**DIY**

1. Attach 4 wheel motors to bottom base board.
2. Attach wheels to the motors.
3. Attach leds to bottom and plug into Arduino I2C port.
4. Connect Arduino to the Control Board Extender.
5. Feed wires through top baseboard and connect to Arduino M1, M2, M3, M4 Ports.
6. Attach battery pack to back.
7. Attach servo to front and plug in ultrasonic detector.
8. Wire servo into servo port on Arduino
9. Attach additional Arduino to back.
10. Attach breadboard on top of battery pack.
11. Wire LCD Screen to Arduino ports.