

# Problem Set 5 - ECON 880

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## Question 1

We have given  $f(x) = (x^{1/2} + 1)^{2/3}$ , with a starting value  $x_0 = 1$ . The first derivative is given by

$$f'(x) = \frac{1}{3x^{1/2}(x^{1/2} + 1)^{1/3}},$$

while the second one is given by

$$f''(x) = \frac{-1}{18x(x^{1/2} + 1)^{4/3}} - \frac{1}{6x^{3/2}(x^{1/2} + 1)^{1/3}}$$

### 1(a) Taylor Series Approximation

The first-order Taylor series approximation is given by:

$$\begin{aligned} f(x) &= f(x_0) + f'(x_0)(x - x_0) \\ &= 1.5874 + 0.2646(x - 1) \end{aligned}$$

The second-order Taylor series approximation is given by:

$$\begin{aligned} f(x) &= f(x_0) + f'(x_0)(x - x_0) + \frac{(x - x_0)^2}{2} f''(x_0) \\ &= 1.5874 + 0.2646(x - 1) - 0.0772(x - 1)^2 \end{aligned}$$

### 1(b) Padé Approximation

We want to compute Padé Approximation (1,1)

$$P_{M=1}^{N=1}(x) = \frac{a_0 + a_1(x - x_0)}{b_0 + b_1(x - x_0)},$$

where  $b_0 = 1$  (normalized). The Padé coefficients are normally best found from an  $(M + N)$ -th order Taylor series expansion of  $f(x)$  :

$$\begin{aligned} T_2(x) &= \frac{a_0 + a_1(x - 1)}{1 + b_1(x - 1)} \\ 1.5874 + 0.2646(x - 1) - 0.0772(x - 1)^2 &= \frac{a_0 + a_1(x - 1)}{1 + b_1(x - 1)} \end{aligned}$$

Multiplying up the denominator of the RHS with the LHS gives the following equivalent set of coefficient relations:

$$a_0 = 1.5874 \quad (1)$$

$$a_1 = 1.5874b_1 + 0.2646 \quad (2)$$

$$0 = 0.2646b_1 - 0.0772 \quad (3)$$

From equation 3, we obtain  $b_1 = 0.2917$ . Then, we plug it in into equation 2 to obtain  $a_1 = 0.7276$ . Finally, the Padé Approximation (1,1) for  $f(x)$  is given by

$$P_{M=1}^{N=1}(x) = \frac{1.5874 + 0.7276(x-1)}{1 + 0.2917(x-1)},$$

## Question 2

Consider the function

$$f(x) = e^{4x-2}$$

over  $[0, 2]$  interval, and construct the following approximations to it:

- (a) Chebyshev polynomials of degree 4; choose 5 points to use as nodes.
- (b) Cubic spline over 5 equally spaced points in  $[0, 2]$ .

Then evaluate the approximations over 101 equally spaced points in  $[0, 2]$  and plot them along with the true function.

### 2(a) Chebyshev Interpolation

We use the following algorithm<sup>†</sup> to construct the Chebyshev interpolation of order 4. The code is saved as `chebyshev.m`. The result is shown on Figure 1.

Step 1. Compute five Chebyshev interpolation nodes on  $[0, 2]$  using the following formula

$$z_k = -\cos\left(\frac{2k-1}{2m}\pi\right), \quad k = 1, \dots, m$$

Step 2. Adjust the nodes to the  $[0, 2]$  interval:

$$x_k = (z_k + 1) \left(\frac{2-0}{2}\right) + 0 = z_k + 1, \quad k = 1, \dots, m$$

Step 3. Evaluate  $f$  at the approximation nodes

$$y_k = f(x_k), \quad k = 1, \dots, m$$

Step 4. Compute Chebyshev coefficients  $\{a_i\}_{i=0}^n$

$$a_i = \frac{\sum_{k=1}^m y_k T_i(z_k)}{\sum_{k=1}^m T_i(z_k)^2},$$

where  $T_i(x) = 2xT_{i-1}(x) - T_{i-2}(x)$ , with  $T_0(x) = 1$  and  $T_1(x) = x$ , for  $i = 2, \dots, n$

Step 5. The approximation for  $f(x)$ ,  $x \in [0, 2]$  is given by:

$$\hat{f}(x) = \sum_{i=0}^n a_i T_i(x-1).$$

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<sup>†</sup>Kenneth L. Judd, 1998. "Numerical Methods in Economics," MIT Press Books, The MIT Press, p.223

## 2(a) Cubic Spline Interpolation

We use the following algorithm to construct the cubic spline interpolation. The result is shown on Figure 1.

Step 1. Suppose we have the dataset  $\{(x_i, y_i) | i = 1, \dots, n\}$ . First, do some precalculations:

- $h_i = x_{i+1} - x_i$ , for  $i = 1, \dots, n-1$
- $v_i = 2(h_{i-1} + h_i)$ , for  $i = 1, \dots, n-1$
- $f_i = 6 \left( \frac{y_{i+1} - y_i}{h_{i-1}} - \frac{y_i - y_{i-1}}{h_i} \right)$ , for  $i = 1, \dots, n-1$
- $f_1 = f_n = 0$

Step 2. Solve the triagonal system

$$\begin{bmatrix} 1 & 0 & 0 & \dots & \dots & \dots & 0 \\ 0 & v_1 & h_1 & & & & \\ 0 & h_1 & v_2 & h_2 & & & \\ \vdots & & h_2 & v_3 & h_3 & & \\ \vdots & & & \ddots & \ddots & \ddots & \\ \vdots & & & & \ddots & \ddots & h_{n-1} & 0 \\ \vdots & & & & & h_{n-1} & v_{n-1} & 0 \\ 0 & 0 & 0 & \dots & \dots & 0 & 1 \end{bmatrix} \begin{pmatrix} s_1 \\ s_2 \\ s_3 \\ \vdots \\ \vdots \\ s_{n-1} \\ s_n \end{pmatrix} = \begin{pmatrix} 0 \\ f_2 \\ f_3 \\ \vdots \\ \vdots \\ f_{n-1} \\ 0 \end{pmatrix}$$

Step 3. For  $i = 1, \dots, n-1$ , compute

$$\begin{aligned} a_i &= (s_{i+1} - s_i)/6h_i \\ b_i &= s_i/2 \\ c_i &= (y_{i+1} - y_i)/h_i - (2h_i s_i + h_i s_{i+1})/6 \\ d_i &= y_i \end{aligned}$$

Step 1-3 is performed by calling `splinecoefs.m`.

Step 4. Calculate the cubic spline approximation function

$$s_i(x) = a_i(x - x_i)^3 + b_i(x - x_i)^2 + c_i(x - x_i) + d_i,$$

for  $i = 1, \dots, n-1$ . This step is performed by calling `evspline.m`.

Comment: Cubic spline works better because the approximated curve is relatively much closer to the true function. Higher order Chebyshev coefficients seem to be smaller because the curve looks more like a third order polynomial curve. Both approximation methods have a matching slope and curvature with the true function only for the interval  $x > 1$ . For  $x < 1$ , cubic spline has more accurate curvature approximation to the true function.

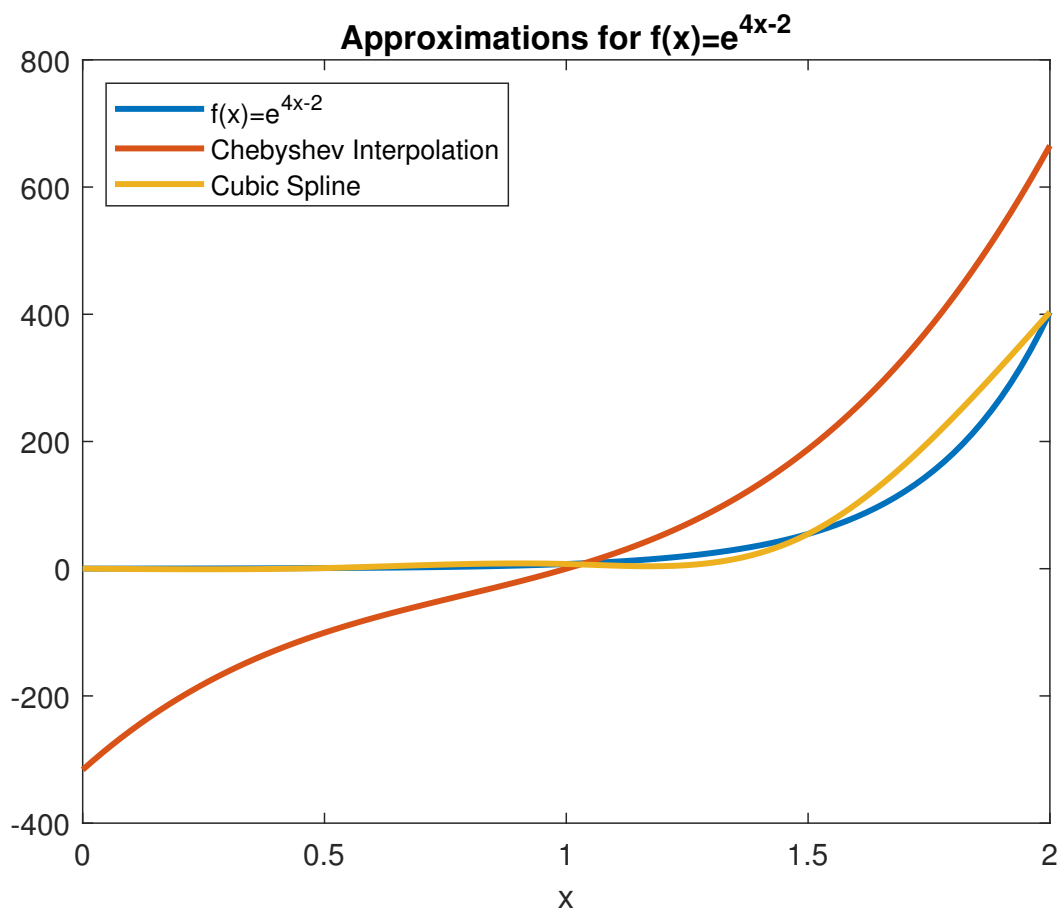


Figure 1: Approximations for  $f(x) = e^{4x-2}$