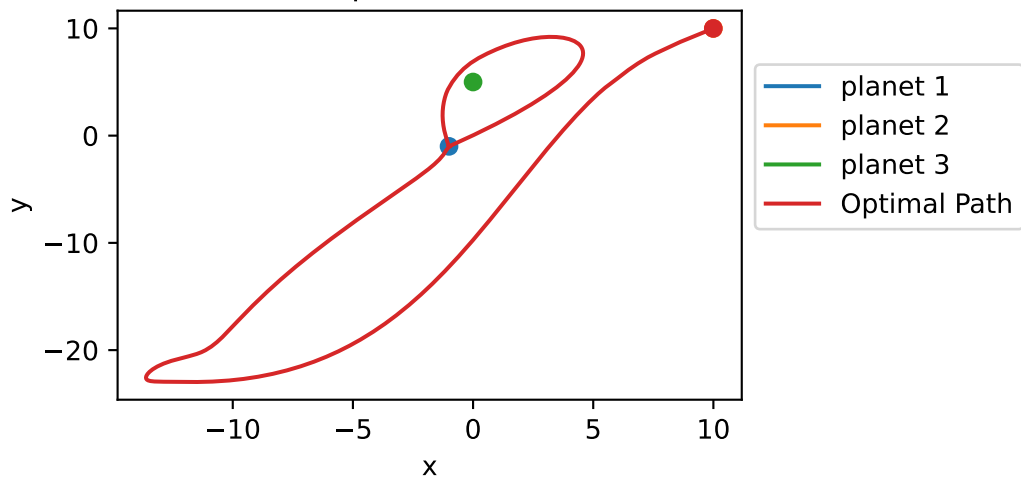


### Optimal Path



### Optimal Control

