

# Week 3

## Advanced Sorting Algorithms

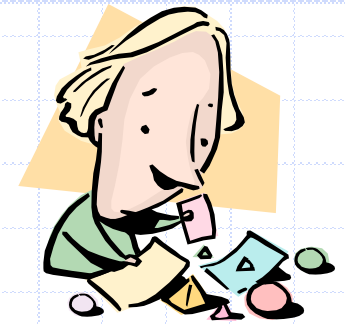
## Linear Data Structures

## Amortization

Algorithms and Data Structures  
COMP3506/7505

# Week 3 – Sorting & Linear DS

1. Bucket-sort and radix-sort
2. Arrays
3. Linked Lists
4. Extensible Lists and Amortization



# Comparison Sorts

- Sorted order determined by comparing keys

```
if  $A[k] < A[k+1]$ :  
    # Do some swapping
```

- Examples
  - Bubble, insertion, selection, merge and quick sorts
    - ◆ Everything we've seen so far!

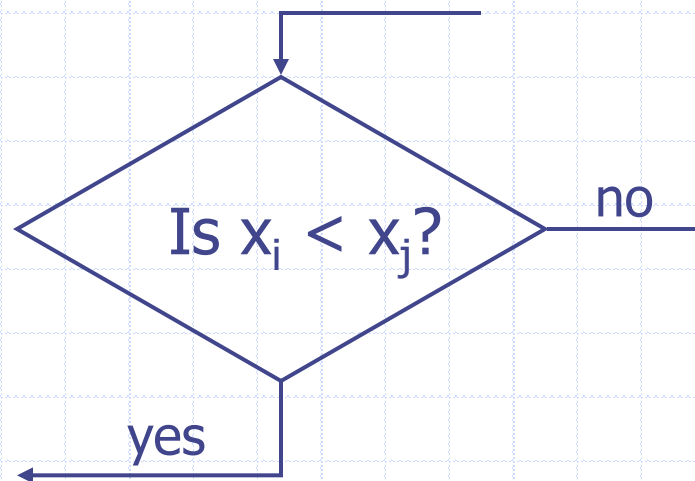
# “Hang on, last week you said”

- I told you that it doesn't get any better than *mergesort*
  - At least, in terms of the *number of comparisons* that must be done to sort the input
  - That is, any comparison-based sorting algorithm must have  $\Omega(n \log_2 n)$  comparisons in the worst case



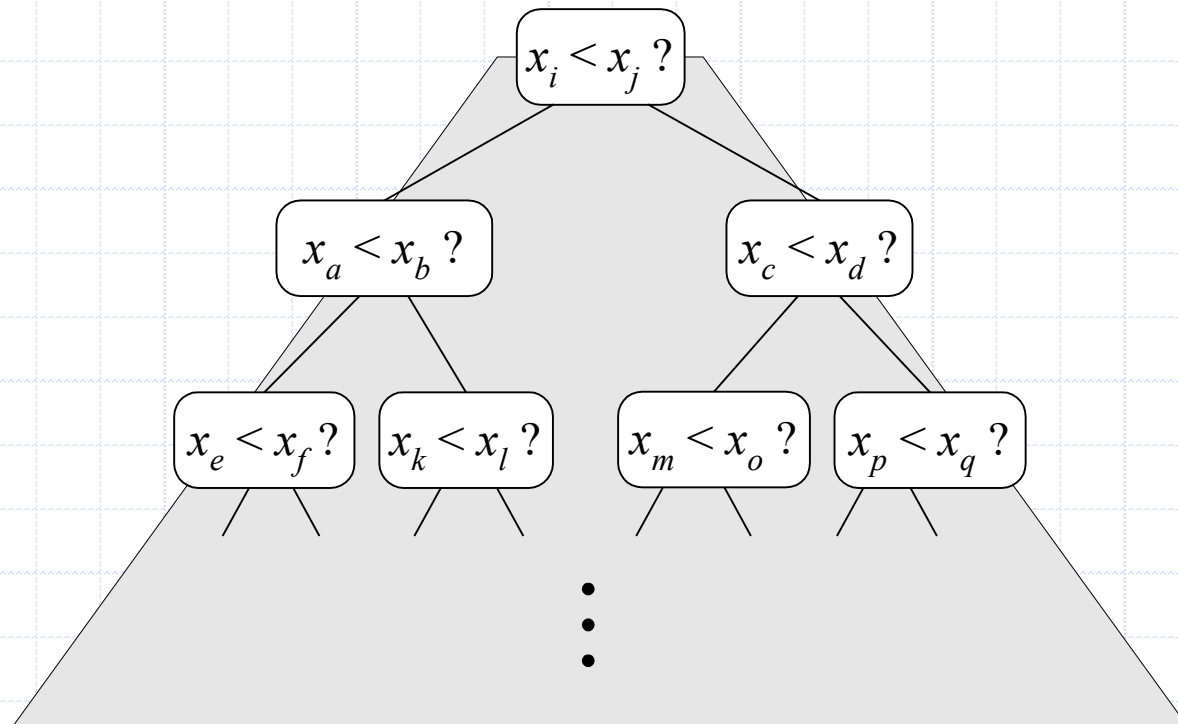
# Determining Performance

- Derive a **worst-case lower bound** on running time of any algorithm that uses **comparisons** to sort  $n$  elements,  $x_1, x_2, \dots, x_n$



# Counting Comparisons

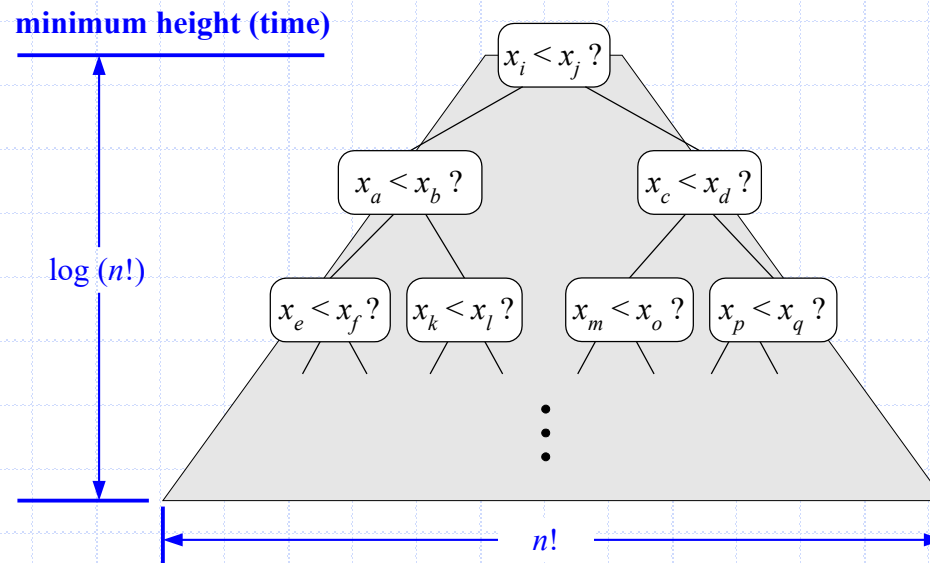
- Each possible run of the algorithm corresponds to a root-to-leaf path in a **decision tree**



# Think Permutations...

# Decision Tree Height

- Height of decision tree is a **lower bound** on running time
- Every unique input permutation must lead to a separate leaf output
  - if not, some input ...4...5... would have same output ordering as ...5...4..., which would be wrong
- There are  $n! = 1 \cdot 2 \cdot \dots \cdot n$  leaves – height is at least  **$\log(n!)$**





# Proof.

$$\begin{aligned} 2^h \geq n! &\Rightarrow h \geq \log(n!) \\ &= \log(n(n-1)(n-2) \cdots (2)) \\ &= \log n + \log(n-1) + \log(n-2) + \cdots + \log 2 \\ &= \sum_{i=2}^n \log i \\ &= \sum_{i=2}^{n/2-1} \log i + \sum_{i=n/2}^n \log i \\ &\geq 0 + \sum_{i=n/2}^n \log \frac{n}{2} \\ &= \frac{n}{2} \cdot \log \frac{n}{2} \\ &= \Omega(n \log n) \end{aligned}$$

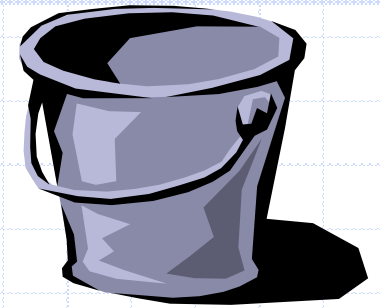
# Lower Bound

- Comparison-based sorting algorithms takes at least  $\log(n!)$  time
- $\therefore$  any such algorithm takes at least
  - $\log(n!) \geq \log \left(\frac{n}{2}\right)^{n/2} = (n/2) \log(n/2)$
- Any comparison-based sorting algorithm must run in  $\Omega(n \log n)$  time
  - merge and heap sorts are **asymptotically optimal**
    - ◆ no other comparison sorts are faster by more than a **constant factor**

# Can We Do Better?

- ❑ Do we have to compare every key to sort data?
- ❑ Do we have to compare anything???
- ❑ Idea: Use a data structure to help us...

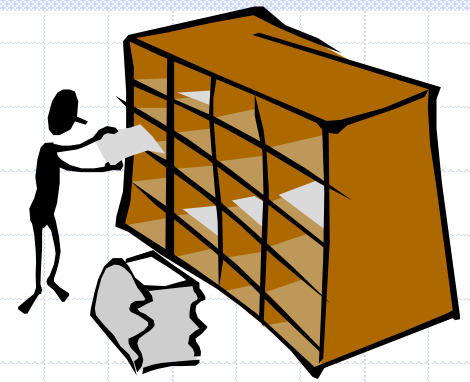




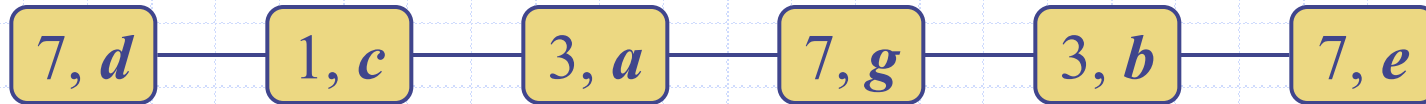
# Bucket-Sort

- Let  $S$  be a list of  $n$  (key, element) items with keys in the range  $[0, N - 1]$
- Bucket-sort uses the keys as indices into an auxiliary array  $B$  of lists (buckets)
  - **Phase 1:** Empty list  $S$  by moving each entry  $(k, o)$  into its bucket  $B[k]$
  - **Phase 2:** For  $i = 0, \dots, N - 1$ , move the entries of bucket  $B[i]$  to the end of list  $S$

# Example

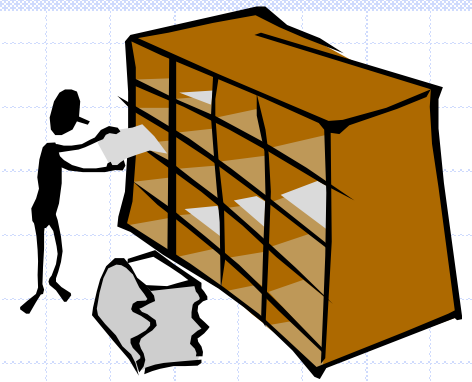


- Key range  $[0, 9]$

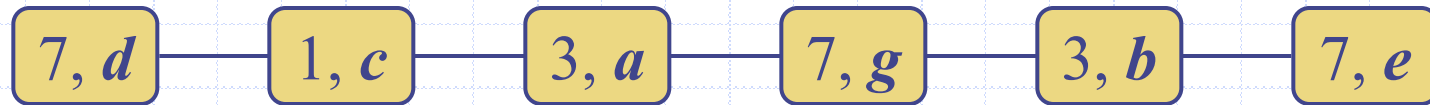


<b><i>B</i></b>	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$
	0	1	2	3	4	5	6	7	8	9

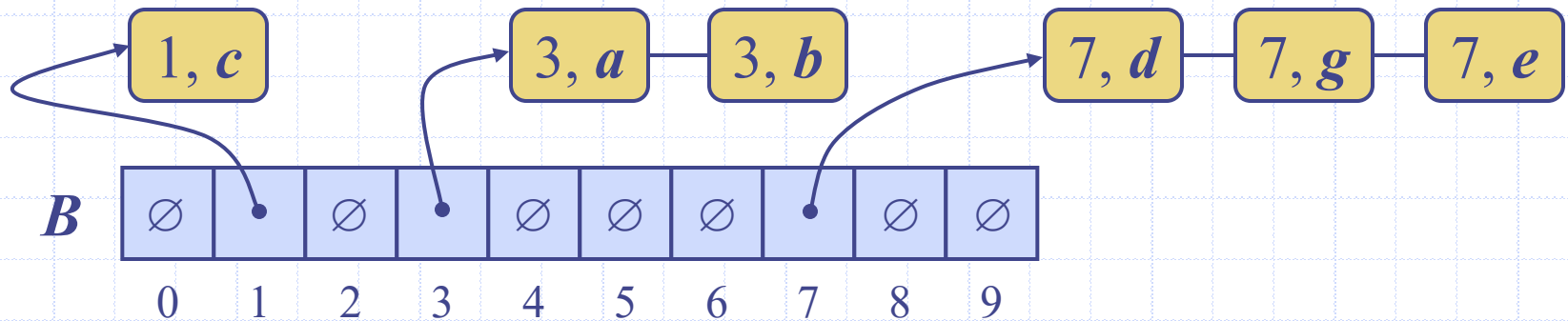
# Example



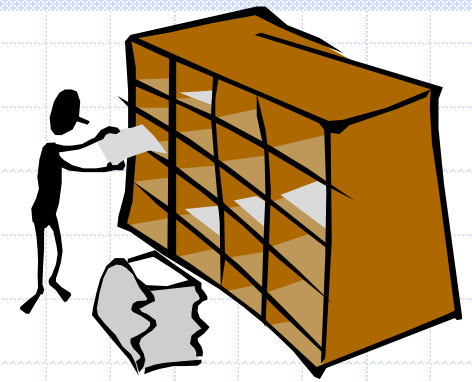
- Key range  $[0, 9]$



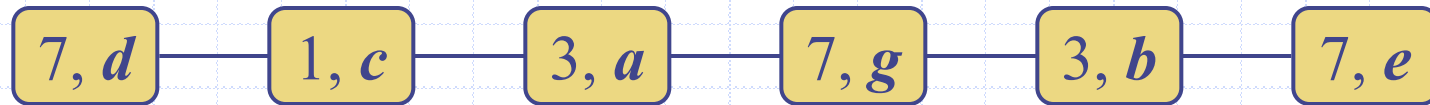
Phase 1



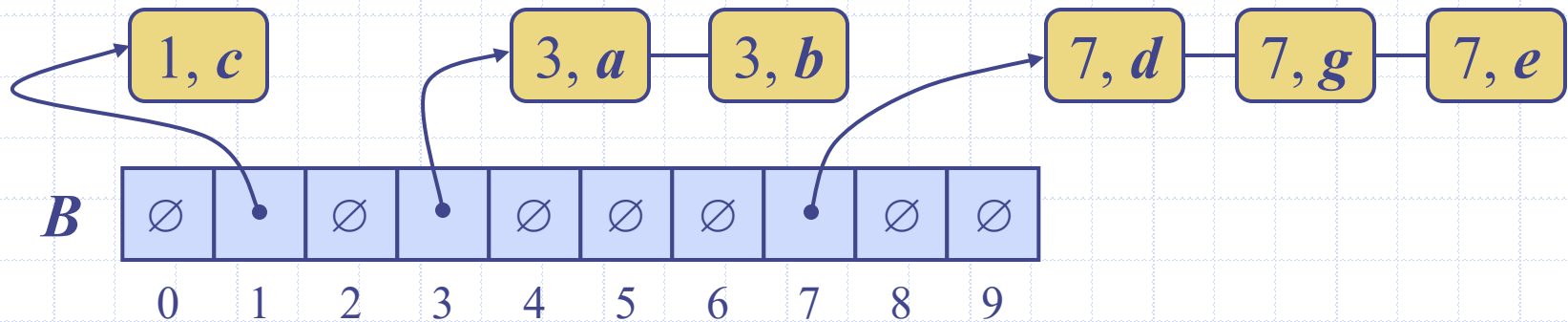
# Example



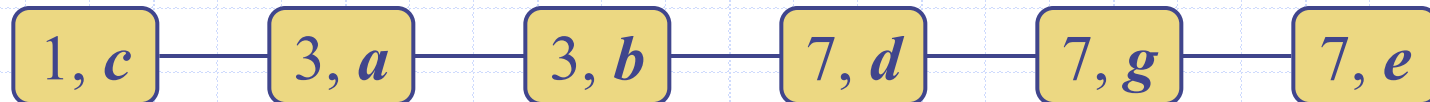
- Key range  $[0, 9]$

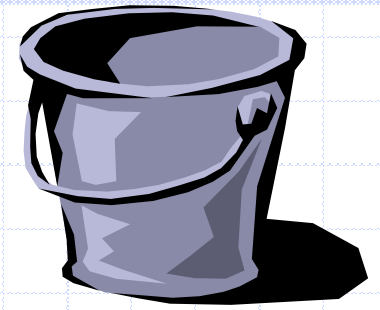


Phase 1



Phase 2





# Bucket-Sort

**Algorithm** *bucketSort*( $S$ ):

**Input:** sequence  $S$  of  $n$  entries with integer keys in the range  $[0, N - 1]$

**Output:** sequence  $S$  sorted in nondecreasing order of the keys

$B \leftarrow$  array of  $N$  empty sequences

**for each** entry  $e$  **in**  $S$  **do**

$k \leftarrow$  key of  $e$

    remove  $e$  from  $S$

    insert  $e$  at the end of bucket  $B[k]$

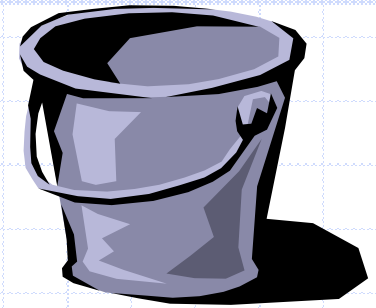
**for**  $i \leftarrow 0$  **to**  $N-1$  **do**

**for each** entry  $e$  **in**  $B[i]$  **do**

        remove  $e$  from  $B[i]$

        insert  $e$  at the end of  $S$





# Bucket-Sort

**Algorithm** *bucketSort*( $S$ ):

**Input:** sequence  $S$  of  $n$  entries with integer keys in the range  $[0, N - 1]$

**Output:** sequence  $S$  sorted in nondecreasing order of the keys

→  $B \leftarrow$  array of  $N$  empty sequences

→ **for each** entry  $e$  **in**  $S$  **do**

$k \leftarrow$  key of  $e$

    remove  $e$  from  $S$

    insert  $e$  at the end of bucket  $B[k]$

→ **for**  $i \leftarrow 0$  **to**  $N-1$  **do**

**for each** entry  $e$  **in**  $B[i]$  **do**

        remove  $e$  from  $B[i]$

        insert  $e$  at the end of  $S$

## □ Analysis

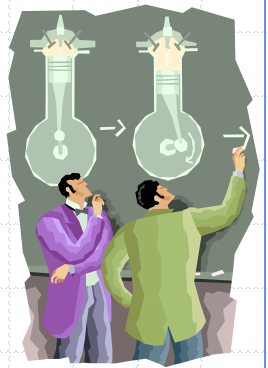
- Initialising the bucket array takes  $O(N)$  time

- Phase 1 takes  $O(n)$  time

- Phase 2 takes  $O(n + N)$  time

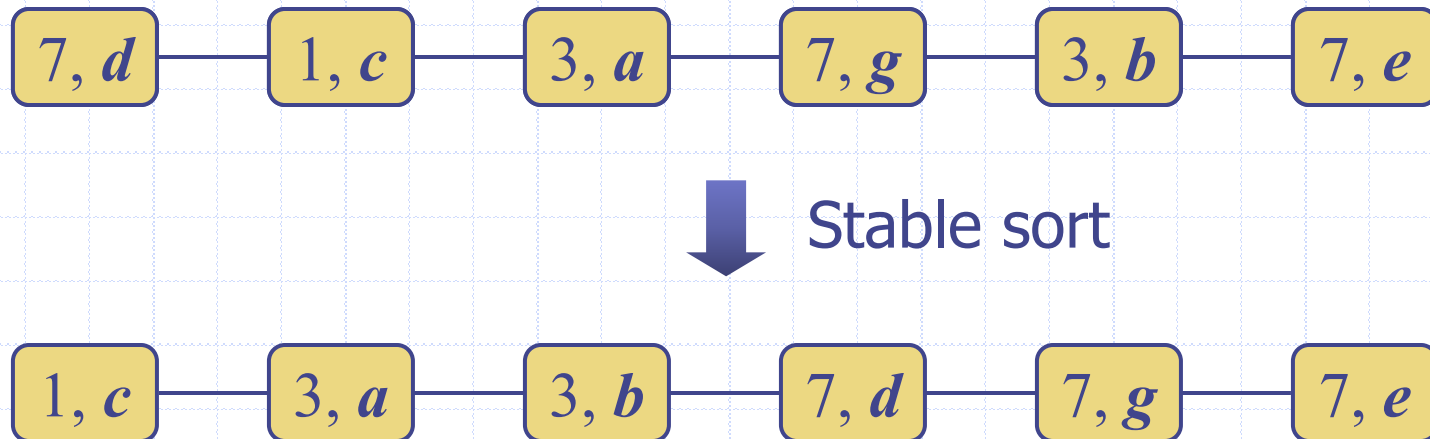
□ Bucket-Sort takes  $O(n + N)$  time

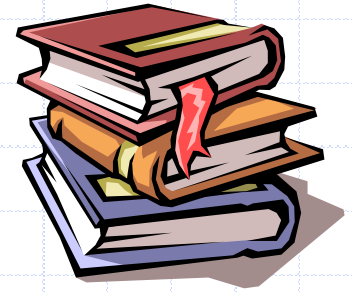
# Properties and Extensions



- **Stable Sort Property**

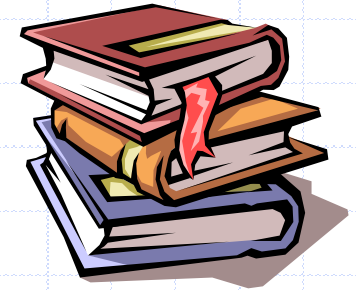
- **Relative order** of any two items with the same key is **preserved** after the execution of the algorithm





# Lexicographic Order

- $d$ -tuple is a sequence of  $d$  keys  $(k_1, k_2, \dots, k_d)$ , where key  $k_i$  is said to be the  $i$ -th dimension of the tuple
  - e.g. Cartesian coordinates of a point in space are a 3-tuple
  - e.g. ant < apple



# Lexicographic Order

- Lexicographic order of two  $d$ -tuples is recursively defined as follows

$$(x_1, x_2, \dots, x_d) < (y_1, y_2, \dots, y_d)$$



$$x_1 < y_1 \vee x_1 = y_1 \wedge (x_2, \dots, x_d) < (y_2, \dots, y_d)$$

- i.e. tuples are compared by the first dimension, then by the second dimension, etc.
  - $(2, 1, 4) < (3, 2, 5)$  since  $2 < 3$
  - $(2, 1, 4) < (2, 2, 5)$  since  $2 = 2$  and  $1 < 2$
  - $(2, 1, 4) < (2, 1, 5)$  since  $2 = 2$ ,  $1 = 1$  and  $4 < 5$

# Lexicographic-Sort (aka Tuple Sort)

- ◆  $C_i$  – comparator that compares two tuples by their  $i$ -th dimension
- ◆  $stableSort(S, C)$  – stable sorting algorithm that uses comparator  $C$
- ◆  $lexicographicSort$  sorts a sequence of  $d$ -tuples in lexicographic order by executing  $stableSort$ ,  $d$  times
  - once per dimension
- ◆ Runs in  $O(d \cdot T(n))$  time
  - where  $T(n)$  is the running time of  $stableSort$

**Algorithm** *lexicographicSort*( $S$ )

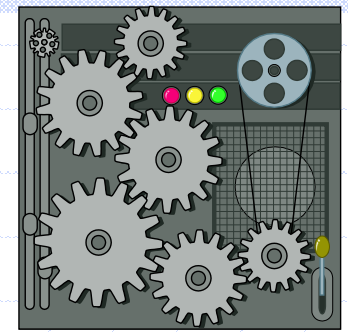
**Input** sequence  $S$  of  $d$ -tuples

**Output** sequence  $S$  sorted in lexicographic order

**for**  $i \leftarrow d$  **downto** 1  
     $stableSort(S, C_i)$

## Example

(7,4,6) (5,1,5) (2,4,6) (2,1,4) (3,2,4)  
(2,1,4) (3,2,4) (5,1,5) (7,4,6) (2,4,6)  
(2,1,4) (5,1,5) (3,2,4) (7,4,6) (2,4,6)  
(2,1,4) (2,4,6) (3,2,4) (5,1,5) (7,4,6)



# Radix-Sort

- Specialisation of lexicographic-sort
  - uses bucket-sort as the stable sorting algorithm in each dimension
- Applicable to tuples where the keys in each dimension  $i$  are integers in the range  $[0, N - 1]$
- Runs in time  $O(d \cdot (n + N))$

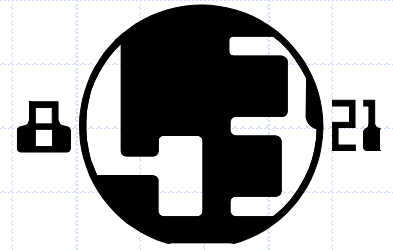
**Algorithm** *radixSort*( $S, N$ )

**Input** sequence  $S$  of  $d$ -tuples such that  $(0, \dots, 0) \leq (x_1, \dots, x_d)$  and  $(x_1, \dots, x_d) \leq (N - 1, \dots, N - 1)$  for each tuple  $(x_1, \dots, x_d)$  in  $S$

**Output** sequence  $S$  sorted in lexicographic order

**for**  $i \leftarrow d$  **downto** 1

*bucketSort*( $S, N$ )



# Radix-Sort for Binary Numbers

- Consider a sequence of  $n$   $b$ -bit integers
  - $x = x_{b-1} \dots x_1 x_0$
- Represent each element as a  $b$ -tuple of integers in the range  $[0, 1]$  and apply radix-sort with  $N = 2$
- Runs in  $b \cdot (n+2)$  or  $O(b \cdot n)$  time

**Algorithm** *binaryRadixSort(S)*

**Input** sequence  $S$  of  $b$ -bit integers

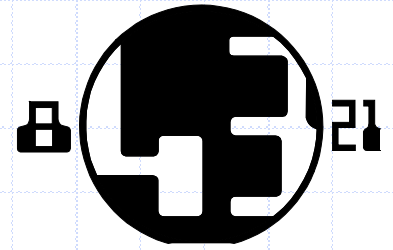
**Output** sequence  $S$  sorted

replace each element  $x$  of  $S$  with item  $(0, x)$

**for**  $i \leftarrow 0$  **to**  $b - 1$

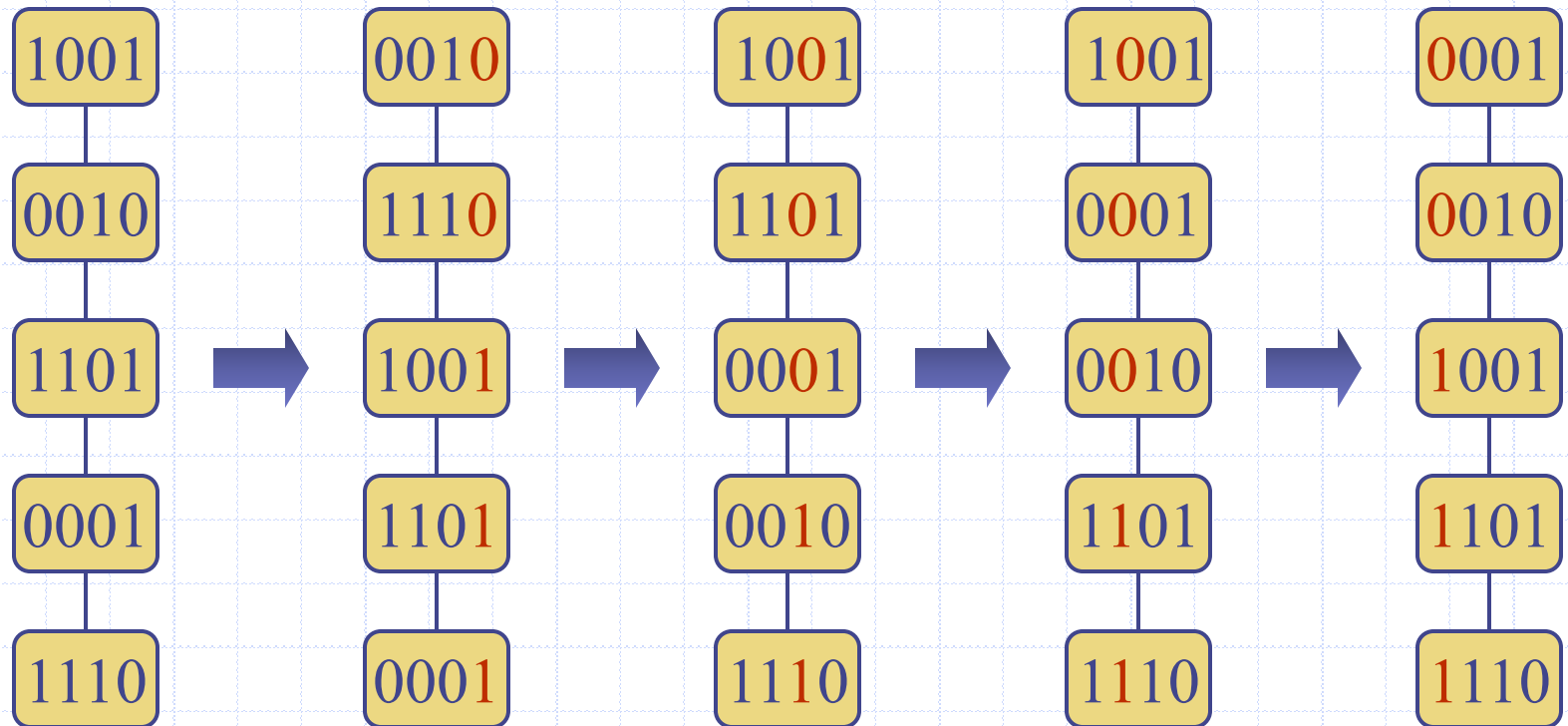
replace key  $k$  of item  $(k, x)$  with bit  $x_i$  of  $x$

*bucketSort(S, 2)*



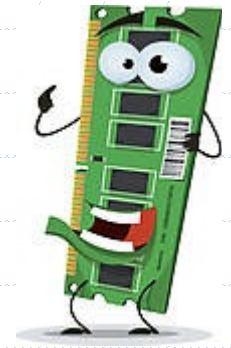
# Example

- Sorting a sequence of 4-bit integers





# Memory Usage



- Original sequence and bucket array

- $O(n + N)$

- Sort: 10, 999, 3, 100 000 000, 20

- ◆ Bucket Sort

- $O(5 + 100\,000\,000)$

- ◆ (Binary) Radix Sort

- $O(5 + 2)$

- ◆ (Bytewise) Radix Sort

- $O(5 + 256)$

# Week 3 – Sorting & Linear DS

1. Bucket-sort and radix-sort
2. Arrays
3. Linked Lists
4. Extensible Lists and Amortization

# General Linear Structures

A linear structure is one whose elements can be seen as being in a sequence. That is, one element follows the next.

- Lists
  - Stacks
  - Queues
  - Vectors
- Recall the static sequence from Lec 1

# Static Sequence ADT

- Given a list of items  $X$  in some order:  $x_1, x_2, \dots, x_n$

`build(X)` :    Make new data structure for items in  $X$

`len(X)` :        Return  $n$

`get(i)` :        Return the element at position  $i$

`set(i, x)` :    Set  $x_i$  to  $x$

- Note that the way we store the data and compute those functions depend on the *data structure we use*

# Dynamic Sequence ADT

- Given a list of items  $X$  in some order:  $x_1, x_2, \dots, x_n$

`build(X)` :     Make new data structure for items in  $X$

`len(X)` :        Return  $n$

`get(i)` :        Return the element at position  $i$

`set(i, x)` :     Set  $x_i$  to  $x$

**`add(x)`** :       Add  $x$  to  $X$

# Implementing Linear Structures

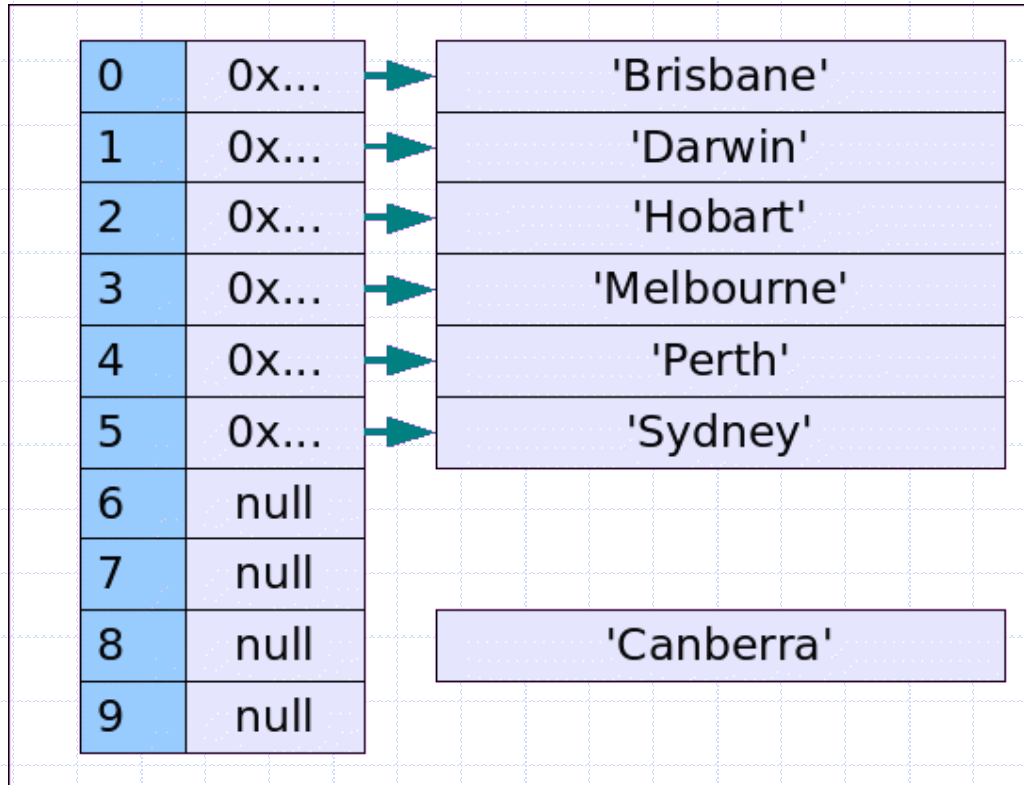
- Arrays: Sequence of consecutive memory cells
- Size must be specified at creation (static!)
- What does it get us?
  - Constant time random access – nice!
  - But what if we want to insert something?
  - What if we need more space?

# Arrays (insert)

Insert the value 'Canberra', so that the array maintains sorted order

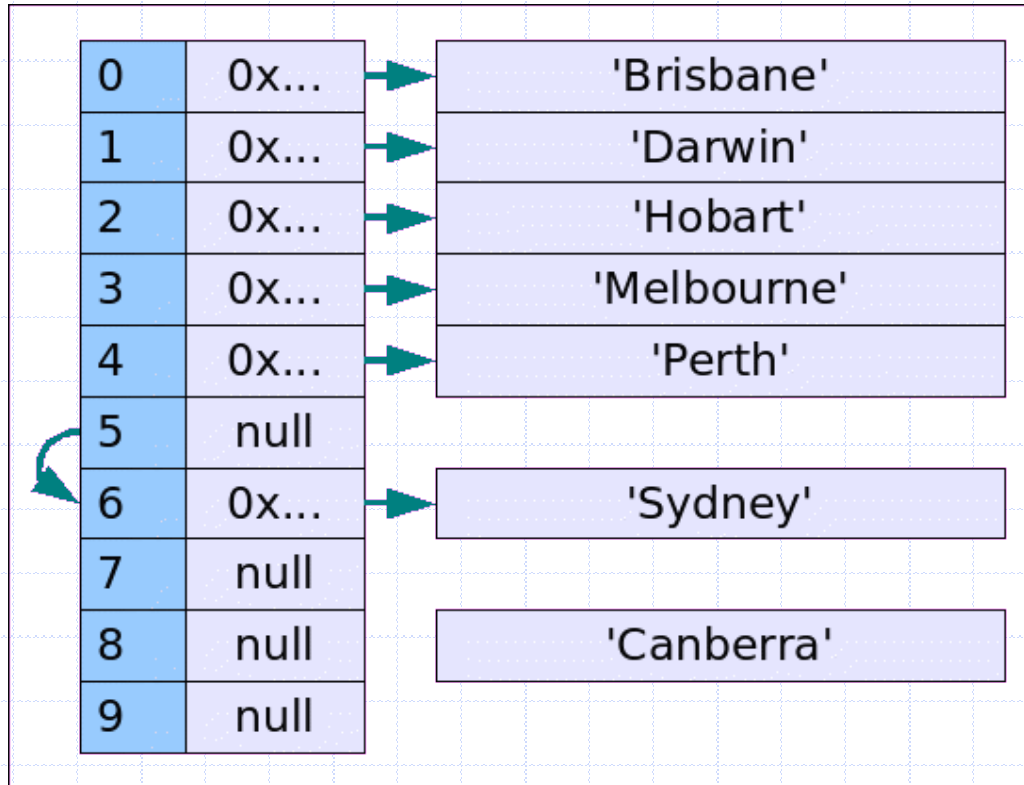
0	0x...	→	'Brisbane'
1	0x...	→	'Darwin'
2	0x...	→	'Hobart'
3	0x...	→	'Melbourne'
4	0x...	→	'Perth'
5	0x...	→	'Sydney'
6	null		
7	null		
8	null		
9	null		

# Arrays (insert)

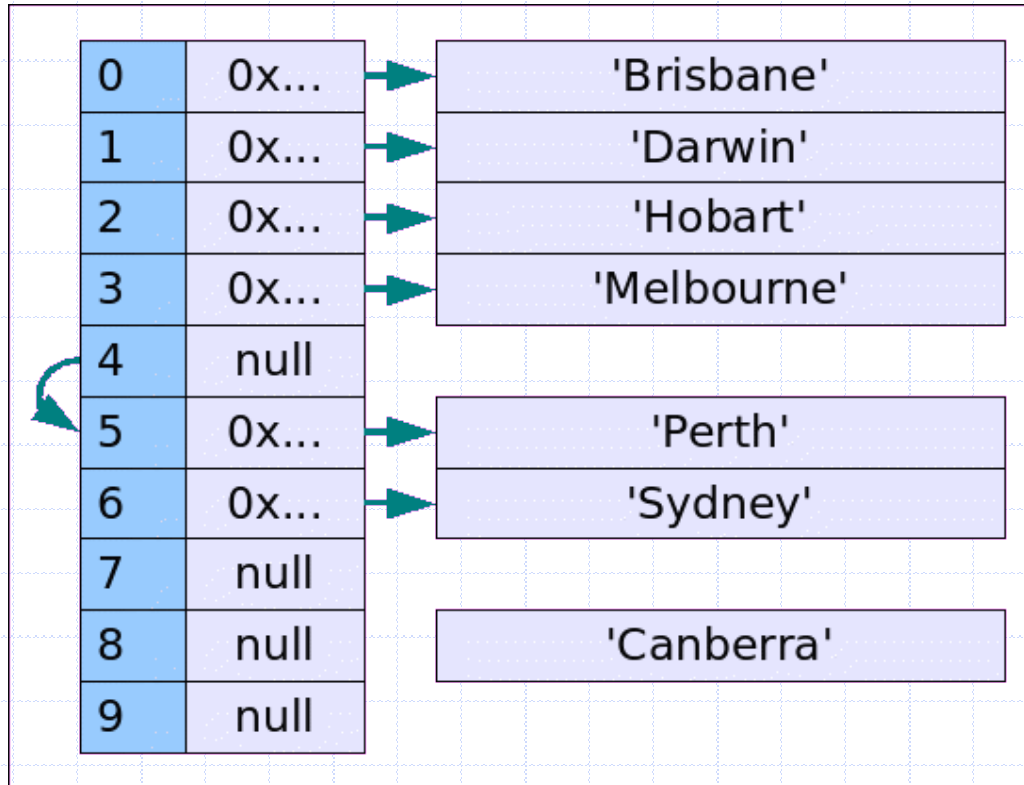




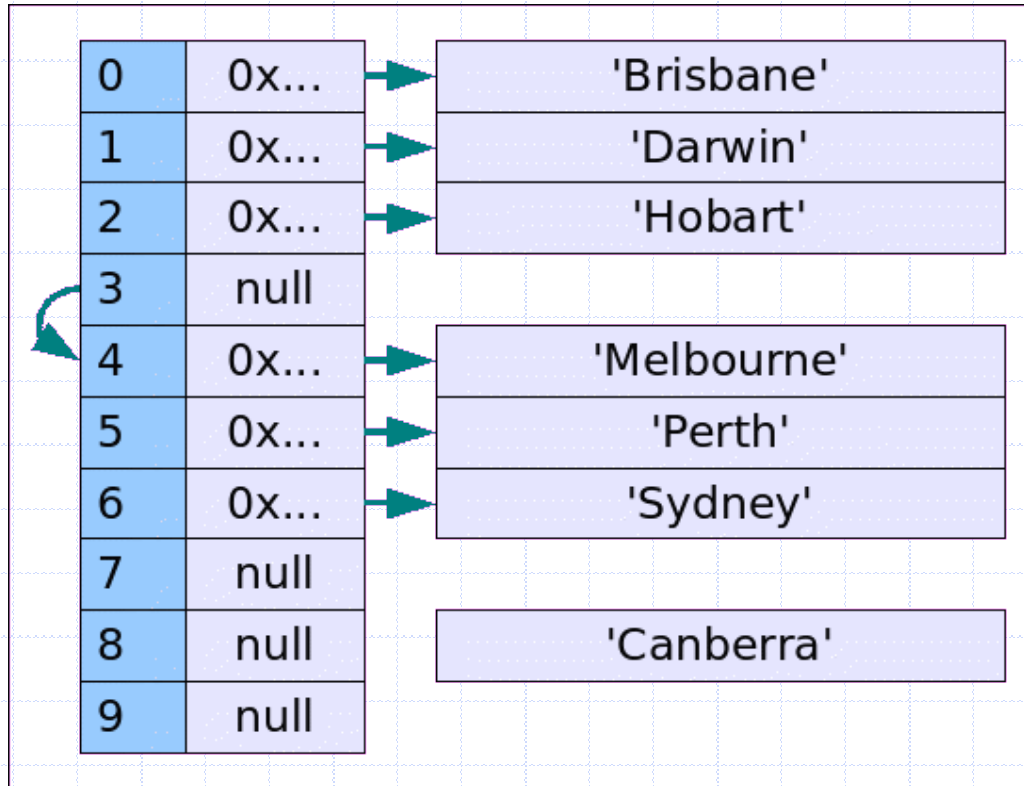
# Arrays (insert)



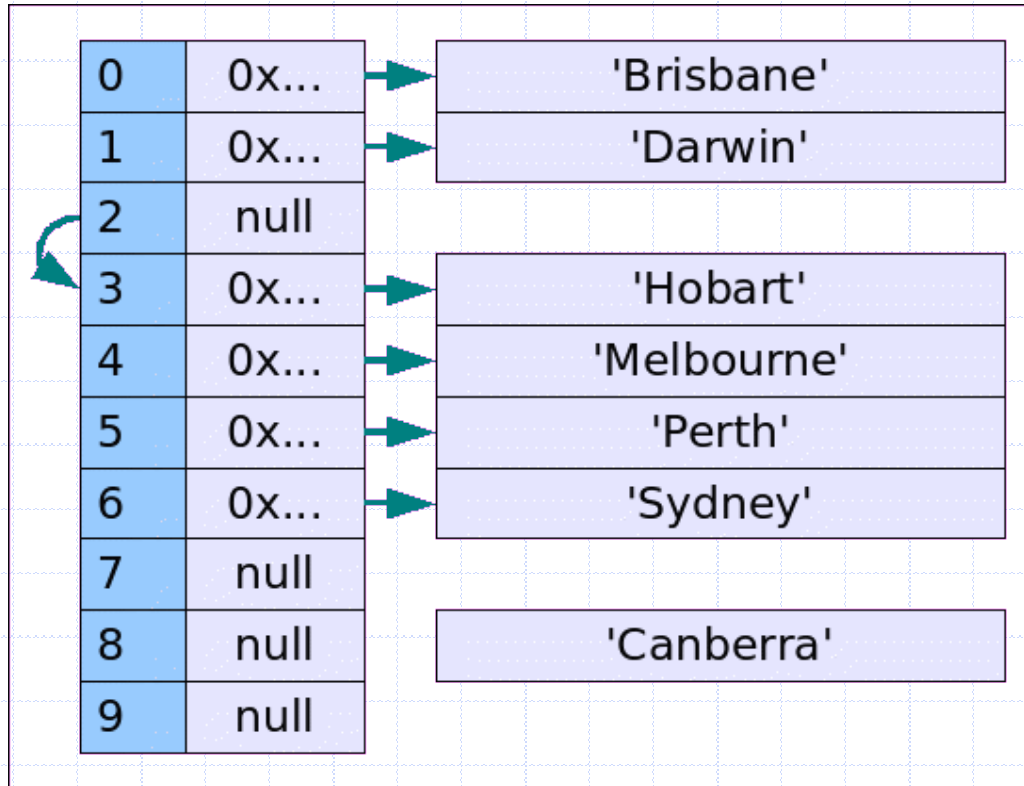
# Arrays (insert)



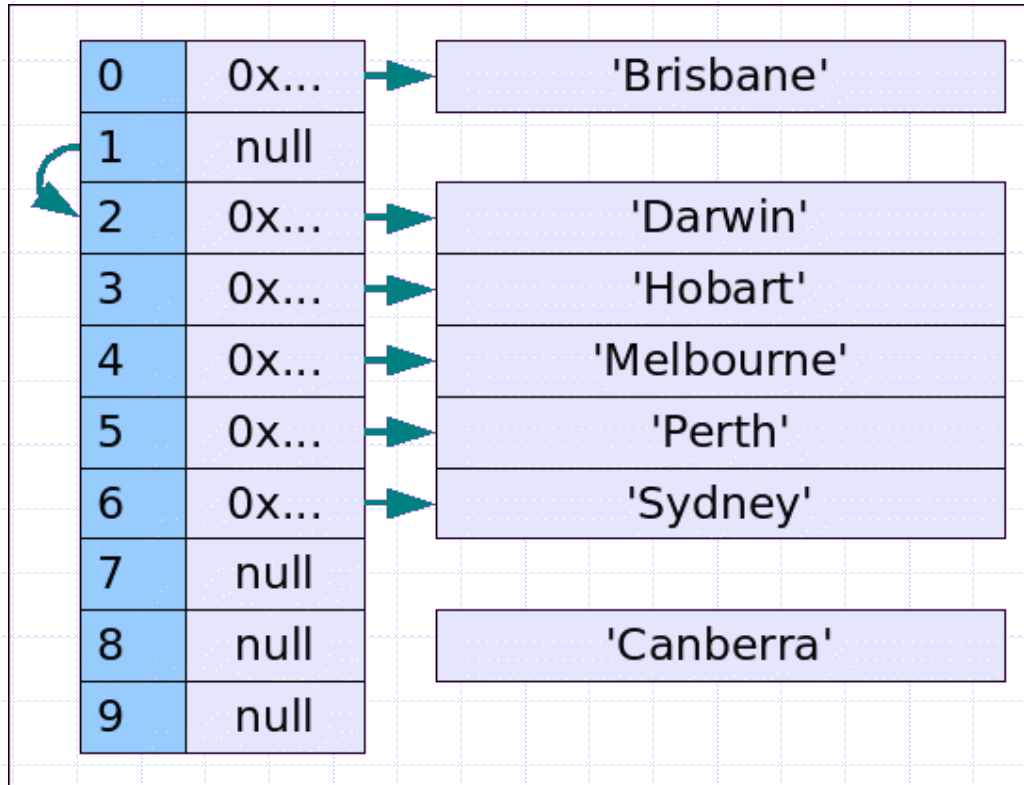
# Arrays (insert)



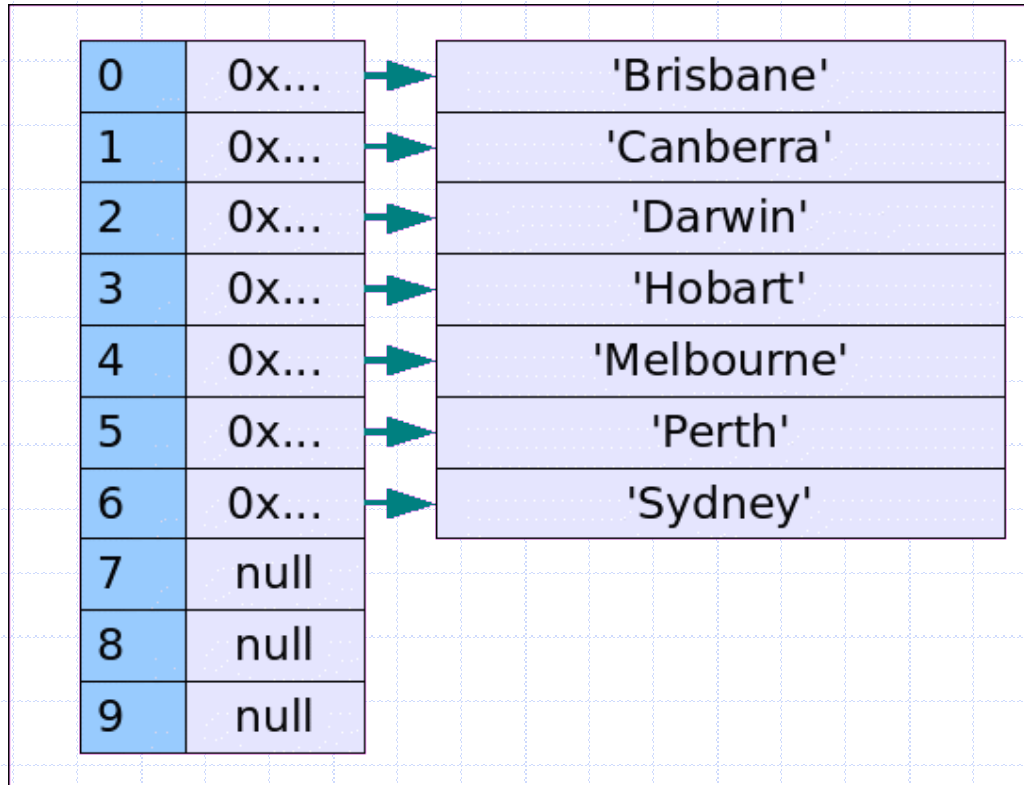
# Arrays (insert)



# Arrays (insert)



# Arrays (insert)



# Array Implementation Efficiency

- ❑ Accessing an element (by index)
  - $O(1)$
- ❑ Iterating over elements
  - $O(n)$
- ❑ Insert / Delete element
  - $O(n)$
- ❑ Memory usage
  - $O(n)$

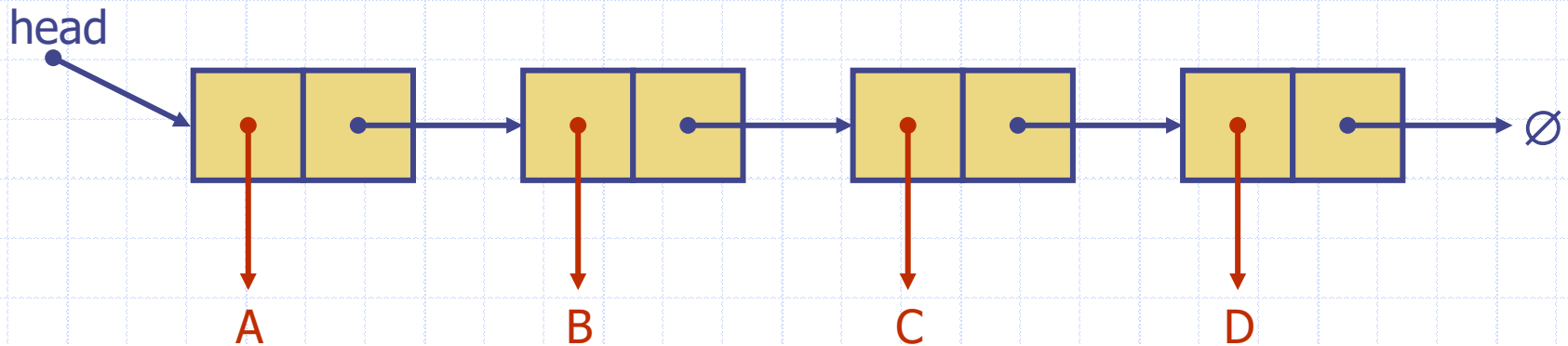
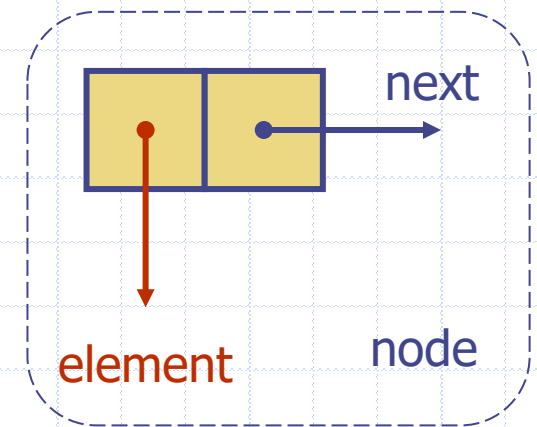
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2. Arrays
3. Linked Lists
4. Extensible Lists and Amortization

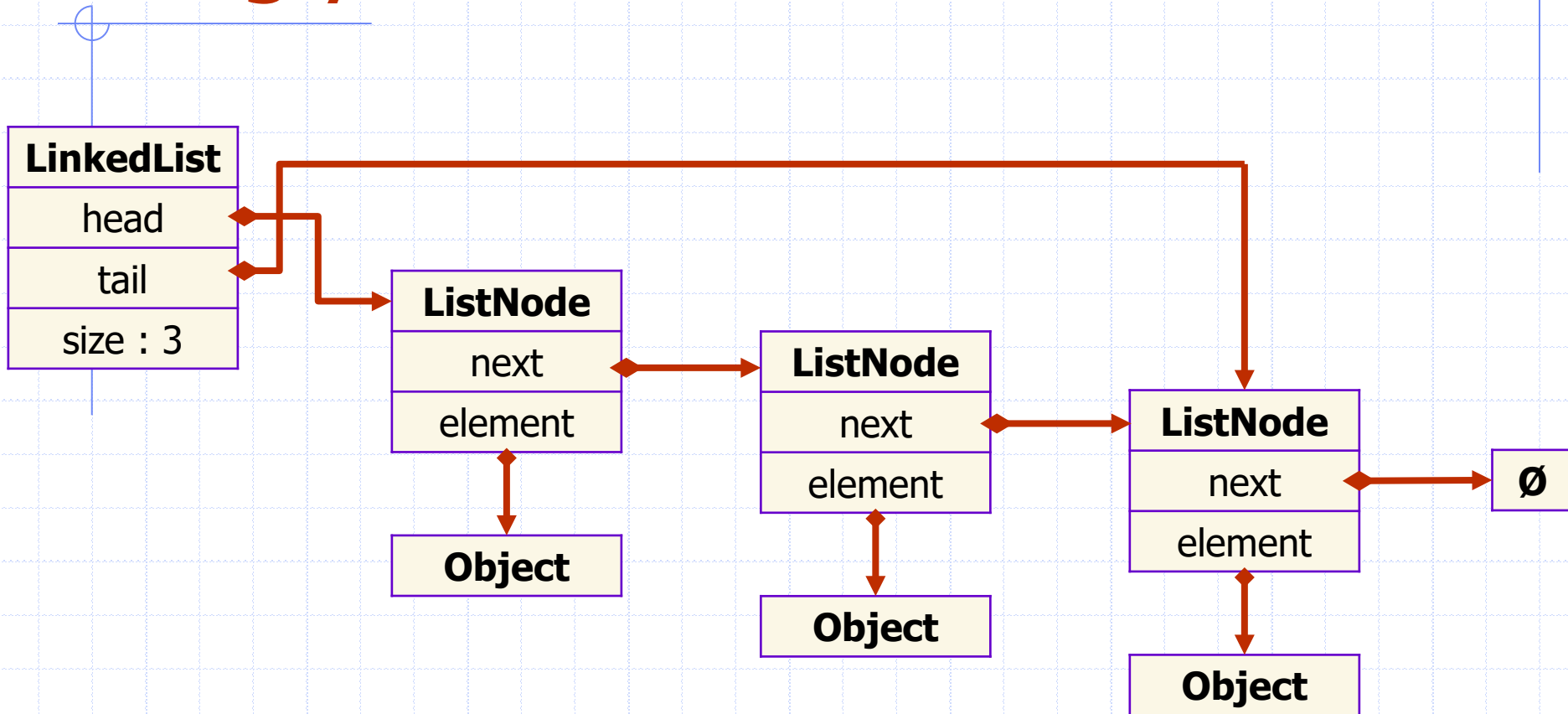


# Singly Linked List

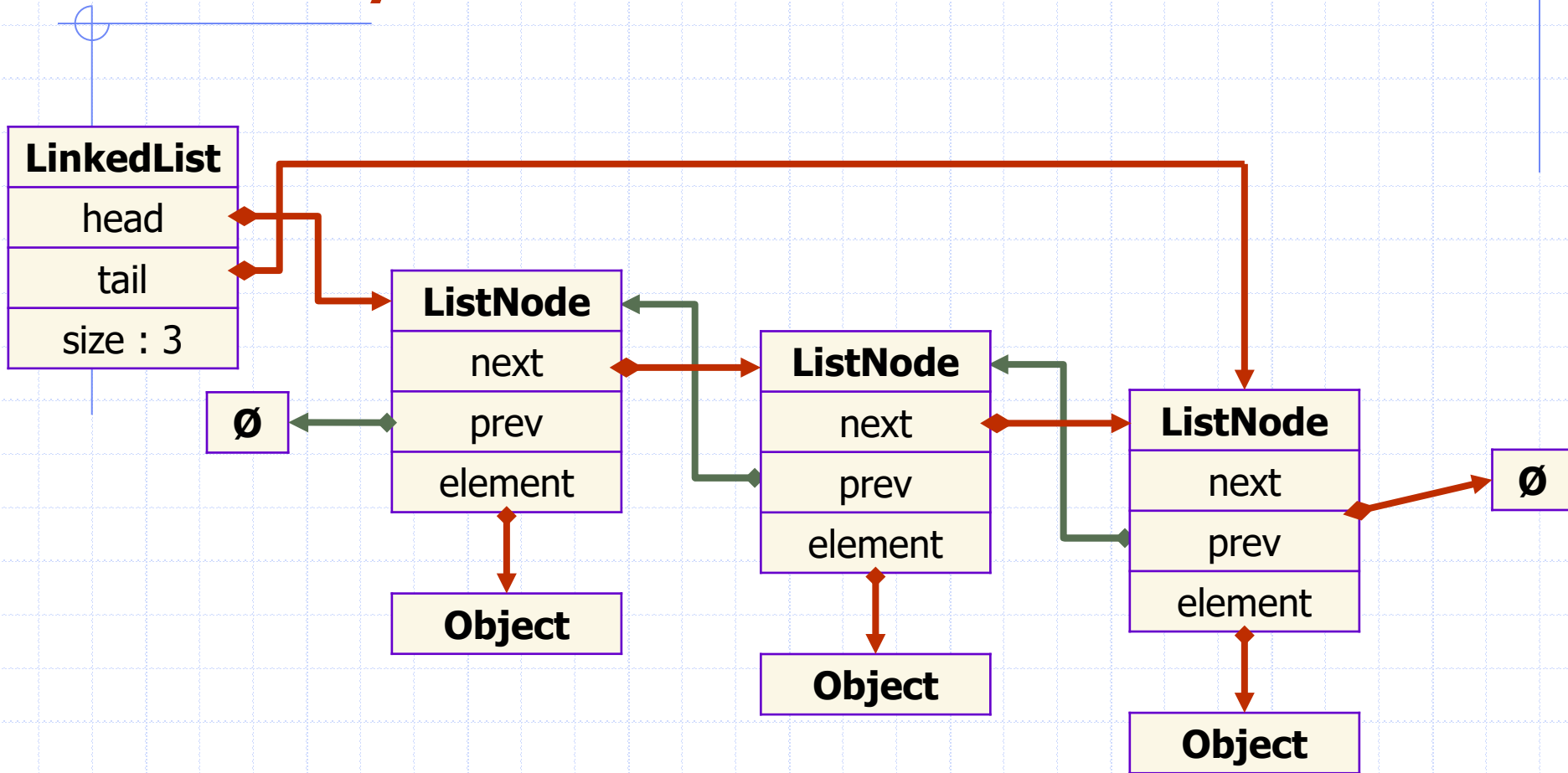
- Concrete data structure
  - sequence of nodes
  - head pointer
- Nodes store
  - element
  - link to next node



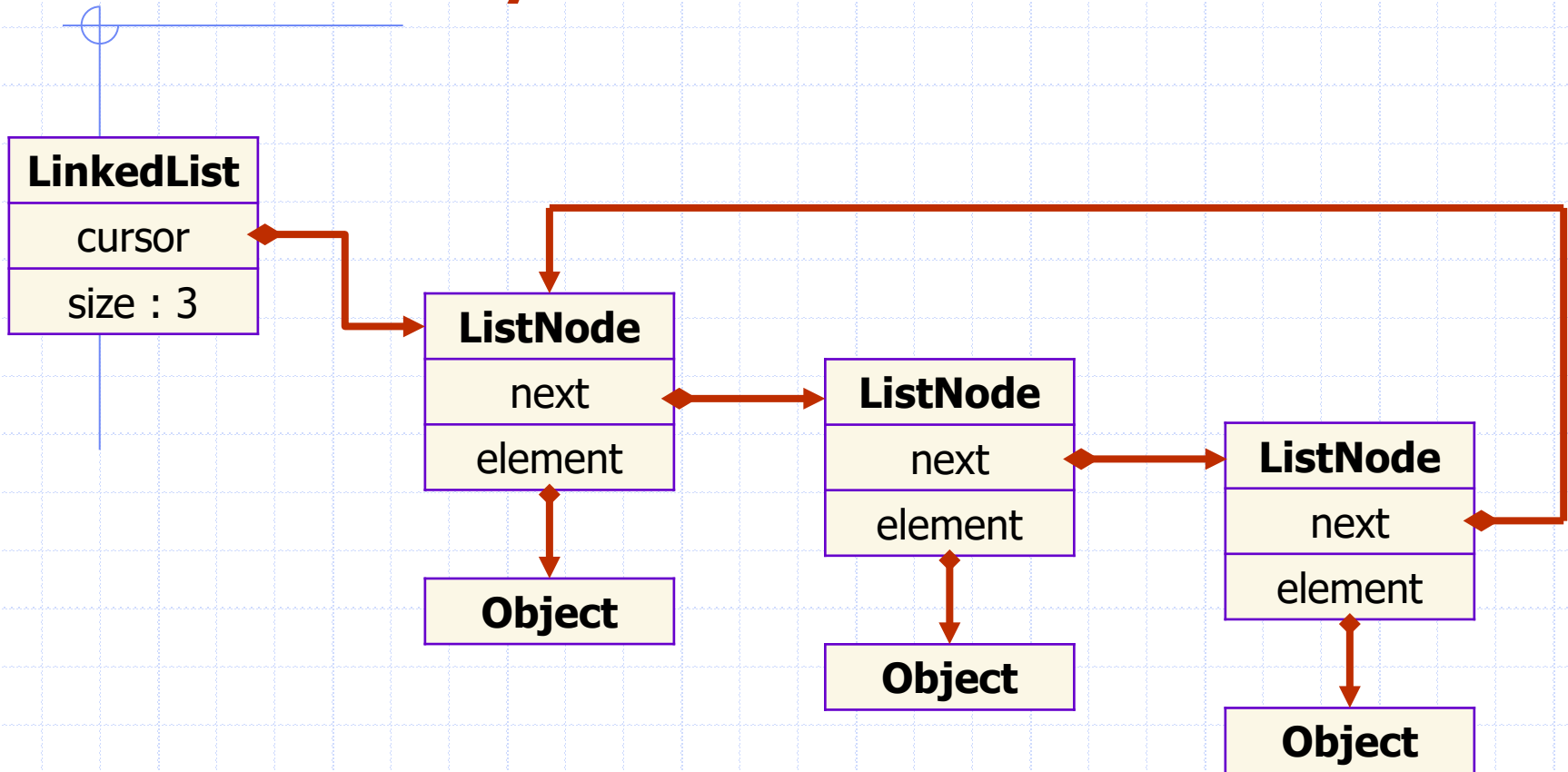
# Singly Linked List



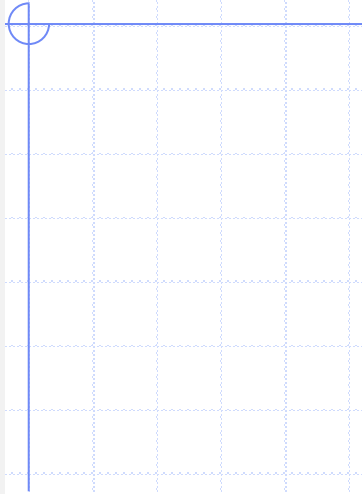
# Doubly Linked List



# Circularly Linked List



# Linked List Sketch



Joel's note to self: We will draw the in-memory layout of a linked list (word RAM)

# A python linked list

```
class Node:
    def __init__(self, data):
        self.__data = data
        self.__next = None

    def set_data(self, data):
        self.__data = data

    ...

    def get_next(self):
        return self.__next
```

```
class LinkedList:
    def __init__(self):
        self.__head = None
        self.__size = 0

    ...

    def insert_to_front(self, node):
        if self.__head != None:
            node.set_next(self.get_head())
        self.__head = node
        self.size += 1

    ...
```

# Linked List Implementation Efficiency

- ❑ Accessing head
  - $O(1)$
- ❑ Iterating over elements
  - $O(n)$
- ❑ Memory usage
  - $O(n)$

# Data Structure Augmentation

- Accessing tail
  - $O(n)$  😞
  - How can we do better? Easy!

```
class LinkedList:  
    def __init__(self):  
        self.__head = None  
        self.__tail = None  
        self.__size = 0
```

...



# Common Bugs

Joel's note to self: We will draw the in-memory layout of a linked list (word RAM)

# Week 3 – Sorting & Linear DS

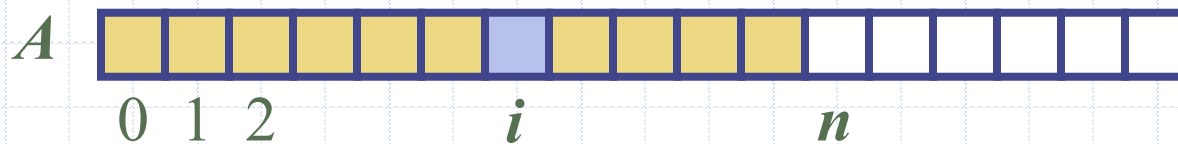
1. Bucket-sort and radix-sort
2. Arrays
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4. Extensible Lists and Amortization
5. Comparing Linear Structures

# Example: Sequence of List operations

Method	Return Value	List Contents
add(0, A)	—	(A)
add(0, B)	—	(B, A)
get(1)	A	(B, A)
set(2, C)	<i>error</i>	(B, A)
add(2, C)	—	(B, A, C)
add(4, D)	<i>error</i>	(B, A, C)
remove(1)	A	(B, C)
add(1, D)	—	(B, D, C)
add(1, E)	—	(B, E, D, C)
get(4)	<i>error</i>	(B, E, D, C)
add(4, F)	—	(B, E, D, C, F)
set(2, G)	D	(B, E, G, C, F)
get(2)	G	(B, E, G, C, F)

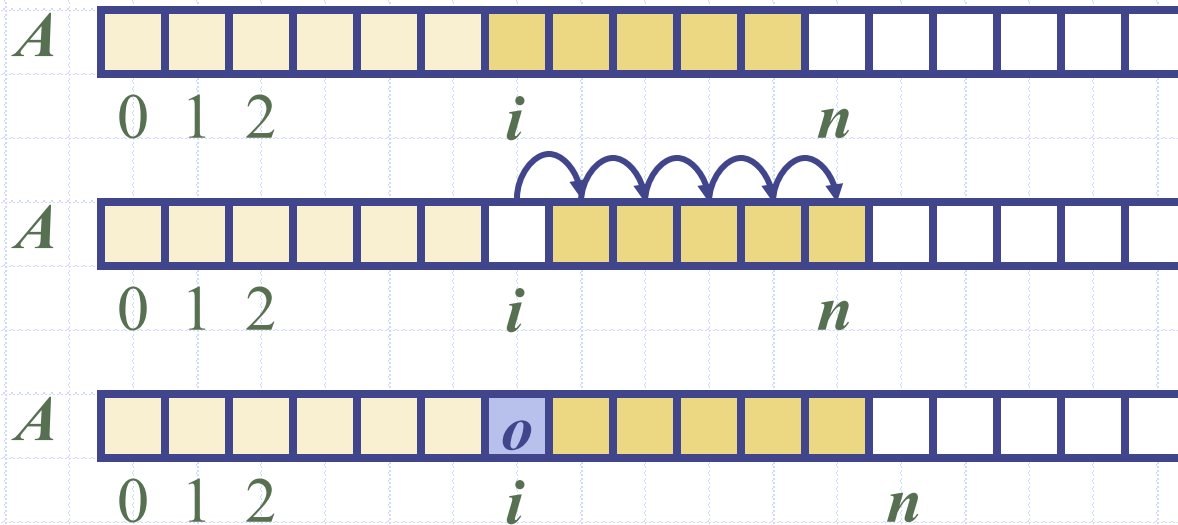
# Array Lists = Extensible Lists = Growable Arrays = Python Lists = ...

- An obvious choice for implementing the list ADT is to use an array,  $A$
- `get(i)` and `set(i,e)`



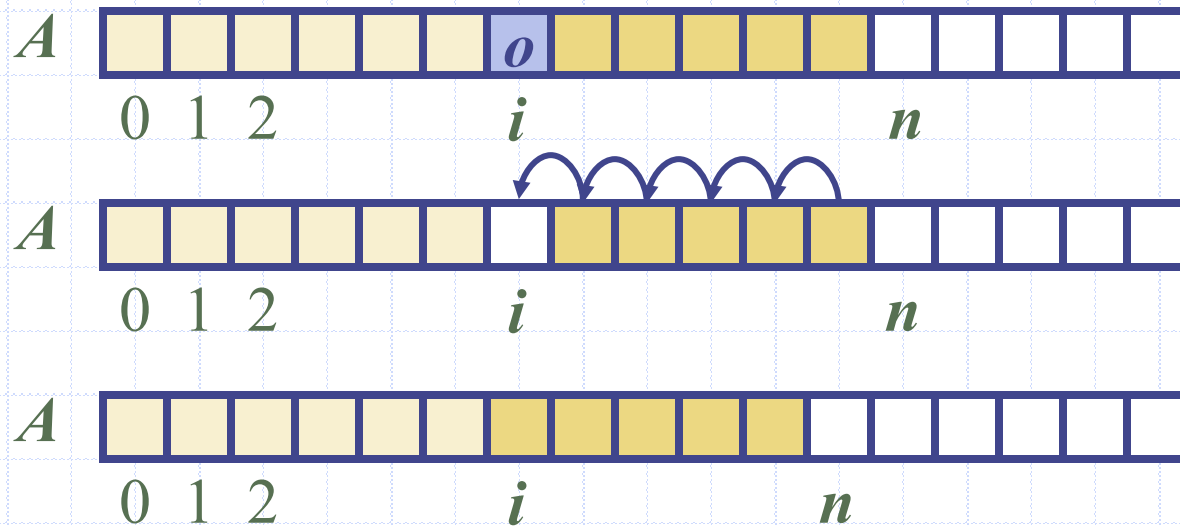
# Insertion

- *add*( $i, o$ ) – make room for the new element
- Worst case ( $i = 0$ ), takes  $O(n)$  time



# Removal

- ❑ *remove*( $i$ ) – fill the hole left by the removed element
- ❑ Worst case ( $i = 0$ ), takes  $O(n)$  time



# Performance

- Array-based implementation of a dynamic list
  - space used by the data structure is  $O(n)$
  - accessing the element at  $i$  takes  $O(1)$  time
  - *add* and *remove* run in  $O(n)$  time
- *add* – when array is full
  - instead of throwing an exception
  - replace the array with a larger one ...

# Extensible List

- **push(o)/add(o)/append(o)**: adds element **o** at the end of the list
- How large should the new array be if we run out of capacity?
  - **Incremental strategy**
    - increase size by a constant  $c$
  - **Doubling strategy**
    - double the size



# Extensible List

- **push(o)/add(o)/append(o)**: adds element **o** at the end of the list

## Algorithm *push(o)*

**if**  $capacity = S.length - 1$  **then**

$A \leftarrow$  **new array of size** *[something larger]*

$capacity =$  *[new larger value]*

**for**  $i \leftarrow 0$  **to**  $n-1$  **do**

$A[i] \leftarrow S[i]$       *// copy stuff!*

$S \leftarrow A$       *// update reference to new list*

$S[n] \leftarrow o$

# Comparison of Strategies

- Compare incremental and doubling strategies
  - Analysing total time  $T(n)$  needed to perform a series of  $n$  push operations
- **Amortised time** of a push operation is the average time taken by a push operation over the series of operations
  - i.e.  $T(n) \div n$
  - *Amortization Intuition: Chocolate...*

# Incremental Strategy Analysis

- Over  $n$  push operations, array is replaced  $k = n/c$  times, where  $c$  is a constant
  - EG: If we extend by  $c=4$  elements each time:
    - ◆ After 4 pushes, we extend ( $n = 4, k = 4/4 = 1$ )
    - ◆ After 4 more pushes, we extend again ( $n = 8, k = 8/4 = 2$ )
    - ◆ ...
    - ◆ After  $n$  pushes, we have extended  **$k=n/c$**  times.

# Incremental Strategy Analysis

- Over  $n$  push operations, array is replaced  $k = n/c$  times, where  $c$  is a constant
- Total time  $T(n)$  of a series of  $n$  push operations is proportional to

$$\begin{aligned}n + c + 2c + 3c + 4c + \dots + kc &= \\n + c(1 + 2 + 3 + \dots + k) &= \\n + c(k(k + 1) / 2)\end{aligned}$$

- Since  $c$  is a constant,  $T(n)$  is  $O(n + k^2)$ , i.e.  $O(n^2)$
- Thus, the amortised time of push is  $T(n) / n = n^2/n = O(n)$

# Doubling Strategy Analysis

- Array is replaced  $k = \log_2 n$  times
- Total time  $T(n)$  of a series of  $n$  push operations is proportional to

$$\begin{aligned} & n + 1 + 2 + 4 + 8 + \dots + 2^k \\ &= n + 2^{k+1} - 1 \text{ [geometric series]} \\ &= n + 2(2^k) - 1 \\ &= n + 2(2^{\log n}) - 1 \\ &= 3n - 1 \end{aligned}$$

- $T(n)$  is  $O(n)$
- Amortised time of push is  $T(n) \div n = O(1)$

# Further Reading and Up Next

- ❑ Data Structures and Algorithms in Python
  - Chapter 5
  - Chapter 7.1 to 7.3
  - Chapter 12.4
- ❑ Introduction to Algorithms
  - Chapter 8
  - Chapter 10.1, 10.2