

AMMM-COURSE PROJECT

Description

The goal of this project is to select faculty members from the university to form a committee to update the curriculum of the computer science degree. The selection process must match department-specific requirements and ensure that the selected members are compatible, according to a compatibility matrix. Furthermore, the average compatibility among selected members should be maximized while satisfying the following constraints.

CPLEX

Files

- **Model File:**

The model file **project.mod** contains the mathematical model for the optimization problem. It serves as the primary source for the optimization logic.

```
var src = new IloOplModelSource("project.mod");
```

- **Data File:**

The data file **project.1.dat** contains the input parameters for the model. If you want to change the input data for the optimization, you must edit this file accordingly.

```
var data = new IloOplDataSource("project.1.dat"); ### Execution to run the project, use IBM ILOG CPLEX to load the model and data files. The program will use project.mod as the model source and project.1.dat as the input data source.
```

HEURISTICS

Algorithm Overview

This project provides three different heuristic and meta heuristic algorithms: **Greedy**, **Local Search**, and **GRASP**. The main difference between these algorithms is the selection strategy for forming the committee and the associated parameters.

You can choose which algorithm to use by simply modifying the **algorithm** parameter in the configuration file.

Configuration:

- **algorithm:** Specifies which algorithm to use. Set this to one of the following options:
 - **greedy** — for the Greedy algorithm.

- `local_search` — for the Local Search algorithm.
- `grasp` — for the GRASP algorithm.
- **input_file**: Path to the input file containing problem instance data. Default value is `data/project.1.dat`
- **solution_file**: Path to the output file where the solution will be saved. Default value is `output_greedy.sol`
- **verbose**: Verbose mode: set to `True` for detailed output, `False` for minimal output. Default value is `True`.

For Greedy and Local Search, the `tune`, the `alpha`, the `max_iterations` and GRASP-specific parameters (like `alpha_start`, `alpha_end`, `alpha_step`) are not required.

GREEDY

Execution:

- Navigate to the `heuristics/` directory:
\$ `cd heuristics/`
- Run the following command \$ `python3 heuristic.py --config_file config/greedy.dat`
- The generated instances will be saved in the solutions directory.

GREEDY + LOCAL SEARCH

Execution:

- Navigate to the `heuristics/` directory:
\$ `cd heuristics/`
- Run the following command \$ `python3 heuristic.py --config_file config/local_search.dat`
- The generated instances will be saved in the solutions directory. `## GRASP`

Configuration

These configurations are specific parameters for the grasp algorithm. - **alpha_start**: Starting value of alpha for GRASP tuning

- **alpha_end**: Ending value of alpha for GRASP tuning
- **alpha_step**: Step size for alpha in GRASP tuning
- **alpha**: Fixed alpha value used in GRASP if tuning is not needed
- **max_iterations**: Maximum number of iterations for the algorithm
- **tune**: Set to `True` to tune the alpha parameter, `False` to use the fixed alpha value

Two Modes of GRASP

1) Fixed Alpha Mode (**tune=False**):

- If **tune=False**, the algorithm will use the single fixed value for alpha that you provide in the configuration.
 - The **alpha** parameter controls the trade-off between greedy (deterministic) choices and random (adaptive) choices in the construction phase. #####
- ### 2) Tuning Mode (**tune=True**):
- If **tune=True**, the algorithm will automatically search for the optimal **alpha** value by trying multiple values in the range from **alpha_start** to **alpha_end** with a step size of **alpha_step**.
 - In this case, the **alpha** value is not used directly. Instead, the algorithm will run multiple times, each time with a different value of alpha, and will choose the one that gives the best performance.

Execution

- Navigate to the **heuristics/** directory:
\$ cd heuristics/
- Run the following command \$ python3 heuristic.py --config_file config/grasp.dat
- The generated instances will be saved in the solutions directory. # INSTANCE GENERATOR ## Configuration

The **config.py** file allows you to customize the instance generation process. Below is the default configuration:

```
class Config:
    instancesDirectory = 'output'
    fileNamePrefix = 'project.'
    fileNameExtension = 'dat'
    numInstances = 10
    minDepartments = 2
    maxDepartments = 4
    minMembers = 50
    maxMembers = 70
```

Explanation of Parameters

- **instancesDirectory**: Directory where the generated instances will be saved.
- **fileNamePrefix**: Prefix for the generated instance file names.
- **fileNameExtension**: File extension for the generated instance files.
- **numInstances**: Number of instances to generate.
- **minDepartments / maxDepartments**: Minimum and maximum number of departments in an instance.
- **minMembers / maxMembers**: Minimum and maximum number of members in an instance.

Execution

To run the instance generator, follow these steps: - Navigate to the **instance-Generator/** directory:

\$ cd instanceGenerator/ - Modify the **config.py** file located under the config directory to adjust the generation parameters.

- Run the following command to generate random instances: **\$ python3 main.py** The generated instances will be saved in the output directory.