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Classroom Work Assignment C9

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**Problem C9.1 (Data Terms for Large Displacements)**

- (a) Write down the optic flow constraints that model the combined brightness and gradient constancy of a grey value image sequence, if one refrains from Taylor linearisation.
- (b) How does the corresponding quadratic data term look like?
- (c) One can transform the previous quadratic data term into a nonquadratic formulation, by applying robust functions  $\Psi_j$  in different ways on the quadratic data term. Discuss the different possibilities and their respective advantages and disadvantages. Also state scenarios where the different formulations make sense.

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## Homework Assignment H9

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### Problem H9.1 (Joint Image- and Flow-driven Regularisation)

2+2+2+3P

- (a) Let  $\mathbf{v}$  be a vector, normalised to 1, and let  $\partial_{\mathbf{v}} u := \mathbf{v}^\top \nabla u$  denote the derivative in  $\mathbf{v}$  direction. Show that the quadratic optic flow regulariser  $S = |\partial_{\mathbf{v}} u_1|^2 + |\partial_{\mathbf{v}} u_2|^2$  creates the diffusion tensor  $\mathbf{D} = \mathbf{v}\mathbf{v}^\top$  in the gradient descent equations.
- (b) Analogously, show that the nonquadratic optic flow regulariser  $S = \Psi(|\partial_{\mathbf{v}} u_1|^2 + |\partial_{\mathbf{v}} u_2|^2)$  yields the diffusion tensor  $\Psi'(|\partial_{\mathbf{v}} u_1|^2 + |\partial_{\mathbf{v}} u_2|^2) \mathbf{v}\mathbf{v}^\top$ .
- (c) Use the previous results to construct a diffusion tensor that uses eigenvectors parallel and perpendicular to the spatial edges of the image sequence  $f$ . Its eigenvalues should be given by a decreasing function of the squared flow derivatives along these eigenvectors.
- (d) What would be the corresponding optic flow regulariser for the diffusion tensor in (c)? Justify your answer.

*Note: The method in (c) is a joint image- and flow-driven method, since its eigenvectors depend on the image sequence  $f$ , and its eigenvalues on the flow field  $\mathbf{u}$ . It benefits from the nice edge structure of  $f$ , while its actual amount of smoothing is reduced at flow discontinuities. Hence, it does not suffer from the typical oversegmentation problems of pure image-driven optic flow methods.*

### Problem H9.2 (Algorithms for the Parabolic and Elliptic Problem)

2+2+1P

Consider the energy functional

$$E(u, v) = \frac{1}{2} \int_{\Omega} (\mathbf{w}^\top \mathbf{J} \mathbf{w} + \alpha (|\nabla u|^2 + |\nabla v|^2)) dx dy$$

where  $\mathbf{w} = (u, v, 1)^\top$  denotes the optic flow, and  $\mathbf{J} = (J_{i,k}) : \Omega \rightarrow \mathbb{R}^{3 \times 3}$  is some motion tensor field.

Derive two iterative numerical algorithms for  $u_{i,j}^{k+1}$  and  $v_{i,j}^{k+1}$  that solve the corresponding Euler-Lagrange equations at inner positions  $(i, j)$ . Proceed in the following steps:

- (a) Discretise the parabolic problem. Use the modified explicit scheme with an implicitly stabilised data term. How does the iterative scheme for  $u_{i,j}^{k+1}$  and  $v_{i,j}^{k+1}$  look like?
- (b) Discretise the elliptic problem. Use the Jacobi method to derive equations for  $u_{i,j}^{k+1}$  and  $v_{i,j}^{k+1}$ .
- (c) Compare the two methods for some inner pixel  $(i, j)$ . What do you notice?

Use central differences for approximating second order derivatives and write down the equations for the grid sizes  $h_1 = h_2 = h$ .

### Problem H9.3 (Flow-driven Isotropic Optic Flow)

4+6P

- (a) Supplement the program `optic.c` with the missing code such that it becomes a modified explicit scheme for flow-driven isotropic optic flow estimation with the Charbonnier diffusivity

$$g(s^2) = \Psi'(s^2) = \frac{1}{\sqrt{1 + s^2/\lambda^2}}.$$

- (b) Use it for computing the optic flow between the images `ole8.pgm` and `ole9.pgm` with the following three parameter settings:

- $\alpha = 500$  and  $\lambda = 0.01$ ,
- $\alpha = 5000$  and  $\lambda = 0.01$ ,
- $\alpha = 500$  and  $\lambda = 10000$ .

In all cases, use 20000 iterations with time step size  $\tau = 0.2$ .

How does  $\alpha$  influence the result? What is the role of  $\lambda$ ? Which optic flow model is approximated for the third setting?

**Submission:** Please create a directory `Ex09_<your_name>` with the following files (and nothing else):

- a pdf file – which can also be a scanned handwritten solution – that contains
  - the names of all people working together for this assignment
  - the solutions of the theoretical Problems 1–2 and answers to the questions in Problem 3
- for Problem 3: the completed file `optic-complete.c` and the flow fields `ole-of1.ppm`, `ole-of2.ppm`, and `ole-of3.ppm` for the three parameter settings in Problem 3(b)

Compress the directory to a zip file `Ex09_<your_name>.zip`.

Submit the file via CMS.

**Deadline for submission is Friday, January 5, 14:00.**