 Sharad Vikram 2 Matthew D. Hoffman 2 Andrew Gordon Wilson 1

# A quick recap

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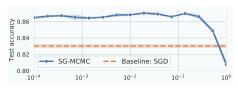
## A quick recap

- $p(\theta|D) \propto \exp(\frac{-U(\theta)}{T})$
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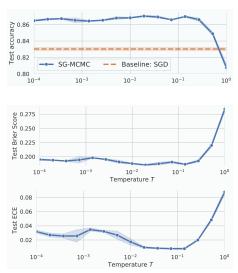
MCMC is compute intensive but accurate.

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Related work that uses T < 1 posteriors in SG-MCMC. The following table lists work that uses SG-MCMC on deep neural networks and tempers the posterior.<sup>3</sup>

Reference	Temperature $T$
(Li et al., 2016)	$1/\sqrt{n}$
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This is problematic since we artificially sharpen the posterior and scale the variance of the prior.

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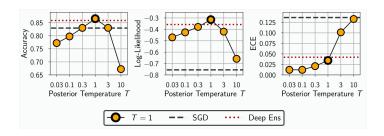
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- Inadequate prior
- SGD does not work with Bayesian methods

Izmailov et al. (2021) conduct large scale HMC experiments.

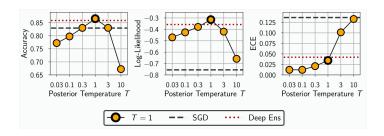
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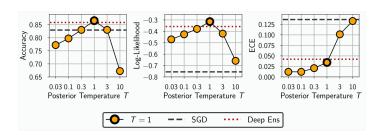
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- Batch-norm → filter-response normalization



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- We want an inexpensive and accurate model that captures the Bayes posterior

# Ensembles

# **Emergence of Ensembles**

Revisiting earlier experiments

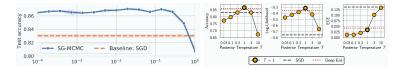
# **Emergence of Ensembles**

#### Revisiting earlier experiments



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- Cold posteriors are better
- Deep ensembles match the accuracy and calibration of HMC.

We focus on ensembles, which are finite particle approximations of the posterior

$$p(\theta|D) \approx \sum_{i=1}^{k} \frac{1}{k} \delta(\theta - \theta_i)$$

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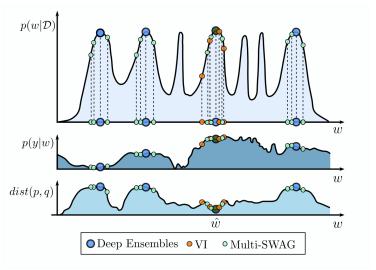
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we train k copies of it, each initialized randomly:

$$\theta_1 \quad \theta_2 \quad \cdots \quad \theta_k$$

### Why do they work?

Ensembles capture different modes (Wilson and Izmailov, 2020).



#### Why do they work?

Variational inference methods are not nearly as diverse (Fort et al., 2019).

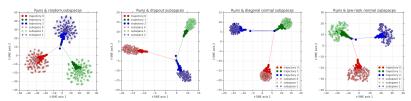


Figure: 1) Random 2) Dropout 3) Diagonal Gaussian 4) Low-rank Gaussian

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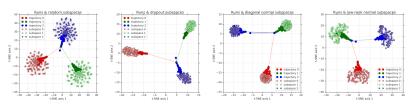


Figure: 1) Random 2) Dropout 3) Diagonal Gaussian 4) Low-rank Gaussian

Initialization influences diversity in predictions more than other factors.

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In practice, we don't use the repulsion term and find random initializations to be sufficient.

Ovadia et al. (2019) evaluate ensembles under distribution shift (heavy augmentations)











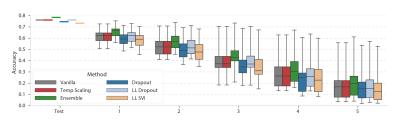


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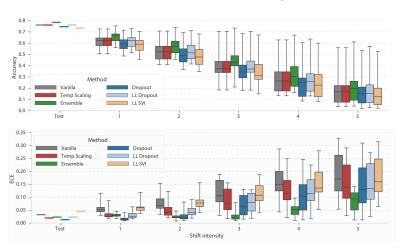


We focus in evaluations in Imagenet, which used at most 10 models for ensembling.

Ensembles are well-calibrated and usually more accurate.



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#### What about the prior?

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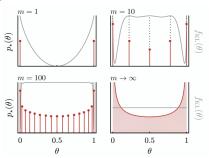
$$p(\theta) \stackrel{d}{=} \mathcal{N}(0, I)$$

Wilson and Izmailov (2020); Wenzel et al. (2020) mention the importance of the prior but it is relatively unexplored beyond Gaussians.

Gao et al. (2022) attempt to learn the prior from unlabeled data.

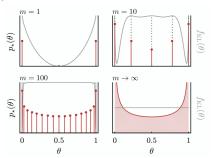
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Reference priors are "uninformative" and let the data dominate the posterior.

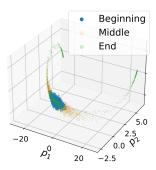


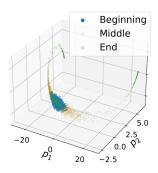
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Reference priors are supported on a finite number of atoms





Method	Samples				
	50	100	250	500	1000
MixMatch	64.21	80.29	88.91	90.35	92.25
FixMatch (RA)	86.19 ± 3.37 (40)	90.12	$94.93\pm0.65$	93.91	94.3
Deep Reference Prior	85.45 ± 2.12	$88.53 \pm 0.67$	92.13 ± 0.39	$92.94 \pm 0.22$	$93.48 \pm 0.24$

#### Conclusion

We approximate the Bayes posterior using ensembles, which are effective even on large datasets.

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Can we do better?

#### References I

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