

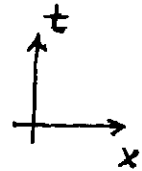
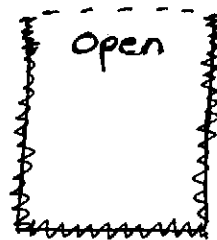
# Parabolic Equations

Prototype Form:  $\frac{\partial u}{\partial t} = L(u)$

↑  
Elliptic Operator  
(spatial derivatives)

Characteristics (2 identical real curves) dictate some "open" boundaries

e.g.



- Space ... handle same as Elliptic Case

$$u(x, t) \implies u_i(t)$$

$$L(u) \implies L_i(u_i) \quad \text{"FD molecule"}$$

$$\frac{du_i}{dt} = \underbrace{L_i(u_i)}_{F_i(t, u_i)} \quad \begin{array}{l} \text{"Lumped System"} \\ \text{discrete in space} \\ \text{continuous in time} \end{array}$$

Can consider as coupled set of ODEs involving variables  $u_i$  for  $i=1, 2, \dots, N$

All of the techniques for ODEs from EN6569 are available

- Time ... can take several views:

1.) FD in time 
$$\frac{u_i(t+\Delta t) - u_i(t)}{\Delta t} = L_i(u_i)^*$$

$u_i$  evaluated at some time point on  $[t, t+\Delta t]$

2.) Integrate in time

$$\int_t^{t+\Delta t} \frac{du_i}{dt} dt = \int_t^{t+\Delta t} L_i(u_i) dt$$

some type of averaged value on  $[t, t+\Delta t]$

$$u_i(t+\Delta t) - u_i(t) = \Delta t L_i(u_i)$$

These are alternate views of the same thing.

Speak of "Discrete System" when fully discretized  
(i.e. discrete in space)  
discrete in time

- Numerically then sol'n will propagate through time ... begin with IC's, constrained by BC's

Can accomplish this point by point or line by line

Classic equation to study:  $\frac{\partial u}{\partial t} = \nabla \cdot (\nabla u)$

## Possible Discrete Systems (discrete in space) (discrete in time)

(2)

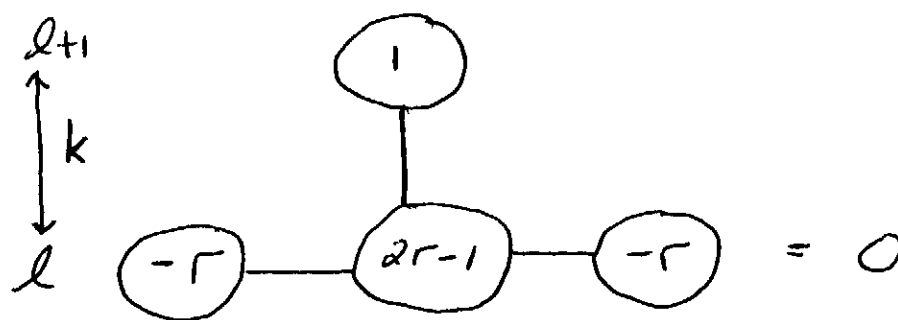
Example:  $\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$

Simplest treatment:  $\frac{\partial^2}{\partial x^2} \Rightarrow \frac{\int_x^2}{h^2} \Rightarrow \frac{\partial u_i}{\partial t} = \frac{D \int_x^2 u_i}{h^2}$   
 $\frac{\partial}{\partial t} \Rightarrow \frac{\Delta}{k}$  Lumped System

FD molecule:  $\frac{\Delta u_i^l}{k} = \frac{D \int_x^2 u_i^l}{h^2}$

$$u_i^{l+1} - u_i^l - \frac{Dk}{h^2} (u_{i-1}^l - 2u_i^l + u_{i+1}^l) = 0$$

$$\Gamma \equiv \frac{Dk}{h^2}$$



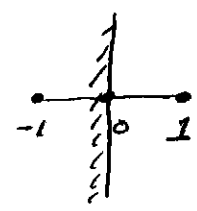
- "Explicit"
- pointwise propagation
- $O(k + h^2)$
- Forward Difference in  $t$  (or Euler integration)
- Conditional stability

- BCs handled same as elliptic problem

Type I: stop molecule "inside" the boundary

Type II, III: use shadow node strategy

e.g. at  $i=0$ ,  $-D \frac{\partial^2 u}{\partial x^2} = g_0$

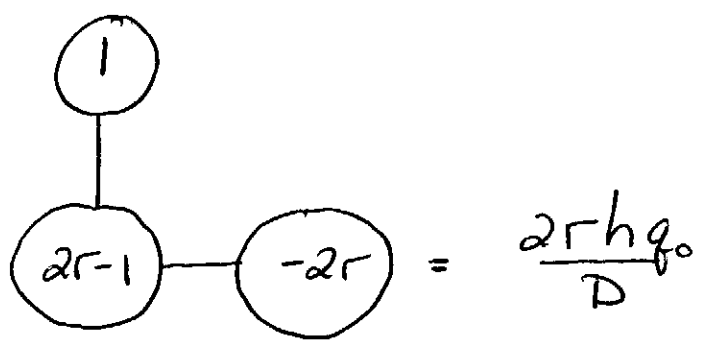


"shadow"  $\rightarrow \frac{u_{-1} - u_1}{2h} = \frac{g_0}{D} \Rightarrow u_{-1} = \frac{2hg_0}{D} + u_1$

PDE template:  $\frac{du_0}{dt} = \frac{D}{h^2} (u_{-1} - 2u_0 + u_1)$

Combine:  $\frac{du_0}{dt} = \frac{D}{h^2} (2u_1 - 2u_0 + \frac{2hg_0}{D})$

Molecule at  $i=0$ :

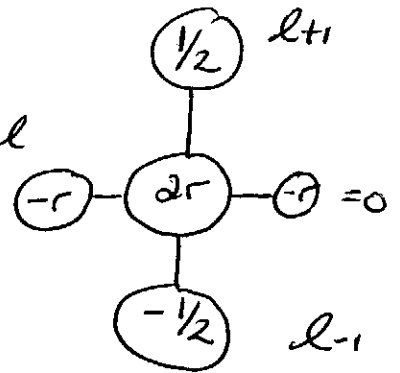




• Other time discretization possibilities...

1) "Leapfrog"

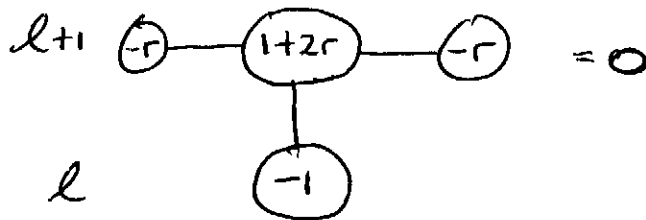
$$\frac{u_i^{l+1} - u_i^{l-1}}{2k} = \frac{D}{h^2} \sum_x u_i^l \Rightarrow \frac{u_i^{l+1} - u_i^{l-1}}{2} - r \sum_x u_i^l$$



Centered in  $t$  (equivalent to Midpoint Rule  $\int dt$ )

$O(h^2 + k^2)$ , but unconditionally unstable! Perfect example of intuition gone astray

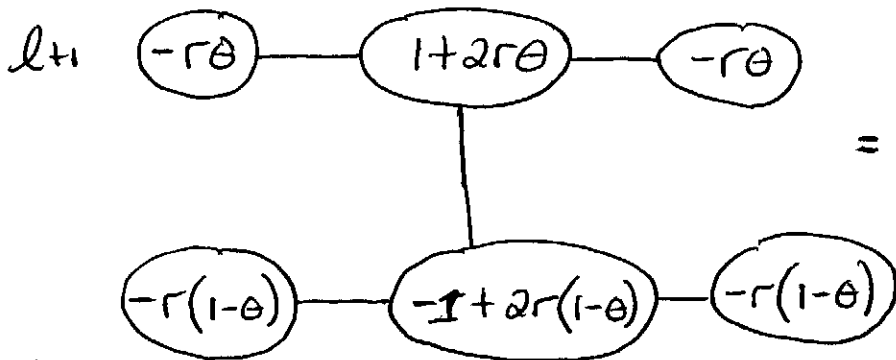
2) Backward difference:  $u_i^{l+1} - u_i^l = r \sum_x u_i^{l+1}$  (Implicit)



Matrix sol'n

3) Generalization:  $u_i^{l+1} - u_i^l = r\theta \sum_x u_i^{l+1} + r(1-\theta) \sum_x u_i^l$

averaging of  $u_i^l + u_i^{l+1}$  weighted by  $\theta$



$\theta = 1$  fully implicit  
 $\theta = 0$  explicit  
 $\theta = .5$  "Crank-Nicolson" (molecule centered at  $l + 1/2$ )  
 $O(k^2 + h^2)$   
 $\theta \geq .5$  Unconditional stability  
 $< .5$  Conditional Stability