CS 365, Lecture 6 Foundations of Data Science Boston University

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Bayesian inference in the real-world

Reminder: Bayes' theorem

Bayes' theorem (aka Bayes' Law and Bayes' rule) is a direct application of conditional probabilities.

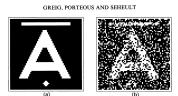


$$Pr[H|D] = \frac{Pr[D|H]Pr[H]}{Pr[D]}$$
, and $Pr[D] > 0$, or ...

posterior \propto likelihood \times prior.

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Problem: Given (b) can we infer (a)? In other words, can we restore the image from its corrupted-by-noise version?



How to formulate the problem? Any ideas?

Let's be Bayesian!

 $x = (x_1, ..., x_n)$ the original image (shown in (a)) $y = (y_1, ..., y_n)$ the observed corrupted image (e.g., the one shown in (b))

Assumption: The records y_1, \ldots, y_n are conditionally independent given x, and each has known conditional density $f(y_i|x_i)$ that depends only on x_i .

By Bayes' theorem:

$$p(x|y) \propto \underbrace{p(y|x)}_{\text{likelihood:how do we compute it?}} \times \underbrace{p(x)}_{\text{prior:what is a good prior?}}$$

Goal: output

$$x^* = \operatorname{arg\,max} p(x|y)$$

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Likelihood and Prior

Given our assumption, the likelihood function is

$$p(y|x) = \prod_{i=1}^{n} f(y_i|1)^{x_i} f(y_i|0)^{1-x_i}.$$

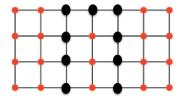
- What kind of patterns would we like the prior to enforce?
- Let's imagine how these characters would look on a binary image:

a,b,c,f,y,x,z,1,&,\$,@

Homogeneous patches that occasionally change discontinuously

Prior p(x)

$$p(x) \propto \exp\left\{\frac{1}{2}\sum_{i \neq i}\beta_{ij}\left(x_ix_j+(1-x_i)(1-x_j)\right)\right\}$$



• For an edge (u, v) where val(u) = val(v)

$$x_{\mu}x_{\nu} + (1 - x_{\nu})(1 - x_{\mu}) = x_{\mu}^{2} + (1 - x_{\mu})^{2} = 1.$$

• On the contrary for an edge where $val(u) \neq val(v)$

$$x_{u}(1-x_{u})+(1-x_{u})x_{u}=0.$$

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Our MAP inference becomes equivalent to minimizing (details on whiteboard)

$$\sum_{i=1}^{n} x_{i} \max(0, -\lambda_{i}) + \sum_{i=1}^{n} \max(0, \lambda_{i})(1 - x_{i}) + \frac{1}{2} \sum_{i \sim j} \beta_{ij} (x_{i} - x_{j})^{2},$$

where
$$\lambda_i = \frac{f(y_i|1)}{f(y_i|0)}$$
.

Let's rephrase this problem. Suppose $b_{ij} = b$ for all neighboring nodes for simplicity.

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- We have a $n \times m$ binary matrix
- We impose a grid structure
- We call two neighboring nodes bad if they have different values. We pay K units for each such pair.
- We are allowed to flip the value of any node, but we have to pay R units.
- The total cost is the sum of these two terms. How do we find the best assignment of values to nodes?

Any ideas? Is it NP-hard, poly-time solvable?

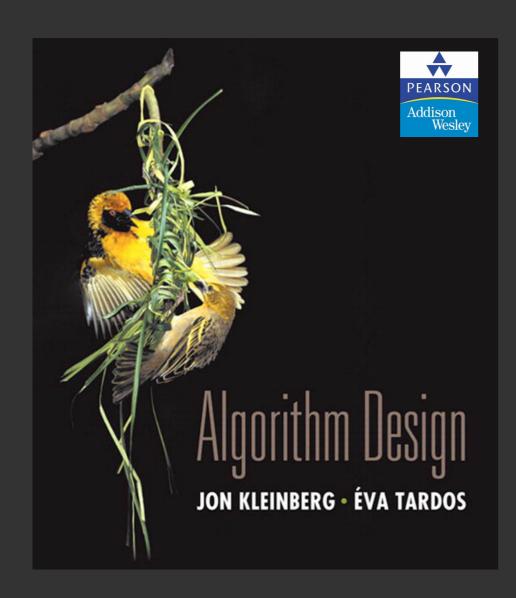
Max flow problem!

- Source s, sink t
- Arc of capacity R from s to each node u with value 0.
- Arc of capacity R from each u node with value 1 to sink t.
- Directed arcs from each node u to its neighbors with capacity K.

Details on whiteboard.

Assigned reading: Exact maximum a posteriori estimation for binary images

https://github.com/tsourolampis/cs365-spring22/blob/main/greig-porteous-seheult.pdf

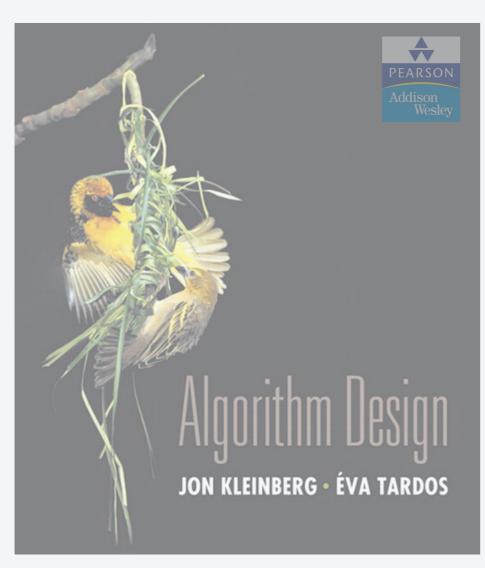


Lecture slides by Kevin Wayne
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http://www.cs.princeton.edu/~wayne/kleinberg-tardos

7. NETWORK FLOW I

- max-flow and min-cut problems
- ▶ Ford–Fulkerson algorithm
- max-flow min-cut theorem
- capacity-scaling algorithm
- shortest augmenting paths
- Dinitz' algorithm
- simple unit-capacity networks



SECTION 7.1

7. NETWORK FLOW I

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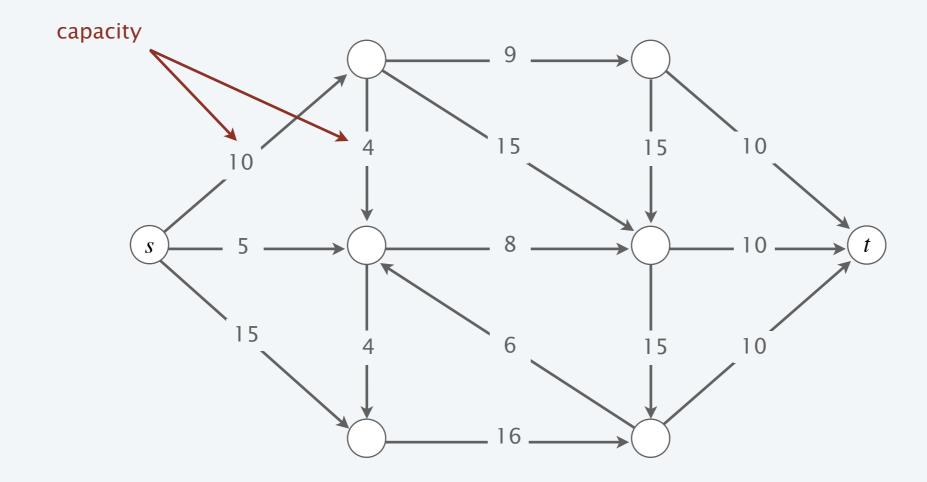
Flow network

A flow network is a tuple G = (V, E, s, t, c).

- Digraph (V, E) with source $s \in V$ and sink $t \in V$.
- Capacity $c(e) \ge 0$ for each $e \in E$.

assume all nodes are reachable from s

Intuition. Material flowing through a transportation network; material originates at source and is sent to sink.

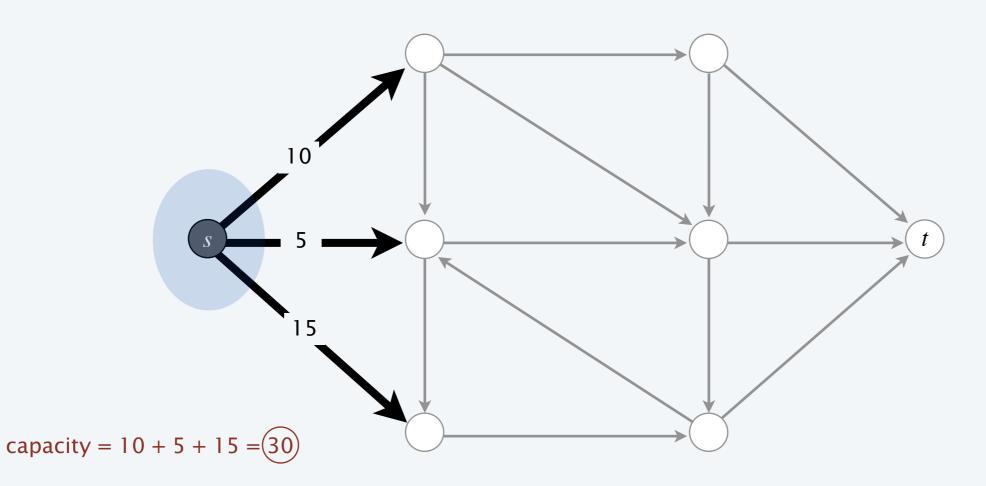


Minimum-cut problem

Def. An *st*-cut (cut) is a partition (A, B) of the nodes with $s \in A$ and $t \in B$.

Def. Its capacity is the sum of the capacities of the edges from A to B.

$$cap(A, B) = \sum_{e \text{ out of } A} c(e)$$

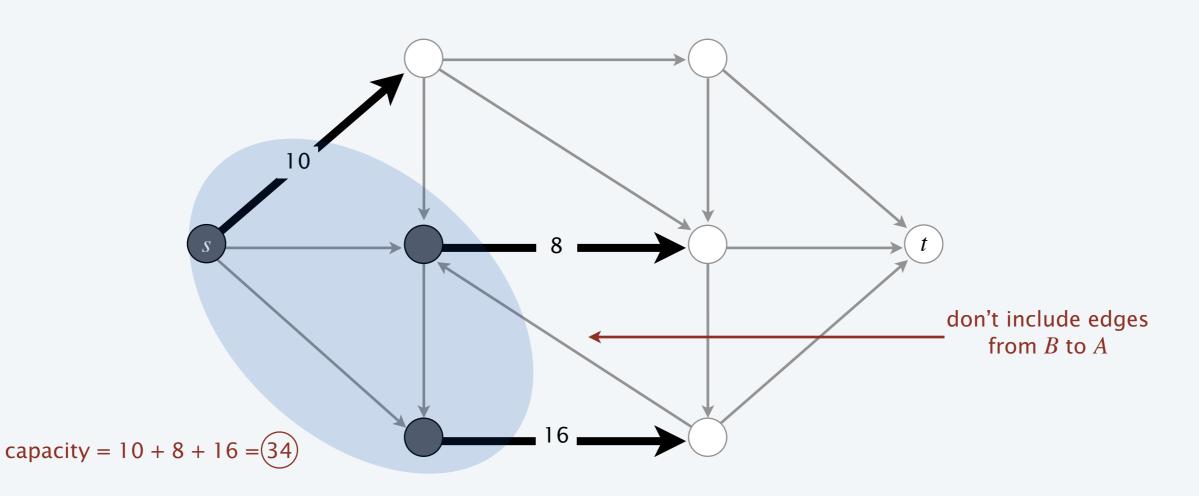


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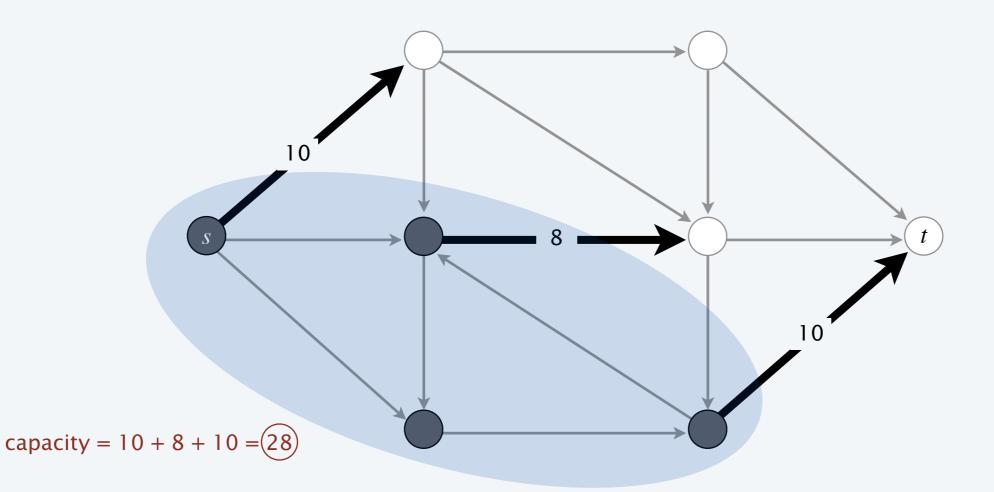
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Min-cut problem. Find a cut of minimum capacity.



Network flow: quiz 1

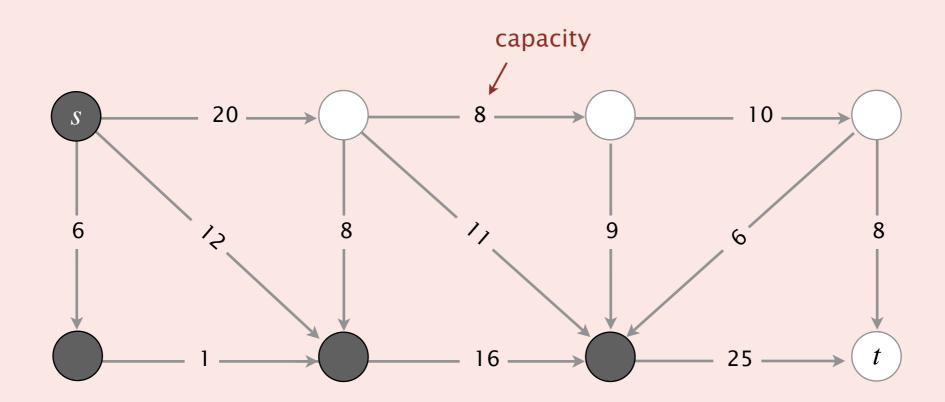


Which is the capacity of the given st-cut?

A.
$$11 (20 + 25 - 8 - 11 - 9 - 6)$$

C.
$$45 (20 + 25)$$

D.
$$79 (20 + 25 + 8 + 11 + 9 + 6)$$

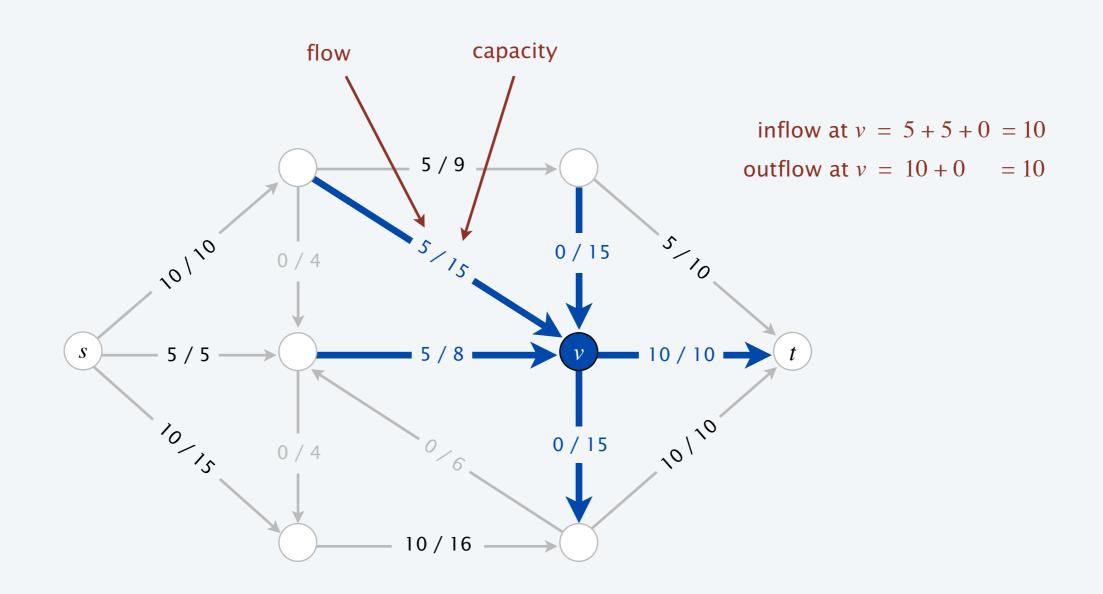


Maximum-flow problem

Def. An st-flow (flow) f is a function that satisfies:

- For each $e \in E$: $0 \le f(e) \le c(e)$ [capacity]

- For each $v \in V \{s, t\}$: $\sum f(e) = \sum f(e)$ [flow conservation]



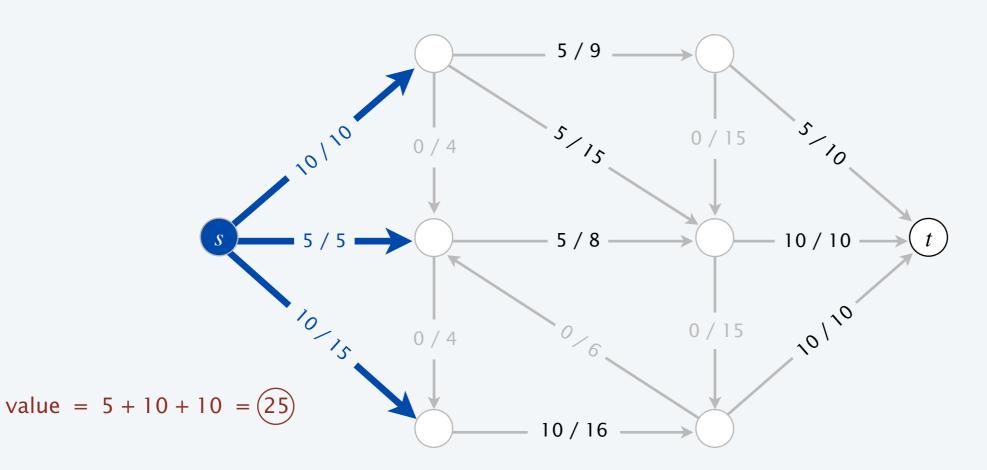
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Def. The value of a flow f is: $val(f) = \sum f(e) - \sum f(e)$ e out of s



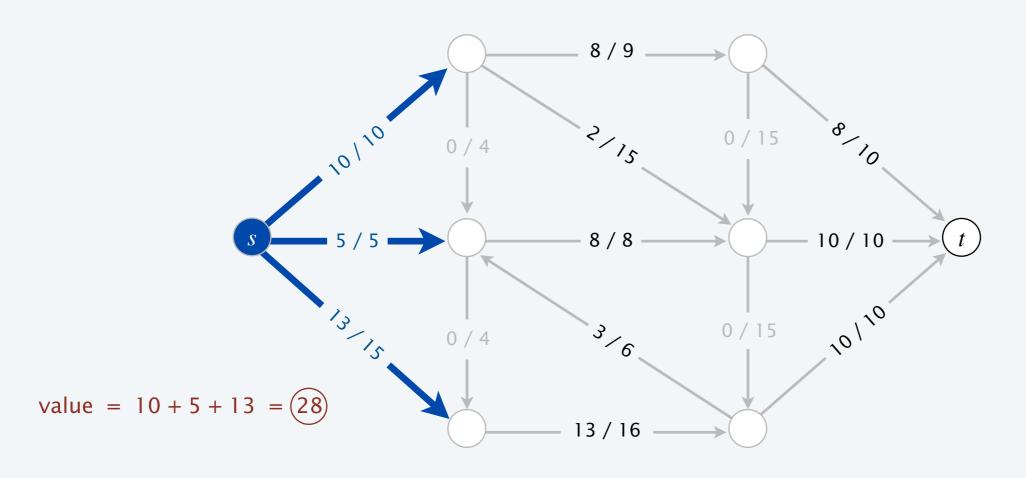
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Def. The value of a flow
$$f$$
 is: $val(f) = \sum_{e \text{ out of } s} f(e) - \sum_{e \text{ in to } s} f(e)$

Max-flow problem. Find a flow of maximum value.



Max-flow min-cut theorem

Max-flow min-cut theorem. Value of a max flow = capacity of a min cut.

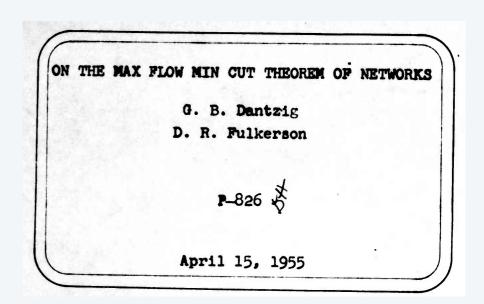


MAXIMAL FLOW THROUGH A NETWORK

L. R. FORD, JR. AND D. R. FULKERSON

Introduction. The problem discussed in this paper was formulated by T. Harris as follows:

"Consider a rail network connecting two cities by way of a number of intermediate cities, where each link of the network has a number assigned to it representing its capacity. Assuming a steady state condition, find a maximal flow from one given city to the other."



A Note on the Maximum Flow Through a Network*

P. ELIAS†, A. FEINSTEIN‡, AND C. E. SHANNON§

Summary—This note discusses the problem of maximizing the rate of flow from one terminal to another, through a network which consists of a number of branches, each of which has a limited capacity. The main result is a theorem: The maximum possible flow from left to right through a network is equal to the minimum value among all simple cut-sets. This theorem is applied to solve a more general problem, in which a number of input nodes and a number of output nodes are used.

from one terminal to the other in the original network passes through at least one branch in the cut-set. In the network above, some examples of cut-sets are (d, e, f), and (b, c, e, g, h), (d, g, h, i). By a simple cut-set we will mean a cut-set such that if any branch is omitted it is no longer a cut-set. Thus (d, e, f) and (b, c, e, g, h) are simple cut-sets while (d, g, h, i) is not. When a simple cut-set is