Homework 4

September 19, 2019

0.0.1 Problem 3

```
[315]: import numpy as np
       import matplotlib.pyplot as plt
       import scipy.integrate as integrate
       def create_gram(N):
           phi = lambda z: np.exp(-z**2)
           gram_matrix = np.zeros((N,N))
           for i in range(N):
               for j in range(N):
                   matrix_elem = lambda z: phi(N*z - (i+1) + 0.5)*phi(N*z - (j+1) + 0.
        ⇒5)
                   gram_matrix[i][j] = integrate.quad(matrix_elem, -np.inf, np.inf)[0]
           return gram_matrix
       def plot_basis(N, n):
          G = create_gram(N)
           H = np.linalg.inv(G)
           x = np.arange(0,1,0.001)
           y = np.zeros(len(x))
           for t in range(len(y)):
               y[t] = dual_basis(N, n, x[t], H)
           plt.plot(x, y)
           plt.show()
       def dual_basis(N, n, t, H):
           phi = lambda x: np.exp(-x**2)
           dual_basis = 0
```

```
for l in range(N):
        temp_phi = phi((N*t) - (1+1) + 0.5)
        dual_basis += (H[n][1])*temp_phi
    return dual_basis
def plot_kernel(N, tau):
    phi = lambda x: np.exp(-x**2)
    G = create_gram(N)
    H = np.linalg.inv(G)
    x = np.arange(0,1,0.001)
    y = np.zeros(len(x))
    for t in range(len(y)):
        for n in range(N):
            y[t] += phi((N*tau) - (n+1) + 0.5)*dual_basis(N, n, x[t], H)
    plt.plot(x, y)
    plt.show()
def plot_kernel_2d(N):
    phi = lambda x: np.exp(-x**2)
    G = create_gram(N)
    H = np.linalg.inv(G)
    x = np.arange(0,1,0.005)
   tau = np.arange(0,1, 0.005)
    y = np.zeros((len(x), len(tau)))
    for t in range(len(y)):
        for j in range(len(tau)):
            for n in range(N):
                y[t][j] += phi((N*tau[j]) - (n+1) + 0.5)*dual_basis(N, n, x[t],_u)
H)
    plt.imshow(y)
    plt.show()
def compare_functions(N, t0, t1):
    phi = lambda x: np.exp(-x**2)
    G = create_gram(N)
    H = np.linalg.inv(G)
    alphas = np.random.rand(N)*100
    x = np.arange(t0, t1, 0.001)
```

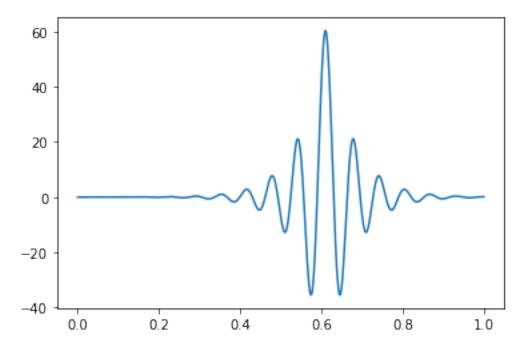
```
y_kernel = np.zeros(len(x))
y_regular = np.zeros(len(x))

for t in range(len(x)):
    temp = np.matmul(np.transpose(alphas), np.transpose(G))
    y_kernel[t] = np.matmul(temp, np.array([dual_basis(N, n, x[t], H) for n_u
in range(N)]))
    y_regular[t] = sum([alphas[i]*phi(N*x[t] - (i+1) + 0.5) for i in_u
range(N)])

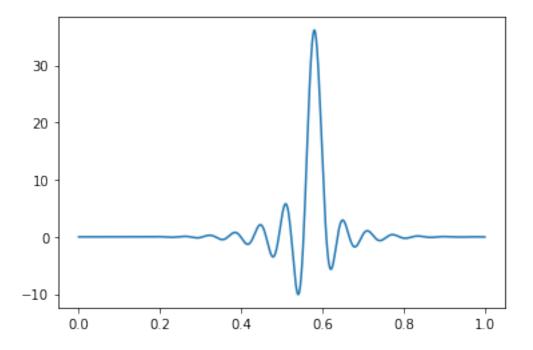
print("Sum Squared Difference Between <f, K> and f(t) = {}".

format(sum(y_kernel - y_regular)))
    print("The difference is negligible and due to rounding error which shows_u
that <f, K> = f(t)")
    plt.plot(x, y_kernel, label="<f, K>")
    plt.plot(x, y_regular, label="f(t)")
    plt.legend()
```

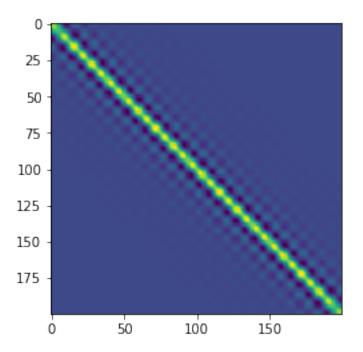
[292]: plot_basis(32, 19)



[267]: plot_kernel(32, .581723)

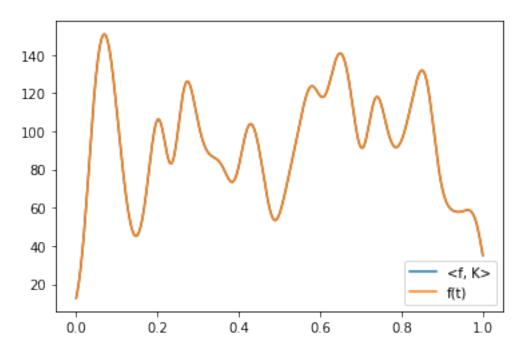


[277]: plot_kernel_2d(32)



[316]: compare_functions(32, 0, 1)

Sum Squared Difference Between <f, K> and f(t) = -2.4993340730361524e-12 The difference is negligible and due to rounding error which shows that <f, K> = f(t)



0.0.2 Problem 4

```
[170]: import scipy.io

mat = scipy.io.loadmat('hw4p4.mat')

u_data = mat['udata']

y_data = mat['ydata']

[171]: def generate_A_matrix(u_data):
    basis = [lambda s,t: s**2, lambda s,t: t**2, lambda s,t: s*t, lambda s,t:
    →s, lambda s,t: t, lambda s,t: 1]

A = np.zeros((100,6))

for i in range(100):
    for j in range(6):
        A[i][j] = basis[j](u_data[0][i], u_data[1][i])
```

return A

```
[226]: def solve_least_squares(u_data, y_data):
    A = generate_A_matrix(u_data)
    A_t = np.transpose(A)

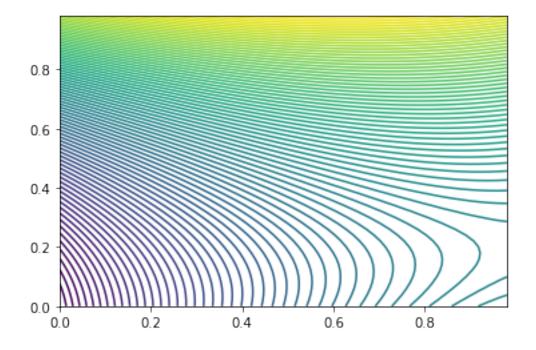
    A_t_A_inv = np.linalg.inv(np.matmul(A_t, A))

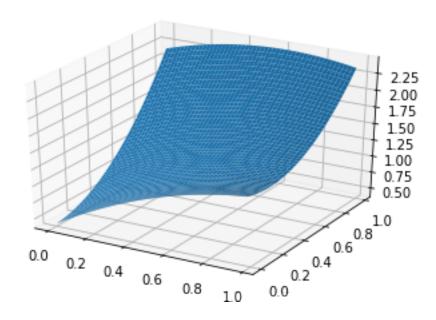
alphas = np.matmul(np.matmul(A_t_A_inv, A_t), y_data)

return alphas

alphas = solve_least_squares(u_data, y_data)
```

```
[259]: from mpl_toolkits.mplot3d import Axes3D
       from matplotlib import cm
       def plot_3d(alphas):
           fig = plt.figure()
           ax = fig.gca(projection='3d')
           X = np.arange(0,1,0.02)
           Y = np.arange(0,1,0.02)
           X, Y = np.meshgrid(X, Y)
           Z = alphas[0]*X**2 + alphas[1]*Y**2 + alphas[2]*X*Y + alphas[3]*X + L
        \rightarrowalphas[4]*Y + alphas[5]
           surface = ax.plot_surface(X, Y, Z)
           plt.show()
       def contour_plot(alphas):
           X = np.arange(0,1,0.02)
           Y = np.arange(0,1,0.02)
           X, Y = np.meshgrid(X, Y)
           Z = alphas[0]*X**2 + alphas[1]*Y**2 + alphas[2]*X*Y + alphas[3]*X +_{\square}
        \rightarrowalphas[4]*Y + alphas[5]
           plt.contour(X, Y, Z, 100)
           plt.show()
       contour_plot(alphas)
```





0.0.3 Problem 5

```
[287]: def generate Q matrix():
           G = np.matrix([[lambda s: 2*s, lambda s: 0, lambda s: s,
                            lambda s: 1, lambda s: 0, lambda s: 0],
                           [lambda s: 0, lambda s: 2*s, lambda s: s,
                            lambda s: 0, lambda s: 1, lambda s: 0]])
           G_t = np.transpose(G)
           Q = np.zeros((6,6))
           for i in range(6):
               for j in range(6):
                   Q[i][j] = integrate.quad(lambda x: G_t[i,0](x)*G[0,j](x), 0, 1)[0]_{U}
        \rightarrow+ integrate.quad(lambda x: G_t[i,1](x)*G[1,j](x), 0, 1)[0]
           return Q
       def gradient_ridge_regression(xs, ys, delta):
           A = generate_A_matrix(xs)
           \#Q = generate\_Q\_matrix() \ didn't \ work \ for \ some \ reason
           Q = np.matrix([[4/3, 0, 1/2, 1, 0, 0],
                           [0, 4/3, 1/2, 0, 1, 0],
                           [1/2, 1/2, 2/3, 1/2, 1/2, 0],
                           [1, 0, 1/2, 1, 0, 0],
                           [0, 1, 1/2, 0, 1, 0],
                           [0, 0, 0, 0, 0, 0]])
           At_A = np.matmul(np.transpose(A), A)
           At_A_reg = At_A + (delta*Q)
           At_A_reg_inv = np.linalg.inv(At_A_reg)
           x hat = np.matmul(np.matmul(At_A_reg_inv, np.transpose(A)), ys)
           return x_hat
       def compare_deltas(d1, d2, d3):
           x_hat1 = gradient_ridge_regression(u_data, y_data, d1)
           x_hat2 = gradient_ridge_regression(u_data, y_data, d2)
           x_hat3 = gradient_ridge_regression(u_data, y_data, d3)
           print(np.transpose(x_hat1))
           print(np.transpose(x_hat2))
           print(np.transpose(x_hat3))
```