$$\begin{array}{c|c}
\hline
a \\
u(r,\pi h)=0 \\
\hline
T \\
\hline
2u(a,0)=0 \\
\hline
property \\
\hline
2
\end{array}$$

$$\nabla \dot{u} = 0 = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$

$$U = -\frac{\mathbf{T}_0}{\sigma} R \left( \frac{\Gamma^{k} + \alpha^{2k} \Gamma^{-k}}{R^{k} + \alpha^{2k} R^{-k}} \right) \cos k\theta$$

$$\frac{\partial U}{\partial r} = \frac{-T_0}{\sigma} \left( \frac{k r^{k-1} - c^{2k} k \dot{r}^{k-1}}{D^k + a^{2k} D^{-k}} \right) \cos k\theta$$

$$\frac{\Gamma \partial u}{\partial \Gamma} = \frac{-\text{IoR}}{\sigma} \left( \frac{K \Gamma^{k} - a^{2k} K \Gamma^{-k}}{\Omega^{k} + a^{2k} R^{-k}} \right) \cos k\theta$$

$$\frac{\partial}{\partial \Gamma} \left( \frac{\partial U}{\partial \Gamma} \right) = -\frac{\Gamma_0 R}{\sigma} \left( \frac{R^2 \Gamma^{R-1} + \alpha^{2R} R^2 \Gamma^{-R}}{R^2 + \alpha^{2R} R^2 \Gamma^{-R}} \right) COSKB$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial u}{\partial r}\right) = -\underline{\mathrm{To}}\,\mathrm{R}\,\mathrm{k}^2\left(\frac{r^{k-2}+a^{2k}r^{-k-2}}{\mathrm{R}^k+a^{2k}\mathrm{R}^{-k}}\right)\,\mathrm{COS}\,\mathrm{R}\,\theta$$

$$\frac{\partial^2 \mathcal{U}}{\partial \theta^2} = \frac{\mathbf{T} \cdot \mathbf{R} \, \mathbf{k}^2}{\sigma} \left( \frac{\Gamma^{\mathbf{k}} + a^{2\mathbf{k}} \Gamma^{-\mathbf{k}}}{\mathbf{R}^{\mathbf{k}} + a^{2\mathbf{k}} \mathbf{R}^{-\mathbf{k}}} \right) \cos \mathbf{k} \theta$$

$$\frac{1}{\int_{0}^{2} \frac{\partial U}{\partial \theta^{2}}} = \frac{1}{\int_{0}^{2} \Omega k^{2}} \left( \frac{\int_{0}^{k-2} + \alpha^{2k} \int_{0}^{k-2} k^{2k}}{\Omega^{2k} + \alpha^{2k} \Omega^{-k}} \right) COSK\theta$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(\frac{r}{\partial r}\frac{\partial u}{\partial r}\right) + \frac{1}{r^2}\frac{\partial^2 u}{\partial \theta^2} = -\frac{T_0R}{\sigma}R^2\left(\frac{r^{k-2} + a^{2k}r^{-k-2}}{R^k + a^{2k}R^{-k}}\right)\cos R\theta +$$

$$\frac{\sum_{Q} Q k^{2} \left( \frac{r^{k-2} + a^{2k} r^{-k-2}}{Q^{k} + a^{2k} R^{-k}} \right) COSK\theta} = 0$$

it satisfies the diff eq

$$U(r_1\pi/2) = \frac{-T_0}{\sigma} R \left( \frac{\Gamma^{k} + a^{2k} \Gamma^{-k}}{\Gamma^{k} + a^{2k} R^{-k}} \right) \cos \frac{k\pi}{2}, \quad k \text{ is odd } \therefore U(r_1\pi/2) = 0$$

$$U(R,\theta) = -\frac{T_0}{\sigma} R \left( \frac{R^{k} + a^{2k} R^{-k}}{R^{k} + a^{2k} R^{-k}} \right) \cos k\theta = -\frac{T_0}{\sigma} R \cos k\theta$$

$$\frac{\partial U}{\partial r}\left(a,\theta\right) = \frac{-\text{To}}{\sigma} \left(\frac{ka^{k-1} - c^{2k}ka^{-k-1}}{R^k + a^{2k}R^{-k}}\right) \cos k\theta = \frac{-\text{To}Rk}{\sigma} \left(\frac{a^{k-1} - a^{2k-k-1}}{R^k + a^{2k}R^{-k}}\right) \cos k\theta = 0$$

$$\frac{\partial U}{\partial \theta} = \frac{\text{To} R \, k \left( \frac{\Gamma^{k} + a^{2k} \Gamma^{-k}}{R^{k} + a^{2k} R^{-k}} \right) \text{ sin } k \theta$$

$$\frac{\partial U}{\partial \theta} (r, 0) = \frac{\text{To} R \, k}{\sigma} \left( \frac{\Gamma^{k} + q^{2k} \Gamma^{-k}}{R^{k} + q^{2k} R^{-k}} \right) \sin 0 = 0 \quad \checkmark$$

... 
$$U = -\frac{\Gamma_0}{\sigma} R \left( \frac{\Gamma^k + \alpha^{2k} \Gamma^{-k}}{R^k + \alpha^{2k} R^{-k}} \right) \cos k\theta$$
 is analytical rd

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta}$$

$$-\nabla u = \frac{To}{r} R \kappa \left( \frac{r^{\kappa-1} - a^{2\kappa} r^{-\kappa-1}}{R^{\kappa} + a^{2\kappa} R^{-\kappa}} \right) \cos k\theta \hat{r} - \frac{To}{r} R \kappa \left( \frac{r^{\kappa-1} + a^{2\kappa} r^{-\kappa-1}}{R^{\kappa} + a^{2\kappa} R^{-\kappa}} \right) \sin k\theta \hat{\theta}$$

$$= \frac{To}{r} R \kappa \left( \frac{r^{\kappa-1} - a^{2\kappa} r^{-\kappa-1}}{R^{\kappa} + a^{2\kappa} R^{-\kappa}} \right) \cos k\theta \hat{r} - \left( \frac{r^{\kappa-1} + a^{2\kappa} r^{-\kappa-1}}{R^{\kappa} + a^{2\kappa} R^{-\kappa}} \right) \sin k\theta \hat{\theta}$$

$$\nabla u = 0 = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$

$$O = \frac{1}{1} \left( \frac{3c}{3n} + c \frac{3c_s}{3n} \right) + \frac{c_s}{1} \frac{3\theta_s}{3n}$$

$$\frac{\partial^2 U_i}{\partial r^2} = \frac{U_{i+1} - 2U_{i} + U_{i-1}}{\Delta r^2}$$

$$\frac{\partial^2 u}{\partial \theta^2} = \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta \theta^2}$$

$$\frac{1}{r_{i}} \left( \frac{u_{i+1,j} - u_{i-1,j}}{2Dr} + r_{i} \left( \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{\Delta r^{2}} \right) \right) + \frac{1}{r_{i}^{2}} \left( \frac{u_{i,j+1} - 2u_{i,j+1} + u_{i,j-1}}{\Delta \theta^{2}} \right) = 0$$

$$\left(\left(\frac{1}{\Gamma_{i}}\right)\left(\frac{1}{2\Delta\Gamma}\right) + \left(\frac{1}{\Delta\Gamma^{2}}\right)\right)U_{i+1}j^{j} + \left(-\left(\frac{1}{\Gamma_{i}}\right)\left(\frac{1}{2\Delta\Gamma}\right) + \left(\frac{1}{\Delta\Gamma^{2}}\right)\right)U_{i-1}j^{j} - 2\left(\frac{1}{\Delta\Gamma^{2}} + \frac{1}{\Gamma_{i}^{2}\Delta\Theta^{2}}\right)U_{i,j} + \left(\frac{1}{\Gamma_{i}}\right)\left(\frac{1}{\Delta\Gamma^{2}}\right) + \left(\frac{1}{\Delta\Gamma^{2}}\right)\left(\frac{1}{\Delta\Gamma^{2}}\right) + \left(\frac{1}$$

$$\left(\frac{1}{\Gamma_{i}^{2}\Delta\theta^{2}}\right)U_{i,j+1} + \left(\frac{1}{\Gamma_{i}^{2}\Delta\theta^{2}}\right)U_{i,j-1}$$

$$A = \left( \left( \frac{1}{\Gamma_i} \right) \left( \frac{1}{2\Delta \Gamma} \right) + \frac{1}{\Delta \Gamma^2} \right)$$

Alli-1, j + Bli-1, j + Cli, j +

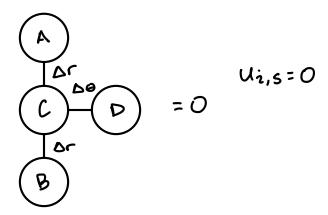
Duz,j-1+Duz,j+1

$$B = \left(-\left(\frac{1}{f_i}\right)\left(\frac{1}{2\Delta r}\right) + \frac{1}{\Delta r^2}\right)$$

$$C = -2 \left( \frac{1}{\Delta r^2} + \frac{1}{r_1^2 \Delta \theta^2} \right)$$

$$D = \left(\frac{1}{\Gamma_{i}^{2} \Delta \theta^{2}}\right)$$

$$\frac{\partial u}{\partial \theta} (f,0) = 0 = \underbrace{u_{i,2} - u_{i,0}}_{2\Delta \theta}$$



$$\frac{\partial u}{\partial r}(a,\theta) = 0 = \frac{u_{2,i} - u_{0,i}}{2\Delta r}$$

$$U(Q,\Theta) = f(\Theta) = -\frac{Io}{\sigma} R \cos k\Theta$$

$$= -Af(\Theta)$$

$$D$$

$$C \longrightarrow D = -A f(\pi/2)$$

$$B$$

$$C = C$$

$$C = C$$