

VIDEO 1

$$G(s) = \frac{20(s+5)}{s(s+1)(s+4)} \quad \left\{ \begin{array}{l} 0\% = 9,5\% \\ t_s = 0,74 \text{ seg} \end{array} \right.$$

$$U(s) \rightarrow \left[\frac{1}{s^3 + 5s^2 + 4s} \right] \xrightarrow{X_1(s)} \left[0s^2 + 20s + 100 \right] \rightarrow Y(s)$$

$$\frac{X_1(s)}{U(s)} = \frac{1}{s^3 + 5s^2 + 4s}$$

$$(s^3 + 5s^2 + 4s) X_1(s) = U(s)$$

$$\ddot{\dot{x}}_1 + 5\dot{x}_1 + 4\dot{x}_1 = u$$

\downarrow \downarrow \downarrow
 x_3 x_3 x_2

$$x_1 = x_1$$

$$x_2 = \dot{x}_1$$

$$x_3 = \dot{x}_2 = \ddot{x}_1$$

$$\dot{x}_3 = \ddot{x}_1$$

$$\dot{x}_3 = -5x_3 - 4x_2 + u \quad (1)$$

$$Y(s) = (b_2 s^2 + b_1 s + b_0) X_1(s)$$

$$= (0s^2 + 20s + 100) X_1(s)$$

$$= (20s + 100) X_1(s)$$

$$= 20 \dot{x}_1 + 100 x_1 \Rightarrow y = 20x_2 + 100x_1 \quad (2)$$

\downarrow \downarrow
 x_2 x_1

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -4 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 100 & 20 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$7.05 = e^{-\left(\frac{z\pi}{\sqrt{1-z^2}}\right)} \times 100$$

$$0.075 = e^{-\left(\frac{z\pi}{\sqrt{1-z^2}}\right)}$$

$$\ln(0.075) = \ln\left(e^{-\left(\frac{z\pi}{\sqrt{1-z^2}}\right)}\right)$$

$$-2.3539 = \frac{-z\pi}{\sqrt{1-z^2}} \rightarrow \left(2.3539(\sqrt{1-z^2})\right)^2 = (z\pi)^2$$

$$5.5407(1-z^2) = z^2\pi^2$$

$$5.5407 - 5.5407z^2 = z^2\pi^2$$

$$5.5407 = z^2\pi^2 + 5.5407z^2$$

$$5.5407 = z^2(\pi^2 + 5.5407)$$

$$z^2 = \frac{5.5407}{\pi^2 + 5.5407}$$

$$z = 0.5996$$

S-PLANE

$$s = \sigma + j\omega d$$

$$\omega d = z\omega_n$$

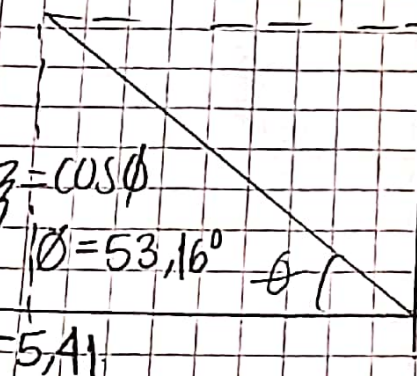
$$t_s = 0.74$$

$$\sigma = \frac{4}{0.74}$$

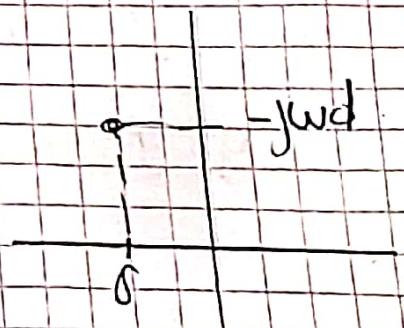
$$\sigma = 5.405$$

$$t_s = \frac{4}{\sigma}$$

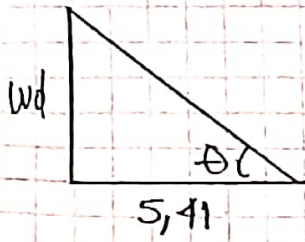
$$\sigma = z\omega_n$$



$$q \cos d(0.5996) = 53.1587$$



$$5.405 = 0.5996\omega_n \rightarrow \omega_n = 9.02$$



$$\tan \theta = \frac{Wd}{5,41}$$

$$\tan(53,16) \times 5,41 = Wd$$

$$Wd = 7,21$$