Differential Equations in Image Processing and Computer Vision

WS 2023 Saarland University

Classroom Work Assignment C12

Problem C12.1 (Directional Derivatives)

(a) In Assignment H9, Problem 1 we used $\partial_{\boldsymbol{v}} u = \boldsymbol{v}^{\top} \boldsymbol{\nabla} u$ with a normalised vector \boldsymbol{v} . Show that

$$\partial_{\boldsymbol{v}\boldsymbol{v}}u = \boldsymbol{v}^{\top} \mathbf{Hess}(u) \, \boldsymbol{v},$$

where $\mathbf{Hess}(u)$ is the Hessian of u.

(b) Let \boldsymbol{v} and \boldsymbol{w} be normalised 2-D vectors with $\boldsymbol{v} \perp \boldsymbol{w}$. Using (a), prove that the 2-D Laplacian Δu can be written as

$$\Delta u = \partial_{vv} u + \partial_{vvv} u$$
.

What does this tell you about the Laplacian?

Homework Assignment H12

Problem H12.1 (Curvature-Based Morphology)

6P

Prove the following equivalences for MCM:

$$\begin{array}{lcl} \partial_t u & = & \partial_{\xi\xi} u \\ & = & \frac{u_y^2 u_{xx} - 2u_x u_y u_{xy} + u_x^2 u_{yy}}{u_x^2 + u_y^2} \\ & = & \Delta u - \frac{1}{|\boldsymbol{\nabla} u|^2} \boldsymbol{\nabla} u^\top \mathbf{Hess} \left(u \right) \boldsymbol{\nabla} u \\ & = & |\boldsymbol{\nabla} u| \operatorname{\mathbf{div}} \left(\frac{\boldsymbol{\nabla} u}{|\boldsymbol{\nabla} u|} \right). \end{array}$$

Problem 12.2 (Affine Invariant Arc-length)

6P

Consider a curve \boldsymbol{c} in \mathbb{R}^2 with the parametrisation $\boldsymbol{c}(p) = (x(p), y(p))^{\top}$, and an affine transformation $f: \boldsymbol{x} \mapsto \boldsymbol{A}\boldsymbol{x} + \boldsymbol{b}$, where $\boldsymbol{A} \in \mathbb{R}^{2 \times 2}$ satisfies det $\boldsymbol{A} = 1$, and $\boldsymbol{b} \in \mathbb{R}^2$ is a translation vector.

Show that the affine arc-lengths of c and f(c) are equal.

Problem H12.3 (Mean Curvature Motion)

2+1+1+2P

- (a) Supplement the missing code in mcm.c such that it performs mean curvature motion.
- (b) Compile the program as usual and use it for shape simplification of the image tyre.pgm. Useful parameters: $\alpha = 0.49, \ \gamma = 1, \ \tau = 0.4, \ \text{and} 50/250/1000$ iterations.
- (c) Apply mcm.c to schaeuble.pgm with the parameters from (b). Why is mcm.c not useful for fingerprint processing?
- (d) The images check1.pgm and check2.pgm are visually very similar. How do they evolve under MCM? Is this in contradiction to the theory?

Problem H12.4 (Corner Detection of Alvarez/Morales)

3+3P

The program corner_detect.c uses the ideas of Alvarez and Morales to investigate the corner evolution with the affine morphological scale-space.

- (a) Compile it and apply the program to the images corner01.pgm and corner02.pgm with $\alpha=0,\ \gamma=1,\ \tau=0.01,$ and 10000 iterations. The exact corner angles are 90° for corner01.pgm and 53.13° for corner02.pgm. How good are the results with respect to different stopping times?
- (b) To check the robustness of the method under noise, also try the images corner01_50.pgm and corner02_50.pgm. How is the result influenced by noise?

Submission: Please create a directory Ex12_<your_name> with the following files (and nothing else):

- a pdf file which can also be a scanned handwritten solution that contains
 - the names of all people working together for this assignment
 - the solutions of the theoretical Problems 1–2 and answers to the questions in Problem 3 and 4
- for Problem 3(a): the completed file mcm-complete.c,
- for Problem 3(b): the resulting images tyre{50,250,1000}.pgm
- for Problem 3(c): the resulting images schaeuble \{50,250,1000\}.pgm
- for Problem 3(d): the resulting images check1-mcm.pgm and check2-mcm.pgm
- for Problem 4: the estimated coordinates of the corner point and the corner angle.

Compress the directory to a zip file Ex12_<your_name>.zip.

Submit the file via CMS.

Deadline for submission is Friday, January 26, 14:00.