

# Credit card fraud detection using a clustering approach

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**Abstract**—In this article is presented a comparison of 5 clustering algorithms to segregate data on credit card fraud detection, these algorithms are: k-means, an extension to k-means, fuzzy c-means, subtractive and mountain clustering. These algorithms are first evaluated in the iris dataset, and finally in our case study. Several metrics for finding the clusters are compared and a variation of parameters is performed.

**Index Terms**—Cluster, k-means, credit card, fraud.

## I. INTRODUCTION

Given the current global economic context, increasing efforts are being made to both prevent and detect fraud. Credit card financial products can derive in unsecured and unplanned credit card risks and should not be underestimated. Stopping credit card fraud has become a hot issue in academia and industry. In the field of credit card fraud, the mistake of letting go of fraudulent transactions is much more expensive than mistakenly intercepting normal transactions, and the number of fraudulent transactions is far less than the normal number of transactions.

Clustering, as unsupervised data mining technique, deals with the problem of dividing a given set of entities into meaningful subsets. Clusters resulted from this data segmentation are required to be to be homogeneous and/or well separated, entities within the same group being similar while entities within different groups being dissimilar.

## II. LITERATURE REVIEW

A survey for the methods on fraud detection via clustering is presented in [1]. This survey takes into account the algorithm used and the type of fraud the models are attacking. Is clear that the prevalent method is the k-means, however, some other types of clustering including graph based, hierarchical and density based algorithms were also implemented in the reviewed works.

As an example, some of the methods that make good use of the k-means clustering are: [2], who compares the performance of Support Vector Machines along with clustering algorithms and other classification approaches, and finds put that the former is better at handling highly unbalanced data. [3] uses a Naive Bayes clustering approach (as well as [4]) along with k-means clustering. In these algorithms, there is a clear pattern of hybrid methodologies, some other examples include [5], [6], and [7] that use Hidden Markov models along with k-means clustering

with the objective of reducing the false alarms produced by other algorithms of fraud detection and to include information about past transactions to build a costumer profile. However, some authors like [4] use only Naive Bayes clustering along with a Multi Layer perceptron to build a clustering engine and [8] makes use of fuzzy c-means clustering and builds stochastic models along with artificial neural networks to achieve the same objectives. Finally, hierarchical clustering paired with classification techniques is also useful, as shown in [9].

In this work we aim to use only clustering techniques to analyze a dataset containing some fraudulent transactions and the features associated with them. These clustering techniques will be analyzed in order to get some insights about the data and the costumers.

## III. METHODOLOGY

### A. Data

- 1) *Toy dataset*: The initial test dataset for the algorithms was the iris dataset, that contains 3 classes of iris flowers (versicolor, virginica and setosa) and has 4 features (sepal length and height and petal length and width) with 150 samples.
- 2) *Credit card dataset*: This dataset was downloaded from Kaggle (<https://www.kaggle.com/mlg-ulb/creditcardfraud>) and contains transactions made by credit cards in September 2013 by european cardholders. This dataset presents transactions that occurred in two days, where we have 492 frauds out of 284,807 transactions. The dataset is highly unbalanced, the positive class (frauds) account for 0.172% of all transactions.

### B. Pipeline

- 1) *Preprocessing*: Elimination of missing values and normalization. The normalization method performed is dividing by the maximum of each feature. This to ensure that all the data points are mapped into the hypercube [0,1].
- 2) *Statistical analysis*: In order to asses the complexity of the problem, several statistical tests were taken, including normality tests, Independence tests, dsitribution tests and stationarity tests.

- 3) *Feature selection and extraction*: This step was performed differently in both datasets, the toy dataset and the credit card dataset. In the first one, 4 characteristics were extracted, augmenting the dimension from 4 to 8. In the second one, 28 characteristics were provided, and a reduction of dimensionality via PCA was performed.
- 4) *Embedding*: The T-distributed Stochastic Neighbor Embedding was used as embedding algorithm, due to its distance conserving property. This embedding was used to visualize the results and also to learn in lower dimensions.
- 5) *Learning*: 5 clustering algorithms were implemented in both datasets, performing the learning task in the higher, medium and lower dimensional space and comparing the results.

### C. Algorithms

Let  $\{x_1, \dots, x_n\}$  be  $n$  data points in an  $M$  dimensional space, normalized to an hypercube. Also, let  $d(x, y)$  be a distance function in  $\mathbb{R}^n$ .

- 1) *Subtractive clustering*: This method takes all the points as cluster centers candidates. The steps for the algorithm are:

- a) Calculate a density function for each pint  $x_i$ , given by:

$$D_i = \sum_{j=1}^n \exp \left( -\frac{d(x_i, x_j)^2}{(r_a/2)^2} \right)$$

where  $r_a$  is a positive constant representing a neighborhood radius.

- b) Choose the cluster center  $x_{c_i}$  as the point having the largest density value  $D_{c_i}$ .
- c) Revise each point's density function by eliminating the effect of the previously chosen center as follows:

$$D_i = D_i - D_{c_i} \exp \left( -\frac{d(x_i, x_{c_i})^2}{(r_b/2)^2} \right)$$

where  $r_b$  is a positive constant which defines a neighborhood that has measurable reductions in density measure.

- d) If a sufficient number of clusters is reached, or the value of the density function is too small, stop. If not, go back to step 2.

- 2) *Mountain clustering*: This method, instead of taking each point as a cluster candidate, it forms a grid in the data space, where the intersections of the grid lines represent the potential cluster centers. These points are stored in set  $V$ . Then, we apply the following algorithm:

- a) Calculate a mountain function for each point  $v_j$  in  $V$ , given by:

$$m_j = \sum_{i=1}^n \exp \left( -\frac{d(v_j - x_i)^2}{2\sigma^2} \right)$$

where  $\sigma$  is a positive constant representing the height and the smoothness of the mountain.

- b) Choose the cluster center  $v_{c_i}$  as the point having the largest mountain value  $m_{c_i}$ .
- c) Revise each point's mountain function by eliminating the effect of the previously chosen center as follows:

$$m_j = m_j - m_{c_i} \exp \left( -\frac{d(v_j - v_{c_i})^2}{2\beta^2} \right)$$

where  $\beta$  is a positive constant.

- d) If a sufficient number of clusters is reached, or the value of the mountain function is too small, stop. If not, go back to step 2.

- 3) *k-means clustering* In this algorithm, the dataset is going to be partitioned in  $k$  groups  $G_i$ ,  $i = 1, \dots, k$ . The cost function, based on a distance  $d(x, y)$ , can be defined by:

$$J = \sum_{i=1}^c J_i = \sum_{i=1}^c \left( \sum_{k, x_k \in G_i} d(x_k, c_i)^2 \right)$$

For the development, we follow these steps:

- a) Randomly initialize the cluster centers  $c_i$ ,  $i = 1, \dots, k$ .
- b) Determine a membership matrix for each group,  $U$  by:

$$u_{ij} = \begin{cases} 1 & \|x_j - c_i\|^2 \leq \|x_j - c_k\|^2 \quad \forall k \neq i \\ 0 & \text{Otherwise} \end{cases}$$

- c) Compute the cost function. Stop if it is bellow a certain tolerance  $\varepsilon$  or its improvement is irrelevant.
- d) Update the cluster centers by:

$$c_i = \frac{1}{|G_i|} \sum_{k, x_k \in G_i} x_k$$

Then, go to the second step.

- 4) *Fuzzy c-means clustering* In this algorithm, each point of the dataset belongs to each of the  $c$  clusters in a certain degree of membership, between 0 and 1. The steps to follow are:

- a) Initialize the membership matrix  $U$  with random values between 0 and 1 such that:

$$\sum_{i=1}^c u_{ij} = 1 \quad \forall j = 1, \dots, n$$

- b) Calculate  $c$  fuzzy cluster centers  $c_i$ ,  $i = 1, \dots, n$  by:

$$c_i = \frac{\sum_{j=1}^n u_{ij}^m x_j}{\sum_{j=1}^n u_{ij}^m}$$

- c) Compute the cost function:

$$J(U, c_1, \dots, c_c) = \sum_{i=1}^c J_i = \sum_{i=1}^c \sum_{j=1}^n u_{ij}^m d_{ij}^2$$

where  $u_{ij}$  is between 0 and 1,  $c_i$  is the cluster center of fuzzy group  $i$ ,  $d_{ij} = d(c_i, x_j)$  and  $m \in [1, \infty)$  is a weighting exponent. Stop if it

is either bellow a certain tolerance  $\varepsilon$  or if there is no improvement.

- d) Compute a new membership matrix using the following:

$$u_{ij} = \frac{1}{\sum_{k=1}^c \left( \frac{d_{ij}}{d_{kj}} \right)^{\frac{2}{m-1}}}$$

Then, go to step 2.

- 5) *K-medians clustering* This is a variation of the k-means clustering [10] in which, instead of computing the mean of the points in a cluster, one calculates the median. This algorithm is more robust to outliers in the dataset.

#### D. Distance functions

As defined above, all of the mentioned algorithms calculate distances between points. Let  $x = (x_1, \dots, x_n)$  and  $y = (y_1, \dots, y_n)$  be two points in  $n$ . The distance functions that are going to be used are the following:

- *Euclidean distance*

$$d(x, y) = \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$$

- *Manhattan distance*

$$d(x, y) = \sum_{i=1}^n |x_i - y_i|$$

- *Cosine similarity*

$$d(x, y) = \frac{\sum_{i=1}^n x_i y_i}{\sum_{i=1}^n x_i^2 \sum_{i=1}^n y_i^2}$$

#### E. Validation

Both datasets contain groundtruths for the classes of each sample. The previously presented algorithms will be evaluated using some indices (intra cluster and extra cluster) with both of the datasets. Let  $c_i$ ,  $i = 1, \dots, k$  be the cluster centers and  $C_i$  be the sets containing the points of each cluster. The indices used are described in [11] and include:

- *Davies-Bouldin (DB) index* This index us a function of the *within cluster scatter* and the *between cluster separation*. We define:

- 1) Within cluster scatter:  $S_i = \frac{1}{|C_i|} \sum_{x \in C_i} \|x - z_i\|$ .
- 2) Between cluster separation: Is simply the distance  $d_{ij}$  between two cluster centers  $\|c_i - c_j\|$ .
- 3)  $R_{i,qt} = \max_{j, j \neq i} \left\{ \frac{S_{i,q} + S_{j,q}}{d_{ij}t} \right\}$

And the index is defined as:

$$DB = \frac{1}{k} \sum_{i=1}^k R_{i,qt}$$

The objective is to minimize this index for proper clustering.

- *Calinski Harabasz (CH) Index* Let  $c$  be the centroid of the entire dataset. The index is defined as

$$CH = \frac{\left[ \frac{\sum_{l=1}^k |C_l| \|c_l - c\|^2}{k-1} \right]}{\left[ \frac{\sum_{l=1}^k \sum_{i=1}^{|C_l|} \|x_i - c_l\|^2}{n-k} \right]}$$

## IV. RESULTS

### A. Iris dataset

- **Subtractive clustering**

The iris dataset contains a ground truth of 3 clusters. In Tables I, II and III are described the number of clusters found by the subtractive algorithm with various configurations of neighborhood ratios  $r_a$  and metrics. The Figures 1 and 2 show the initial state of the density function and the final state for one configuration ( $r_a = 0.5$ , metric euclidean), respectively.

$r_a$	euclidean	cosine	cityblock
0.4	4	1	6
0.5	3	1	4
0.7	2	1	3

TABLE I  
NUMBER OF CLUSTERS GIVEN BY THE SUBTRACTIVE CLUSTER FOR THE IRIS DATASET.

$r_a$	euclidean	cosine	cityblock
0.4	99	4	99
0.5	93	4	99
0.7	8	3	94

TABLE II  
NUMBER OF CLUSTERS GIVEN BY THE SUBTRACTIVE CLUSTER FOR THE AUGMENTED IRIS DATASET.

$r_a$	euclidean	cosine	cityblock
0.4	99	3	99
0.5	91	2	99
0.7	37	2	48

TABLE III  
NUMBER OF CLUSTERS GIVEN BY THE SUBTRACTIVE CLUSTER FOR THE EMBEDDED IRIS DATASET.

Despite the fact that the dataset provides clearly at least 2 groups, the results vary among the different parameters for the subtractive algorithm. We observe that, for the embbeded data, the cosine norm is usually better than the others, as well as for the augmented dataset. But the euclidean norm works better for the original dataset, as shown in Figure 3. In Tables IV and V we observe two indices for the clustering performed in the original dataset. Note that, for the cosine norm the number of clusters achieved is 1, and the metric is not defined for less than 2 groups. We can observe that the highest score

$r_a$	euclidean	cosine	cityblock
0.4	523.017618	NaN	415.515675
0.5	603.592099	NaN	522.011796
0.7	497.999891	NaN	594.486176

TABLE IV  
CALINSKI-HARABASZ SCORE FOR THE IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	0.800206	NaN	1.054853
0.5	0.634911	NaN	0.817205
0.7	0.390944	NaN	0.640144

TABLE V  
DAVIES-BOULDIN INDEX FOR THE IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

and the lowest index are achieved with the euclidean norm, as we stated in the results for the number of clusters. In Tables VI and VII are shown the results

$r_a$	euclidean	cosine	cityblock
0.4	76625.576579	3.018177	78208.081628
0.5	53652.621959	3.874866	74559.857679
0.7	2.602149	4.132075	55651.428403

TABLE VI  
CALINSKI-HARABASZ SCORE FOR THE AUGMENTED IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	0.217657	1.903561	0.219811
0.5	0.221893	1.861367	0.228289
0.7	2.739684	1.963818	0.258687

TABLE VII  
DAVIES-BOULDIN INDEX FOR THE AUGMENTED IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

for the validation on the augmented dataset. As seen before, the cosine norm achieves an appropriate number of clusters for this dataset, however, its indices and scores are the worst performed, probably because the other metrics achieve clusters that, even when they are not much informative, separate well the data and overfits the score.

$r_a$	euclidean	cosine	cityblock
0.4	9150.473726	2055.146690	8762.051647
0.5	6450.492142	1626.713464	8176.198965
0.7	3367.100226	1626.713464	3643.894411

TABLE VIII  
CALINSKI-HARABASZ SCORE FOR THE EMBEDDED IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	0.270312	0.423202	0.279279
0.5	0.327560	0.216722	0.290310
0.7	0.626248	0.216722	0.564174

TABLE IX  
DAVIES-BOULDIN INDEX FOR THE EMBEDDED IRIS DATASET CLUSTERED WITH THE SUBTRACTIVE ALGORITHM.

Finally, in Tables IX and VIII we observe the validation results for the embedded dataset (that contained only 2 features). Again, as for the augmented dataset, the euclidean and cityblock metrics are performing better, but we observe that is probably because the number of clusters achieved is huge.

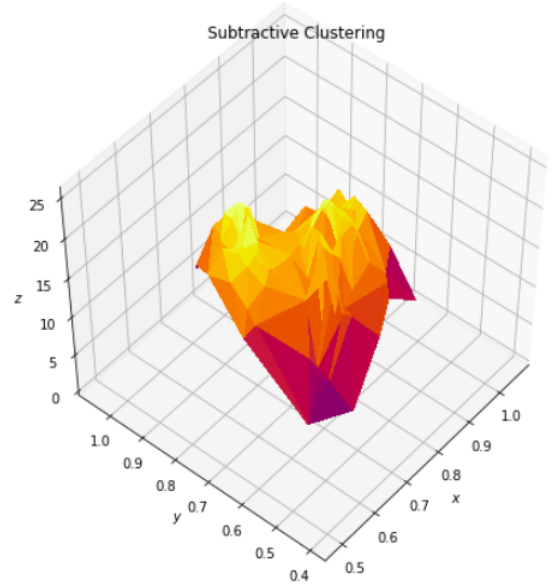


Fig. 1. Initial density function for the subtractive clustering using the euclidean norm.

- **Mountain clustering:** In Tables X, XI and XII are described the number of clusters found by the mountain algorithm with various configurations of smoothing parameters  $\sigma$  and metrics. For  $\sigma = 1.5$  and the euclidean metric, the first and last mountain function is shown in Figures 4 and 2, respectively.

$\sigma$	euclidean	cosine	cityblock
0.4	5	3	7
0.5	3	2	4
0.7	2	1	3

TABLE X  
NUMBER OF CLUSTERS FOUND BY THE MOUNTAIN ALGORITHM IN THE IRIS DATASET.

In comparison with the subtractive algorithm, the mountain algorithm is able to approximate better the number of clusters existing in the iris dataset, for any configuration

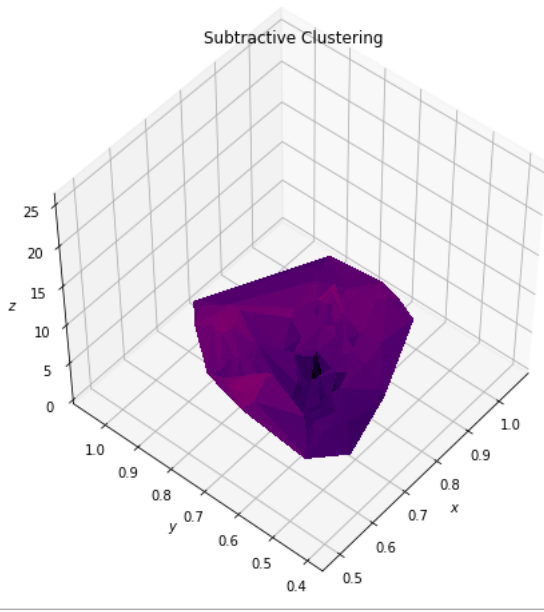


Fig. 2. Final density function for the subtractive clustering using the euclidean norm.

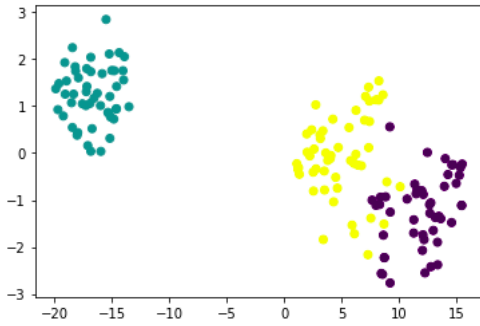


Fig. 3. Clustering for the iris dataset using the subtractive algorithm.

$\sigma$	euclidean	cosine	cityblock
0.4	4	4	2
0.5	3	4	2
0.7	2	2	2

TABLE XI

NUMBER OF CLUSTERS FOUND BY THE MOUNTAIN ALGORITHM IN THE AUGMENTED IRIS DATASET.

$\sigma$	euclidean	cosine	cityblock
0.4	2	3	2
0.5	2	3	2
0.7	3	2	3

TABLE XII

NUMBER OF CLUSTERS FOUND BY THE MOUNTAIN ALGORITHM IN THE EMBEDDED IRIS DATASET.

shown in the results of Figure 6, some configurations are better than others in finding the correct amount of clusters.

$\sigma$	euclidean	cosine	cityblock
0.4	392.333739	NaN	245.874313
0.5	586.577476	NaN	419.084383
0.7	497.999891	NaN	567.385797

TABLE XIII

CALINSKI-HARABASZ SCORE FOR THE IRIS DATASET CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	0.803257	NaN	1.185689
0.5	0.641318	NaN	0.678465
0.7	0.390944	NaN	0.662073

TABLE XIV

DAVIS BOULDIN INDEX FOR THE IRIS DATASET CLUSTERED BY THE MOUNTAIN ALGORITHM.

In Tables XIII and XIV are shown the validity indices for the original iris dataset. We can see that, despite the fact that the mountain with the cosine metric finds more than 1 cluster, the centroids of some of them are so far away from the data that one ends up having only one cluster, and that is why the indices are not defined in that point. We observe that, in this case, the euclidean metric gives the best overall performance.

$\sigma$	euclidean	cosine	cityblock
0.4	0.807805	4.606519	0.299737
0.5	1.235066	1.092758	0.299737
0.7	0.860060	1.378751	0.299737

TABLE XV

CALINSKI-HARABASZ SCORE FOR THE AUGMENTED IRIS DATASET CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	4.605520	2.506750	7.163532
0.5	10.291972	2.595677	7.163532
0.7	4.561892	2.061052	7.163532

TABLE XVI

DAVIS BOULDIN INDEX FOR THE AUGMENTED IRIS DATASET CLUSTERED BY THE MOUNTAIN ALGORITHM.

In Tables XV and XVI are shown the results for the validation of the mountain algorithm in the augmented dataset. In this case, we have always more than 1 cluster, which is a good result. Here, the cityblock (Manhattan) distance shows the best performance overall.

Finally, in Tables XVII and XVIII are shown the validity indices for the embedded dataset. Again, we have more

of the smoothing parameter  $\sigma$  and metric. However, as

$\sigma$	euclidean	cosine	cityblock
0.4	61.900352	1400.846404	62.435134
0.5	61.900352	1400.846404	62.435134
0.7	106.215548	1626.713464	104.916325

TABLE XVII  
CALINSKI-HARABASZ SCORE FOR THE EMBEDDED IRIS DATASET  
CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	0.820981	0.522071	0.833421
0.5	0.820981	0.522071	0.833421
0.7	0.685696	0.216722	0.686128

TABLE XVIII  
DAVIS BOULDIN INDEX FOR THE EMBEDDED IRIS DATASET CLUSTERED  
BY THE MOUNTAIN ALGORITHM.

than 1 cluster and the manhattan and euclidean distance show a similar performance overall, being both better than the cosine distance.

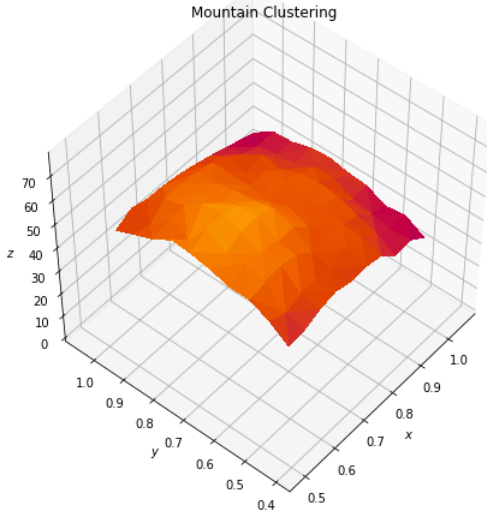


Fig. 4. Initial mountain function for the mountain clustering using the euclidean norm.

- 1) *k-means clustering*:
- 2) *c-means clustering*:
- 3) *k-medians clustering*:
- 4) *Comparison of the methods*: In Figures 7, 8, 9 and 10 are shown the different centers provided by the different algorithms explored in this work, for the iris dataset.

Is clear that, even when the number of centers are the same, they vary in terms of localization, sometimes more than others. The three algorithms that need the number of centers tend to give more similar ones, while the ones that explore the whole space differ more in this particular dataset.

#### B. Credit card dataset

This dataset includes two classes, highly unbalanced: fraud or not fraud.

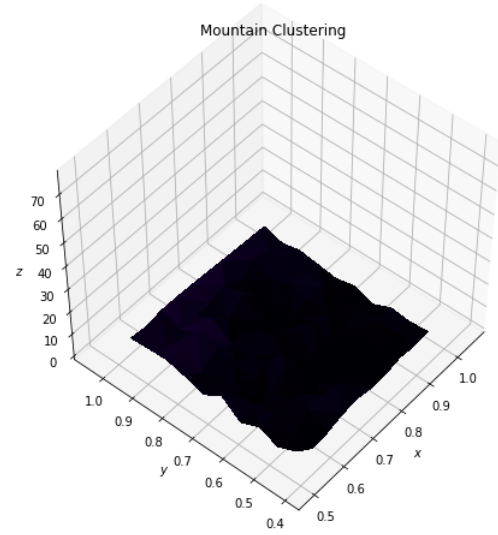


Fig. 5. Final mountain function for the mountain clustering using the euclidean norm.

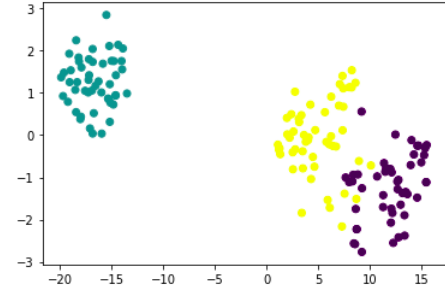


Fig. 6. Clustering for the iris dataset using the mountain algorithm.



Fig. 7. Clusters given by different methods,  $k = 2$ .

1) *Subtractive clustering*: In Tables XIX, XX and XXI are shown the number of clusters found for the three datasets of credit card fraud. In this case, we observe that the cosine norm achieves 2 clusters, the expected ones. But probably more clusters are not a wrong performance, rather than a different form of viewing the data. We will refer then to the validation indices to see when the performance is better. Also,



Fig. 8. Clusters given by different methods,  $k = 3$ .

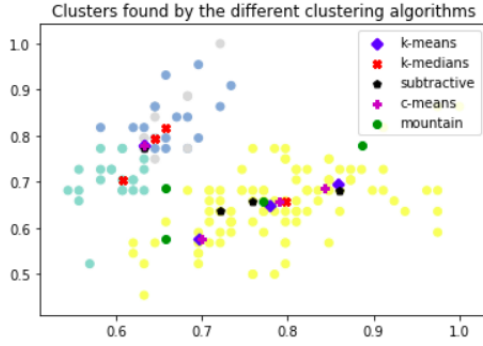


Fig. 9. Clusters given by different methods,  $k = 4$ .

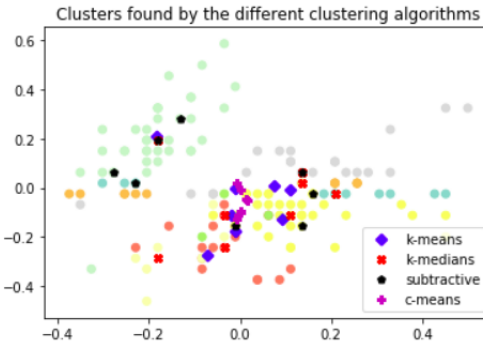


Fig. 10. Clusters given by different methods,  $k = 7$ .

in Figure 11 is shown the initial density function for the credit card reduced dataset and  $r_a = 0.5$ , with the euclidean distance. Figure 12 shows the final state.

$r_a$	euclidean	cosine	cityblock
0.4	10	2	52
0.5	7	2	21
0.7	4	2	8

TABLE XIX  
NUMBER OF CLUSTERS FOUND BY THE SUBTRACTION ALGORITHM FOR THE CREDIT CARD DATASET.

The algorithm has an emergency stopping criteria, the

$r_a$	euclidean	cosine	cityblock
0.4	8	2	23
0.5	5	2	11
0.7	3	2	5

TABLE XX  
NUMBER OF CLUSTERS FOUND BY THE SUBTRACTION ALGORITHM FOR THE CREDIT CARD REDUCED DATASET.

$r_a$	euclidean	cosine	cityblock
0.4	99	8	99
0.5	99	7	99
0.7	99	4	99

TABLE XXI  
NUMBER OF CLUSTERS FOUND BY THE SUBTRACTION ALGORITHM FOR THE CREDIT CARD EMBEDDED DATASET.

number of iterations. Due to the fact that they are 100, is clear that for the euclidean distance in the embedded dataset much more clusters are achieved. This may be due to the spatial distribution of the data, as shown in the results of Figure 13.

$r_a$	euclidean	cosine	cityblock
0.4	3.029305	0.981477	3.374885
0.5	3.441991	0.981142	3.349646
0.7	3.737428	0.981221	4.300733

TABLE XXII  
DAVIES BOULDIN INDEX FOR THE CREDIT CARD DATASET CLUSTERED BY THE SUBTRACTION ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	34200.815670	181518.597459	4712.546985
0.5	45858.080636	181504.729539	10983.494778
0.7	67334.688094	181520.031384	30413.670844

TABLE XXIII  
CALISNKI-HARABSZ SCORE FOR THE CREDIT CARD DATASET CLUSTERED BY THE SUBTRACTION ALGORITHM.

In Tables XXII and XXII are shown the results for the validation of the clustering in the original credit card dataset. We saw that, for the cosine metric the number of clusters found are the expected, and is actually revised by these scores, that classify this metric as the one that performs the better.

$r_a$	euclidean	cosine	cityblock
0.4	2.409494	0.875412	3.139200
0.5	2.088824	0.875412	2.601788
0.7	1.468652	0.875644	3.157173

TABLE XXIV  
DAVIES BOULDIN INDEX FOR THE CREDIT CARD REDUCED DATASET CLUSTERED BY THE SUBTRACTION ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	47725.987561	210512.707501	12023.907405
0.5	92681.517486	210512.707501	31914.695617
0.7	113693.471190	210511.841004	59832.246699

TABLE XXV

CALISNKI-HARABSZ SCORE FOR THE REDUCED CREDIT CARD DATASET CLUSTERED BY THE SUBTRACTIVE ALGORITHM.

In Tables XXIV and XXV are shown the indices for the reduced dataset by PCA. Again, the performance shown by these corresponds to the fact that the cosine metric achieves the expected number of clusters.

$r_a$	euclidean	cosine	cityblock
0.4	1.080875	1.176533	1.253805
0.5	1.050448	1.093338	1.333077
0.7	0.953949	0.866116	1.043586

TABLE XXVI

DAVIES BOULDIN INDEX FOR THE CREDIT CARD EMBEDDED DATASET CLUSTERED BY THE SUBTRACTIVE ALGORITHM.

$r_a$	euclidean	cosine	cityblock
0.4	83056.373617	174368.043596	77677.563496
0.5	109156.916197	185793.584797	88929.724177
0.7	142020.902180	217192.867615	116444.149920

TABLE XXVII

CALISNKI-HARABSZ SCORE FOR THE REDUCED CREDIT CARD DATASET CLUSTERED BY THE SUBTRACTIVE ALGORITHM.

Finally, Tables XXVI and XXVII are shown the validity indices or the embedded dataset. These indices show a poor performance in all cases, reflecting the amount of clusters found by the algorithm in this particular dataset. Probably, the information given by the embedding is not enough to show the full structure of the data.

2) *Mountain clustering*: Tables XXVIII and XXIX show the number of clusters found by the mountain algorithm in the embedded and reduced dataset, with variations in the smoothing parameter  $\sigma$  and the metric.

$\sigma$	euclidean	cosine	cityblock
0.4	8	7	2
0.5	4	5	2
0.7	3	3	2

TABLE XXVIII

NUMBER OF CLUSTERS FOUND BY THE MOUNTAIN ALGORITHM IN THE REDUCED CREDIT CARD DATASET.

In this case, we observe that the number of clusters is reduced in comparison with the subtractive algorithm, however, the metric that only finds the two existing clusters in the dataset is the manhattan, and only in the reduced one. The embedded one, again, does not seem to provide enough information to perform a good clustering.

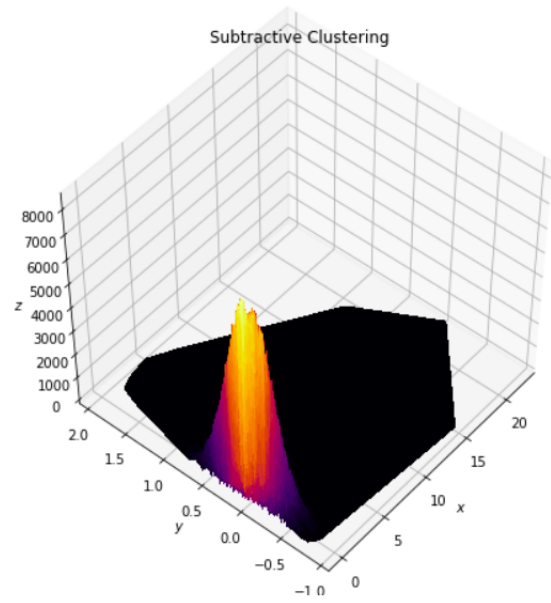


Fig. 11. Initial density function for the credit card dataset in the subtractive clustering algorithm.

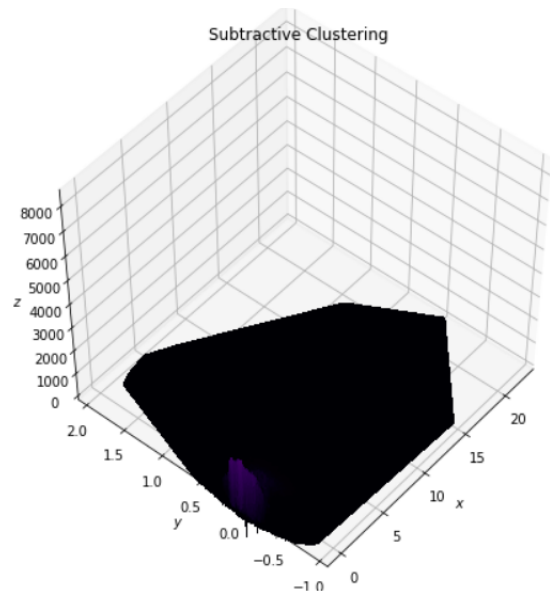


Fig. 12. Final density function for the credit card dataset in the subtractive clustering algorithm.

$\sigma$	euclidean	cosine	cityblock
0.4	10	5	9
0.5	9	4	10
0.7	9	4	9

TABLE XXIX

NUMBER OF CLUSTERS FOUND BY THE MOUNTAIN ALGORITHM IN THE EMBEDDED CREDIT CARD DATASET.

In Tables XXX and XXXI are shown the validity indices for the clustering in the reduced dataset.



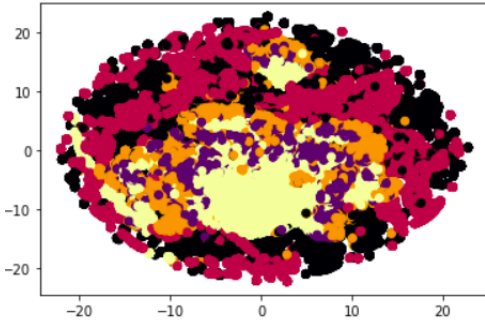


Fig. 13. Clustering for the credit card dataset in the subtractive clustering algorithm.

$\sigma$	euclidean	cosine	cityblock
0.4	5.395964	2.539999	6.582867
0.5	5.076245	3.047503	6.582867
0.7	4.635804	1.861457	6.582867

TABLE XXX  
DAVIES BOULDIN INDEX FOR THE REDUCED CREDIT CARD DATASET  
CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	2612.705876	41225.158046	4029.893595
0.5	3689.213460	58473.394701	4029.893595
0.7	3966.374184	110716.512521	4029.893595

TABLE XXXI  
CALINSKI-HARABASZ SCORE FOR THE REDUCED CREDIT CARD DATASET  
CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	0.891413	0.967157	0.946406
0.5	0.884992	0.878476	0.891413
0.7	0.884992	0.865683	0.884992

TABLE XXXII  
DAVIES BOULDIN INDEX FOR THE EMBEDDED CREDIT CARD DATASET  
CLUSTERED BY THE MOUNTAIN ALGORITHM.

$\sigma$	euclidean	cosine	cityblock
0.4	198415.832838	193511.849750	188520.438083
0.5	208251.768500	207307.628003	198415.832838
0.7	208251.768500	217172.104734	208251.768500

TABLE XXXIII  
CALINSKI-HARABASZ SCORE FOR THE EMBEDDED CREDIT CARD  
DATASET CLUSTERED BY THE MOUNTAIN ALGORITHM.

## V. CONCLUSIONS

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