# WHY MODEL? AN INTRODUCTION TO MODELING

Barbra Dickerman, Joy Shi, Miguel Hernán
DEPARTMENT OF EPIDEMIOLOGY



# Learning objectives At the end of this lecture you will be able to

- Explain what a model is
- Explain why models are used in research
- Describe the most commonly used models

## ☐ Key concepts

- Estimand, estimator, estimate
- Consistent estimator
- Parametric and nonparametric estimators
- Linear and logistic regression

# Plan for today

- A. The need for models: A motivation
- B. Types of models frequently used in epidemiology
- C. Linear regression and logistic regression

Modeling

# A. The need for models: A noncausal motivation

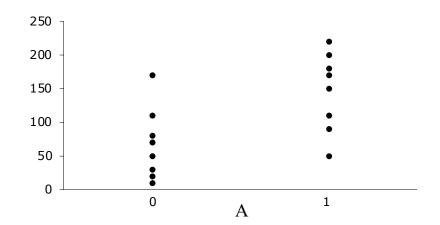
- ☐ Consider the following study
- ☐ Study population: 16 individuals living with HIV
  - Not 16,000 or 16 million
- $\square$  Predictor: antiretroviral therapy A
  - Each individual receives certain level *a*
- $\square$  Outcome: CD4 cell count at the end of follow-up Y
  - A continuous variable

# Goal of our predictive analysis

- $\square$  To estimate the mean of Y among individuals with treatment level A=a in the population from which these individuals were randomly sampled
- $\square$  This conditional population mean is represented as E[Y|A=a]
  - **E**xpected value of Y given (among those with) treatment A equal to a

Modeling 5

# Dichotomous predictor



| Your best estimate | e of the mean outcome in those receiving A=1 in the population?   | ₩ 0 |
|--------------------|---|-----|
| <b>(A)</b> 200     |   | 0%  |
| <b>(B)</b> 150     |   | 0%  |
| <b>(C)</b> 100     |   | 0%  |
|                    |   |     |
|                    |   |     |
|                    |   |     |
|                    | Start the presentation to see live content. For screen share software, share the entire screen. Get help at <b>pollev.com/app</b> |     |

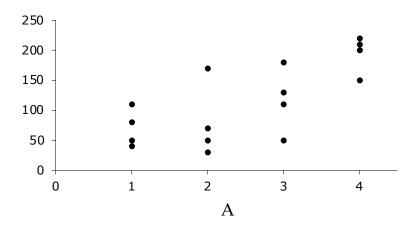
# Estimand, Estimator, Estimate □ The estimand is the unknown population parameter ■ The mean of Y among those with A=1 in the population □ An estimator is some function of the data that is used to estimate the estimand ■ The sample average of Y among those with A=1 □ An estimate is the result of applying the estimator to a particular data set ■ 146.25

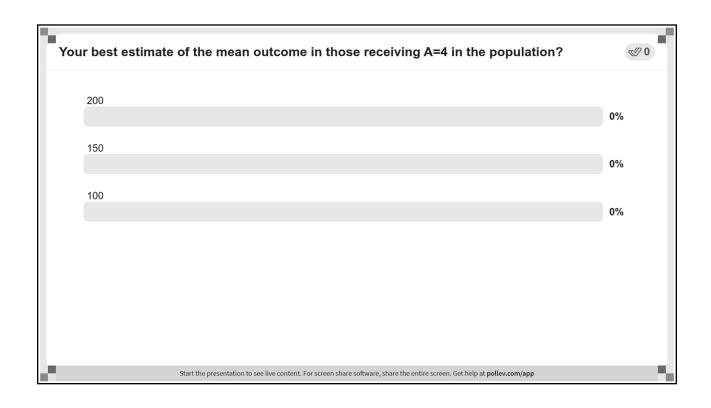
## A consistent estimator

- □ "The larger the sample size, the closer the sample estimate to the population estimand"
  - Formally: an estimator provides a consistent estimate  $\hat{\mathbb{E}}[Y|A=a]$  of the estimand  $\mathbb{E}[Y|A=a]$  if the difference  $\hat{\mathbb{E}}[Y|A=a] \mathbb{E}[Y|A=a]$  approaches zero as the sample size increases towards infinity
  - The hat ^ commonly used to refer to estimates
- ☐ Examples:
  - Consistent estimator of the population mean: the sample average
  - Inconsistent estimator of the population mean: the value of the first observation in the data
- ☐ We require that estimators be consistent

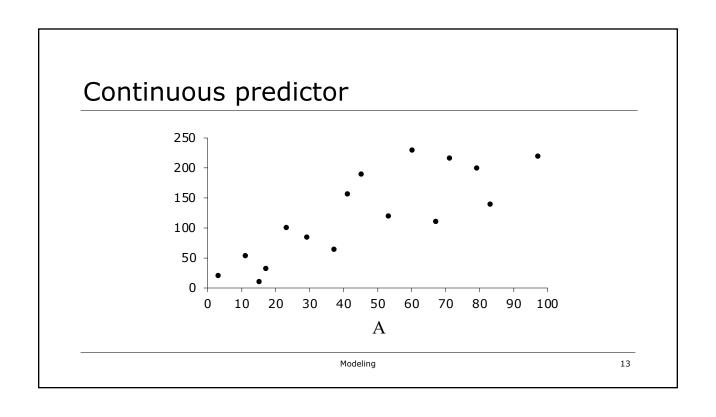
Modeling 9

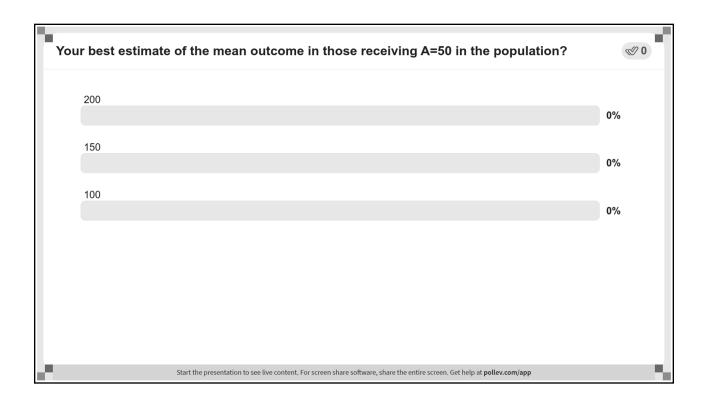
# Polytomous predictor





# Discrete predictor (dichotomous or polytomous) ☐ As the number of categories increase, the number of individuals per category decreases ☐ Variance increases ☐ But the sample average is still a consistent estimator of the population mean ☐ The average of Y in each level of A in our sample consistently estimates the mean of Y in each level of A in the population





# Continuous predictor

- ☐ Conceptually, a categorical variable with an infinite number of categories
  - What if there are no individuals with treatment value A=a?
  - Cannot use the average of Y in each level of A
- $\square$  In general, it is impossible to consistently estimate E[Y|A=a] by using the data only
- ☐ We need to supply additional information
  - A priori knowledge that is not in the data

Modeling 15

## An example of a priori information

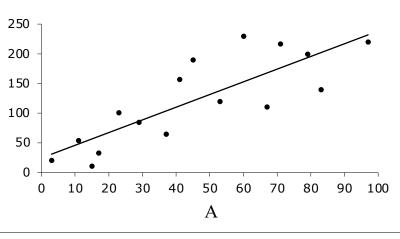
- $\square$  The mean of *Y* follows a straight line
  - $\blacksquare$  the mean of Y is directly proportional to the value of A
  - The mean of Y is  $\theta_0$  when A=0, and increases (or decreases) by  $\theta_1$  units per unit of A
- ☐ Or, more compactly,

$$E[Y|A] = E[Y|A=0] + \theta_1 A = \theta_0 + \theta_1 A$$

- $\blacksquare$   $\theta_0$  is known as the intercept
- $\blacksquare$   $\theta_1$  is known as the slope

# A linear model

$$E[Y|A] = \theta_0 + \theta_1 A$$

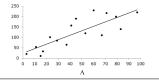


Modeling

17

A linear model

 $E[Y|A] = \theta_0 + \theta_1 A$ 



- $\square$  The parameters  $\theta_0$  and  $\theta_1$  are consistently estimated by ordinary least squares estimation
- ☐ Find the line that results in the minimum sum of squared differences between each point and the straight line
  - lacksquare  $\theta_0$  is estimated as the point at which the line crosses (intercepts) the vertical axis
  - $\blacksquare$   $\theta_1$  is estimated as the slope of the line

Modeling

# Smoothing with a linear model

$$E[Y|A] = \theta_0 + \theta_1 A$$

- $\square$  One can use the estimates of  $\theta_0$  and  $\theta_1$  to predict the mean of Y for any possible value A=a, including those values not present in the data
- $\square$  The mean of Y in those with A=a, i.e.,  $\mathrm{E}[Y|A=a]$  is estimated by borrowing information from individuals with A not equal to a
  - Because ordinary least squares estimation uses all data points to find the best line

Modeling 19

# Definition of Model: a restriction on the possible values of the quantity of interest

- $\square$  Consider our linear model for the conditional mean  $\mathrm{E}[Y|A] = \theta_0 + \theta_1 A$ 
  - the mean of Y for A=50 cannot take any value
  - It is restricted to be in between the mean of *Y* for *A*=40 and the mean of *Y* for *A*=60
  - The restriction is encoded by parameters like  $\theta_0$ ,  $\theta_1$
- ☐ How do we choose the restrictions of the model?
  - Using a priori knowledge, if available, or
  - Making unverifiable (modeling) assumptions

## Parametric and nonparametric estimators

- □ Nonparametric estimators
  - Use ONLY the data
  - Do not impose a priori restrictions on the value of the estimate
  - Example: the sample average
- ☐ Parametric estimators
  - Use the data plus a priori restrictions on the value of the estimate
  - Example: the above linear model

Modeling 21

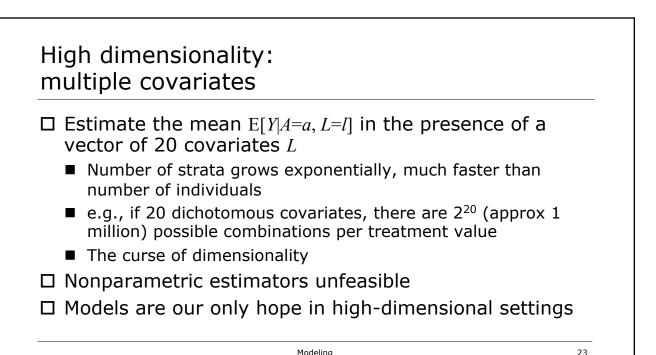
# Nonparametric models: not really models

- ☐ No a priori restrictions because they have
  - as many parameters as quantities the model can estimate
  - also known as saturated models
- ☐ Example: for a dichotomous treatment

$$E[Y|A] = \theta_0 + \theta_1 A$$

is not really a model

■ Just says that E[Y|A=1] is equal to E[Y|A=0] plus a quantity  $\theta_1$ , which is of course always true, so there is no restriction

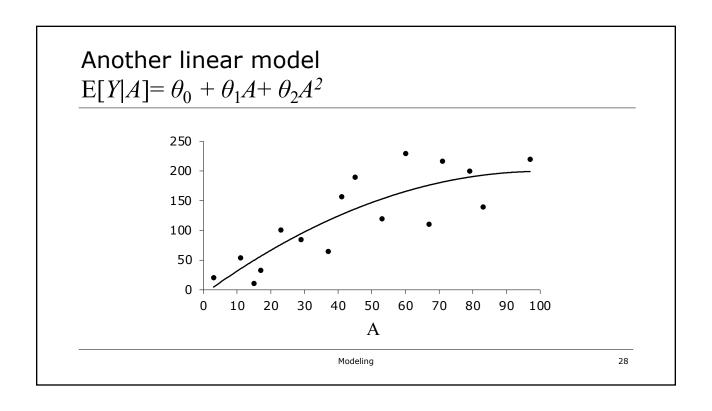


# The price of modeling ☐ Models allow us to estimate quantities that cannot be nonparametrically consistently estimated ☐ But not a free lunch ☐ Parametric inference correct only if the model is correctly specified ☐ Model specification can be empirically checked only to some extent ☐ Causal inference with models requires the condition of no model misspecification

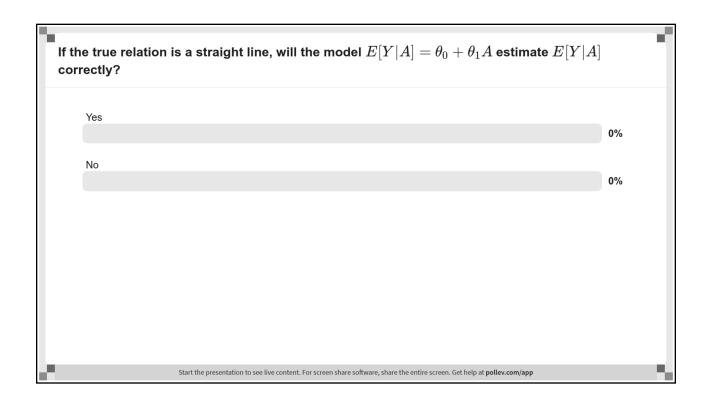
| epidemiology |
|--------------|
|              |
| ssion        |
|              |
| ssion        |

| □ Linea | r models        |            |  |
|---------|-----------------|------------|--|
| □ Gene  | ralized linear  | models     |  |
| □ Gene  | ralized additi  | ve models  |  |
| □ Mode  | els for surviva | l analysis |  |
| > Knov  | ın as regressi  | on models  |  |

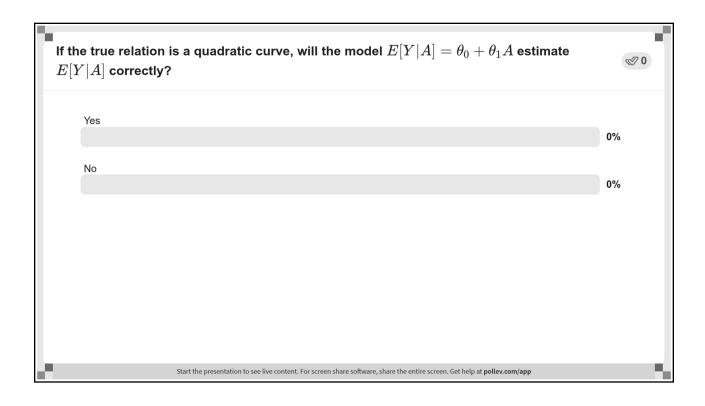
A linear model 
$$E[Y|A] = \theta_0 + \theta_1 A$$



### We need to decide which model to use to estimate E[Y|A]☐ Problem: we don't know what the true 150 relation between A and 100 50 Y is ■ a straight line or a curve? 250 ☐ If we knew the shape of the true relation, it'd 150 100 be easy to decide. Right? Modeling 29

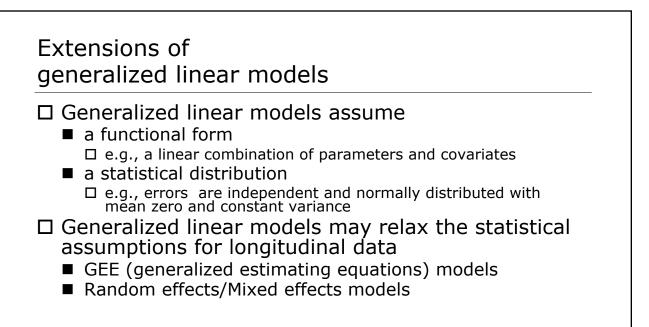


| If the true relation $E[Y A]$ correctly? | is a straight line, will the model $E[Y A] = 	heta_0 + 	heta_1 A + 	heta_2 A^2$ estimate                                   | Ĭ    |
|--|--|------|
| Yes                                      |  | 0%   |
| No                                       |  | 0%   |
|  |  | 0 78 |
|  |  |      |
|  |  |      |
|  |  |      |
|  | Start the presentation to see live content. For screen share software, share the entire screen. Get help at pollev.com/app | - N  |



| Which linear mode relation? | el imposes more restrictions on (makes more assumptions about) the t  | rue |
|-----------------------------|---|-----|
| The straight line           |   | 0%  |
| The quadratic curv          | ve  | 0%  |
|                             |   |     |
|                             |   |     |
|                             |   |     |
|                             | Start the presentation to see live content. For screen share software, share the entire screen. Get help at <b>pollev.com/app</b> |     |

| $E[V \Lambda] = \theta_1 + \theta_2 \Lambda$ |   |
|--|---|
| $E[I A] = \theta_0 + \theta_1 A$             |   |
|  |   |
| $ln(E[Y A]) = \theta_0 + \theta_1 A$         |   |
|  |   |
|  |   |
| 1(77574 47)                                  |   |
| $logit(E[Y A]) = \theta_0 + \theta_1 A$      |   |
|  | $E[Y A] = \theta_0 + \theta_1 A$ $ln(E[Y A]) = \theta_0 + \theta_1 A$ $logit(E[Y A]) = \theta_0 + \theta_1 A$ |



Modeling

# Generalized additive models □ Like generalized linear models but they replace the linear function of covariates by a sum of functions of the covariates ■ Examples of functions: moving average, locally-weighted running mean □ E[Y|A=a] may be estimated by borrowing information from some, but not all, individuals with A not equal to a ■ More "nonparametric", varying degrees of smoothing

# Models for survival (failure time) data Need to accommodate censoring Parametric Exponential Weibull Semiparametric Cox proportional hazards model Accelerated failure time model Baseline hazard is unspecified (not restricted a priori)

Modeling

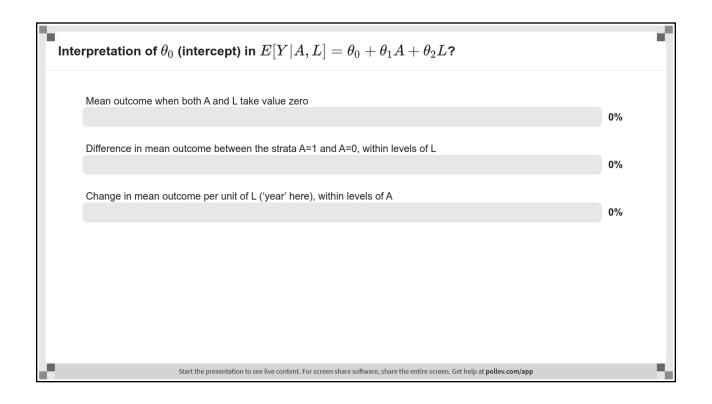
# Plan for today

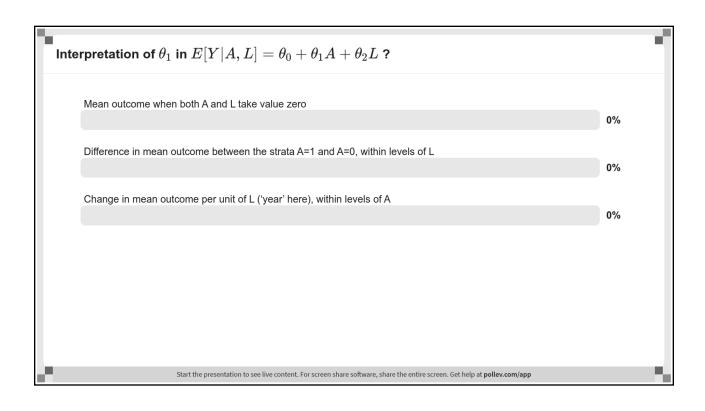
- A. The need for models: A motivation
- B. Types of models frequently used in epidemiology
- C. Linear regression and logistic regression

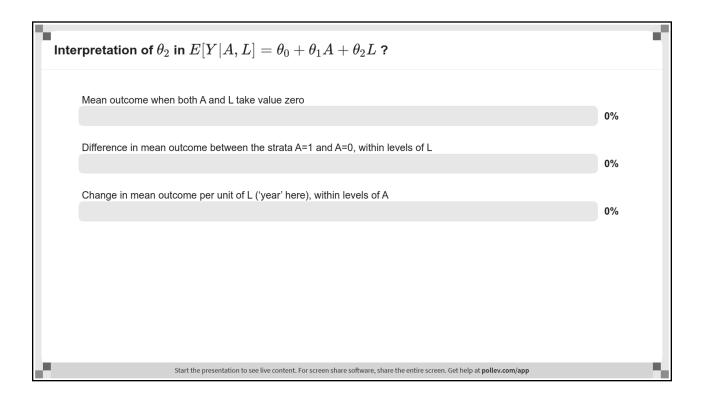
Modeling 38

| C. Linear and logistic regression   |    |
|---|----|
| ☐ Two types of general linear models  |    |
| ☐ Linear regression for continuous outcomes<br>■ e.g., blood pressure           |    |
| ☐ Logistic regression for dichotomous outcomes<br>■ e.g., death (1: yes, 0: no) |    |
|   | 39 |

| Linear regression   |    |
|---|----|
| <ul> <li>□ Can be used to estimate the mean Y conditional on treatment A and covariates L</li> <li>□ For example</li> <li>■ Y is weight gain</li> <li>■ A smoking cessation (1: yes, 0: no)</li> <li>■ L is age (in years)</li> </ul> |    |
| □ Consider the model $\mathrm{E}[Y A,L] = \theta_0 + \theta_1 A + \theta_2 L$ ■ Parameter estimates for $\theta_0$ , $\theta_1$ , $\theta_2$ are obtained by ordinary least squares or maximum likelihood (see Biostatistics courses) |    |
| Modeling  | 40 |







### Predicted values

 $\hat{E}[Y|A=a, L=l]$ 

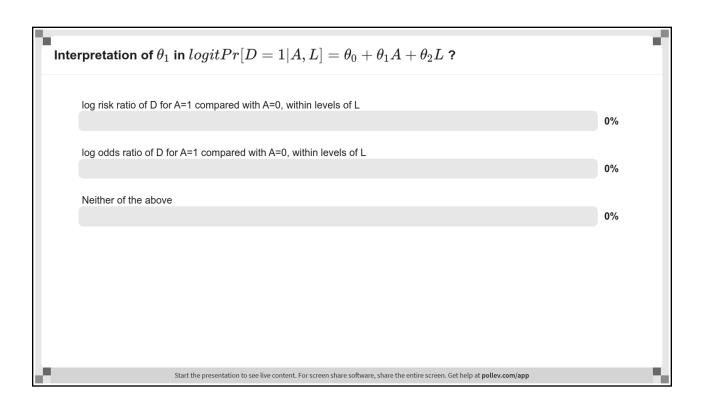
- $\square$  The estimates of  $\mathrm{E}[Y|A=a,L=l]$  for each combination of values of treatment A=a and covariates L=l
  - Obtained by replacing the parameters  $\theta_0$ ,  $\theta_1$ ,  $\theta_2$  by their estimates  $\hat{\theta}_0$ ,  $\hat{\theta}_1$ ,  $\hat{\theta}_2$
  - Example:
    - $\Box$  for treated individuals aged 30 years, the predicted value is  $\Box$   $\triangle[Y|A=a, L=l] = \widehat{\theta}_0 + \widehat{\theta}_1 \times 1 + \widehat{\theta}_2 \times 30$
  - Residual: the difference between an individual's value of Y and the predicted value  $\hat{\mathbb{E}}[Y|A=a,L=l]$  for their combination of values of A and L

# Logistic regression

- $\square$  Can be used to estimate the probability of an event D conditional on treatment A and covariates L
- ☐ Consider the logistic model

logit Pr[
$$D$$
=1| $A$ , $L$ ]=  $\theta_0 + \theta_1 A + \theta_2 L$ 

- *D* is death (1: yes, 0: no)
- $\blacksquare$  *A* is smoking cessation (1: yes, 0: no)
- $\blacksquare$  *L* is age (in years)



### See Homework #1

- For a detailed interpretation of the parameters of logistic models and a description of the logit function
- ☐ See Biostatistics courses
  - For a description of maximum likelihood estimation to obtain parameters estimates for  $\theta_0$ ,  $\theta_1$ ,  $\theta_2$

Modeling 47

### Predicted values

- $\square$  The estimates of logit  $\Pr[D=1|A=a,L=l]$  for each combination of values of treatment A=a and covariates L=l
  - Obtained by replacing the parameters  $\theta_0$ ,  $\theta_1$ ,  $\theta_2$  by their estimates  $\hat{\theta}_0$ ,  $\hat{\theta}_1$ ,  $\hat{\theta}_2$
- $\square$  To get the probability  $\Pr[D=1|A=a, L=l]$  rather than the logit of the probability, we need to do some algebra
  - In practice, computers do it for us
  - You will do it yourself in Homework #1

# Why logistic regression for dichotomous outcomes? □ Because the logit transformation ensures that the predicted values will always be between 0 and 1 ■ regardless of the values of the parameter estimates and the covariates □ Other transformations (e.g., probit) also have this property ■ but the logit transformation is by far the most widely used in epidemiologic research

Modeling

| Readings                          |                                  |          |
|-----------------------------------|----------------------------------|----------|
| Readings                          |                                  |          |
| ☐ Chapter 11  ■ Hernán MA, Robins | s JM. <i>Causal Inference: W</i> | 'hat If. |
|                                   |                                  |          |
|                                   |                                  |          |
|                                   |                                  |          |
|                                   |                                  |          |
|                                   | Modeling                         | 50       |

# Progress report

- 1. Introduction to modeling
- 2. Stratified analysis: Outcome regression