

15.095 Homework 2

Kim-Anh-Nhi Nguyen. MIT ID: 9137855521

2018-10-10

1 Algorithmic Framework for Linear Regression

Cf. notebook attached.

For dataset1:

- The variables with non-zero coefficient are: $x[19]$, $x[27]$ and $x[56]$, i.e., x_4^2 , $x_1 2^2$, and $\log(x_{11})$
- The best hyperparameters are: $\Gamma = 0.001$ and $K = 3$
- Training R^2 value: 0.8432352378395275
- Validation R^2 value: 0.8127748811895958
- Testing R^2 value: 0.7697463987128148

For dataset2:

- The variables with non-zero coefficient are: $x[16]$, $x[18]$, $x[19]$, $x[22]$, $x[24]$, $x[27]$ and $x[28]$, i.e., $\sqrt{x_2}$, $\sqrt{x_4}$, $\sqrt{x_5}$, $\log(x_1)$, $\log(x_3)$, $\log(x_6)$, and $\log(x_7)$
- The best hyperparameters are: $\Gamma = 0.01$ and $K = 7$.
- Training R^2 value: 0.9219065010999199
- Validation R^2 value: 0.8982248481520309
- Testing R^2 value: 0.9274666342602617

2 Convex Regression

Cf. notebook attached.

3 Primal and Dual Perspective on Sparse Regression

(a)

i.

To solve the problem the 'primal' way, we can simply minimize $f(\beta) = \|y - \beta\|_2^2 + \|\beta\|_2^2$ by calculating its gradient and find the values of β_i for which the gradient is null and such that the constraint $\|\beta\|_0 \leq k$ is satisfied.

$$\begin{aligned}
\nabla(f) = 0 &\iff \forall i, \frac{\partial f}{\partial \beta_i} = 0 \\
\frac{\partial f}{\partial \beta_i} = 0 &\iff \frac{\partial}{\partial \beta_i} (\sum_{j=1}^n (y_j - \beta_j)^2 + (\beta_j)^2) = 0 \iff \frac{\partial}{\partial \beta_i} ((y_i - \beta_i)^2 + (\beta_i)^2) = 0 \\
&\iff \frac{\partial}{\partial \beta_i} (y_i^2 - 2y_i\beta_i + \beta_i^2 + \beta_i^2) = 0 \iff -2y_i + 4\beta_i = 0 \iff \beta_i = \frac{y_i}{2}
\end{aligned}$$

As we also have the constraint $\|\beta\|_0 \leq k$, we cannot set all the components β_i of β to $\frac{y_i}{2}$. In order to minimize $\|y - \beta\|_2^2$, the optimal β satisfies the following:

Let I_k be the set : $I_k = \{i \mid |y_i| \text{ is among the largest } k \text{ values of } |y_i| \text{ for } 1 \leq i \leq n\}$

So,

$$\beta_i^* = \begin{cases} \frac{y_i}{2} & \text{if } i \in I_k \\ 0 & \text{otherwise} \end{cases}$$

The optimal value of the cost function is then:

$$\begin{aligned}
f(\beta^*) &= \sum_{i=1}^n (y_i^2 - 2y_i\beta_i^* + 2(\beta_i^*)^2) = \sum_{i \in I_k} (y_i^2 - 2y_i\frac{y_i}{2}) + 2(\frac{y_i}{2})^2 + \sum_{j \notin I_k} y_j^2 = \sum_{i \in I_k} (y_i^2 - \frac{y_i^2}{2}) + \sum_{j \notin I_k} y_j^2 \\
f(\beta^*) &= \sum_{i \in I_k} (\frac{y_i^2}{2}) + \sum_{j \notin I_k} y_j^2
\end{aligned}$$

ii.

In the 'dual' way, the dual reformulation that eliminates the variable β is :

$$\begin{aligned}
\min c(s) &= y'(I_n + \frac{1}{\lambda} \sum_j s_j K_j)^{-1} y \\
&\text{s.t. } s \in S
\end{aligned}$$

Where $S := \{s \in \{0, 1\}^p : 1's \leq k\}$

Here, $X = In$ and $\lambda = 1$, so we are left with:

$$\begin{aligned}
c(s) &= y'(I_n + \begin{pmatrix} s_1 & 0 & \dots & 0 \\ 0 & s_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & s_n \end{pmatrix})^{-1} y \\
c(s) &= y' \begin{pmatrix} 1+s_1 & 0 & \dots & 0 \\ 0 & 1+s_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1+s_n \end{pmatrix}^{-1} y \\
c(s) &= y' \begin{pmatrix} \frac{1}{1+s_1} & 0 & \dots & 0 \\ 0 & \frac{1}{1+s_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{1+s_n} \end{pmatrix} y \\
c(s) &= \sum_{i=1}^n \frac{y_i^2}{1+s_i}
\end{aligned}$$

The dual formulation is then :

$$\min \sum_{i=1}^n \frac{y_i^2}{1+s_i}$$

$$s.t. s \in S$$

The optimal solution for this dual formulation is clearly:

$$s_i^* = \begin{cases} 1 & \text{if } i \in I_k \\ 0 & \text{otherwise} \end{cases}$$

The optimal value of the cost function is then:

$$c(s^*) = \sum_{i \in I_k} \left(\frac{y_i^2}{2}\right) + \sum_{j \notin I_k} y_j^2$$

We can notice that this optimal cost is the same as obtained previously for the "primal" way.

(b)

Let's apply the cutting plane method for the dual formulation.

Step 1: We pick $s_1 = [0, 0, \dots, 0] \in S$ and $C_1 = s_1$

Step 2: We calculate

$$z_1^* = \min_{s \in S} \left[\max_{\bar{s} \in C_1} \left(c(\bar{s}) + \sum_{i=1}^n \frac{\partial c(\bar{s})}{\partial s_i} (s_i - \bar{s}_i) \right) \right]$$

$$\text{For a given } s_i, \frac{\partial c(s)}{\partial s_i} = \frac{\partial}{\partial s_i} \left(\sum_{j=1}^n \frac{y_j^2}{1+s_j} \right) = \frac{\partial}{\partial s_i} \left(\frac{y_i^2}{1+s_i} \right) = y_i^2 \frac{\partial}{\partial s_i} \left(\frac{1}{1+s_i} \right) = y_i^2 \frac{\frac{1}{1+s_i} \Big|_{s_i=1} - \frac{1}{1+s_i} \Big|_{s_i=0}}{1-0} = y_i^2 \left(\frac{1}{2} - 1 \right)$$

$$\text{So, for } 1 \leq i \leq n, \frac{\partial c(s)}{\partial s_i} = \frac{-y_i^2}{2}$$

There only is one element in C_1 , so :

$$\begin{aligned} \max_{\bar{s} \in C_1} \left(c(\bar{s}) + \sum_{i=1}^n \frac{\partial c(\bar{s})}{\partial s_i} (s_i - \bar{s}_i) \right) &= c(s_1) + \sum_{i=1}^n \frac{\partial c(s_1)}{\partial s_i} (s_i - (s_1)_i) = \sum_{i=1}^n \frac{y_i^2}{1 + (s_1)_i} + \sum_{i=1}^n \frac{-y_i^2}{2} s_i = \sum_{i=1}^n y_i^2 - \frac{y_i^2}{2} s_i \\ &= \sum_{i=1}^n y_i^2 \left(1 - \frac{s_i}{2} \right) \end{aligned}$$

To minimize this sum over S , we need to minimize each component $y_i^2(1 - \frac{s_i}{2})$, so maximize s_i for the biggest values of y_i^2 , i.e., $|y_i|$.

Therefore, the optimal value is :

$$(s_1^*)_i = \begin{cases} 1 & \text{if } i \in I_k \\ 0 & \text{otherwise} \end{cases}$$

$$z_1^* = \sum_{i=1}^n y_i^2 \left(1 - \frac{(s_1^*)_i}{2} \right) = \sum_{i \in I_k} \left(\frac{y_i^2}{2} \right) + \sum_{j \notin I_k} y_j^2$$

$$c(s_1^*) = \sum_{i \in I_k} \left(\frac{y_i^2}{2} \right) + \sum_{j \notin I_k} y_j^2$$

Step 3: Therefore, $z_1^* = c(s_1^*)$, so the algorithm stops here, after 1 iteration.

We would only add one cut. We can notice again that the final step that we got gives the same solutions s^* and the same cost $c(s^*)$ as previously.