# Joshua(Yuchen) Cao

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# Interests

Research: Learning-based media synthesis (GAN, NeRF). CV+CG, 3D Reconstruction, Mobile Perception.

Engineer: Front/back-end, iOS app/Unity game development, Machine Learning/Computer Vision/SLAM research engineering.



# **Carnegie Mellon University** MS. in Computational Design

Sep 2021 - now

Pittsburgh, PA

- System Courses: Computer System, Distributed System, Parallel Computing, Cloud Computing
- · Research Courses: CG, Learning-based Image Synthesis & Recognition, Computer Photography, PBR

# University of Chinese Academy of Sciences & ShanghaiTech University

Sep 2016 - July 2020

Shanghai, China

MS. in Computer Science

- System Courses: Operating System, Control Theory, Algorithm and Data Structure
- Research Courses: SLAM, CV, ML, Deep Learning, Convex Optimization, Robotics



#### **EXPERIENCE**

**EzPT** July 2022 - Aug 2022

Computer Vision Engineer & iOS Developer

Remote, USA

- Using Google MediaPipe and TensorFlow network & OpenCV for real-time Pose Estimation, assist Physical Therapist exercise.
- SwiftUI iOS development, Firebase BaaS with Cloud Function for data communication with front-end iOS and Web.

#### **Carnegie Mellon University**

Sep 2021 - Aug 2022

Research Assistant

Pittsburgh, PA

- Research Robotic Arm, RGBD-based Localization and Mapping, Surface Defact Detection in DFab with Prof. Joshua Bard.
- Research Path Planning, Pedestrian Detection, 3D Lidar-based SLAM, Ground Robotics with Prof. Daniel Cardoso.

# ShanghaiTech University

Oct 2016 - Dec 2020

Research & Teaching Assistant

Shanghai, China

- Research drone, Object Detection, DJI SDK, Reinforcement Learning in UAV-LAB with Prof. Xiaopei Liu.
- Research Multi-Sensor SLAM, Object Segmentation, 3D Reconstruction, Synthesized Dataset with Prof. Laurent Kneip.
- · Assist teaching Linear Algebra and SLAM course.

**EF Education First** Jan 2019 - Dec 2020

Full Stack Engineer Internship

Remote, China

- Independently design & develop a children-oriented English education webpage: IWB book series by React.js and Node.js.
- Full stack project based on Salesforce, an interactive questionnaire for data collection and market strategy: GoalMap.

# **\$** SKILLS

**Theory Knowledge** Deep Learning, SLAM, Media Generation, 3D vision, Computer Graphics

**Programming** C++ == C# == Python == JS == Swift > Java == Matlab > PHP

**Develop Tools** Pytorch, TensorFlow, OpenCV, OpenGL, Cuda, SwiftUI, ROS; React, JQuery, WebGL, threeJS, p5, NoSQL

Blender, Unity, Ableton Live, PS, C4D, Unreal, Rhino, LR, Ai, Premiere **Design Tools** Communication Chinese (Native), English (proficient), Japanese (listening and speaking)

#### PUBLICATIONS

# Representations and Benchmarking of Modern Visual SLAM Systems

**Sensors Journal** 

First Author https://www.mdpi.com/1424-8220/20/9/2572

Mar 2020

Synthesized Realistic dataset and groundTruth for SLAM task, Benchmark for Evaluation.

# Dense object reconstruction from RGBD images with embedded deep shape representations

**ACCV Workshop** 

Second Author https://arxiv.org/abs/1810.04891

Oct 2018

AutoEncoder-based 3D reconstruction from partial SLAM mapping.

## **PROJECTS**

# Personal CS projects website: https://caoyuchen.github.io/cs/

#### SLAM(Simultaneous Localization and Mapping) systems

Tradtional SLAM algorithm

- A fundamental SLAM system with tracking, mapping and pose optimization in Matlab. It includes SIFT & Harris feature extraction, 78 points, homography method, and LevenBerg-Marquardt average error for pose optimization. https://github.com/CaoYuchen/SLAM-basicframe
- Benchmark for semantic SLAM algorithm, including dataset, ground truth, and evaluation methods. https://github.com/CaoYuchen/SSS-dataset
- Probability estimation method based on particle filter for top-view 2D road scenario and MaskRCNN, used for re-localization

## **Learning-based Image Synthesis**

GAN, NeRF, Deep Learning

- Traditional CV methods of gradient SSD for RGB channel alignment and image trimming; CycleGAN in content-aware image synthesis; Poisson Blending in image blending; StyleGAN in style transfer. https://github.com/CaoYuchen/16726
- NeRF-based 3D architecture reconstruction, with sparse input of raw image and 5D camera ray parameters, generate consistent video frames and 3D models. https://github.com/CaoYuchen/NeRF-based-3D

#### **Robotics Development**

3D vision, ROS, VR/AR

- 2D Incision with Schunk Arm Robot. Use PyCAM and ROS RVIZ to adjust joints and links coordination. https://robotics.shanghaitech.edu.cn/node/114
- Path Planning with DJI SDK. Building TX1 and Raspberry Pi3 as an intermediate system for DJI M600.
- Flight VR project. Configuring 720 degrees of 8 GoPro on Drone, and stitching the synced stream into one Omni-direction file for VR presentation via AutoPano.
- SIST building 3D reconstruction. Using Faro to capture dense point cloud, using CloudCompare to alignment and merging.

#### **Computer Graphics**

CG, ray-tracing, rendering

• CMU 15662 projects: Draw SVG, MeshEdit, RayTracing, Animation: https://github.com/CaoYuchen/Scotty3D.

#### **Computer System & Architecture**

computer system

 CMU 15213 projects, Stack & Disassemble, Malloc(heap) implementation, Cache Simulator, I/O redirection, Web Proxy: https://github.com/CaoYuchen/CMU15513.

#### **Game & Web Development**

game, interactive media

- 48 hours GGJ 2D puzzle game based on Unity3D: Dr.Dox Quest for Time.
- · Advanced Game Studio project, asymmetric split-screen multi-players game. Cooperation, Puzzle Solving, Surviving: Penumbra.
- Website development for interactive teaching tools: IWB.
- 3D animated webs by three.js and WebGL: Dreamatic.

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### ■ Photography & Screenwriting & Cinematography

- Instagram: https://www.instagram.com/joshua\_cyc 500px: https://500px.me/caoyuchen
- Certificate Of Screenwriting from USC(1.5 years). Pieces: "Golden Sun & Silver Moon", "Batman: The Great Normal", "The Trace".

# ♬ Digital Music & 3D Art

SoundCloud: https://soundcloud.com/joshua-rain-24806913
Personal Portfolio: https://caoyuchen.github.io/portfolio/