

# Operating System Principles

## 操作系统原理

### Memory Management

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# Objectives

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- No Memory Abstraction
- Basic Memory Management
- ~~*Virtual Memory Management*~~



## Parkinson's law

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Programs expand to  
fill the memory  
available to hold  
them!



# Memory Management

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- Memory is an important resource that must be carefully managed

While the average home computer nowadays has a thousand times as much memory as the IBM 7094, the largest computer in the world in the early 1960's

- Memory hierarchy

- *Volatile* cache memory

a small amount, very fast, expensive

- Volatile main memory(RAM)

tens of megabytes, medium-speed, medium-price

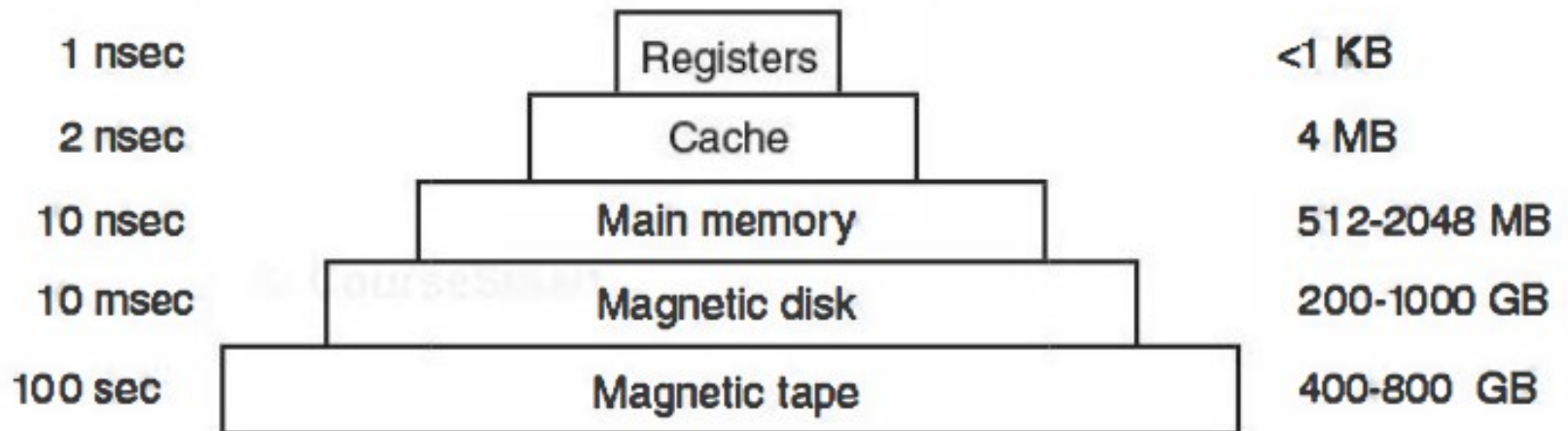
- Nonvolatile disk storage

tens or hundreds of gigabytes, slow, cheap

# Memory Hierarchy

Typical access time

Typical capacity





# Memory Management

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- extend main memory
- control data transmission between main memory and storage
- main memory allocation and revoke
- main memory share and protection



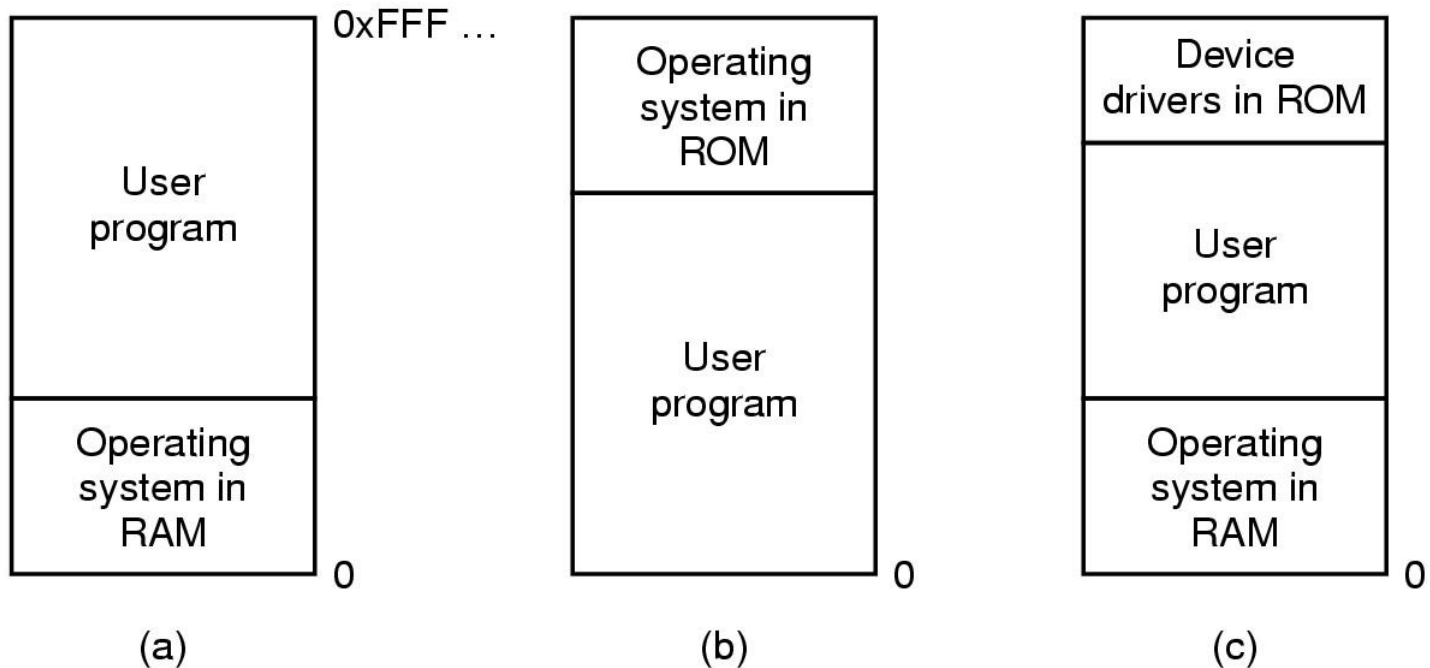
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# No Memory Abstraction

# No Memory Abstraction

- early mainframe computers (<1960)
- early minicomputers (<1970)
- early personal computers (<1980)

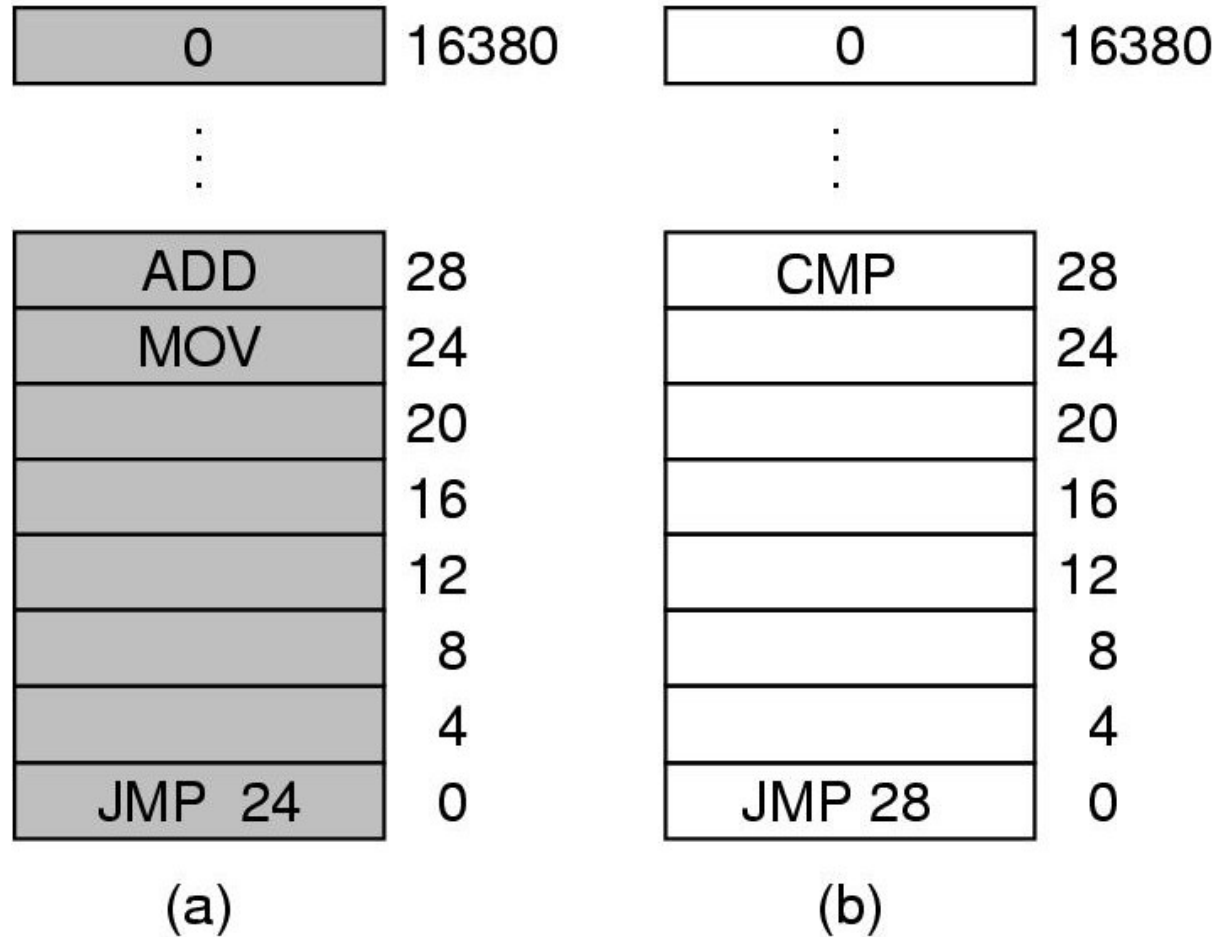
RAM(Random Access Memory), ROM(Read-Only Memory)



Three simple ways of organizing memory with an operating system and one user process.

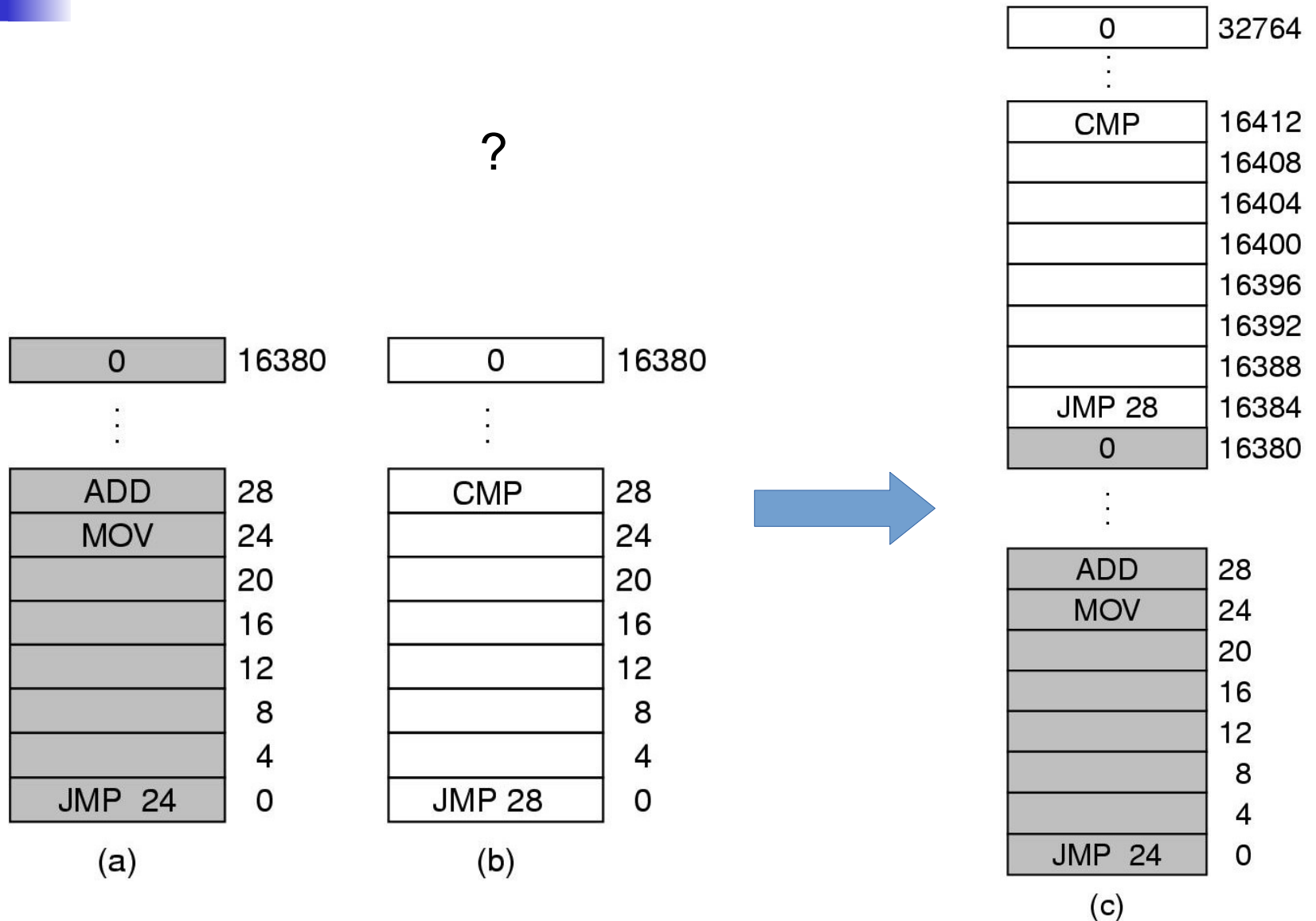


# Issues of No Memory Abstraction



Two Processes

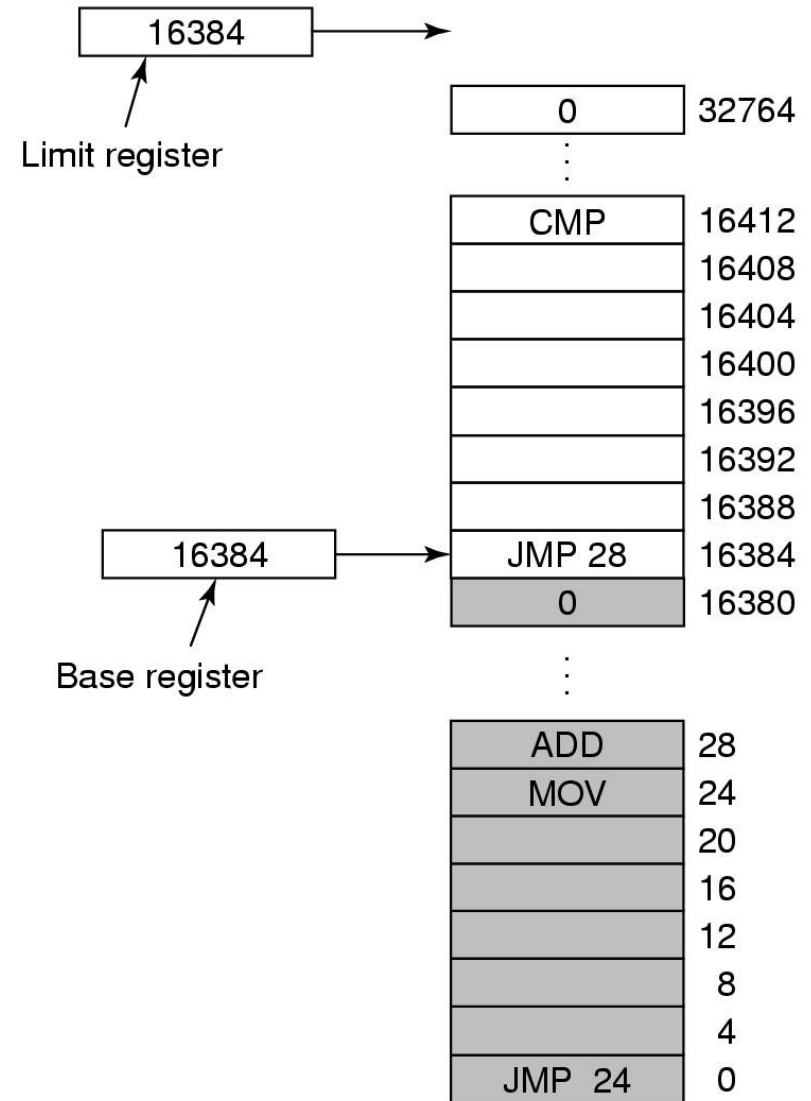
# Issues of No Memory Abstraction



# Issues of No Memory Abstraction

1. separate address space

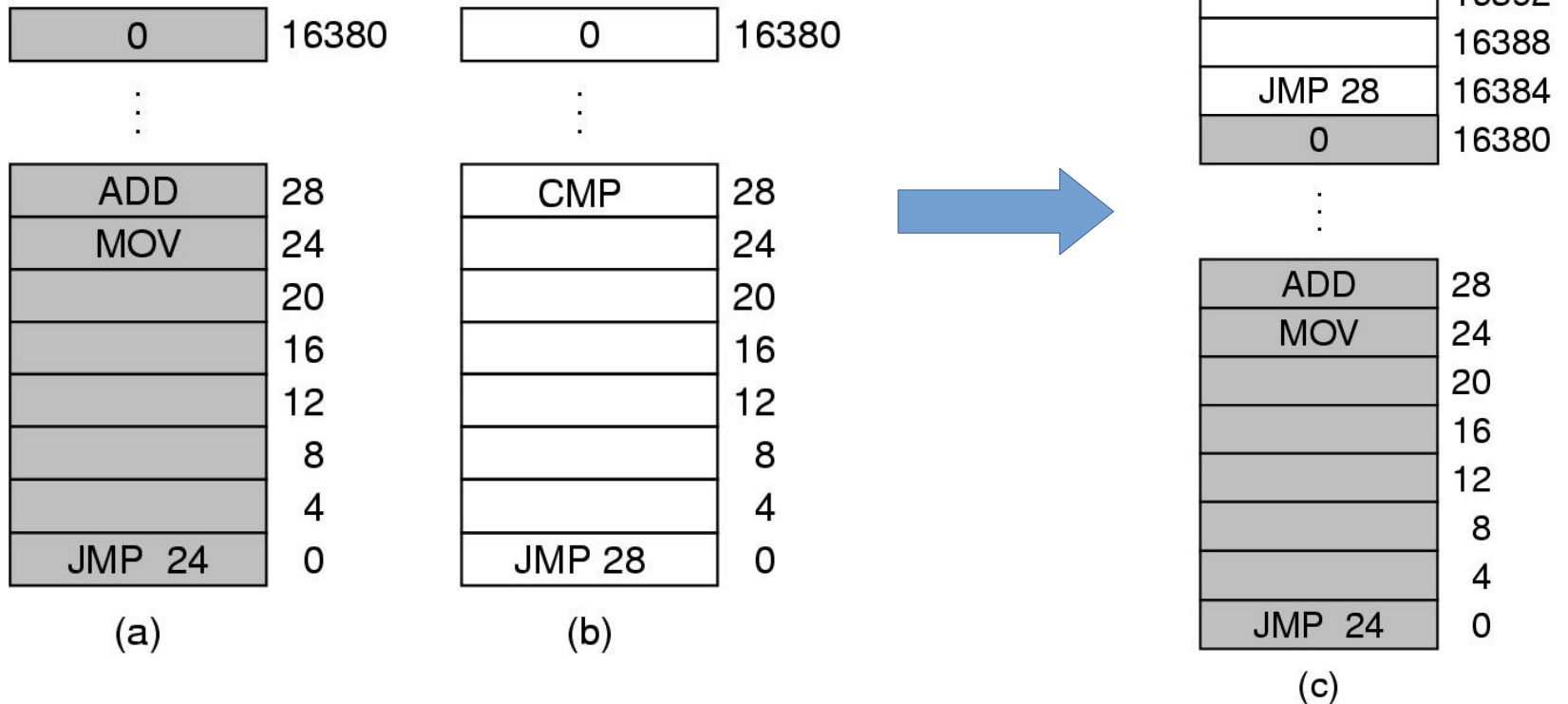
Base register  
Limit register



(c)

# Issues of No Memory Abstraction

## 2. the relocation problem





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# Basic Memory Management

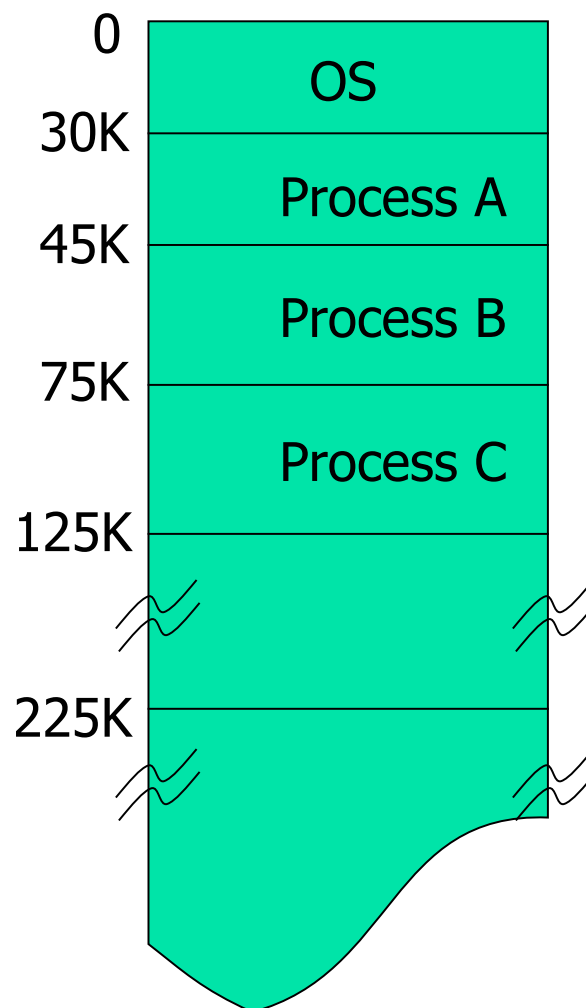
- contiguous allocation

# Multiprogramming with Fixed Partitions

- Partition
  - Fixed, size

ID	Size (KB)	Start Addr (K)	State
1	15	30	used
2	30	45	used
3	50	75	used
4	100	125	available

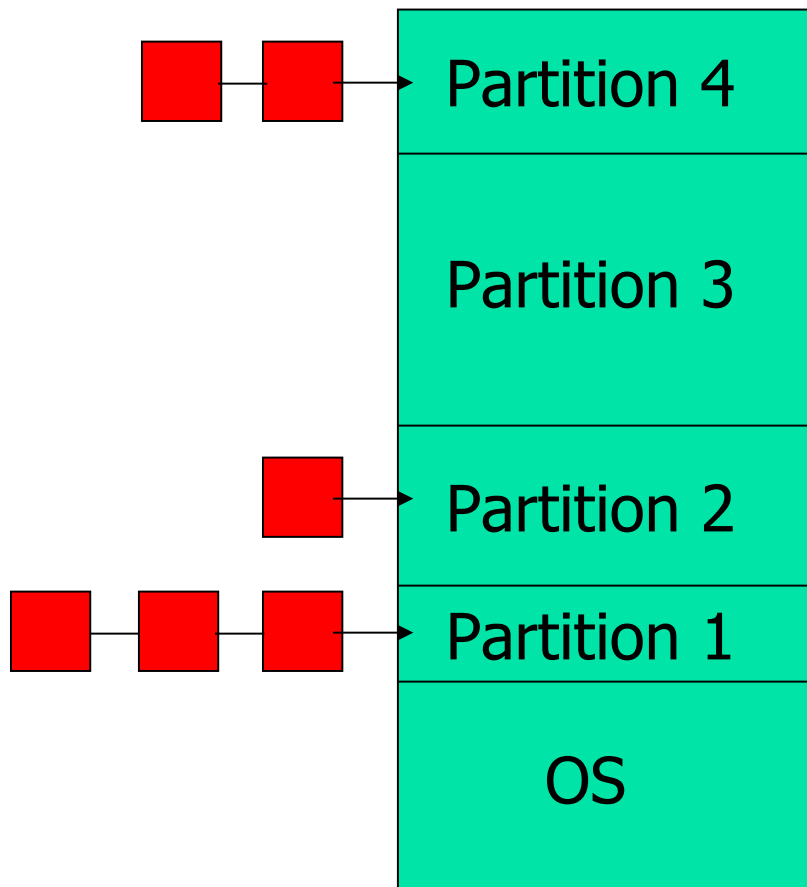
(a) partition desc table



(b) memory layout

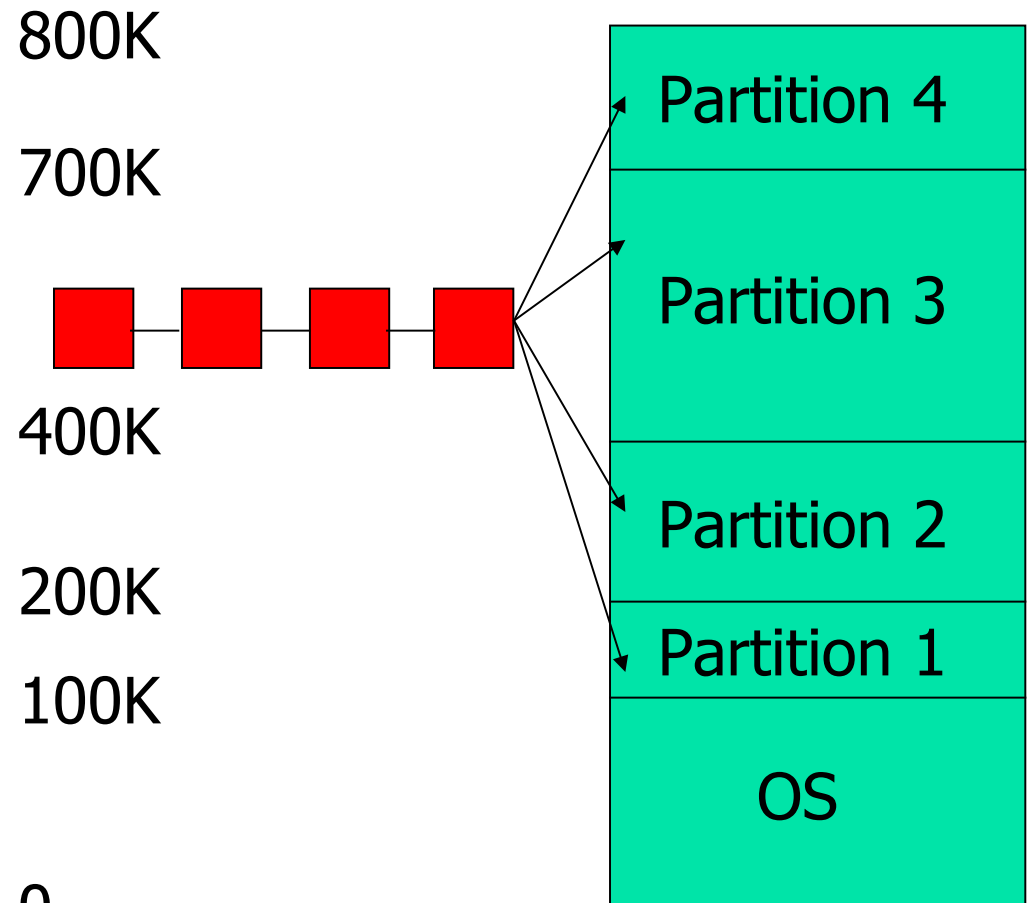
# Multiprogramming with Fixed Partitions

Multiple input queues



(a)

Single input queue

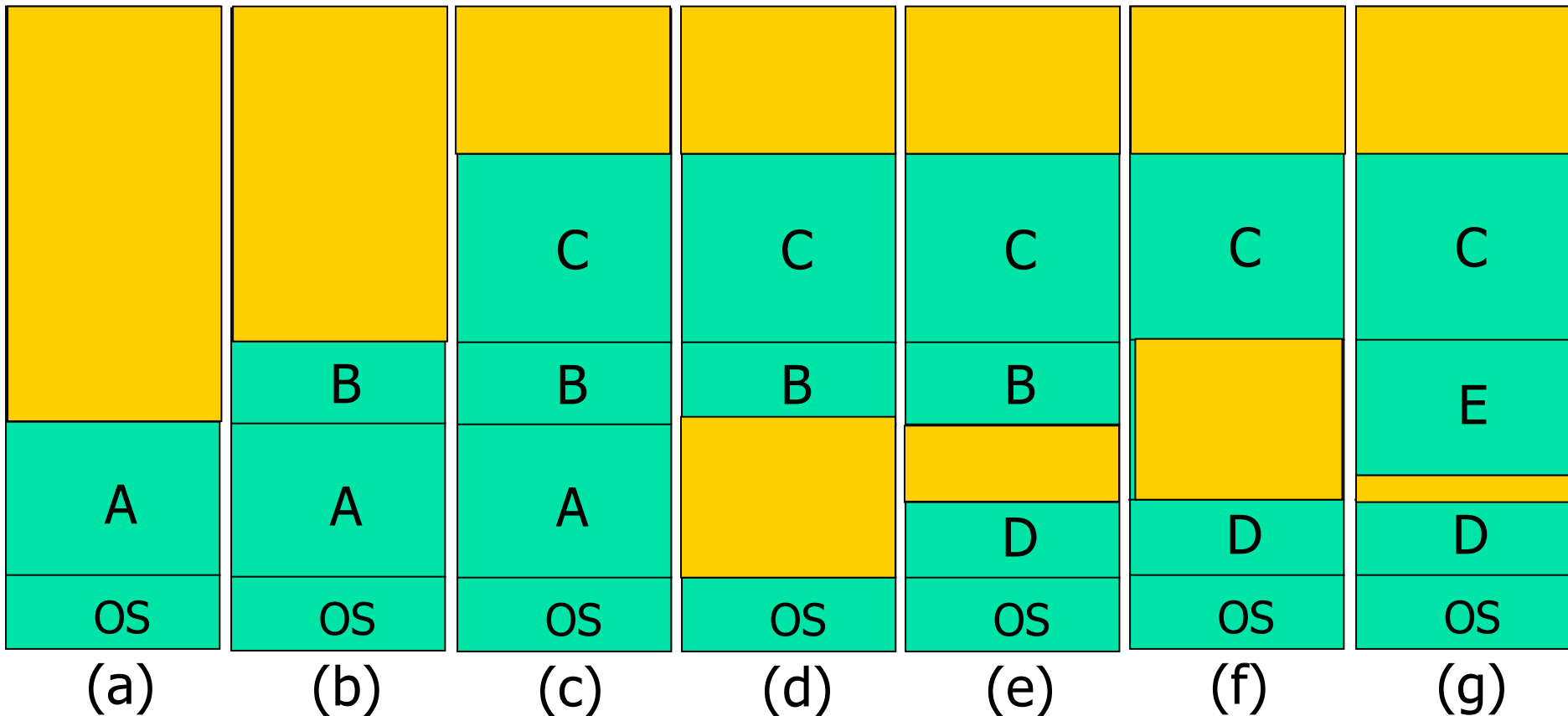


(b)



# Multiprogramming with Variable Partitions

- Allocate a contiguous partition dynamically







# Multiprogramming with Variable Partitions

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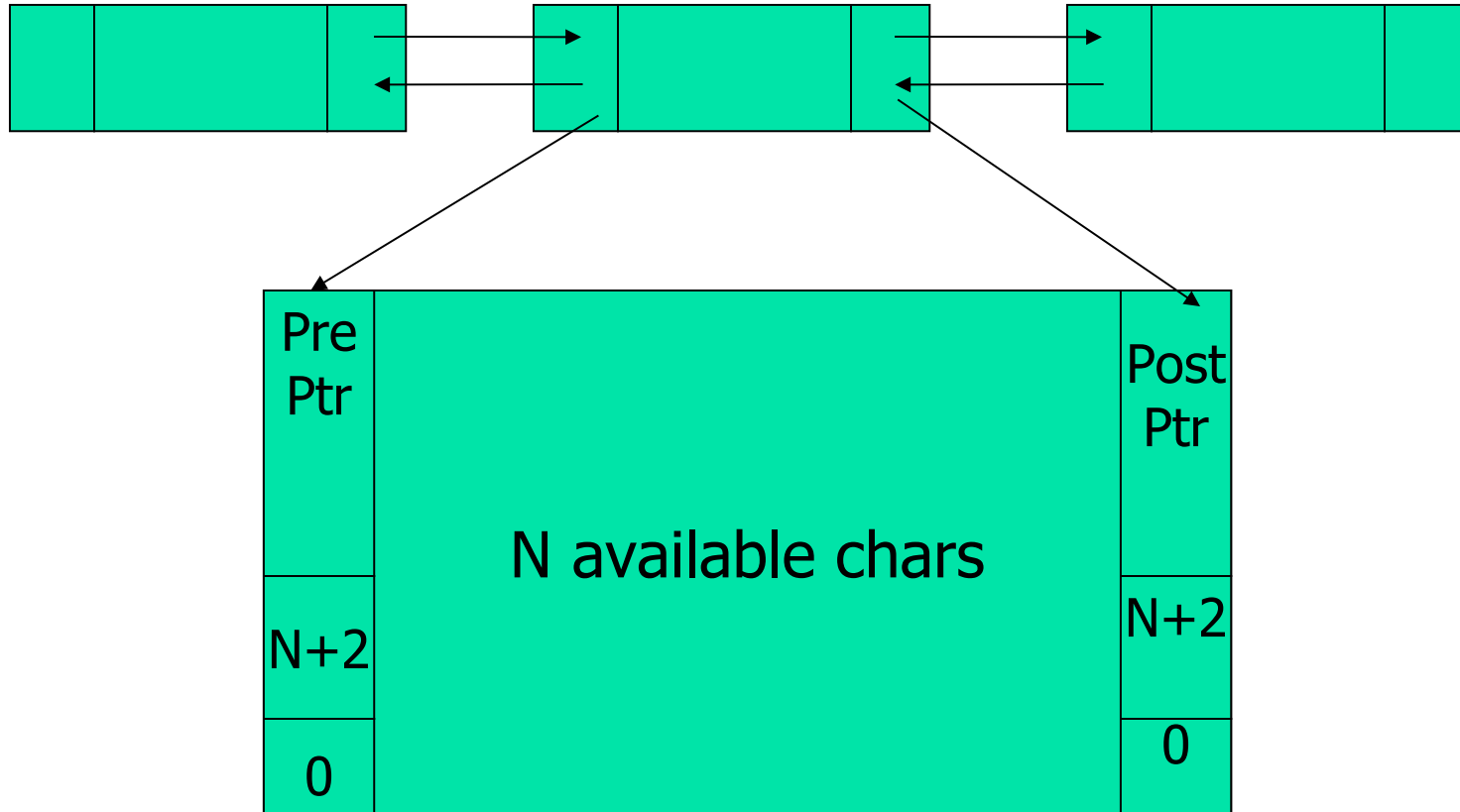
- Structure
- Algorithm
- Allocating and Revoking Procedures



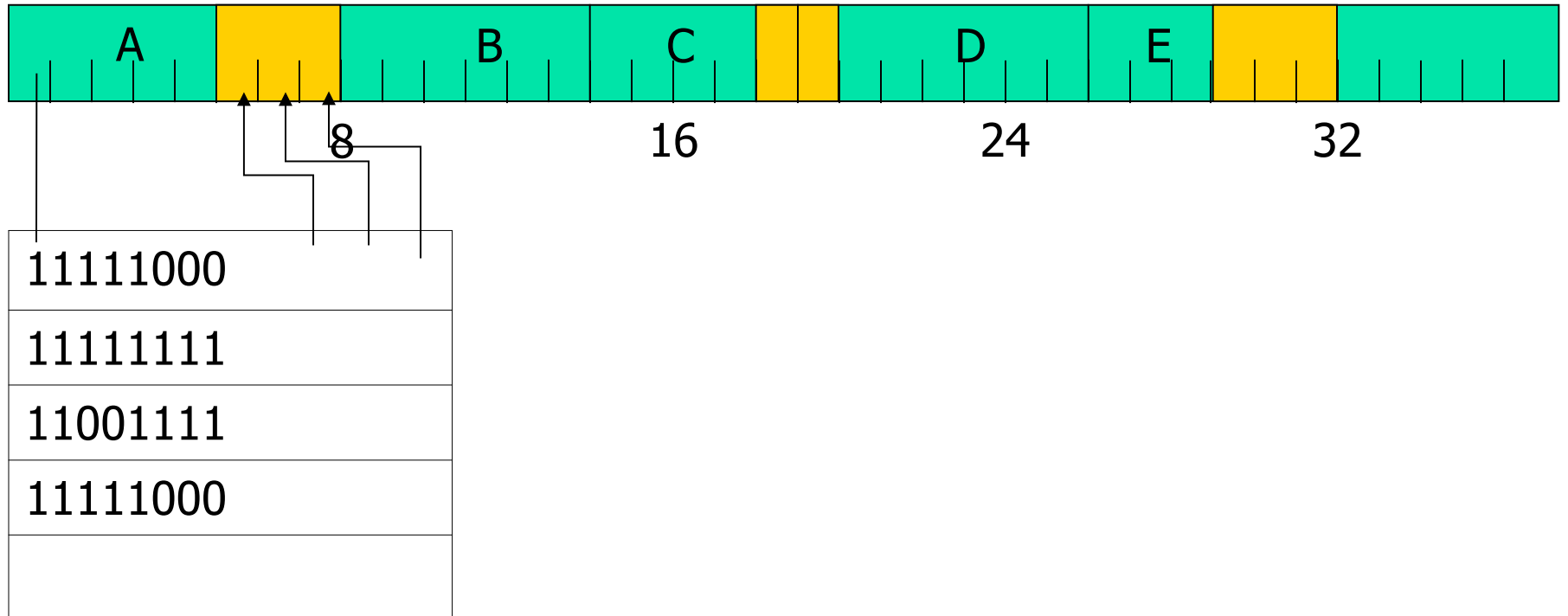
# Variable Partitions: Partition Array Table

ID	Size (KB)	Start Addr (K)	state
1	64	44	available
2	24	132	available
3	40	210	used
4	30	270	available
5	...	...	...

# Variable Partitions: Inline Linked Structure



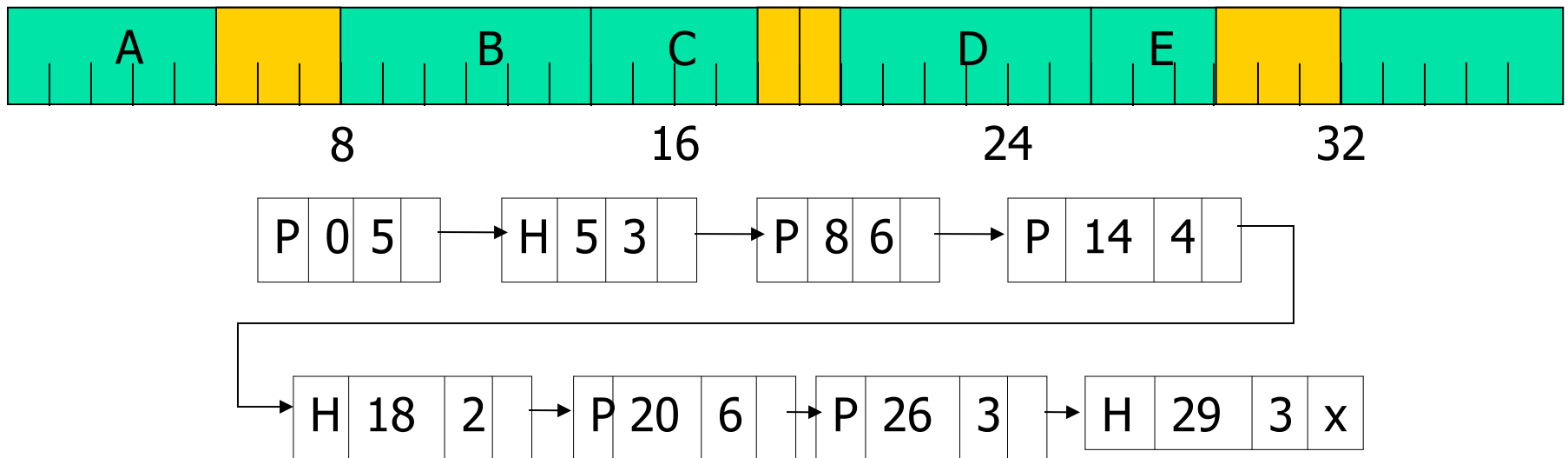
# Variable Partitions: Bitmap 位图



# Variable Partitions: Linked List

P: Process

H: Free space





# Algorithms of Variable Partitions

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- First Fit: FF
- Next FF
- Best Fit: FF
  - 最佳适应算法
  - external fragmentation
    - 碎片
- Worst Fit:WF



# Algorithms of Variable Partitions

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- Quick Fit

- Multi-queues for 4KB, 8KB, 16KB free contiguous space
- Advantages
- Disadvantage
  - Overhead of merging free partitions



# Algorithms of Variable Partitions

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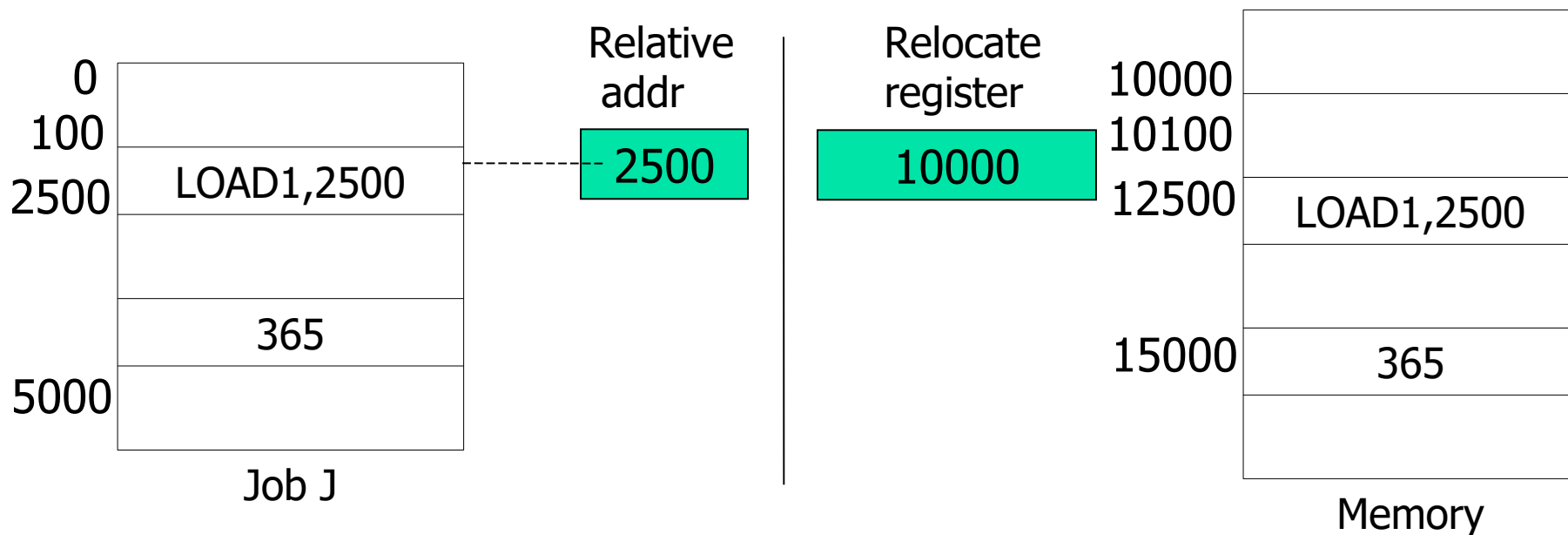
- Buddy memory allocation
  - 伙伴式的内存管理
  - 1963, Harry Markowitz, who won the 1990 Nobel Memorial Prize in Economics
  - each block is subdivided into two smaller blocks
  - $2^i$
  - internal fragmentation





Step	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K	64K
1	2 <sup>4</sup>															
2.1	2 <sup>3</sup>								2 <sup>3</sup>							
2.2	2 <sup>2</sup>				2 <sup>2</sup>				2 <sup>3</sup>							
2.3	2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
2.4	2 <sup>0</sup>	2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
2.5	A: 2 <sup>0</sup>	2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
3	A: 2 <sup>0</sup>	2 <sup>0</sup>	B: 2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
4	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	B: 2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
5.1	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	B: 2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>3</sup>							
5.2	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	B: 2 <sup>1</sup>		D: 2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>3</sup>							
6	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	2 <sup>1</sup>		D: 2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>3</sup>							
7.1	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>3</sup>							
7.2	A: 2 <sup>0</sup>	C: 2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
8	2 <sup>0</sup>	C: 2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
9.1	2 <sup>0</sup>	2 <sup>0</sup>	2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
9.2	2 <sup>1</sup>		2 <sup>1</sup>		2 <sup>2</sup>				2 <sup>3</sup>							
9.3	2 <sup>2</sup>				2 <sup>2</sup>				2 <sup>3</sup>							
9.4	2 <sup>3</sup>								2 <sup>3</sup>							
9.5	2 <sup>4</sup>															

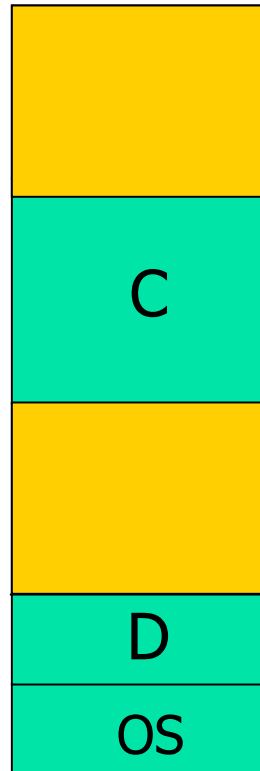
# Dynamical Relocation



# Memory Compaction

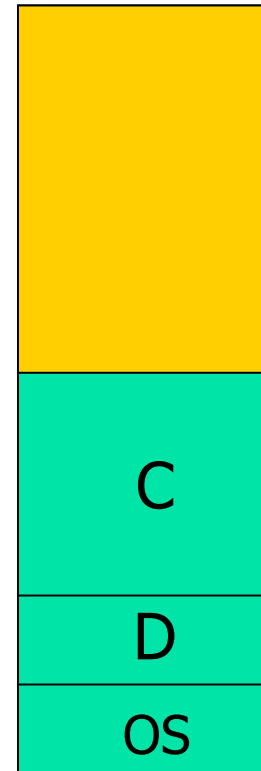
■ 紧凑

?fragmentation



(f)

Before comp.

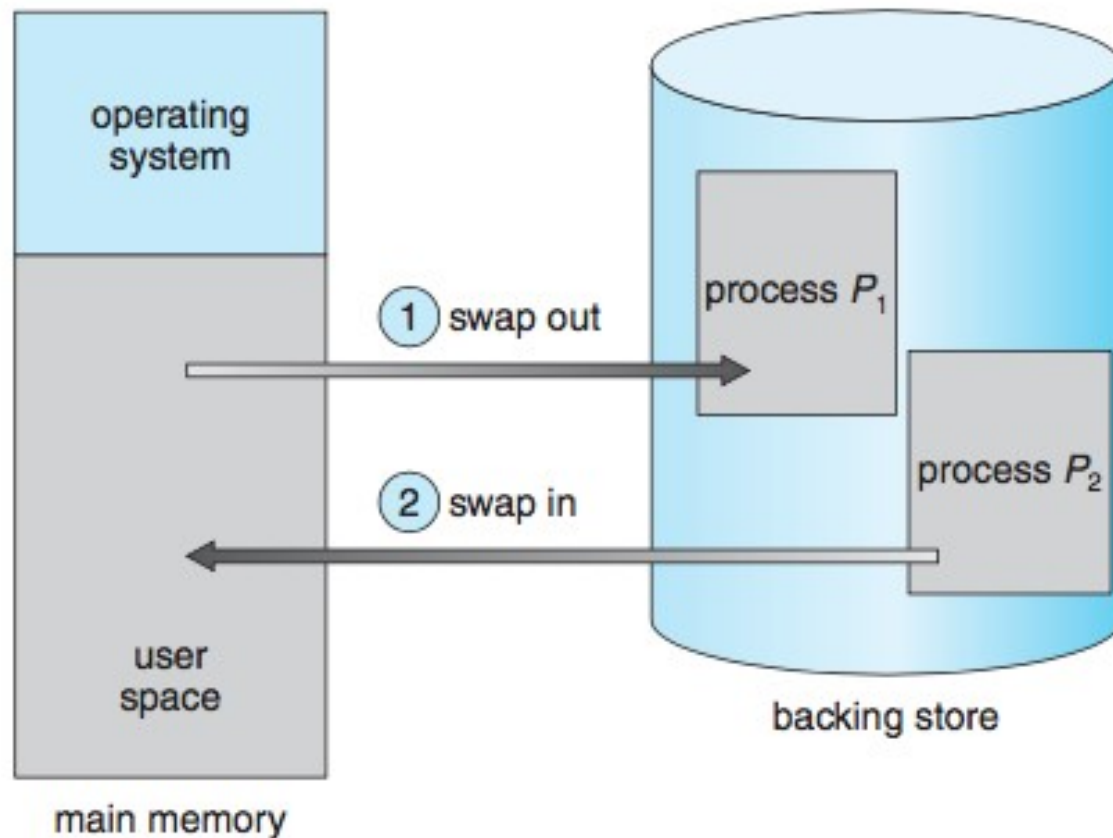


(f\*)

After comp.

# Swapping

- bring in each process in its entirety, running it for a while, then putting it back on the disk



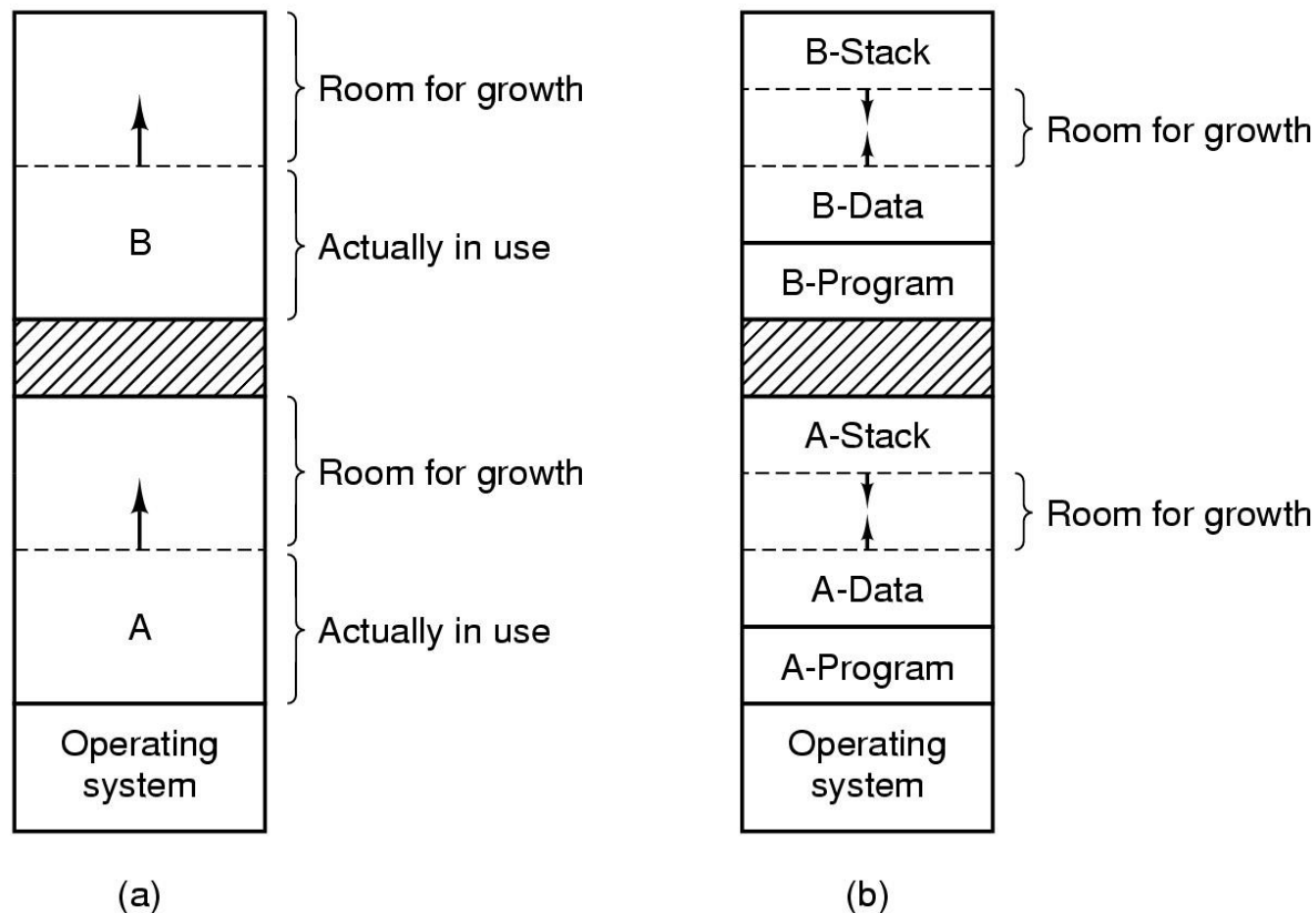


# Overlay

- Replacement of a block of stored instructions or data with another
- a way to describe sections which are to be loaded as part of a single memory image but are to be run at the same memory address

```
OVERLAY [start] : [NOCROSSREFS] [AT ( ldaddr )]
{
    secname1
    {
        output-section-command
        output-section-command
        ...
    } [:phdr...] [=fill]
    secname2
    {
        output-section-command
        output-section-command
        ...
    } [:phdr...] [=fill]
    ...
} [>region] [:phdr...] [=fill] [,]
```

# Issues of Variable Partitions



(a) Allocating space for growing data segment.

(b) Allocating space for growing stack, growing data segment.



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# Basic Memory Management

- discrete allocation



# Discrete Memory Allocation

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- Segmentation
- Paging

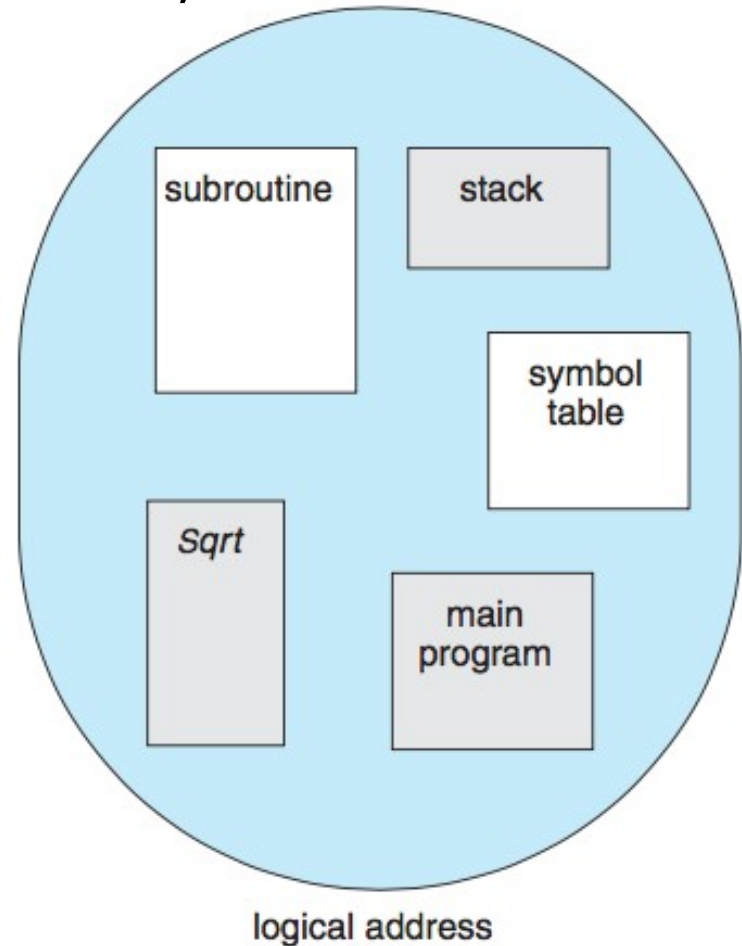


# Segmentation

two tuple: <segment-number, offset>

- Logical Segmentations
  - 1. The code
  - 2. Global variables
  - 3. The heap, from which memory is allocated
  - 4. The stacks used by each thread
  - 5. The standard C library

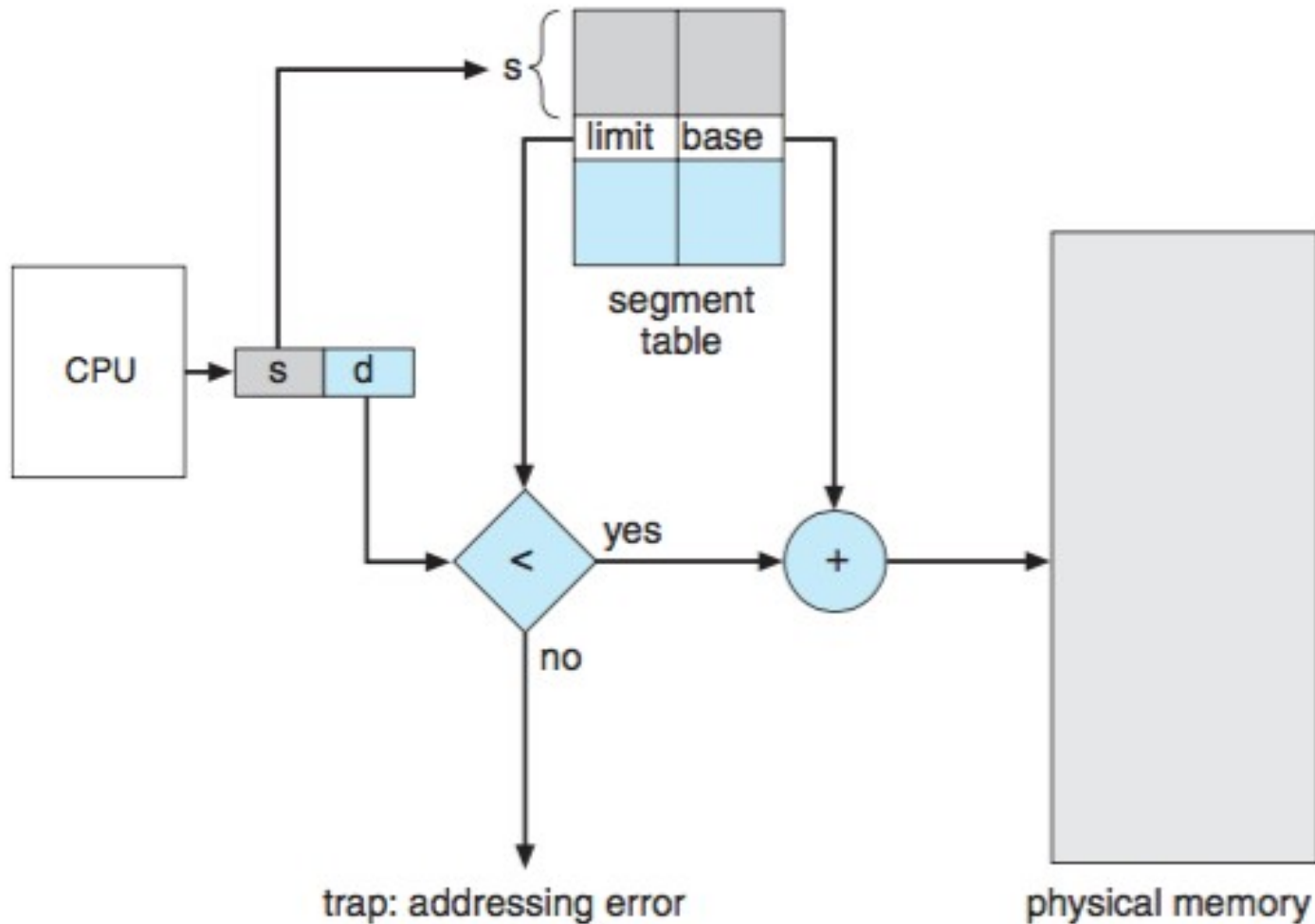
?fragmentation



Programmer's view of a  
program

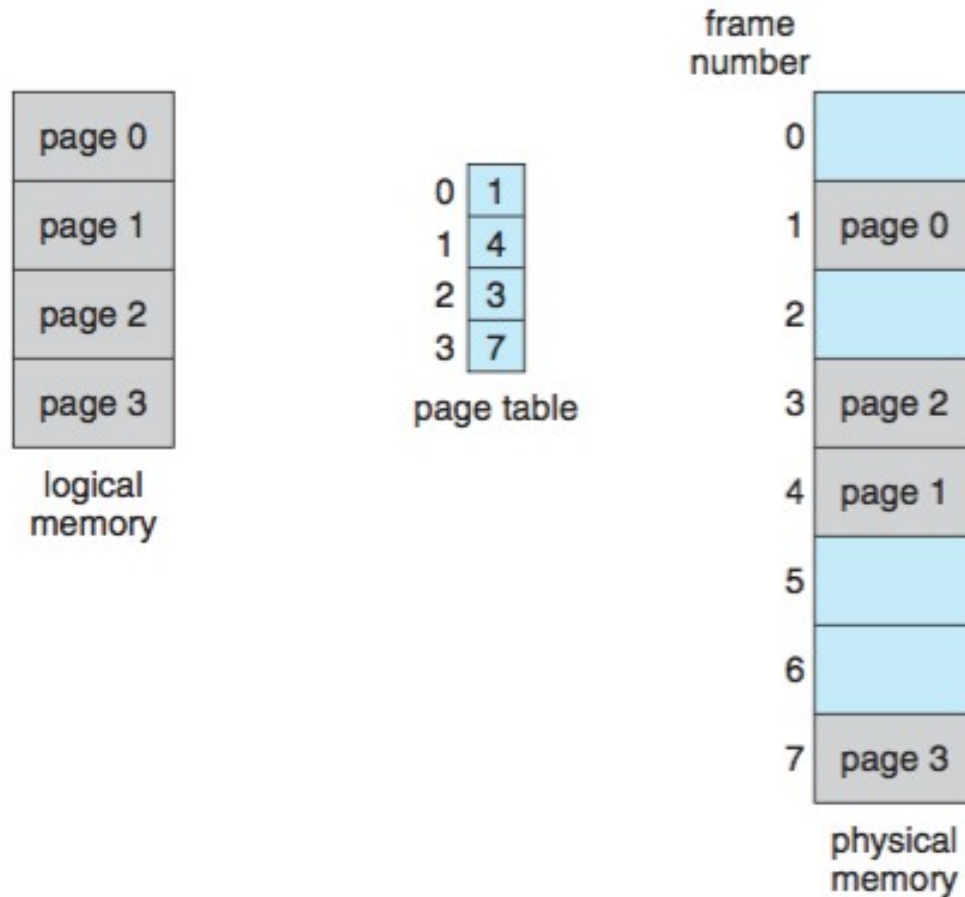
leexudong@nankai.edu.cn

# Segmentation



Segmentation  
hardware

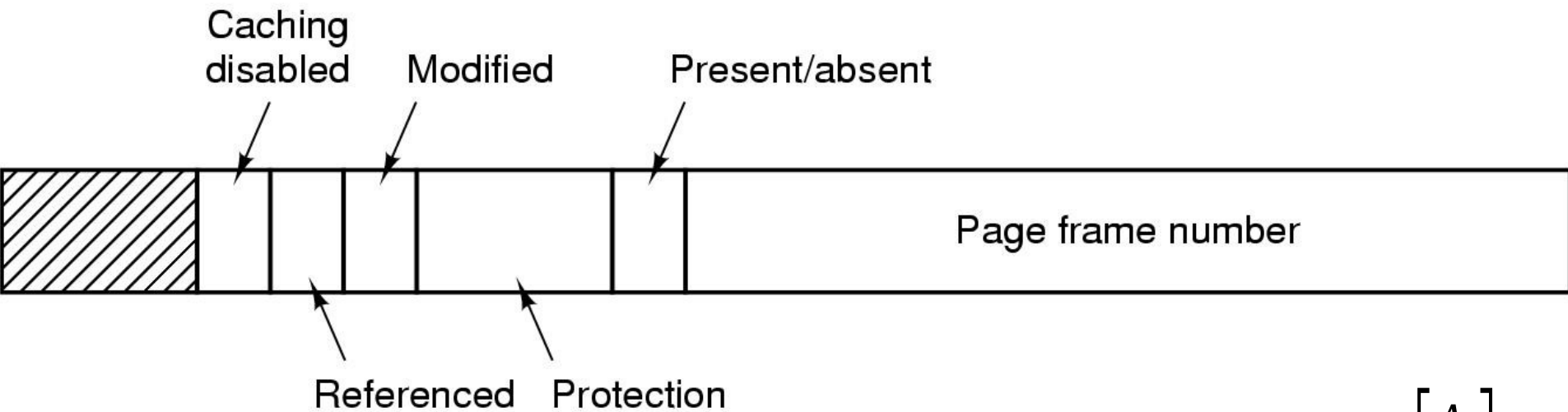
# Paging



- Page
- Frame
- Page Table

Paging model of logical and physical memory

# Paging: page table



Address= (Page number, offset)

One Tuple

?fragmentation

$$PageNum = INT \left[ \frac{A}{L} \right]$$

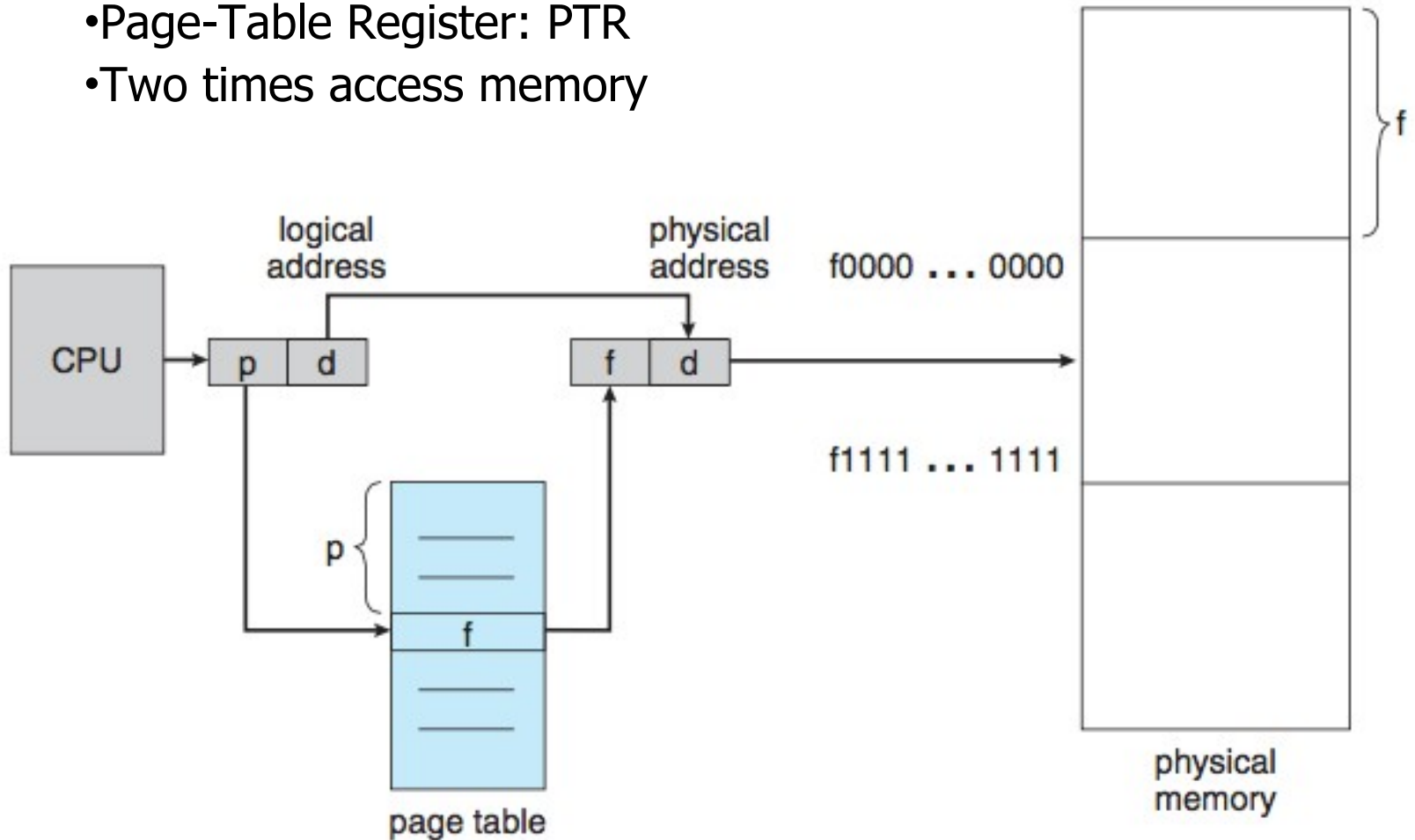
$$offset = [A] MOD L$$

A: Logical Address

L: Page Size

# Paging: hardware

- Page-Table Register: PTR
- Two times access memory

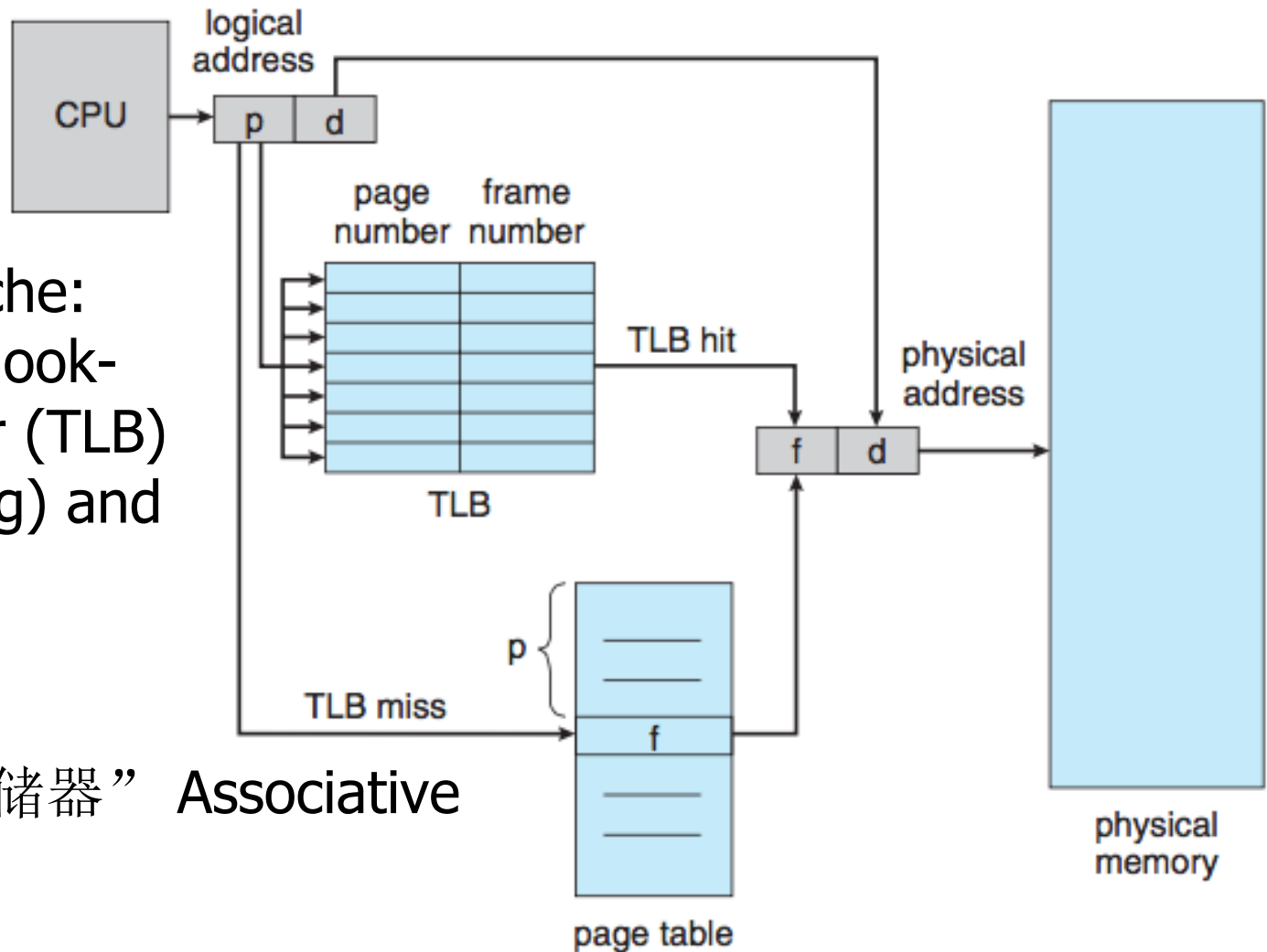


# Paging: hardware with TLB

hardware cache:

- translation look-aside buffer (TLB)
- key (or tag) and value

- 快表 ,
- “联想存储器” Associative Memory





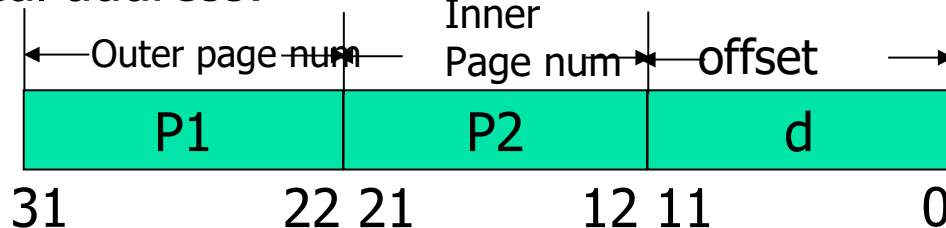
# Paging: hardware with TLB

Valid	Virtual page	Modified	Protection	Page frame
1	140	1	RW	31
1	20	0	R X	38
1	130	1	RW	29
1	129	1	RW	62
1	19	0	R X	50
1	21	0	R X	45
1	860	1	RW	14
1	861	1	RW	75

A TLB to speed up paging

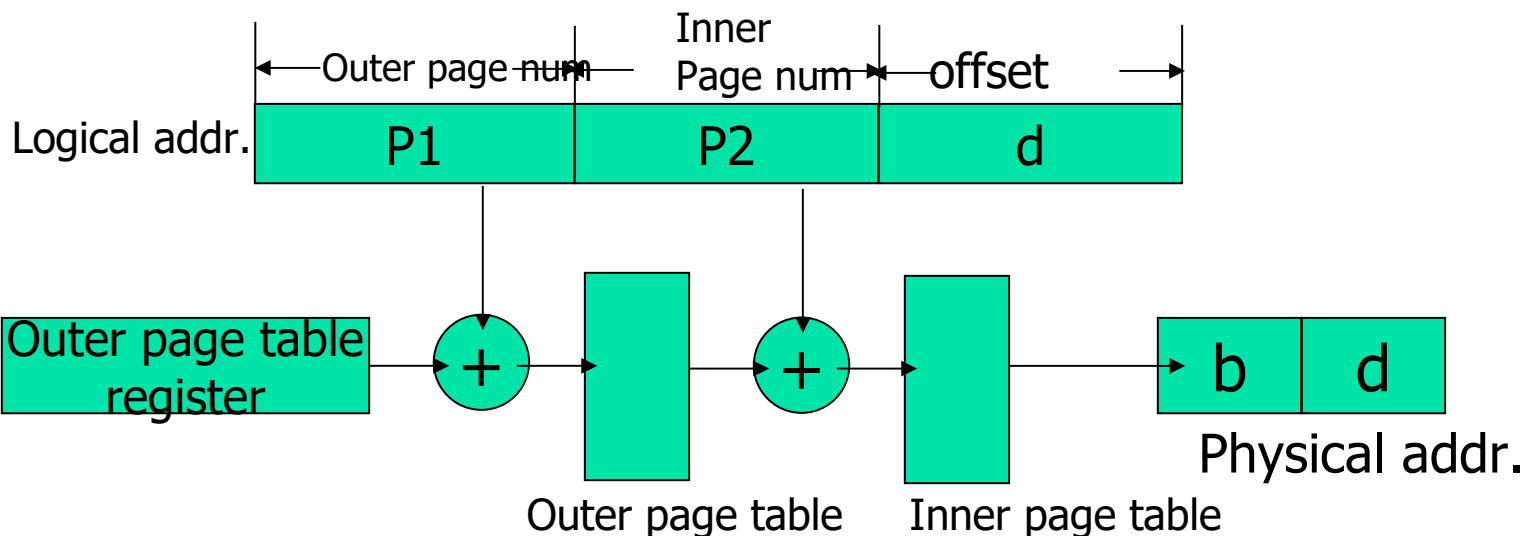
# Paging: Multi-level Page Table

Logical address:



外层页表

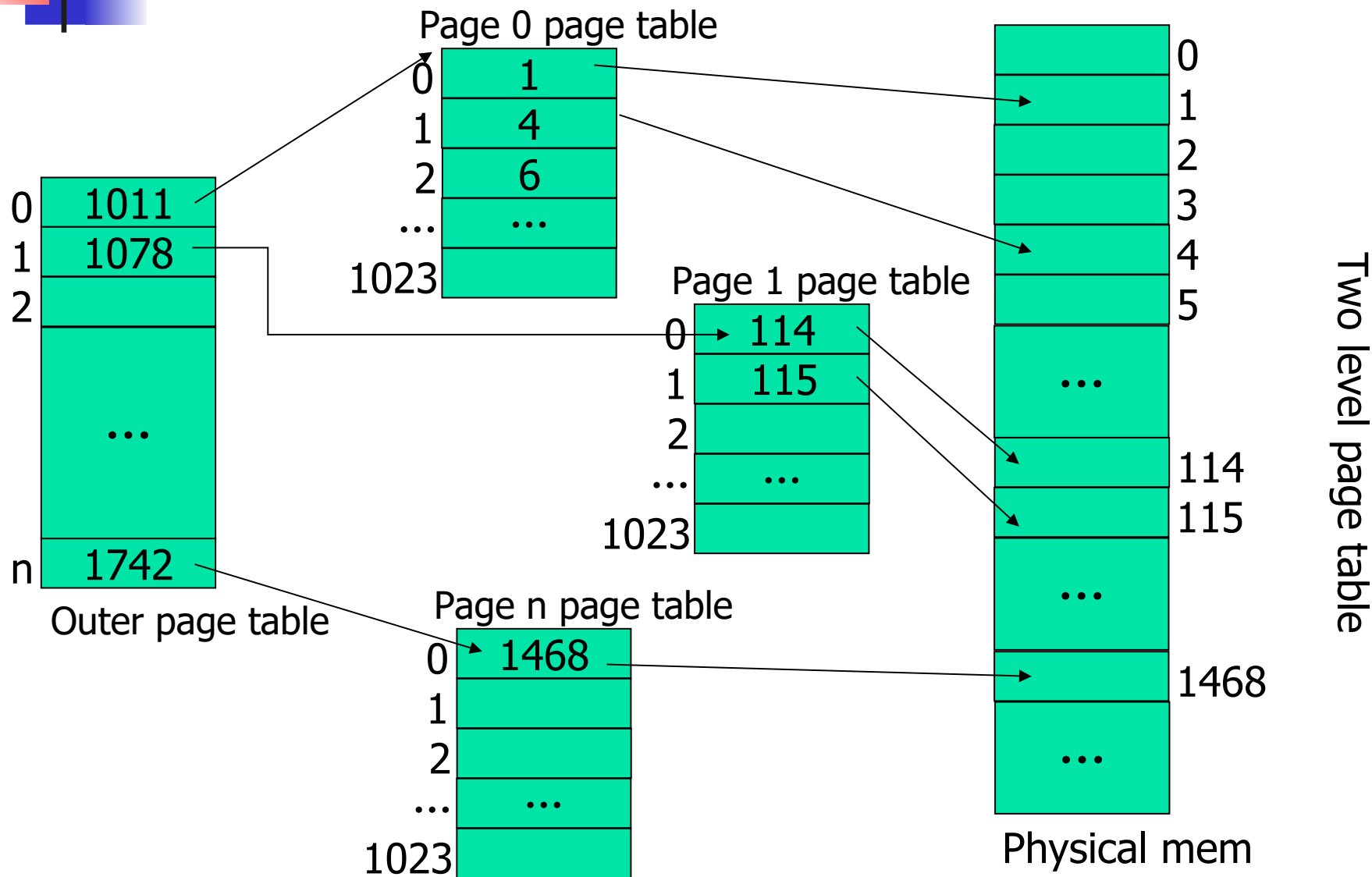
Outer Page Table  
Page Directory



Two level page table

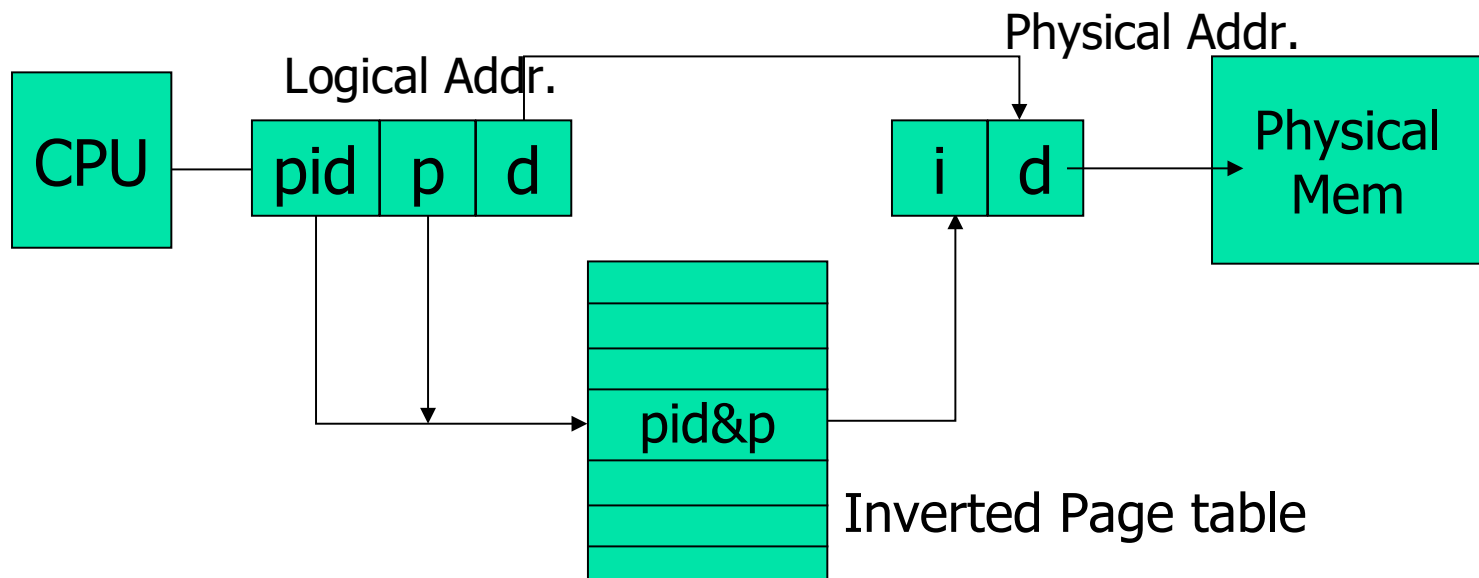


# Paging: Multi-level Page Table



# Inverted Page Tables

<process-id, page-number,  
offset>

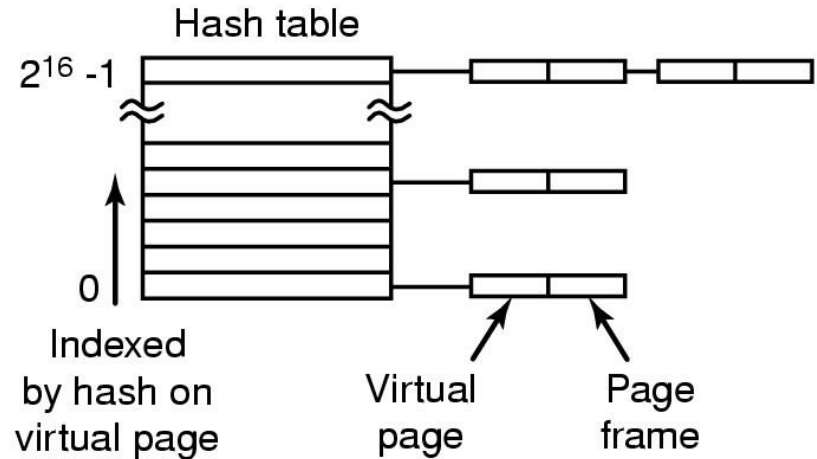
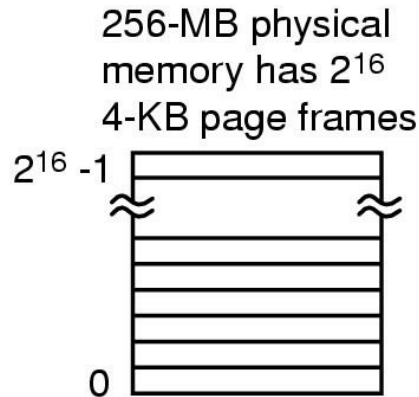
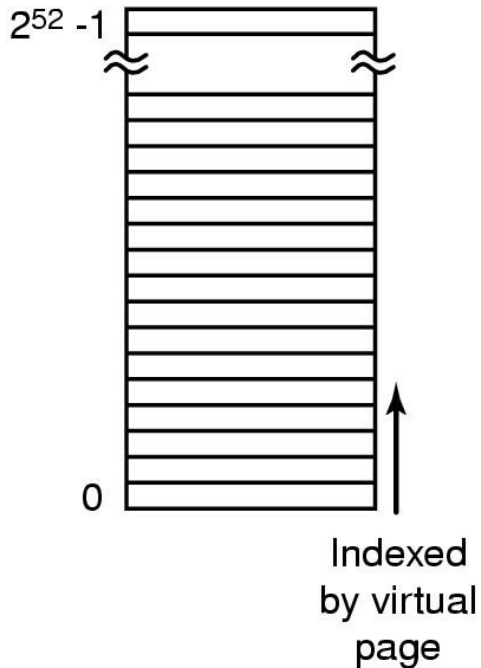


# Inverted Page Tables

Traditional page table with an entry for each of the  $2^{52}$  pages

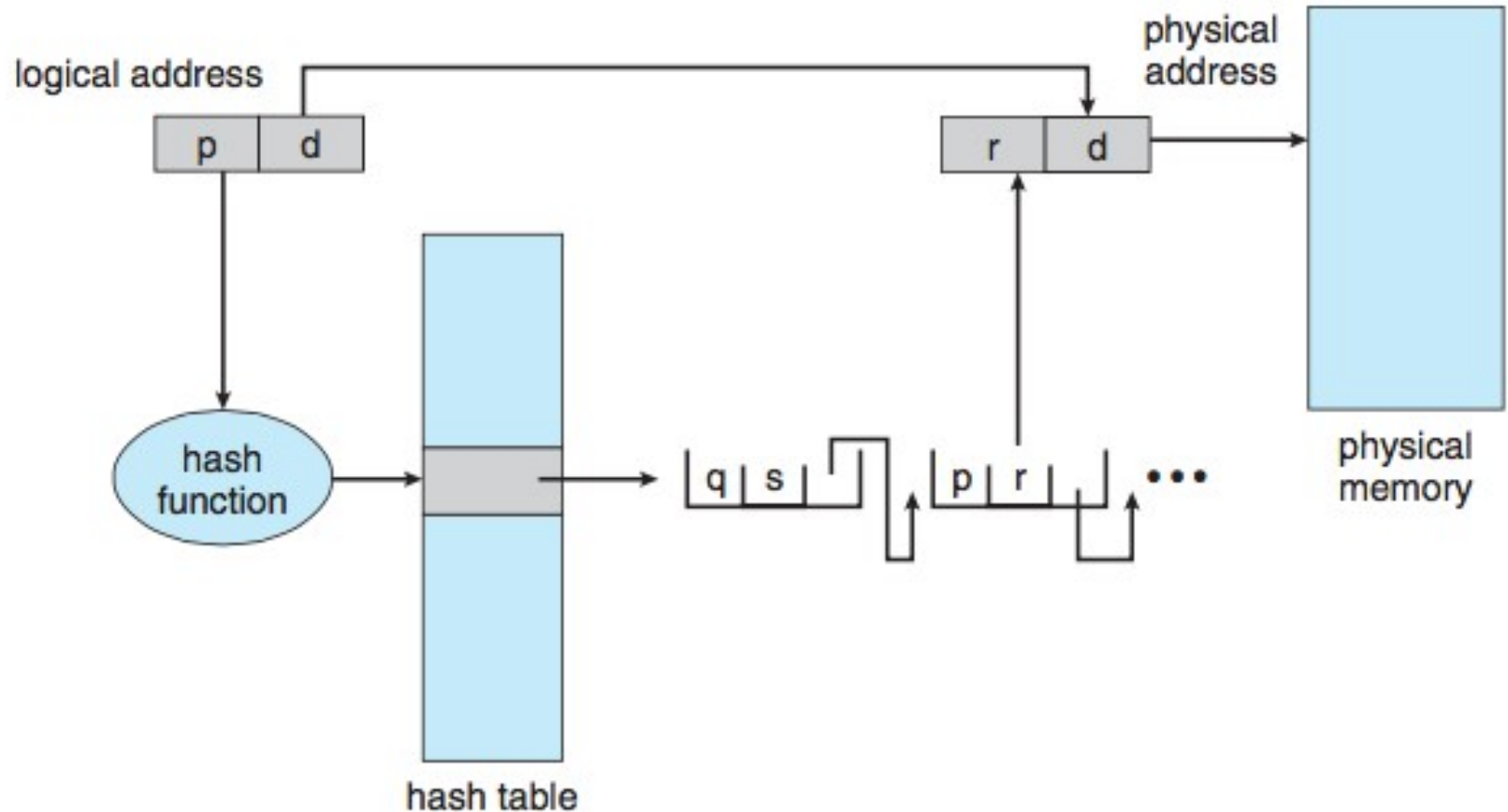
64bits CP

4kb/page



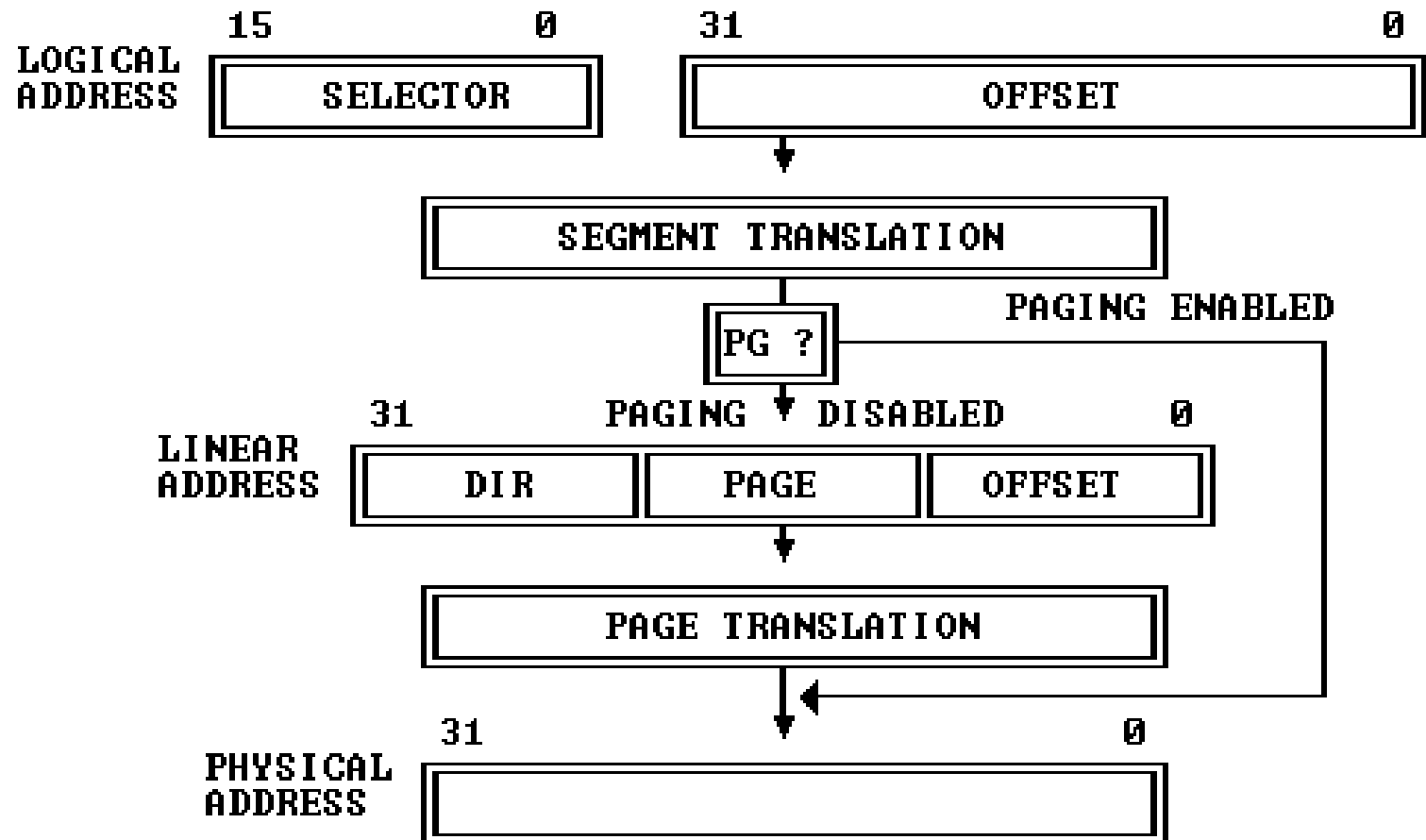
Comparison of a traditional page table with an inverted page table

# Hashed Page Tables

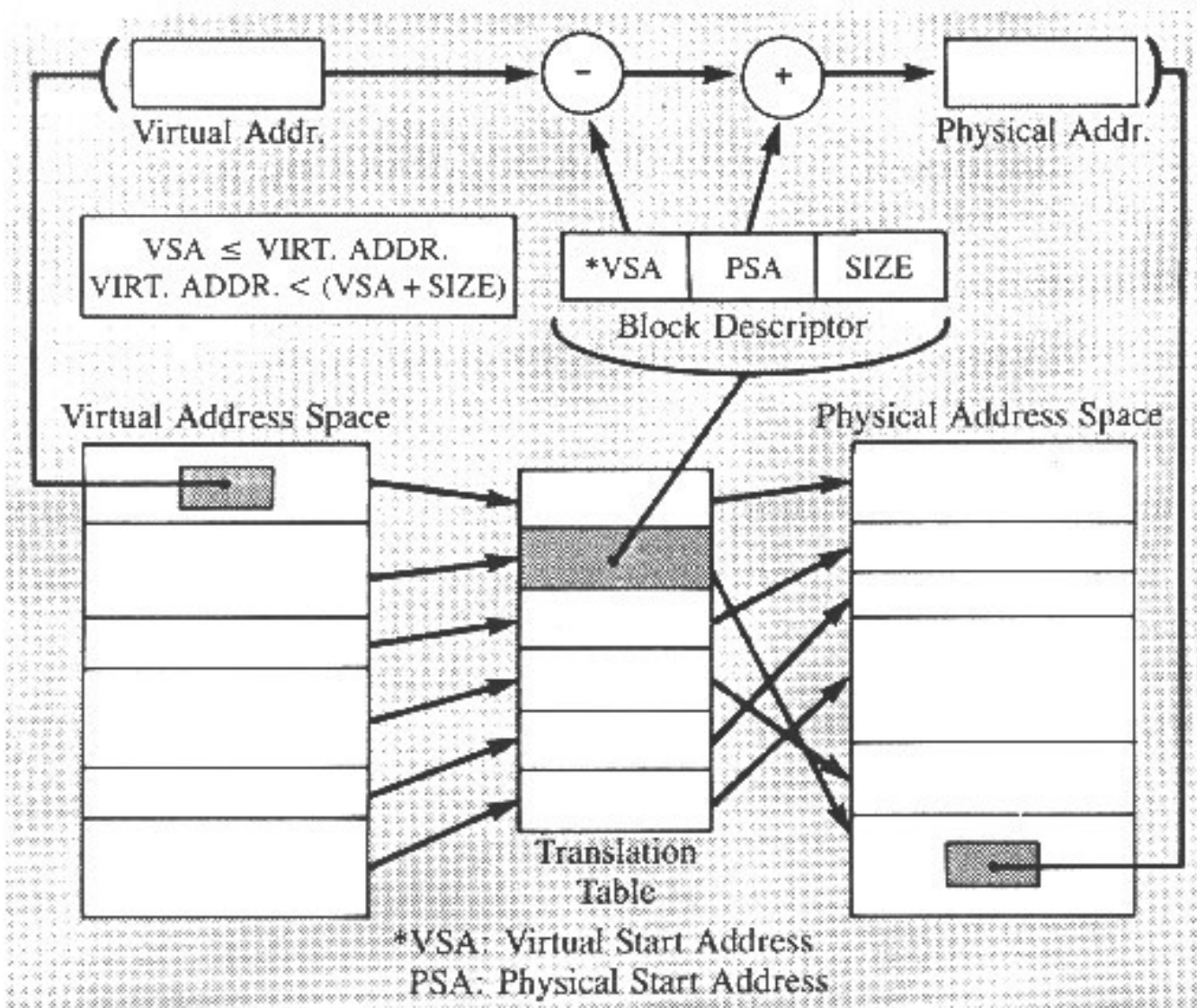


# CURR MEMORY TRANSLATION

Logical Addr. -> (Virtual/)Linear Addr. -> Physical Addr.



# CURR MEMORY TRANSLATION





# Summary

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- Memory Partitioning
- Swapping
- Segmentation
- Paging