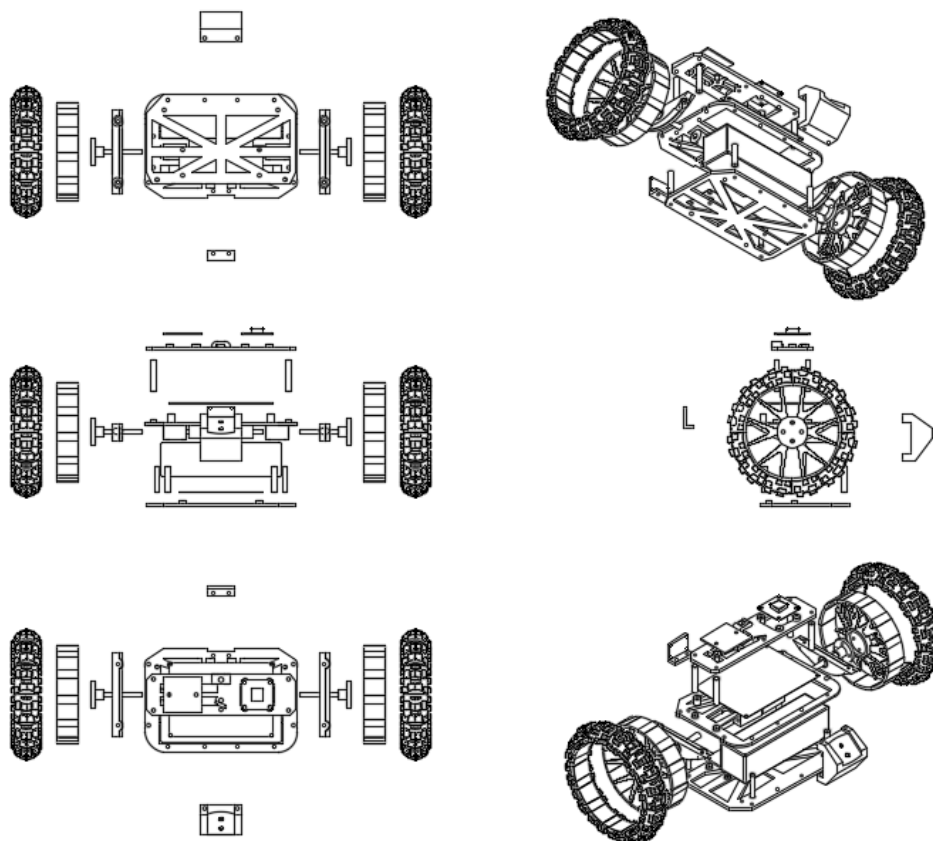


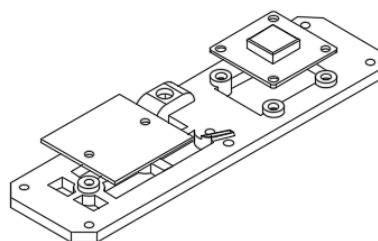
CanSat 組み上げ書

全体図



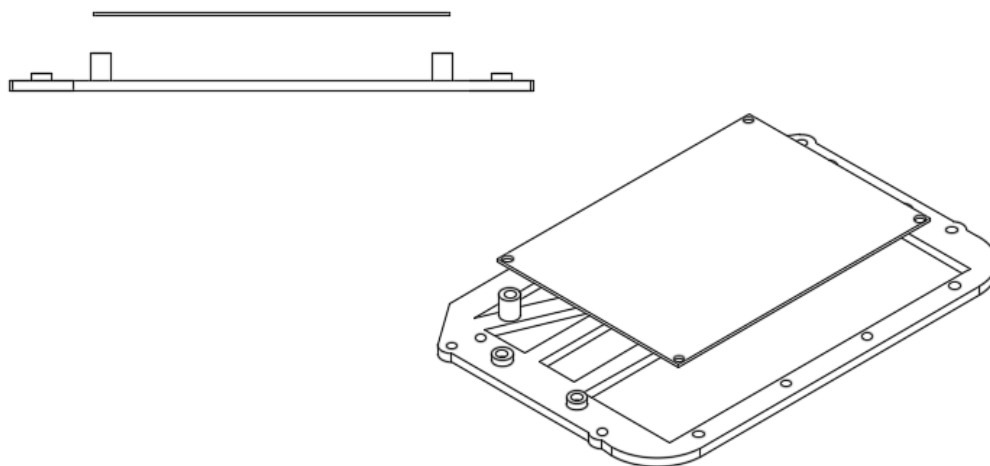
1.

1層目に9軸センサとGPSモジュールをねじ止めします。



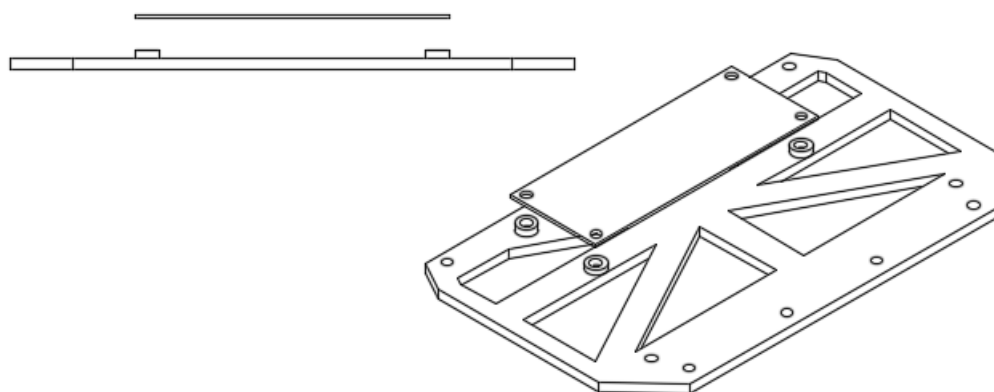
2.

2層目とメイン基板をねじ止めします.



3.

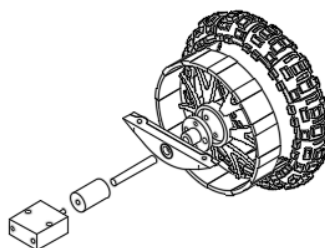
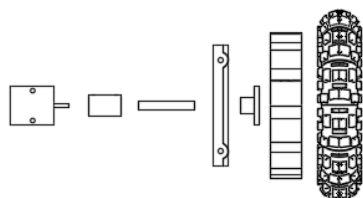
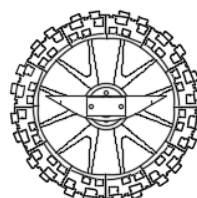
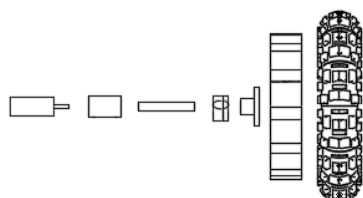
3層目と raspberrypi pico の基板をねじ止めします.



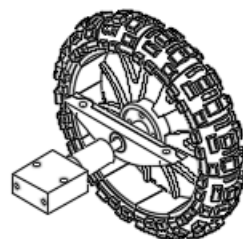
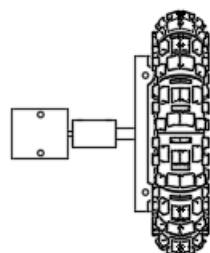
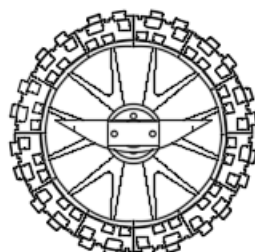
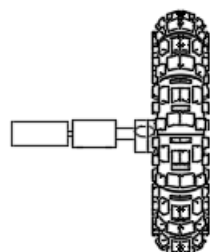
4.

タイヤを組み上げます.

組み上げ前



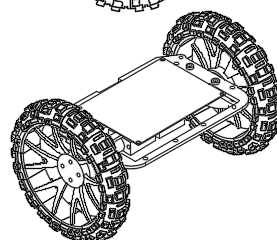
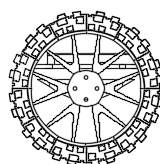
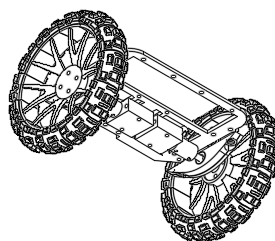
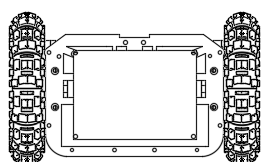
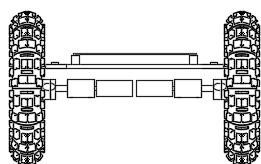
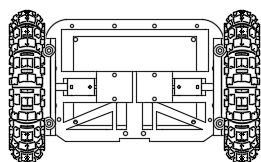
組み上げ後



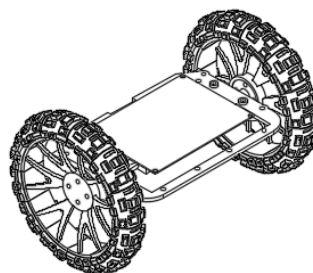
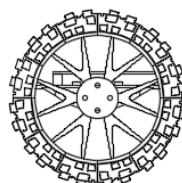
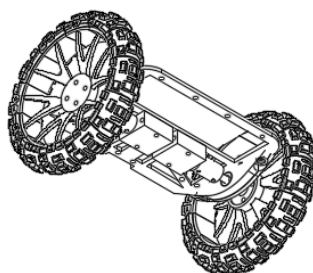
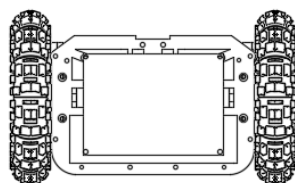
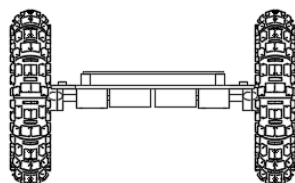
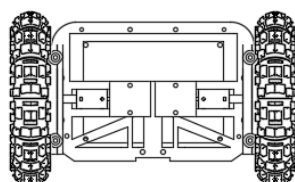
5.

タイヤを2層目にねじ止めします.

組み上げ前

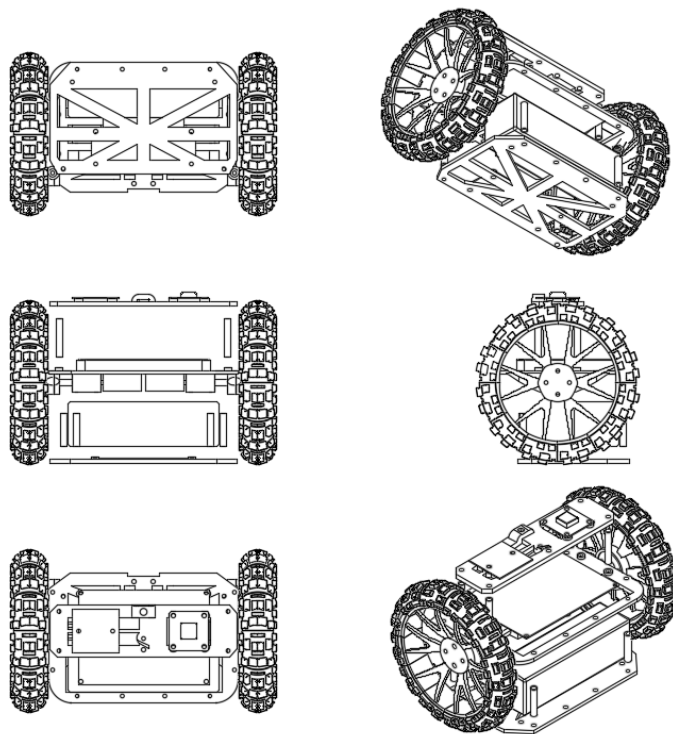


組み上げ後



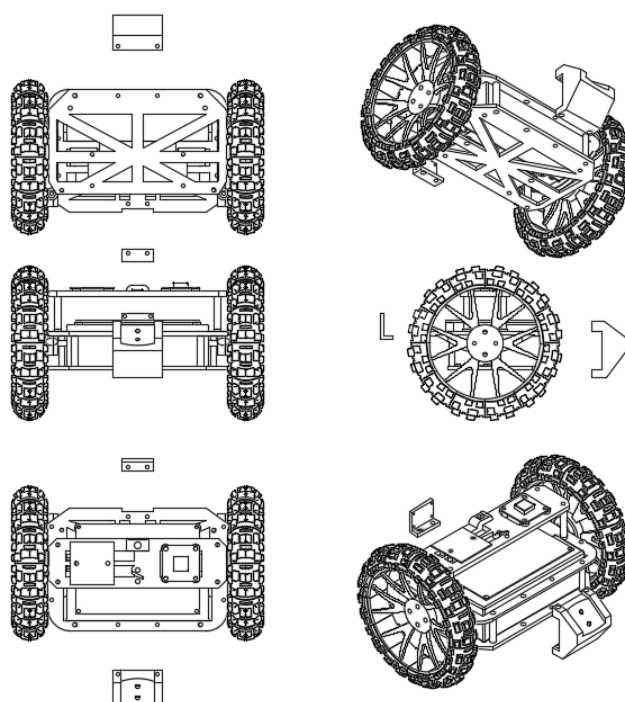
6.

1層目と3層目とリポバッテリーを2層目にスペーサーで止めます。



7.

カメラ締結部とスタビライザーを結合します。



8.

完成です.

