

```
1 #include <iostream>
2 #include "Controller/Controller.hpp"
3
4 int main(int argc, char* argv[]) {
5     const int NB_ARGS = 5;
6
7     if (argc != NB_ARGS) {
8         std::cerr << "Please enter a valid number of parameters : " << argv[0]
9             << "<width> <height> <number of humans> <number of vampires
10            >" 
11             << std::endl;
12     }
13
14     size_t width, height, nbHumans, nbVampires;
15     try {
16         for (int i = 1; i < argc; ++i) {
17             if (std::stoi(argv[i]) < 0) {
18                 std::cerr << "Values should be positives." << std::endl;
19                 return 1;
20             }
21         }
22         width = static_cast<size_t>(std::stoul(argv[1]));
23         height = static_cast<size_t>(std::stoul(argv[2]));
24         nbHumans = static_cast<size_t>(std::stoul(argv[3]));
25         nbVampires = static_cast<size_t>(std::stoul(argv[4]));
26     } catch (const std::invalid_argument& e) {
27         return 1;
28     } catch (const std::out_of_range& e) {
29         std::cerr << "An argument is out of range." << std::endl;
30         return 1;
31     }
32
33     Controller controller(width, height, nbHumans, nbVampires);
34     controller.run();
35
36     return 0;
37 }
```

```

1 /**
2  * @file Field.cpp
3  * @brief Declaration of the Field class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include "Field.hpp"
8
9 Field::Field(const size_t width, const size_t height, size_t nbHumans,
10              size_t nbVampires): width(width), height(height), nbHumans(
11              nbHumans),
12              nbVampires(nbVampires), turn(0)
13 {
14     for (size_t i = 0; i < nbHumans; i++) {
15         humanoids.emplace_back(
16             new Human(Position::random(width, height)));
17     }
18     for (size_t i = 0; i < nbVampires; i++) {
19         humanoids.emplace_back(
20             new Vampire(Position::random(width, height)));
21     }
22     humanoids.emplace_back(new Buffy(Position::random(width, height)));
23 }
24
25 int Field::nextTurn() {
26     // Déterminer les prochaines actions
27     for (std::list<Humanoid *>::iterator it = humanoids.begin();
28          it != humanoids.end(); it++)
29         (*it)->setAction(*this);
30     // Executer les actions
31     for (std::list<Humanoid *>::iterator it = humanoids.begin();
32          it != humanoids.end(); it++)
33         (*it)->executeAction(*this);
34     // Enlever les humanoïdes tués
35     for (std::list<Humanoid *>::iterator it = humanoids.begin();
36          it != humanoids.end();) {
37         if (!(*it)->isAlive()) {
38             Humanoid *ToDelete = *it;
39             it = humanoids.erase(it); // suppression de l'élément dans la liste
40             delete ToDelete; // destruction de l'humanoïde référencé
41         } else
42             ++it;
43     }
44     return turn++;
45 }
46 size_t Field::getNbHuman() const {
47     return nbHumans;
48 }
49
50 size_t Field::getNbVampire() const {
51     return nbVampires;

```

```
52 }
53
54 std::list<Humanoid*> Field::getHumanoids() const {
55     return humanoids;
56 }
57
58 size_t Field::getWidth() const {
59     return width;
60 }
61
62 size_t Field::getHeight() const {
63     return height;
64 }
65
66 int Field::getTurn() const {
67     return turn;
68 }
69
70 void Field::vampireDie() {
71     if(nbVampires) --nbVampires;
72 }
73
74 void Field::humanDie() {
75     if(nbHumans) --nbHumans;
76 }
77
78 void Field::vampireBorn() {
79     ++nbVampires;
80 }
81
82 void Field::addHumanoid(Humanoid* humanoid) {
83     for(auto it = humanoids.begin(); it != humanoids.end(); it++)
84         if(*it == humanoid) return;
85     humanoids.emplace_back(humanoid);
86 }
87
88
89
```

```

1 /**
2  * @file Field.hpp
3  * @brief Definition of the Field class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #ifndef LAB4_FIELD_HPP
8 #define LAB4_FIELD_HPP
9
10 #include <list>
11 #include <limits>
12 #include "../Person/Humanoid.hpp"
13 #include "../Person/Human.hpp"
14 #include "../Person/Vampire.hpp"
15 #include "../Person/Buffy.hpp"
16
17 class Humanoid;
18
19 class Human;
20
21 class Vampire;
22
23 /**
24  * @brief Class representing a field.
25  * @details A field has a width, a height, a number of humans and a number
26  * of vampires.
27 */
28 class Field {
29     std::list<Humanoid *> humanoids;
30     int turn = 0;
31     const size_t width, height;
32     size_t nbHumans, nbVampires;
33
34 public:
35
36     /**
37      * @brief Constructor of the Field class.
38      * @param width Width of the field.
39      * @param height Height of the field.
40      * @param nbHumans Number of humans on the field.
41      * @param nbVampires Number of vampires on the field.
42      */
43     Field(const size_t width, const size_t height, size_t nbHumans,
44           size_t nbVampires);
45
46
47     /**
48      * @brief We prepare and execute the action of each humanoid, removing
49      * those
50      * that are dead and moving on to the next round.
51      */
52     int nextTurn();

```

```
52
53     /**
54      * @brief Find the closest humanoid of a specific type to a given
55      * humanoid.
56      * @param T The type of humanoid to find.
57      * @param h The humanoid from which to find the closest humanoid.
58      * @return The closest humanoid of the specified type.
59      */
60     template<typename T>
61     T *findClosest(const Humanoid &h) const {
62         T *closest = nullptr;
63         int minDist = std::numeric_limits<int>::max();
64         T *specificType;
65
66         for (Humanoid *humanoid: humanoids) {
67             specificType = dynamic_cast<T *>(humanoid);
68             if (specificType != nullptr) {
69                 int dist = humanoid->getPosition().distance(h.getPosition());
70                 if (dist < minDist) {
71                     minDist = dist;
72                     closest = specificType;
73                 }
74             }
75         }
76         return closest;
77     }
78
79     /**
80      * @brief Get the number of humans on the field.
81      * @return The number of humans on the field.
82      */
83     size_t getNbHuman() const;
84
85     /**
86      * @brief Get the number of vampires on the field.
87      * @return The number of vampires on the field.
88      */
89     size_t getNbVampire() const;
90
91     /**
92      * @brief Get the list of humanoids on the field.
93      * @return The list of humanoids on the field.
94      */
95     std::list<Humanoid *> getHumanoids() const;
96
97     /**
98      * @brief Get the width of the field.
99      * @return The width of the field.
100     */
101    size_t getWidth() const;
102
103    /**
104
```

```
103     * @brief Get the height of the field.  
104     * @return The height of the field.  
105     */  
106     size_t getHeight() const;  
107  
108     /**  
109     * @brief Get the current turn.  
110     * @return The current turn.  
111     */  
112     int getTurn() const;  
113  
114     /**  
115     * @brief Decrease the number of vampires by one.  
116     */  
117     void vampireDie();  
118  
119     /**  
120     * @brief Decrease the number of humans by one.  
121     */  
122     void humanDie();  
123  
124     /**  
125     * @brief Increase the number of vampires by one.  
126     */  
127     void vampireBorn();  
128  
129     /**  
130     * @brief Add a humanoid to the field.  
131     * @param humanoid The humanoid to add.  
132     */  
133     void addHumanoid(Humanoid *humanoid);  
134 };  
135  
136 #endif //LAB4_FIELD_HPP  
137
```

```
1 /**
2  * @file Random.cpp
3  * @brief Declaration of the Random class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include <stdexcept>
8 #include "Random.hpp"
9
10 std::mt19937 Random::gen = std::mt19937(std::random_device()());
11
12 int Random::generateInt(int max) {
13     return generateInt(0, max);
14 }
15
16 int Random::generateInt(int min, int max) {
17     if(max <= min) throw std::invalid_argument("Max must be greater or equal than "
18                                                 "min");
19     std::uniform_int_distribution<int> dist(min, max - 1);
20     return dist(gen);
21 }
22
23 bool Random::generateBool() {
24     // Generate a random integer between 0 and 1 (generateInt not including max)
25     return generateInt(0, 2);
26 }
27
```

```
1 /**
2  * @file Random.hpp
3  * @brief Definition of the Random class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef BUFFY_RANDOM_HPP
8 #define BUFFY_RANDOM_HPP
9
10 #include <random>
11
12 /**
13  * @brief Class representing a random number generator.
14  */
15 class Random {
16     static std::mt19937 gen;
17 public:
18     /**
19      * Generate a random integer between min (including) and max (not
20      * including)
21      * @param min the minimum value
22      * @param max the maximum value
23      * @return a random integer between min and max
24      */
25     static int generateInt(int min, int max);
26
27     /**
28      * Generate a random integer between 0 (including) and max (not including
29      * )
30      * @param max the maximum value
31      * @return a random integer between 0 and max
32      */
33     static int generateInt(int max);
34
35     /**
36      * Generate a random boolean
37      * @return a random boolean
38      */
39     static bool generateBool();
40 };
41 #endif //BUFFY_RANDOM_HPP
42
```

```
1 /**
2  * @file Position.cpp
3  * @brief Declaration of the Position class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include <cmath>
8 #include "Position.hpp"
9 #include "Random.hpp"
10
11 const Position Position::UP = Position(0, -1);
12 const Position Position::UP_RIGHT = Position(1, -1);
13 const Position Position::RIGHT = Position(1, 0);
14 const Position Position::DOWN_RIGHT = Position(1, 1);
15 const Position Position::DOWN = Position(0, 1);
16 const Position Position::DOWN_LEFT = Position(-1, 1);
17 const Position Position::LEFT = Position(-1, 0);
18 const Position Position::UP_LEFT = Position(-1, -1);
19
20 Position::Position() : x(0), y(0) {}
21
22 Position::Position(size_t x, size_t y) : x(x), y(y) {}
23
24 size_t Position::getX() const {
25     return x;
26 }
27
28 size_t Position::getY() const {
29     return y;
30 }
31
32 size_t Position::distance(const Position & pos) const {
33     return (size_t)round(hypot(abs((x - pos.x)), abs((y - pos.y))));}
34 }
35
36 Position Position::random(size_t width, size_t height) {
37     return Position(Random::generateInt(width),
38                     Random::generateInt(height));
39 }
40
41 Position Position::getDirection(const Position &pos) const {
42     int dx = pos.getX() - x;
43     int dy = pos.getY() - y;
44     return Position(dx == 0 ? 0 : dx / abs(dx),
45                     dy == 0 ? 0 : dy / abs(dy));
46 }
47
48 void Position::move(const Position &direction) {
49     x += direction.getX();
50     y += direction.getY();
51 }
52
```

```
1 /**
2  * @file Position.hpp
3  * @brief Definition of the Position class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef LAB4_POSITION_HPP
8 #define LAB4_POSITION_HPP
9
10 #include <cstddef>
11
12 /**
13  * @brief Class representing a position
14  */
15 class Position {
16     size_t x, y;
17
18 public:
19     /**
20      * @brief Static positions representing the 8 directions.
21      */
22     static const Position
23         UP,
24         UP_RIGHT,
25         RIGHT,
26         DOWN_RIGHT,
27         DOWN,
28         DOWN_LEFT,
29         LEFT,
30         UP_LEFT;
31
32     /**
33      * @brief Default constructor of the Position class.
34      */
35     Position();
36
37     /**
38      * @brief Constructor of the Position class.
39      * @param x The x coordinate of the position.
40      * @param y The y coordinate of the position.
41      */
42     Position(size_t x, size_t y);
43
44     /**
45      * @brief Getter for the x coordinate of the position.
46      * @return The x coordinate of the position.
47      */
48     size_t getX() const;
49
50     /**
51      * @brief Getter for the y coordinate of the position.
52      * @return The y coordinate of the position.
53  }
```

```
53     */
54     size_t getY() const;
55
56     /**
57      * @brief Compute the distance between two positions.
58      * @param pos The position to which the distance will be computed.
59      * @return The distance between the two positions.
60      */
61     size_t distance(const Position & pos) const;
62
63     /**
64      * @brief Get the direction to go to reach a position.
65      * @param pos The current position.
66      * @return The position to go to reach the given position.
67      */
68     Position getDirection(const Position& pos) const;
69
70     /**
71      * @brief Move the position in a given direction.
72      * @param direction The direction in which the position will be moved.
73      */
74     void move(const Position& direction);
75
76     /**
77      * @brief Generate a random position in a given width and height.
78      * @param width The width of the field.
79      * @param height The height of the field.
80      * @return A random position in the field.
81      */
82     static Position random(size_t width, size_t height);
83 };
84
85
86
87
88 #endif //LAB4_POSITION_HPP
89
```

```
1 /**
2  * @file Kill.cpp
3  * @brief Declaration of the Kill class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include "Kill.hpp"
8 #include "../Person/Humanoid.hpp"
9
10 Kill::Kill(Humanoid& humanoid) : Action(humanoid) {}
11
12 void Kill::execute(Field& f) {
13     if(getHumanoid()->isAlive()) getHumanoid()->die(f);
14 }
```

```
1 /**
2  * @file Kill.hpp
3  * @brief Definition of the Kill class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef BUFFY_KILL_HPP
8 #define BUFFY_KILL_HPP
9
10 #include "Action.hpp"
11
12 /**
13  * @brief Class representing the action of killing a humanoid.
14  */
15 class Kill : public Action {
16 public:
17     /**
18      * @brief Constructor of the Kill class.
19      * @param humanoid The humanoid that will execute the action.
20      */
21     explicit Kill(Humanoid& humanoid);
22
23     void execute(Field& f) override;
24 };
25
26 #endif //BUFFY_KILL_HPP
27
```

```

1 /**
2  * @file Move.cpp
3  * @brief Declaration of the Move class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include "Move.hpp"
8 #include "../Person/Humanoid.hpp"
9 #include "../Field/Field.hpp"
10 #include "../Utils/Random.hpp"
11
12 Move::Move(const size_t range, Humanoid& humanoid, const Humanoid* target)
13     : range(range), Action(humanoid), target(target) {}
14
15 void Move::execute(Field& field) {
16     Position direction;
17     Position newPosition = getHumanoid()->getPosition();
18
19     for (size_t i = 0; i < range; ++i) {
20         if (target) direction = newPosition.getDirection(target->getPosition());
21         else {
22             std::vector<const Position*> directions =
23                 getDirectionsPossible(newPosition, field);
24             if (directions.empty()) return;
25             direction = *directions.at(Random::generateInt(directions.size()));
26         }
27         newPosition.move(direction);
28     }
29     getHumanoid()->setPosition(newPosition);
30 }
31
32 std::vector<const Position*> Move::getDirectionsPossible(const Position& pos
,
33
34 ) const {
35     std::vector<const Position*> directionsPossible;
36     size_t x = pos.getX();
37     size_t y = pos.getY();
38
39     const Position* directions[] = {
40         &Position::UP,
41         &Position::UP_RIGHT,
42         &Position::RIGHT,
43         &Position::DOWN_RIGHT,
44         &Position::DOWN,
45         &Position::DOWN_LEFT,
46         &Position::LEFT,
47         &Position::UP_LEFT
48     };
49
50     for (const Position* direction : directions) {

```

```
50     size_t newX = x + direction->getX();
51     size_t newY = y + direction->getY();
52     size_t width = field.getWidth();
53     size_t height = field.getHeight();
54     if (newX >= 0 && newX < width && newY >= 0 && newY < height)
55         directionsPossible.emplace_back(direction);
56 }
57 return directionsPossible;
58 }
59
```

```
1 /**
2  * @file Move.hpp
3  * @brief Definition of the Move class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef BUFFY_MOVE_HPP
8 #define BUFFY_MOVE_HPP
9
10 #include "Action.hpp"
11 #include <vector>
12 #include "../Utils/Position.hpp"
13
14 class Humanoid;
15
16 /**
17 * @brief Class representing the action of moving a humanoid.
18 */
19 class Move : public Action {
20     size_t range;
21     const Humanoid* target;
22 public:
23     /**
24      * @brief Constructor of the Move class.
25      * @param range The range of the move.
26      * @param humanoid The humanoid that will execute the move.
27      * @param target The target of the move.
28     */
29     explicit Move(const size_t range, Humanoid& humanoid,
30                  const Humanoid* target = nullptr);
31
32     /**
33      * @brief Execute the move of the humanoid on the field.
34      * @param field The field on which the move will be executed.
35     */
36     std::vector<const Position*> getDirectionsPossible(const Position& pos,
37                                                       const Field& field) const;
38
39     void execute(Field& field) override;
40 };
41
42 #endif //BUFFY_MOVE_HPP
43
```

```
1 /**
2  * @file Action.cpp
3  * @brief Declaration of the Action class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include "Action.hpp"
8
9 Action::Action(Humanoid &humanoid) : humanoid(&humanoid) {}
10
11 Humanoid* Action::getHumanoid() const {
12     return humanoid;
13 }
```

```
1 /**
2  * @file Action.hpp
3  * @brief Definition of the Action class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #ifndef LAB4_ACTION_HPP
8 #define LAB4_ACTION_HPP
9
10 class Field;
11 class Humanoid;
12
13 /**
14  * @brief Class representing an action that a humanoid can execute on the
15  * field.
16 */
17 class Action {
18 public:
19     /**
20      * @brief Constructor of the Action class.
21      * @param humanoid The humanoid that will execute the action.
22      */
23     Action(Humanoid &humanoid);
24
25     /**
26      * @brief Destructor of the Action class.
27      */
28     virtual ~Action() = default;
29
30     // Delete copy constructor and assignment operator of the action class
31     Action(const Action&) = delete;
32     Action& operator=(const Action&) = delete;
33
34     /**
35      * @brief Getter for the humanoid of the action.
36      * @return The humanoid of the action.
37      */
38     Humanoid* getHumanoid() const;
39
40     /**
41      * @brief Execute the action of the humanoid on the field.
42      * @param f The field on which the action will be executed.
43      */
44     virtual void execute(Field& f) = 0;
45 };
46
47
48 #endif //LAB4_ACTION_HPP
49
50
51
```

```
1 /**
2  * @file Transform.cpp
3  * @brief Declaration of the Transform class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include "Transform.hpp"
8 #include "../Person/Vampire.hpp"
9
10 Transform::Transform(Humanoid& humanoid) : Action(humanoid) {}
11
12 void Transform::execute(Field& f) {
13     if (getHumanoid()->isAlive()) {
14         getHumanoid()->die(f);
15         f.addHumanoid(new Vampire(getHumanoid()->getPosition()));
16         f.vampireBorn();
17     }
18 }
```

```
1 /**
2  * @file Transform.hpp
3  * @brief Definition of the Transform class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef BUFFY_TRANSFORM_HPP
8 #define BUFFY_TRANSFORM_HPP
9
10 #include "Action.hpp"
11
12 /**
13  * @brief Class representing the transformation of a human into a vampire.
14  */
15 class Transform : public Action {
16 public:
17     /**
18      * @brief Constructor of the Transform class.
19      * @param humanoid Humanoid to transform.
20      */
21     explicit Transform(Humanoid& humanoid);
22
23     void execute(Field& f) override;
24 };
25
26 #endif //BUFFY_TRANSFORM_HPP
27
```

```
1 /**
2  * @file Buffy.cpp
3  * @brief Declaration of the Buffy class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include <iostream>
8 #include "Buffy.hpp"
9 #include "Human.hpp"
10
11 Buffy::Buffy(const Position& position) : Humanoid(position) {}
12
13 Action* Buffy::getNextAction(const Field& field) {
14     if(field.getNbVampire() == 0) return new Move(Human::getMoveRange(),
15                                                 *this);
16
17     Humanoid* target = field.findClosest<Vampire>(*this);
18     if(target->getPosition().distance(this->getPosition()) <= KILL_RANGE)
19         return new Kill(*target);
20     return new Move(MOVE_RANGE, *this, target);
21 }
22
23 char Buffy::display() const {
24     return 'B';
25 }
26
```

```
1 /**
2  * @file Buffy.hpp
3  * @brief Definition of the Buffy class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef LAB4_BUFFY_HPP
8 #define LAB4_BUFFY_HPP
9
10 #include "Humanoid.hpp"
11 #include "Vampire.hpp"
12 #include "../Action/Kill.hpp"
13 #include "../Action/Move.hpp"
14
15 /**
16  * @brief Class representing a Buffy.
17  * @details A Buffy is a humanoid that can kill vampires.
18  */
19 class Buffy : public Humanoid {
20     static constexpr size_t KILL_RANGE = 1;
21     static constexpr size_t MOVE_RANGE = 2;
22
23 public:
24     /**
25      * @brief Constructor of the Buffy class.
26      * @param position The position of the Buffy.
27      */
28     Buffy(const Position& position);
29
30     char display() const override;
31
32     Action* getNextAction(const Field& field) override;
33 };
34
35 #endif //LAB4_BUFFY_HPP
36
```

```
1 /**
2  * @file Human.cpp
3  * @brief Declaration of the Human class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include <iostream>
8 #include "Human.hpp"
9 #include "../Action/Move.hpp"
10 #include "../Field/Field.hpp"
11
12 Human::Human(const Position& position)
13     : Humanoid(position) {}
14
15 Action* Human::getNextAction(const Field& field) {
16     return new Move(MOVE_RANGE, *this);
17 }
18
19 char Human::display() const {
20     return 'h';
21 }
22
23 size_t Human::getMoveRange() {
24     return MOVE_RANGE;
25 }
26
27 void Human::die(Field& field) {
28     Humanoid::die(field);
29     field.humanDie();
30 }
31
```

```
1 /**
2  * @file Human.hpp
3  * @brief Definition of the Human class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef LAB4_HUMAIN_HPP
8 #define LAB4_HUMAIN_HPP
9
10 #include "Humanoid.hpp"
11
12 /**
13  * @brief Class representing a human.
14  * @details A human can only move
15  */
16 class Human : public Humanoid {
17     static constexpr size_t MOVE_RANGE = 1;
18 public:
19     /**
20      * @brief Constructor of the Human class.
21      * @param position The position of the human.
22      */
23     Human(const Position& position);
24
25     /**
26      * @brief Get the move range of the human.
27      * @return The move range of the human.
28      */
29     static size_t getMoveRange();
30
31     Action* getNextAction(const Field& field) override;
32
33     char display() const override;
34
35     void die(Field& field) override;
36 };
37
38 #endif //LAB4_HUMAIN_HPP
39
```

```
1 /**
2  * @file Vampire.cpp
3  * @brief Declaration of the Vampire class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #include "Vampire.hpp"
8 #include "../Utils/Random.hpp"
9 #include "../Action/Transform.hpp"
10
11 Vampire::Vampire(const Position& position) : Humanoid(position) {}
12
13 Action* Vampire::getNextAction(Field& field) {
14     if(field.getNbHuman() == 0) return nullptr;
15
16     Human* target = field.findClosest<Human>(*this);
17
18     if(target->getPosition().distance(this->getPosition()) <= KILL_RANGE) {
19         if(Random::generateBool()) return new Kill(*target);
20         else return new Transform(*target);
21     }
22     return new Move(MOVE_RANGE, *this, target);
23 }
24
25 char Vampire::display() const {
26     return 'V';
27 }
28
29 void Vampire::die(Field& field) {
30     Humanoid::die(field);
31     field.vampireDie();
32 }
33
```

```
1 /**
2  * @file Vampire.hpp
3  * @brief Definition of the Vampire class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef LAB4_VAMPIRE_HPP
8 #define LAB4_VAMPIRE_HPP
9
10 #include "Humanoid.hpp"
11 #include "../Field/Field.hpp"
12
13 /**
14  * @brief Class representing a vampire on the field.
15  * @details A vampire can kill or transform a human if he is close enough,
16  * otherwise he will move towards the closest human.
17 */
18 class Vampire : public Humanoid {
19     static constexpr size_t KILL_RANGE = 1;
20     static constexpr size_t MOVE_RANGE = 1;
21 public:
22     /**
23      * @brief Constructor of the Vampire class.
24      * @param position The position of the vampire.
25      */
26     Vampire(const Position& position);
27
28     Action* getNextAction(const Field& field) override;
29
30     char display() const override;
31
32     void die(Field& field) override;
33 };
34
35 #endif //LAB4_VAMPIRE_HPP
36
```

```
1 /**
2  * @file Humanoid.cpp
3  * @brief Declaration of the Humanoid class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include "Humanoid.hpp"
8
9 Humanoid::Humanoid(const Position& position) : position(position), alive(
10    true),
11 action(nullptr) {}
12 Humanoid::~Humanoid() {
13     delete action;
14 }
15
16 const Position& Humanoid::getPosition() const {
17     return position;
18 }
19
20 void Humanoid::setPosition(Position pos) {
21     this->position = pos;
22 }
23
24 bool Humanoid::isAlive() const {
25     return alive;
26 }
27
28 void Humanoid::die(Field& field) {
29     if(action != nullptr) {
30         delete action;
31         action = nullptr;
32     }
33     alive = false;
34 }
35
36 void Humanoid::setAction(Field& field) {
37     this->action = getNextAction(field);
38 }
39
40 void Humanoid::executeAction(Field& field) {
41     if (action != nullptr) {
42         action->execute(field);
43         delete action;
44         action = nullptr;
45     }
46 }
```

```

1 /**
2  * @file Humanoid.hpp
3  * @brief Definition of the Humanoid class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #ifndef LAB4_HUMANOIDE_HPP
8 #define LAB4_HUMANOIDE_HPP
9
10 #include "../Utils/Position.hpp"
11 #include "../Action/Action.hpp"
12
13 class Field;
14
15 /**
16  * @brief Class representing a humanoid on the field.
17 */
18 class Humanoid {
19     Position position;
20     bool alive;
21     Action* action;
22
23     public:
24     /**
25      * @brief Constructor of the Humanoid class.
26      * @param pos The position of the humanoid.
27     */
28     explicit Humanoid(const Position& pos);
29
30     // Delete copy constructor and assignment operator of the humanoid class
31     Humanoid(const Humanoid&) = delete;
32     Humanoid& operator=(const Humanoid&) = delete;
33
34     /**
35      * @brief Destructor of the Humanoid class.
36     */
37     virtual ~Humanoid();
38
39     /**
40      * @brief Getter for the position of the humanoid.
41      * @return The position of the humanoid.
42     */
43     const Position& getPosition() const;
44
45     /**
46      * @brief Setter for the position of the humanoid.
47      * @param pos The new position of the humanoid.
48     */
49     void setPosition(Position pos);
50
51     /**
52      * @brief Check if the humanoid is alive.

```

```
53     * @return True if the humanoid is alive, false otherwise.
54     */
55     bool isAlive() const;
56
57     /**
58      * @brief Kill the humanoid.
59      * @param field The field on which the humanoid is.
60      */
61     virtual void die(Field& field);
62
63     /**
64      * @brief Set the action of the humanoid.
65      * @param field The field on which the humanoid is.
66      */
67     void setAction(Field& field);
68
69     /**
70      * @brief Execute the action of the humanoid on the field.
71      * @param field The field on which the action will be executed.
72      */
73     void executeAction(Field& field);
74
75     /**
76      * @brief Get the next action of the humanoid.
77      * @param field The field on which the humanoid is.
78      * @return The next action of the humanoid.
79      */
80     virtual Action* getNextAction(const Field& field) = 0;
81
82     /**
83      * @brief Display the humanoid on the field.
84      * @return The character representing the humanoid on the field.
85      */
86     virtual char display() const = 0;
87 };
88
89 #endif //LAB4_HUMANOIDE_HPP
90
```

```

1 /**
2  * @file Display.cpp
3  * @brief Declaration of the Display class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include <iostream>
8 #include <iomanip>
9 #include "Display.hpp"
10 #include "../Controller/Controller.hpp"
11
12 Display::Display(const Field& field) : field(field), gameBoard(field.
13                                         getHeight(),
14                                         std::vector<const Humanoid*>(field.getWidth(), nullptr))
15 {}
16
17 void Display::print() {
18     const Humanoid** toDisplay = nullptr;
19     for(Humanoid* h : field.getHumanoids()) {
20         gameBoard.at(h->getPosition().getY())
21             .at(h->getPosition().getX()) = h;
22     }
23     printHorizontalBorder(field);
24
25     for(size_t y = 0; y < field.getHeight(); y++) {
26         std::cout << VERTICAL_BORDER;
27         for(size_t x = 0; x < field.getWidth(); x++) {
28             toDisplay = &gameBoard.at(y).at(x);
29             if(*toDisplay) std::cout << (*(*toDisplay)).display();
30             else std::cout << EMPTY;
31         }
32         std::cout << VERTICAL_BORDER << std::endl;
33     }
34     printHorizontalBorder(field);
35     clearGameBoard();
36 }
37
38 void Display::clear() const {
39 #ifdef _WIN32
40     system("cls");
41 #elif __unix__
42     system("clear");
43 #endif
44 }
45
46 void Display::clearGameBoard() {
47     for(auto& line : gameBoard) {
48         for(auto& cell : line) cell = nullptr;
49     }
50 }
51

```

```
52 void Display::printHorizontalBorder(const Field& field) const {
53     std::cout << CORNER << std::setfill(HORIZONTAL_BORDER)
54             << std::setw((size_t)field.getWidth() + 1) << CORNER << std::endl;
55 }
56
57 void Display::printPrompt() const {
58     std::cout << "[" << field.getTurn() << "] "
59             << Controller::QUIT << ">uit "
60             << Controller::STATISTICS << ">tatistics "
61             << Controller::NEXT << ">ext: ";
62 }
```

```
1 /**
2  * @file Display.hpp
3  * @brief Definition of the Display class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5  */
6
7 #ifndef BUFFY_DISPLAY_HPP
8 #define BUFFY_DISPLAY_HPP
9
10 #include "../Field/Field.hpp"
11 #include <vector>
12
13 /**
14  * @brief Class representing the display of the game.
15  */
16 class Display {
17     std::vector<std::vector<const Humanoid*>> gameBoard;
18     const Field& field;
19     static constexpr char CORNER = '+',
20                         HORIZONTAL_BORDER = '-',
21                         VERTICAL_BORDER = '|',
22                         EMPTY = ' ';
23
24     /**
25      * @brief Print the horizontal border of the game board.
26      * @param field The field to print the border of.
27      */
28     void printHorizontalBorder(const Field& field) const;
29 public:
30     /**
31      * @brief Constructor of the Display class.
32      * @param field The field to display.
33      */
34     Display(const Field& field);
35
36     /**
37      * @brief Print the game board.
38      */
39     void print();
40
41     /**
42      * @brief Print the prompt with commands available.
43      */
44     void printPrompt() const;
45
46     /*
47     /**
48      * @brief Clear the console.
49      */
50     /*
51     void clear() const;
52     */
```

```
53
54     /**
55      * @brief Clear the vector representing the game board
56      */
57     void clearGameBoard();
58 };
59
60 #endif //BUFFY_DISPLAY_HPP
61
```

```
1 /**
2  * @file Controller.cpp
3  * @brief Declaration of the Controller class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #include <iostream>
8 #include "Controller.hpp"
9 #include "../Statistics/statisticsCalculator.hpp"
10
11 Controller::Controller(const size_t width, const size_t height, size_t
12 nbHumans,
13                         size_t nbVampires) : field(width, height, nbHumans,
14 nbVampires), display(field), finished(false)
15 {}
16
17 void Controller::run() {
18     display.print();
19     display.printPrompt();
20     while(!finished) handleCommand();
21 }
22
23 void Controller::handleCommand() {
24     char command;
25     std::cin >> command;
26     switch(command) {
27         case Controller::QUIT:
28             quit();
29             break;
30         case Controller::STATISTICS:
31             statistics();
32             break;
33         case Controller::NEXT:
34             nextTurn();
35             break;
36         default:
37             std::cout << "Invalid command" << std::endl;
38             break;
39     }
40     if(!finished) display.printPrompt();
41 }
42
43 void Controller::nextTurn() {
44     field.nextTurn();
45     display.print();
46     //display.clear();
47 }
48
49 void Controller::quit() {
50     finished = true;
51 }
```

```
52 void Controller::statistics() {
53     std::cout << NB_SIMULATIONS << " simulations in progress..." << std::endl;
54     double res = statisticsCalculator::simulate(field.getWidth(),
55                                                 field.getHeight(), field.getNbHuman(),
56                                                 field.getNbVampire(), NB_SIMULATIONS);
57     std::cout << "Buffy's win rate: " << res << "%" << std::endl;
58 }
59
```

```
1 /**
2  * @file Controller.hpp
3  * @brief Definition of the Controller class and related operators.
4  * @authors Demont Kilian & Graf Calvin
5 */
6
7 #ifndef BUFFY_CONTROLLER_HPP
8 #define BUFFY_CONTROLLER_HPP
9
10 #include "../Field/Field.hpp"
11 #include "../Displayer/Display.hpp"
12
13 /**
14  * @brief Class representing the controller of the game.
15 */
16 class Controller {
17     Field field;
18     Display display;
19
20     bool finished;
21     static constexpr size_t NB_SIMULATIONS = 10000;
22
23 /**
24  * @brief Quit the game.
25 */
26 void quit();
27
28 /**
29  * @brief Display Buffy's average win rate with current field status
30 */
31 void statistics();
32
33 /**
34  * @brief Handle the command entered by the user.
35 */
36 void handleCommand();
37
38 /**
39  * @brief Execute the next turn of the game.
40 */
41 void nextTurn();
42
43 public:
44 /**
45  * @brief Constants representing the commands that can be entered by the
46  * user.
47 */
48 static constexpr char QUIT = 'q',
49     STATISTICS = 's',
50     NEXT = 'n';
51 /**
52 */
```

```
52     * @brief Constructor of the Controller class.  
53     * @param width The width of the field.  
54     * @param height The height of the field.  
55     * @param nbHumans The number of humans in the field.  
56     * @param nbVampires The number of vampires in the field.  
57     */  
58     Controller(const size_t width, const size_t height, size_t nbHumans,  
59     size_t  
60     nbVampires);  
61     /**  
62     * @brief Run the game.  
63     */  
64     void run();  
65 };  
66  
67 #endif //BUFFY_CONTROLLER_HPP  
68
```

```
1 /**
2  * @file statisticsCalculator.cpp
3  * @brief Declaration of the statisticsCalculator class and related
4  * operators.
5  * @authors Demont Kilian & Graf Calvin
6  */
7 #include "statisticsCalculator.hpp"
8
9 double statisticsCalculator::simulate(size_t width, size_t height, size_t
10                                         nbHuman,
11                                         size_t nbVampire, size_t nbSimulations
12 ) {
13     if(nbSimulations == 0 || nbHuman == 0) return 0;
14     if(nbVampire == 0) return 100;
15
16     size_t success = 0;
17     for (size_t i = 0; i < nbSimulations; ++i) {
18         Field simulatingField(width, height, nbHuman, nbVampire);
19         while (simulatingField.getNbVampire() > 0) simulatingField.nextTurn();
20         if (simulatingField.getNbHuman() > 0) success++;
21     }
22     return static_cast<double>(success) / static_cast<double>(nbSimulations
23 ) * 100;
24 }
```

```
1 /**
2  * @file statisticsCalculator.hpp
3  * @brief Definition of the statisticsCalculator class and related operators
4  *
5  * @authors Demont Kilian & Graf Calvin
6  */
7 #ifndef BUFFY_STATISTICSCALCULATOR_HPP
8 #define BUFFY_STATISTICSCALCULATOR_HPP
9
10 #include "../Field/Field.hpp"
11
12 /**
13  * @brief Struct representing a statistics calculator.
14  */
15 struct statisticsCalculator {
16
17     /**
18      * @brief Simulate the game with the given parameters.
19      * @param width The width of the field.
20      * @param height The height of the field.
21      * @param nbHuman The number of humans on the field.
22      * @param nbVampire The number of vampires on the field.
23      * @param nbSimulations The number of simulations to run.
24      * @return Buffy's average win rate percentage in simulations.
25     */
26     static double simulate(size_t width, size_t height, size_t nbHuman,
27                           size_t nbVampire, size_t nbSimulations);
28 };
29
30 #endif //BUFFY_STATISTICSCALCULATOR_HPP
31
```