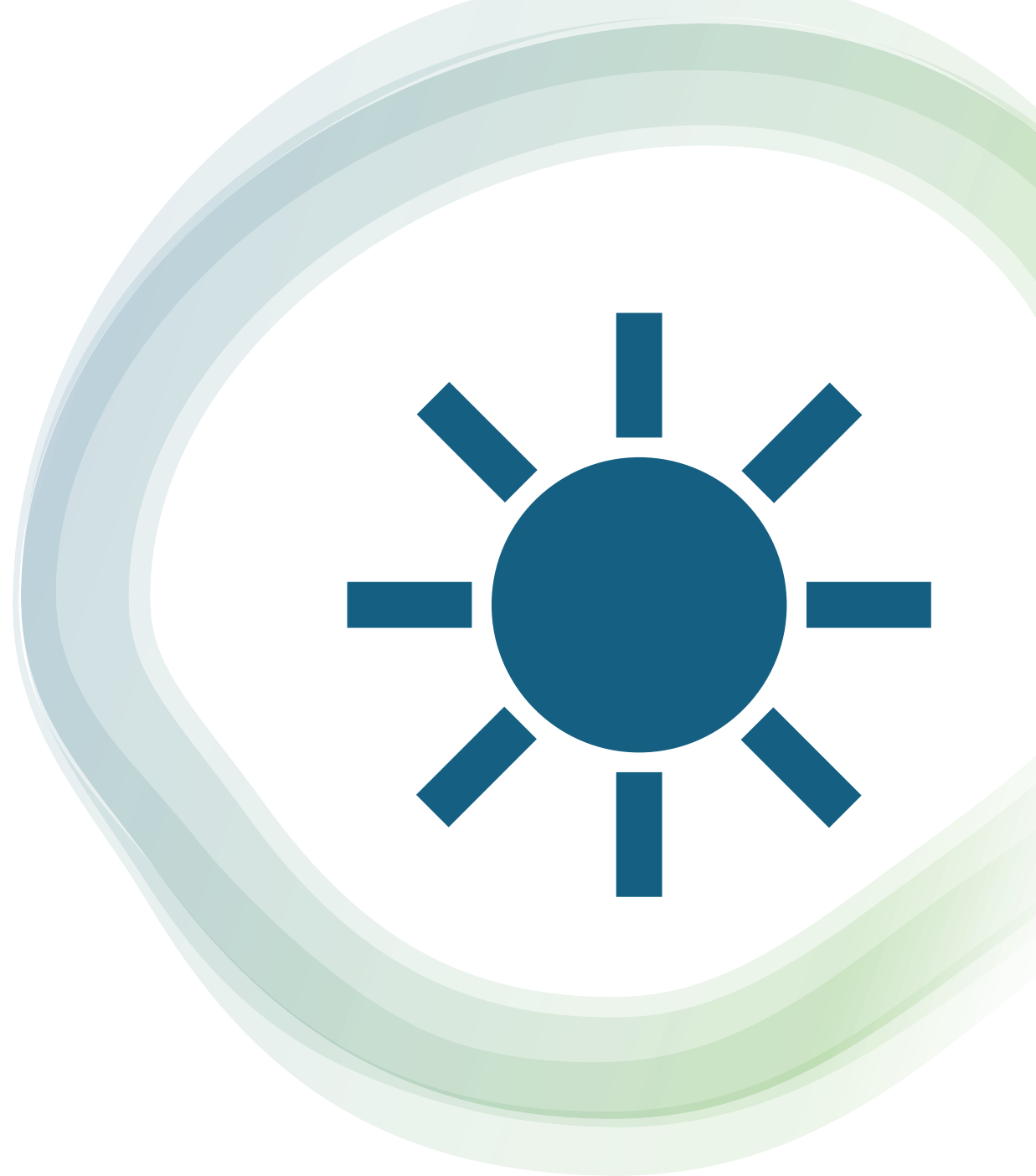


Projection Correction

Kincannon Wilson, James Wedum,
Nithin Weerasinghe

Problem Statement

- Images from projectors are susceptible to environmental perturbations
 - Light color
 - Light intensity
 - Surface color
 - Surface shape
 - Projector angle
- We seek to create a control system to correct for these issues
- Reactive-Adaptive Projection Correction System (RAPcSys)



Existing Solutions

Keystone Correction



```
graph TD; A[Keystone Correction] --> B[Color Management Systems]; B --> C[Ambient Light Sensing]; C --> D[Digital Signal Processing]; D --> E[3D Look-Up Tables];
```

Color Management Systems

Ambient Light Sensing

Digital Signal Processing

3D Look-Up Tables



A previous approach to projection correction

- "Real Time Adaptive Radiometric Compensation" (Grundhoefer & Bimber 2007)
- Requires specialized GPU algorithm

Methodology

Reactive-Adaptive Control System

- Feed-forward controller for image shape
- Feed-back controller for color correction

Low-pass filter

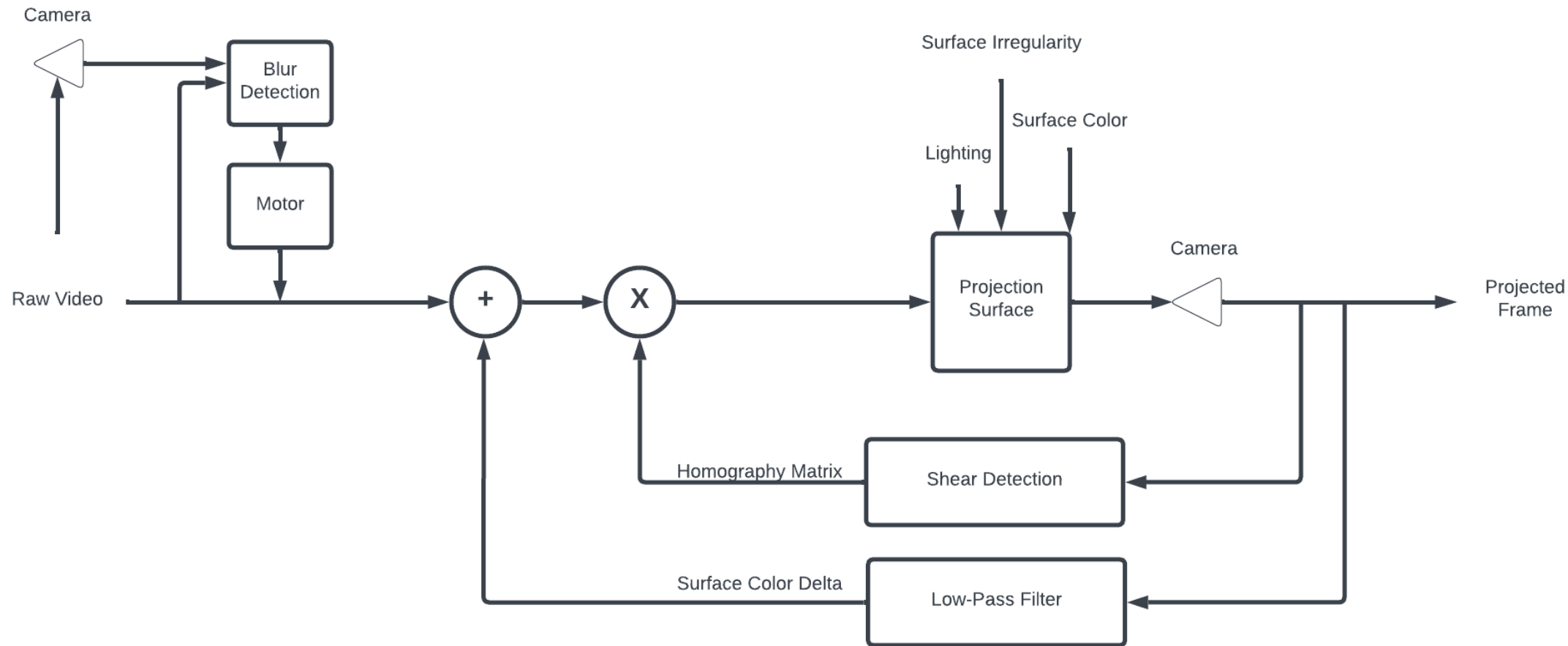
- Attenuate high-frequency information (such as motion)
- Focus on low-frequency delta (background/environment color)

PD controller for motor with rotary encoder for real-time focus adjustment

- Potential correction for rapid perturbations, such as the projector being struck

Single-sensor, low-cost option

- Dual-sensor with rotary encoder



Physical Setup



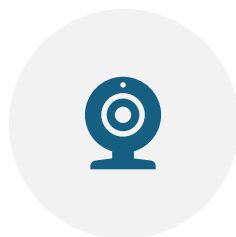
Software Setup



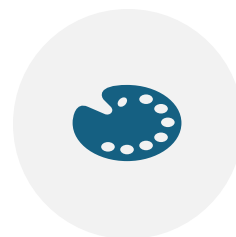
SHOWING IMAGES



TRANSFORMING IMAGES
(BEST SIFT MATCHES,
CONTOUR-BASED, MANUAL)



CAMERA INPUT



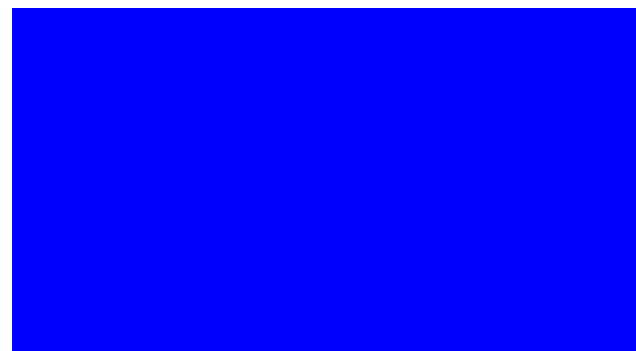
COLOR CORRECTION



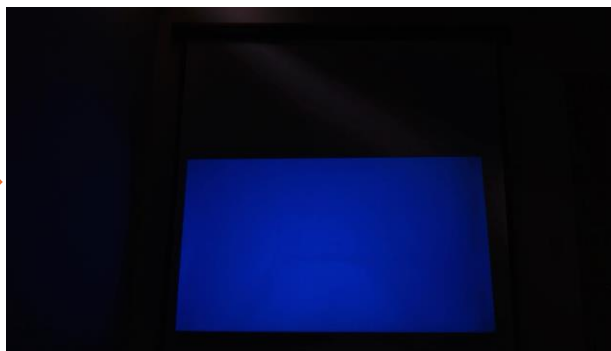
METRICS



Performance Metric



Actual



Recorded



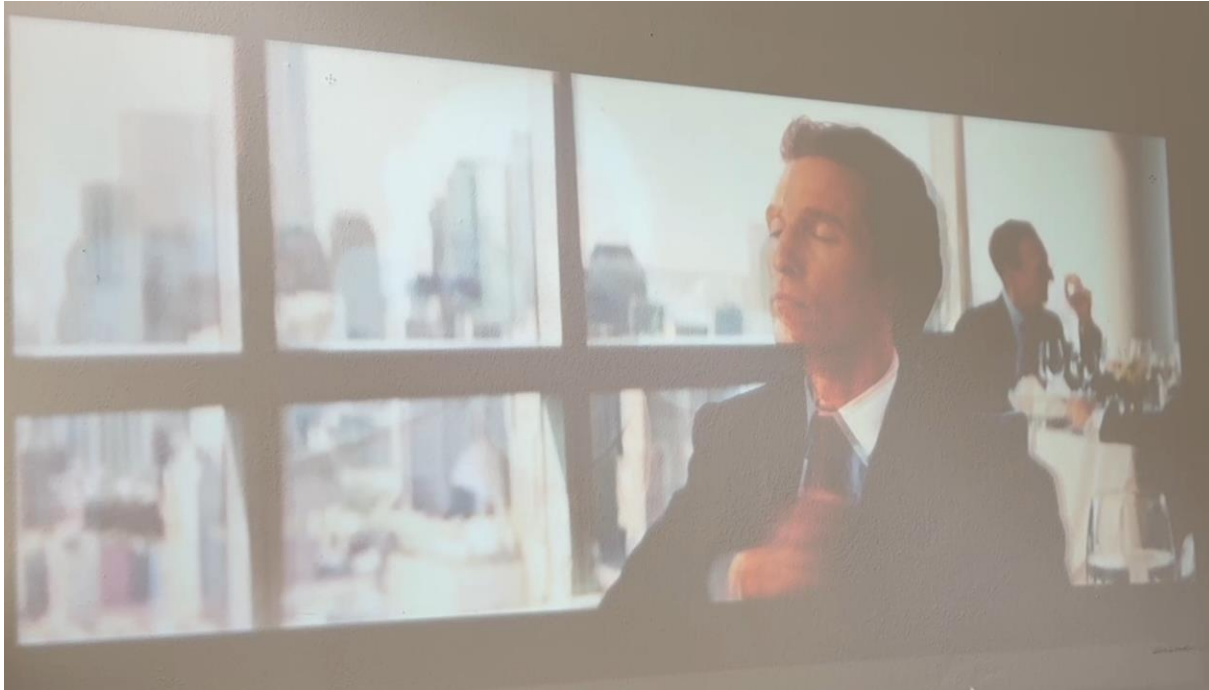
Transformed Recorded



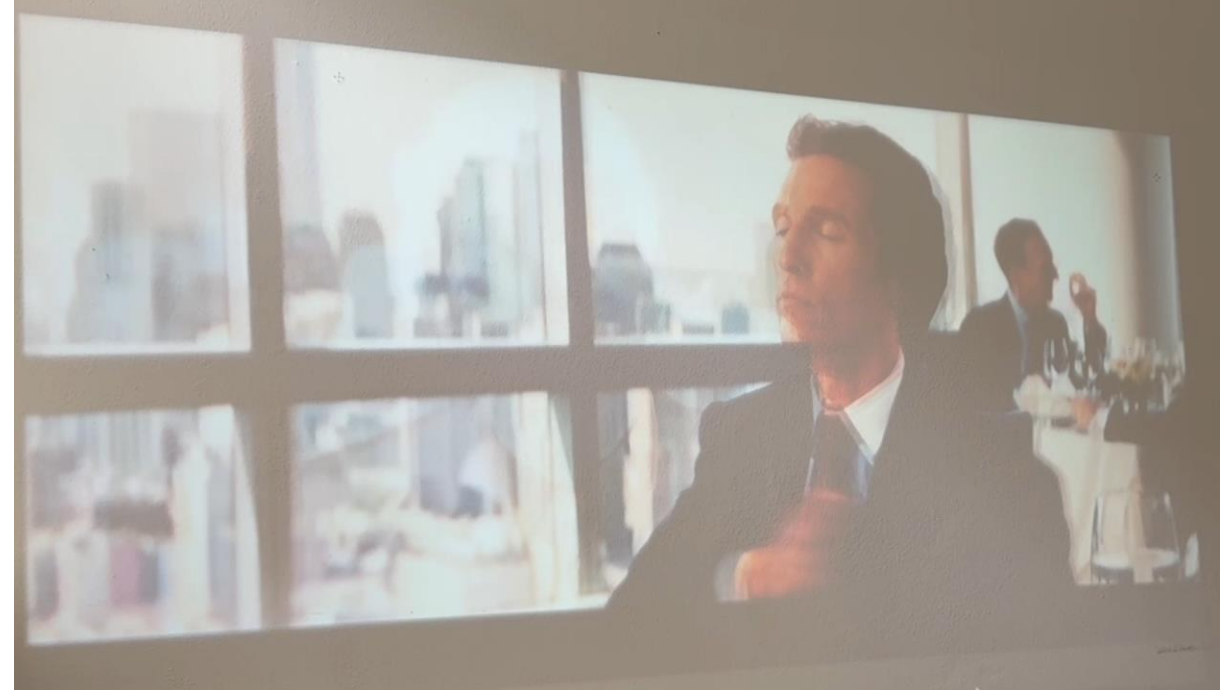
Normalized Pixel
Intensity Difference



Buffer of pixel-wise corrections

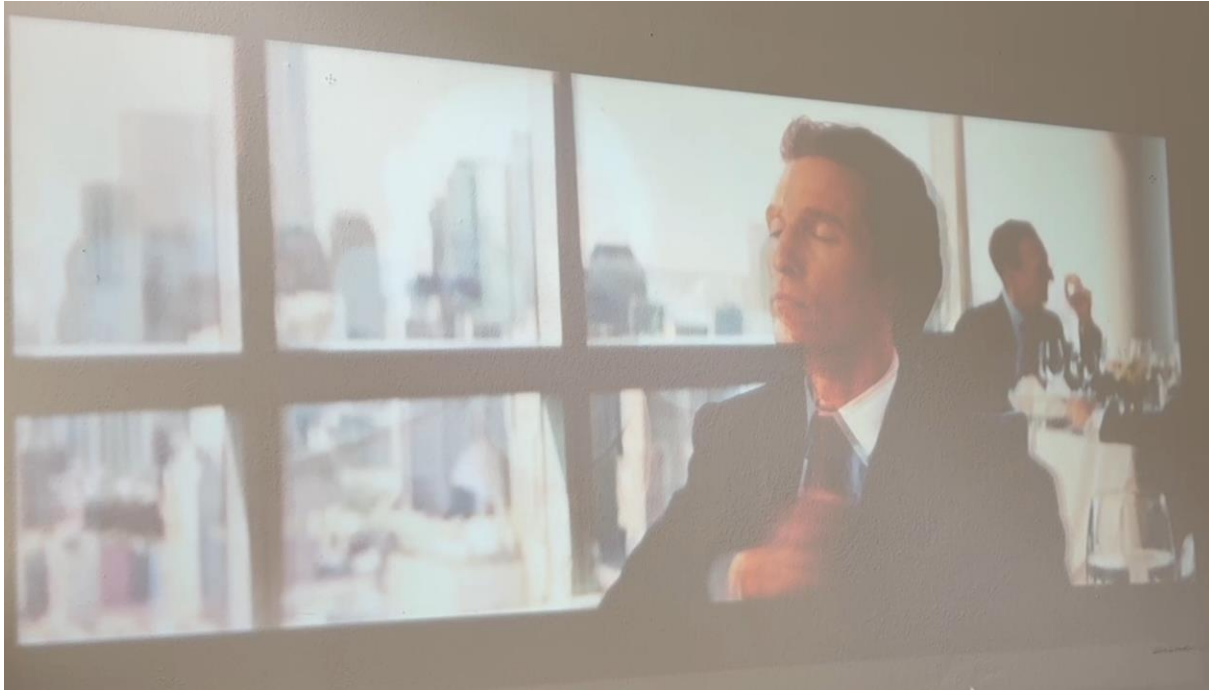


Median

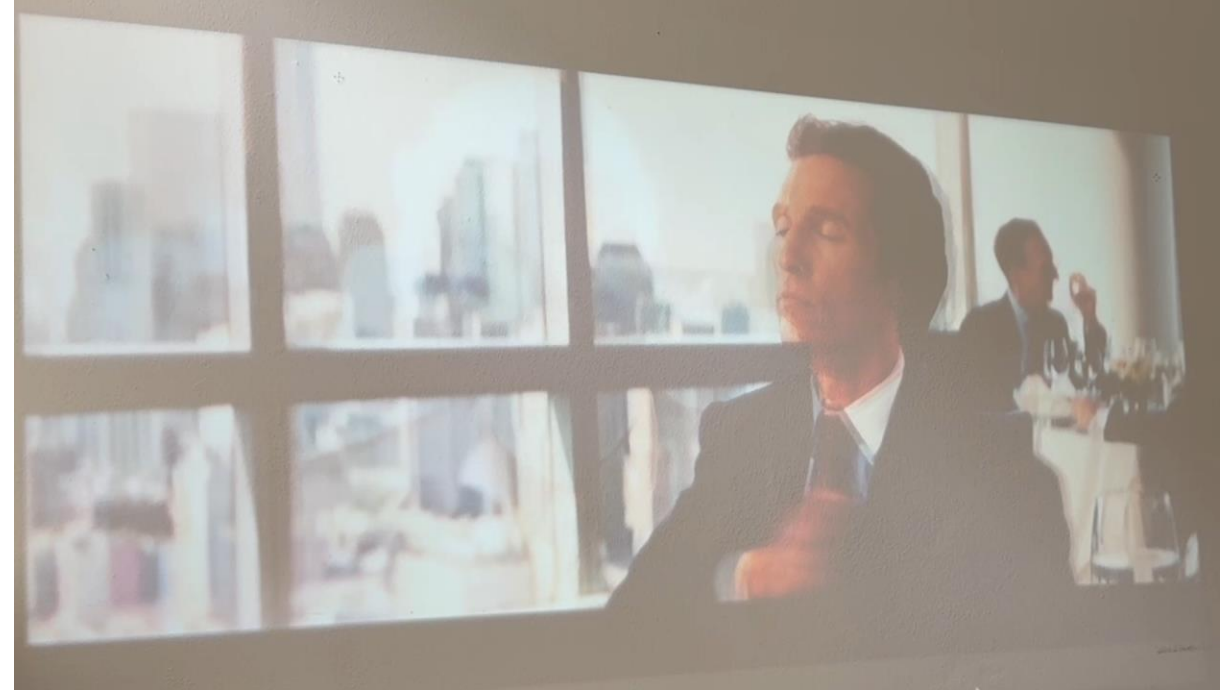


Average

Buffer of mean color corrections



Median

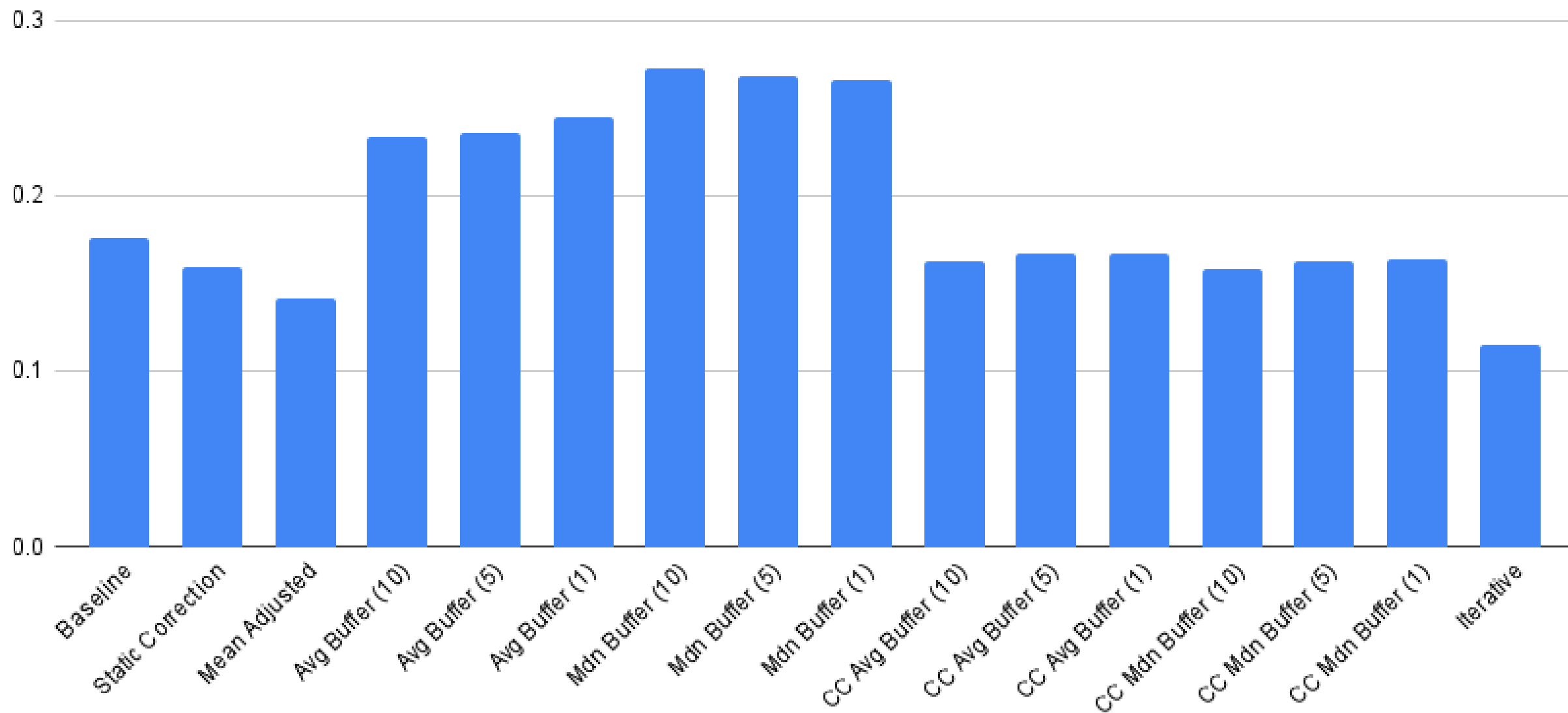


Average

Iterative Corrections



Results



A Closer Look at Iterative Corrections

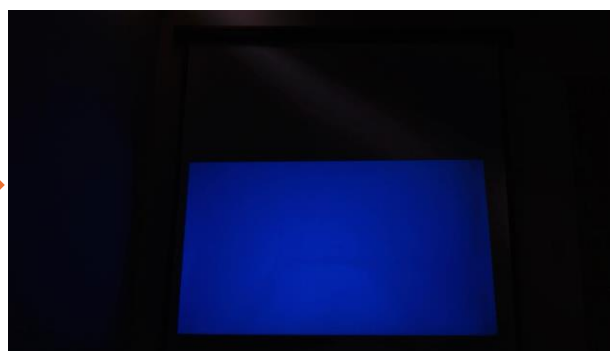




Performance Metric



Actual



Recorded



Transformed Recorded



Normalized Pixel
Intensity Difference





Conclusion

- Began with pixel-wise corrections and shifted to mean-based color corrections but a larger buffer was needed
- Employed an iterative adjustment method to optimize color correction for individual frames
- Future directions:
 - Utilize larger buffer and integrate low pass filter
 - Refine the machine-learning model to improve accuracy and reduce artifacts.



Questions