

ADT Graph																																									
$g = \langle \langle v1, e1 \rangle, \langle v2, e2 \rangle, \dots, \langle vn, en \rangle \rangle$																																									
{inv: $\langle g \neq \emptyset, \forall ei, vn, vm((ei, vn) \wedge (ei, vm)) \Rightarrow vn \in ei \wedge vm \in ei \rangle$ }																																									
Primitive Operations: <table> <tr><td>• addVertex</td><td>GraphXT</td><td>->Graph</td></tr> <tr><td>• addConnection</td><td>Graph</td><td>->Graph</td></tr> <tr><td>• addValue</td><td>GraphXv</td><td>->Graph</td></tr> <tr><td>• search</td><td>GraphXv</td><td>->T</td></tr> <tr><td>• BFS</td><td>Graph</td><td>->Graph</td></tr> <tr><td>• dijkstraPath</td><td>Graph</td><td>->pathGraph</td></tr> <tr><td>• checkConexivity</td><td>Graph</td><td>->Graph</td></tr> <tr><td>• floydWarshall</td><td>Graph</td><td>->pathGraph</td></tr> <tr><td>• prim</td><td>Graph</td><td>->pathGraph</td></tr> <tr><td>• kruskal</td><td>Graph</td><td>->pathGraph</td></tr> <tr><td>• containerOf</td><td>Graph</td><td>.->T</td></tr> <tr><td>• clear</td><td>Graph</td><td>->null</td></tr> <tr><td>• searchVertex</td><td>GraphXT</td><td>->T</td></tr> </table>			• addVertex	GraphXT	->Graph	• addConnection	Graph	->Graph	• addValue	GraphXv	->Graph	• search	GraphXv	->T	• BFS	Graph	->Graph	• dijkstraPath	Graph	->pathGraph	• checkConexivity	Graph	->Graph	• floydWarshall	Graph	->pathGraph	• prim	Graph	->pathGraph	• kruskal	Graph	->pathGraph	• containerOf	Graph	.->T	• clear	Graph	->null	• searchVertex	GraphXT	->T
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addVertex(Graph, l id, T toAdd) ---> void
 "Inserts a vertex to the graph"
 { pre: Graph = Elements $\wedge k \notin$ Elements }
 { pos: Graph = Elements $\wedge k \in$ Elements }

addConnection(Graph, l pointer, l pointed, int weight) ----> void
 "Creates an edge in the graph"
 { pre: Graph = Elements $\wedge k \notin$ Elements }
 { pos: Graph = Elements $\wedge k \in$ Elements }

addValue(Graph, l pointer, l pointed, String direction, int weight) --> void
 "Adds weight to the vertex"
 { pre: Graph = $\wedge k \notin$ Elements }
 { pos: Graph = Elements $\wedge k \in$ Elements }

search(Graph, l id) --> T
 "Search a vertex"
 { pos:Graph = T}

BFS (Graph, l s) --> void
 "Verify if the board is conected"
 { pre: Graph \neq null }
 { pos: \forall vertex that has a path to s, color=2(black) }

DFS (Graph, l s) --> void

"Verify if the board is connected"

{ pre: Graph \neq null }

{ pos: \forall vertex that has a path to s, color=2(black) }

dijkstraPath(Graph, l startID, l endID) --> Stack

"Draws the path of the enemy to the player"

{ pre: Graph \neq null }

{ pos: pathGraph }

checkConexivity(Graph, l start) --> Boolean

"Checks the connection between the edge and the vertex"

{ pre: false, edge \neq null, vertex \neq null }

{ pos:true }

floydWarshall(Graph) --> Hashmap

"Draws the path of the enemy to chase the player"

{ pre: Graph \neq null }

{ pos: pathGraph }

prim(Graph, l rs) --> int

"Finds the minimum coater tree"

kruskal(Graph, l rs) --> TreeSet

"Finds the minimum coater tree"

containerOf(Graph, T value) --> Object

"Returns the vertex"

{ pre: Graph \neq null }

{ pos: returns vertex=T }

clear(Graph, T value) --> void

"clears the current scenario"

{ pre: Graph \neq null }

{ pos: Graph = null }

searchVertex(Graph, l id) --> Object

"Search a vertex"

{ pos:Graph = T }