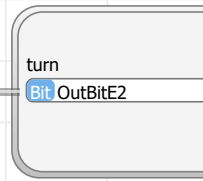
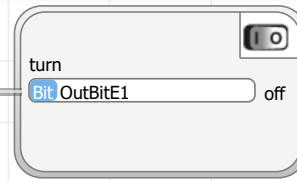
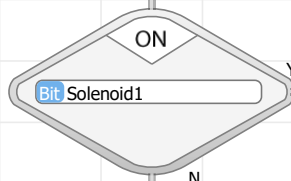
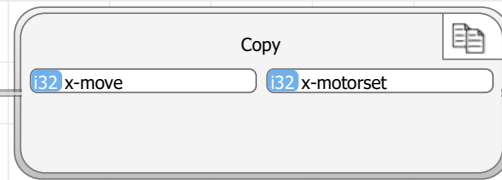
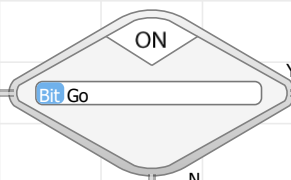


Stops motors when Limit sensors are triggered

Go must be switched on to manually move once. Then location of the arm can be moved without pressing the button again.



Solenoid1 controls both solenoids to close the gripper

