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1 % falsepos_falling_mass
  4 This program uses the false position root finding method to
 5 solve for the mass of a falling object with air resistance. 6 \$\}
 8 % Author: Calvin Sprouse
9 % Date: 2024 February 05
11 % Version 2: Adapted to use false position method
13 % workspace init
14 clear;
15 close all;
16
17 % define constants
18 % acceleration of gravity [m/s^2]
19 g = 9.8;
20 % drag coefficient [kg/m]
21 cd = 0.25;
22 % velocity at t=4s [m/s]
23 v = 36;
24 % time [s]
25 t = 4;
26
27 % define the drag function 28 func = @(x) sqrt(g.*x./cd) .* tanh( sqrt(g.*cd./x) .* t ) - v;
30 % plot the function to make sure there is a root 31 % plt = fplot(func, [0 500], "-k"); 32 % plt.Parent.FontWeight = "normal"; 33 % plt.Parent.FontName = "Times New Roman";
33 % plt.Parent.FontName = "Times New Roman";
34 % plt.Parent.FontSize = 16;
35 % ylim([-10, 10]);
36 % yline(0, "--k");
37 % xlabel("Mass [kg]");
38 % ylabel("Drag Force [N]");
39 % title("Drag force for an object with known velocity", FontWeight="normal");
40 % exportgraphics(gcf, "root_plot.pdf");
42 % define the questioning strings
43 xl_query = 'Enter the lower bound for mass in kg? ';
44 xu_query = 'Enter the upper bound for mass in kg? ';
46 % ask the user for the initial guess
47 xl = input(xl_query);
48 xu = input(xu_query);
50 % evaluate at the initial guesses to make sure they surround the root 51 while func(xl)*func(xu) > 0
           disp('Supplied bounds do not surround the root.')
53
54
          xl = input(xl_query);
xu = input(xu_query);
55 end
56
57 % define initial values for while loop
58 approxerr = 1;
59 count = 0;
60 oldxr = 0;
61
62 % define stop conditions
63 err_thresh = 1e-6;
64 iter_max = 1e3;
65
66 % iterate with bisection method until error is less than 0.05 percent
67 while (approxerr > err_thresh) && (count < iter_max) 68 % calculate xr based on straight line slope
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          xr = (func(xl)*xu - func(xu)*xl) / (func(xl) - func(xu));
           % figure out what side of the midpoint the root is on
           if func(xr)*func(xu) < 0
                % replace the lower bound with the midpoint
                xl = xr;
           else
                % replace the upper bound with the midpoint
                xu = xr;
          % calculate the approximate error approxerr = abs((xr - oldxr) / xr);
          % store old guess for root
          oldxr = xr;
          % increase count value
87
          count = count + 1;
88 end
90 % output the results
91 out_str = 'The root is %5.2f kg. It was found after %i iterations. The approximate error is %6.4f%%.\n';
92 fprintf(out_str, xr, count, approxerr*100);
93
94 % use built in fuction (fzero) to find the root
95 fprintf('The root found with fzero is %5.2f. \n', fzero(func, xl));
```