# **Chapter 3**

# **Class Documentation**

# 3.1 Matrix Class Reference

```
#include <Matrix.hpp>
```

### **Public Member Functions**

- Matrix (const Matrix &m)
- Matrix (int row, int col)
- Matrix (int n)
- ∼Matrix ()
- void setValue (double value, int row, int col) const
- double & getValue (int row, int col) const
- int getNumRow () const
- int getNumCol () const
- double det () const
- Matrix & operator= (const Matrix &m)
- double & operator() (int i, int j)
- · Matrix T () const
- double rowMax (int row, int col=0, bool abs\_true=true) const
- double colMax (int col, int row=0, bool abs\_true=true) const
- int argRowMax (int row, int col=0, bool abs\_true=true) const
- int argColMax (int col, int row=0, bool abs\_true=true) const
- void swapRow (int row1, int row2) const
- void swapCol (int col1, int col2) const
- · void swap (int row1, int col1, int row2, int col2) const
- double norm (int p) const
- double norm (std::string p) const

### **Protected Attributes**

- double \* mData
- · const int mRow
- const int mCol
- const int mSize

### **Friends**

- Matrix operator+ (const Matrix &m1, const Matrix &m2)
- Matrix operator+ (const Matrix &m, const double &a)
- Matrix operator+ (const double &a, const Matrix &m)
- Matrix operator- (const Matrix &m1, const Matrix &m2)
- Matrix operator- (const Matrix &m, const double &a)
- Matrix operator- (const double &a, const Matrix &m)
- Matrix operator\* (const Matrix &m1, const Matrix &m2)
- Matrix operator\* (const Matrix &m, const double &a)
- Matrix operator\* (const double &a, const Matrix &m)
- Matrix operator/ (const Matrix &m, const double &a)
- double dot (const Matrix &m1, const Matrix &m2)
- Matrix gaussianElimination (const Matrix &A\_orig, const Matrix &b)
- Matrix cgs (const Matrix &A, const Matrix &b)
- Matrix operator/ (const Matrix b, const Matrix A)
- std::tuple < Matrix, Matrix, Matrix, int > lu (const Matrix &A)
- double det (const Matrix &A)
- std::tuple < Matrix, Matrix > qr (const Matrix &A, bool reduced=false)
- Matrix Isq (const Matrix &A, const Matrix &b)
- Matrix hessenbergReduction (const Matrix &A)
- Matrix eigenVal (const Matrix &A, double tol=1.0e-10)
- Matrix operator- (const Matrix &m)
- bool operator== (const Matrix &m1, const Matrix &m2)
- bool operator!= (const Matrix &m1, const Matrix &m2)
- Matrix transpose (const Matrix &m)
- const Matrix eye (int row, int col)
- const Matrix eye (int n)
- const Matrix rand (int row, int col)
- const Matrix rand (int n)
- void print (const Matrix &m)
- std::ostream & operator<< (std::ostream &output, const Matrix &m)
- double norm (Matrix &m, int p)
- double norm (Matrix &m, std::string p)
- int \* size (const Matrix &m)

# 3.1.1 Constructor & Destructor Documentation

### 3.1.1.1 Matrix() [1/3]

Copy constructor for the matrix class

Creates a copy of matrix object with the same dimensions and element values.

#### **Parameters**

m The matrix object from which a copy is made

#### Returns

Matrix object with desired number of row and columns

# 3.1.1.2 Matrix() [2/3]

Constructor for the matrix class

Creates a matrix object with the desired number of rows and columns with element values initialised as zero. Inputs row and col become attributes mRow and mCol. mSize := mRow \* mSize.

#### **Parameters**

row	The desired number of row in the matrix
col	The desired number of row in the matrix

### Returns

Matrix object with desired number of row and columns

# 3.1.1.3 Matrix() [3/3]

```
{\tt Matrix::Matrix} ( {\tt int}\ n )
```

Constructor for the matrix class

Creates a square matrix object with the desired number of rows and columns with element values initialised as zero. Input n become attributes mRow and mCol. mSize := mRow \* mSize.

### **Parameters**

n The desired number of rows and columns in the square matrix

### Returns

Matrix object with desired number of row and columns

### 3.1.1.4 $\sim$ Matrix()

```
Matrix::\sim Matrix ( )
```

Destructor for the matrix class

Once a matrix object goes out of scope the destructor is called. It deletes the memory array used to store the matrix element data

# 3.1.2 Member Function Documentation

# 3.1.2.1 argColMax()

```
int Matrix::argColMax (
int col,
int row = 0,
bool abs_true = true ) const
```

Find argument of maximum value in column, by default this is the absolute max

Find column coordinate with maximum value in column, and optionally from a starting row (default is the first row).

## **Parameters**

col	Column to check for max
row	Optional: Rows to start checking for max from
abs_true	Optional: return absolution max or regular max

# Returns

Row position of column max value.

# 3.1.2.2 argRowMax()

```
int Matrix::argRowMax (
int row,
int col = 0,
bool abs_true = true ) const
```

Find argument of maximum value in row, by default this is the absolute max

Find row coordinate with maximum value in column, and optionally from a starting column (default is the first column).

### **Parameters**

row	Row to check for max
col	Optional: Columns to start checking for max from
abs_true	Optional: return absolution max or regular max

### Returns

Column positon of row max value.

### 3.1.2.3 colMax()

```
double Matrix::colMax (
int col,
int row = 0,
bool abs_true = true ) const
```

Find maximum value in column, by default this is the absolute max

Find maximum value in column, and optionally from a starting row (default is the first row).

### **Parameters**

col	Column to check for max
row	Optional: Row to start checking for max from
abs_true	Optional: return absolution max or regular max

# Returns

Row max value.

# 3.1.2.4 det()

```
double Matrix::det ( ) const
```

Calculate determinant of square matrix

Find the determinant of a matrix using LU decomposition

## Returns

the determinant of self/this

### 3.1.2.5 getNumCol()

```
int Matrix::getNumCol ( ) const
```

Getter: Gets the number of columns in Matrix object.

**Returns** 

The number of columns in matrix object

# 3.1.2.6 getNumRow()

```
int Matrix::getNumRow ( ) const
```

Getter: Gets the number of rows in Matrix object.

Returns

The number of rows in matrix object

# 3.1.2.7 getValue()

Getter: Used to get values of matrix elements.

Given valid coordinates this method gets the value at the coordinate location (using 0-indexing)

#### **Parameters**

row	The row position of the element to be returned
col	The row position of the element to be returned

# Returns

Value of element at specified coordinate location

# 3.1.2.8 norm() [1/2]

```
double Matrix::norm ( \quad \text{int } p \text{ ) const}
```

### Calculates matrix norm

Calculates induces matrix 1-norm and 2-norm (for symmetric matrices). If matrices are vectors (1 row or col) calculates vector norm.

#### **Parameters**

```
p choice of norm. For matrices this is 1 or 2-norm, for vectors this can be any positive integer
```

### Returns

Norm calculate for self/this

### 3.1.2.9 norm() [2/2]

```
double Matrix::norm ( {\tt std::string}\ p\ )\ {\tt const}
```

### Calculates matrix norm

Calculates induces matrix frobenius norm and infinity -norm .

#### **Parameters**

```
p choice of norm.
```

### Returns

Norm calculate for self/this

# 3.1.2.10 operator()()

Getter: Allows MATLAB like access of Matrix elements (1-indexing)

Allows matrix elements to be accessed and indexed in a MATLAB fashion i.e.  $A_{ij} = A(i,j)$ 

# **Parameters**

<i>i</i> the row of desired element (in 1-indexing)		the row of desired element (in 1-indexing)
	j	the column of the desired element (in 1-indexing)

### Returns

The element at positon (i,j) (in 1-indexing)

# 3.1.2.11 operator=()

### Assignment operator

Assigns one matrix object to another, however, they are not linked. Essential creates a copy.

#### **Parameters**

```
m Matrix object we wish to "copy" to self/this.
```

### Returns

Updated self/this object with values of m.

# 3.1.2.12 rowMax()

```
double Matrix::rowMax (
int row,
int col = 0,
bool abs_true = true ) const
```

Find maximum value in row, by default this is the absolute max

Find maximum value in row, and optionally from a starting column (default is the first column).

## **Parameters**

row	Row to check for max
col	Optional: Column to start checking for max from
abs_true	Optional: return absolution max or regular max

### Returns

Row max value.

# 3.1.2.13 setValue()

Setter: Used to set values of matrix elements.

Given a value and valid coordinates this method sets the value at the coordinate location to the given value.

### **Parameters**

value	The value assign to the specified coordinates
row	The row position of the element to be updated
col	The row position of the element to be updated

### 3.1.2.14 swap()

```
void Matrix::swap (
int row1,
int col1,
int row2,
int col2 ) const
```

Swap two elements in matrix

### **Parameters**

row1	Element 1 row coordinate
col1	Element 1 column coordinate
row2	Element 2 row coordinate
col2	Element 2 column coordinate

# 3.1.2.15 swapCol()

Swap two columns in matrix

# **Parameters**

col1	Row 1 position
col2	Row 2 position

# 3.1.2.16 swapRow()

Swap two columns in matrix

### **Parameters**

row1	Row 1 position
row2	Row 2 position

# 3.1.2.17 T()

```
Matrix Matrix::T ( ) const
```

Transposes matrix

Create transpose matrix by swapping rows and columns.

Returns

transposed matrix

# 3.1.3 Friends And Related Function Documentation

# 3.1.3.1 cgs

# 3.1.3.2 det

```
double det ( {\tt const\ Matrix\ \&\ A\ )} \quad [{\tt friend}]
```

Calculate determinant of square matrix

Find the determinant of a matrix using LU decomposition

### **Parameters**

A target matrix to find determinant of

### Returns

the determinant of self/this

### 3.1.3.3 dot

Dot product between two matrices (vectors) with one column or row

Performs the vector dot product on matrix or vector objects (i.e those with one column or row)

### **Parameters**

m1	First vector (matrix)
m2	Second vector (matrix)

### Returns

Dot product of vector m1 and vector m2.

# 3.1.3.4 eigenVal

Finds eigenvalues of symmetric matrix using QR Algorithm

Uses QR Algorithm with shift, hessenberg reduction, and deflation to finds eigenvalues.

# **Parameters**

Α	Target matrix for eigenvalues
tol	Tolerance for when eigenvalue has been found. Determined by H(k,k-1) approx 0.

### Returns

eigVals: Vecotr of eigenvalues of A.

# 3.1.3.5 eye [1/2]

```
const Matrix eye ( \quad \text{int } n \text{ )} \quad [\text{friend}]
```

Square identity matrix constructor

Creates a square identity matrix with n rows and n columns.

#### **Parameters**

n The desired number of rows and columns in the square identity matrix

### Returns

Square identity matrix with desired number of row and columns

# 3.1.3.6 eye [2/2]

```
\begin{array}{c} \text{const Matrix eye (} \\ & \text{int } row, \\ & \text{int } col \text{ )} \quad [\text{friend}] \end{array}
```

Identity matrix constructor

Creates an identity matrix with the desired number of rows and columns with ones on the diagonal and zeros everywhere else

## Parameters

row	The desired number of row in the matrix
col	The desired number of row in the matrix

### Returns

Matrix object with desired number of row and columns with ones on the diagonal

### 3.1.3.7 gaussianElimination

Solves full-rank square system Ax = b with Gaussian Elimination.

### **Parameters**

Α	Matrix of the linear system
b	vector of the linear system

### Returns

vector x: solution to the linear system

# 3.1.3.8 hessenbergReduction

Finds upper Hessenberg reduction of matrix A

Compute the upper Hessenberg reduction of A using Householder reflections

# Parameters

```
A Target matrix for upper Hessenberg reduction
```

### Returns

Matrix H, upper Hessenberg reduction of A.

# 3.1.3.9 lsq

Finds least squares solutio to overdetermined system |Ax-b|\_2

It attempts to solve the least squares solution x that minimizes norm(b-A\*x,2). Uses reduced QR factorisation and then gaussian elimination.

#### **Parameters**

Α	Overdetermined matrix in $Ax = b$
b	Vector b

#### Returns

Solution x to least-squares problem

#### 3.1.3.10 lu

Compute LU decompositon with partial pivoting of square matrix

### **Parameters**

A Target matrix for LU decompositon

### Returns

Matrix P - permutation matrix, Matrix L - lower triangular matrix Matrix U - upper triangular matrix, int sign - number of permutation made

### 3.1.3.11 norm [1/2]

### 3.1.3.12 norm [2/2]

# 3.1.3.13 operator"!=

non-equality check between two matrices

Overloads non-equality boolean operator to check non-equality element-wise between two matrices

### **Parameters**

m1	First matrix
m2	Second matrix

#### Returns

True or false

# 3.1.3.14 operator\* [1/3]

Multiplication between doubles and Matrix object

Overloads multiplication operator to support element-wise multiplication of a double number.

### **Parameters**

m	Matrix object
а	double number

# Returns

Matrix object with element updated by multiplication of double value to element values,

### 3.1.3.15 operator\* [2/3]

Multiplication between doubles and Matrix object

Overloads multiplication operator to support element-wise multiplication of a double number.

### **Parameters**

m	Matrix object
а	double number

### Returns

Matrix object with element updated by multiplication of double value to element values,

# 3.1.3.16 operator\* [3/3]

Matrix-matrix multiplication

Overloads multiplication operator for matrix-matrix multiplication. Supports non-square matrices.

#### **Parameters**

m1	Left matrix
m2	Right matrix

### Returns

Matrix multiplication of m1 \* m2

# 3.1.3.17 operator+ [1/3]

Addition between doubles and Matrix object

Overloads addition operator to support element-wise addition of a double number.

### **Parameters**

m	Matrix object
а	double number

### Returns

Matrix object with element updated by addition of double value

### 3.1.3.18 operator+ [2/3]

Addition between doubles and Matrix object

Overloads addition operator to support element-wise addition of a double number.

#### **Parameters**

m	Matrix object
а	double number

### Returns

Matrix object with element updated by addition of double value

### 3.1.3.19 operator+ [3/3]

Addition operator for matrix-matrix addition

Overloads addition operator to support addition of two matrix objects with the same dimensions

### **Parameters**

m1	First matrix object
m1	Second matrix object

#### Returns

Matrix object that results from element-wise addition of m1 and m2.

# 3.1.3.20 operator- [1/4]

Subtraction between doubles and Matrix object

Overloads subtraction operator to support element-wise subtraction of a double number.

### **Parameters**

m	Matrix object
а	double number

### Returns

Matrix object with element updated by addition of double value to negative element values, i.e. a - m[0,0]

### 3.1.3.21 operator- [2/4]

Return element-wise negative of input matrix

Overloads unary operator to perform element-wise negation.

#### **Parameters**

```
m Input matrix
```

## Returns

Negative of input matrix

# 3.1.3.22 operator- [3/4]

Subtraction between doubles and Matrix object

Overloads subtraction operator to support element-wise subtraction of a double number.

# **Parameters**

m	Matrix object
а	double number

### Returns

Matrix object with element updated by subtraction of double from element values.

### 3.1.3.23 operator- [4/4]

Subraction operator for matrix-matrix subtraction

Overloads subtraction operator to support subtraction of two matrix objects with the same dimensions

### **Parameters**

m1	First matrix object
m1	Second matrix object

### Returns

Matrix object that results from element-wise subtraction of m1 and m2.

### 3.1.3.24 operator/ [1/2]

Division between doubles and Matrix object

Overloads division operator to support element-wise division of a double number.

### **Parameters**

т	Matrix object
а	double number

# Returns

Matrix object with element updated by multiplication of double value to element values,

# 3.1.3.25 operator/ [2/2]

### 3.1.3.26 operator <<

Print with in std::cout;

Overloads << operator so that matrices and correctly formatted when using std::cout

### **Parameters**

output	current stream to cout
m	matrix to be printed

### Returns

Updated stream with matrix formating

### 3.1.3.27 operator==

Equality check between two matrices

Overloads equality boolean operator to check equality element-wise between two matrices

# **Parameters**

m1	First matrix
m2	Second matrix

### Returns

True or false

# 3.1.3.28 print

Prints matrix object in formatted way

#### **Parameters**

```
m Matrix to be printed
```

### 3.1.3.29 qr

Calculates QR factorisation of matrix

Performs a qr factorisation on m-by-n matrix A such that A = Q\*R. The factor R is an m-by-n upper triangular matrix and Q is an m-by-m orthogonal matrix.

### **Parameters**

Α	Target matrix for QR factorisation
reduce	Optional: by default false, if true returns reduced QR

### Returns

Matrix Q - orthogonal matrix, Matrix R - upper triangular

## 3.1.3.30 rand [1/2]

```
\begin{array}{c} \text{const Matrix rand (} \\ & \text{int } n \text{ )} & \text{[friend]} \end{array}
```

Random square matrix

Creates square matrix with dimensions  $n \times n$ , elements are given values sampled from uniform distribution between 0 and 1.

### **Parameters**

```
n Number of rows of square matrix
```

### Returns

Matrix object with random element values between 0 and 1 on a uniform distribution.

### 3.1.3.31 rand [2/2]

```
const Matrix rand (
            int row,
            int col ) [friend]
```

Random matrix with desired number of rows and columns

Creates matrix with dimensions row x col, elements are given values sampled from uniform distribution between 0 and 1.

#### **Parameters**

row	Number of rows
col	Number of columns

### Returns

Matrix object with random element values between 0 and 1 on a uniform distribution.

### 3.1.3.32 size

Gets number of rows and columns

# Parameters

m Matrix from which number of rows and columns want to be known

### Returns

Array of size 2 [mRow, mCol];

## 3.1.3.33 transpose

Transposes matrix

Create transpose matrix by swapping rows and columns.

# **Parameters**

m Matrix to be transposed

# Returns

transposed matrix

# 3.1.4 Member Data Documentation

# 3.1.4.1 mCol

const int Matrix::mCol [protected]

### 3.1.4.2 mData

double\* Matrix::mData [protected]

# 3.1.4.3 mRow

const int Matrix::mRow [protected]

### 3.1.4.4 mSize

const int Matrix::mSize [protected]

The documentation for this class was generated from the following files:

- include/Matrix.hpp
- Matrix.cpp