

Outline Chapter 18: Pre-stabilized lasers (B. Willke)

1. laser parameters and the relevance of their fluctuations in GWDs
 - a. which parameter describe laser beam
$$\vec{E}(\vec{r}, t) = E_0(\vec{r}, \omega, t) \cdot \vec{e}_p(\vec{r}) \cdot \cos(\omega t - \vec{k}\vec{r} + \varphi(t))$$
 - b. coupling of laser fluctuations into GWD channel (qualitative discussion of relevant coupling paths)
 - c. requirement for 2nd generation GWDs, outlook to 3rd generation GWDs
2. Laser characterization, free running fluctuations of lasers and their typical physical sources
 - a. Diagnostic breadboard: resonator as frequency, spatial and modal reference
 - b. control loops to convert these references into linear sensors (PHD and length stabilization, differential wave-front sensing and automatic alignment, unity gain frequency dependent readout of control or error signal
 - c. length scan for modal decomposition of laser beam
3. Advanced LIGO PSL Layout as example
 - a. brief description of laser system
 - b. Pre-modecleaner as noise filter and spatial reference for ISS and FSS and as interface to GWD (IO in this case)
 - i. need for long range actuator to compensate temp. and pressure fluctuations
 - ii. filter bandwidth / thermal loading trade-off
 - c. miscellaneous:
 - i. ISS sensing after IMC including pointing-> RIN coupling
 - ii. FSS: VCO-AOM units as actuator for IFO LSC loops
 - iii. pickoff beam for ALS
4. Power stabilization
 - a. cause and transfer of laser power fluctuation
 - b. trade-off between different actuators [with respect to range, speed, cross coupling]: pump diode current of different laser stages / AOM at different locations / detuning of PMC
 - c. sensor noise: shot noise / pointing coupling / scattered light / light in wrong polarization / electronic noise in PD
 - d. performance of aLIGO ISS and outlook (optical AC coupling)
 - e. (maybe rf power noise filtering of PMC)
5. Frequency stabilization
 - a. suspended rigid spacer reference with thermal tuning
 - b. nested high bandwidth control loop (maybe current lock actuator)
 - c. actuator for LSC control loop: VCO-AOM combination, error-point summation
 - d. transfer of frequency stability from reference cavity to IFO (Doppler shift, PMC length fluctuations)
6. Spatial filtering and reduction of pointing fluctuations (I'm not sure if this deserves a full chapter or if it can go into 3.b)
 - a. the mode-cleaning effect of a PMC
 - b. description of pointing via HG₁₀ mode content
 - c. reduction of pointing noise by aLIGO PMC
 - d. (maybe spatial filtering of higher order Gauss modes)
7. Outlook
 - a. challenges for 3rd Generation IFOs
 - b. novel techniques
 - c. ...

chapters with possible cross-links

7. how to think about and control non-fundamental noise sources (Ballmer)
8. control systems (Evans)
9. cavity optics: longitudinal modes, higher order modes, stability (Barsuglia, Ando)
11. EO components / photodiodes (Quetschke)
14. lasers (Munch)
19. Input mode cleaners and associated input optics (Mueller, Genin)
21. Length sensing and control (Grote)